# COMS21202: Symbols, Patterns and Signals Probabilistic Data Models

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# **Data Modelling**

- Deterministic models do not explicitly model uncertainties or 'randomness' in data
- Variability of inferences derived from the data is not included
- In many tasks, we benefit from modelling uncertainty and randomness
- ► This is explicit in Probabilistic Models

## Back to Fish - Discrete

#### Discrete variable:

# Example

A fisherman returns with the daily catch of fish. If we select a fish at random from the hold, what species will it be?

```
\textit{fish} \in \{\textit{salmon}, \textit{seabass}, \textit{cod}, ...\}
```

- A deterministic model would give one value, the most likely
- A probabilistic model quantifies the chance/probability of the selected fish being one of the possible species.
- ▶ Model the probability  $P(x_i = q_i)$  where  $q_i \in \{salmon, seabass, cod, \cdots\}$

## Back to Fish - Continuous

Continuous variable:

## Example

Predict the weight of fish from its length

Let us assume that we think the weight of fish is directly proportional to its length, i.e.  $weight = b \times length + a$ .

A **probabilistic approach** would model weight as a **random variable** and hypothesize that

$$weight = b \times length + a + \epsilon$$

where  $\epsilon$  is a random variable, usually close to zero

## Back to Fish - Continuous

$$weight = b \times length + a + \epsilon$$

- ➤ To model the random variable, we measure the difference between the predicted and measured weight values
- ▶ Modelled using a probability distribution for  $\epsilon$ ,
  - by a uniform distribution
  - by a normal distribution
  - **...**
- ▶ In the next slides, we will make the *logical* simplification (weight = 0 when length = 0)
- As a conclusion, the y-intercept can be set to zero, and

$$weight = a \times length + \epsilon$$

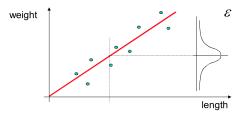
## Back to Fish - Continuous

$$weight = a \times length + \epsilon$$

This is a model with one parameter, apart from the uncertainty

We can assume, for example, that  $\epsilon$  is  $\mathcal{N}(0, \sigma^2)$ 

$$p(\epsilon) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{\epsilon^2}{2\sigma^2}}$$



- Similar to building deterministic models, probabilistic model parameters need to be tuned/trained
- Maximum-likelihood estimation (MLE) is a method of estimating the parameters of a probabilistic model.
- ightharpoonup Assume heta is a vector of all parameters of the probabilistic model
- ▶ MLE is an extremum estimator obtained by maximising an objective function of  $\theta$

#### Definition

Assume  $f(\theta)$  is an objective function to be optimised (e.g. maximised), the *arg max* corresponds to the value of  $\theta$  that attains the maximum value of the objective function f

$$\hat{\theta} = arg \max_{\theta} f(\theta)$$

- Note: this is different than maximising the function (i.e. finding the maximum value  $[max f(\theta)]$ )
- Tuning the parameter is then equal to finding the maximum argument arg max

Given a set of N data points -  $x_i$  is length and  $y_i$  is weight in our *fishy* example

$$D = \{(x_1, y_1), (x_2, y_2), \cdots, (x_N, y_N)\}\$$

- The probabilistic approach would:
  - derive expression for conditional probability of observing data D given parameter a

 using observed data, find paramter value which maximises the conditional probability (i.e. the likelihood)

$$a_{ML} = arg max_a p(D|a)$$

Given a set of N data points

$$D = \{(x_1, y_1), (x_2, y_2), \cdots, (x_N, y_N)\}\$$

Assume that observations are independent - a common assumption often referred to as i.i.d. independent and identically distributed - then :

$$p(D|a) = \prod_{i=1}^{N} p(y_i|x_i, a)$$

Given  $y_i = ax_i + \epsilon$ , and  $\epsilon$  is  $\mathcal{N}(0, \sigma^2)$ , then

$$p(y_i|x_i,a) \sim \mathcal{N}(ax_i,\sigma^2)$$

#### For a large sample:

- ► The average of *y<sub>i</sub>* value will be *a x<sub>i</sub>*
- ▶ The 'spread' will be the same as for  $\epsilon$ , defined by  $\sigma^2$

The conditional probability (for all data) is thus formulated as

$$p(D|a) = \prod_{i=1}^{N} p(y_i|x_i, a)$$
$$= \prod_{i=1}^{N} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{1}{2} \frac{(y_i - ax_i)^2}{\sigma^2}}$$

To tune the parameter, i.e. find the ML parameter,

$$\begin{split} a_{ML} &= arg \max_{a} p(D|a) \\ &= arg \max_{a} \prod_{i=1}^{N} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{1}{2}\frac{(y_{i}-ax_{i})^{2}}{\sigma^{2}}} \\ &= arg \max_{a} \ln \Big( \prod_{i=1}^{N} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{1}{2}\frac{(y_{i}-ax_{i})^{2}}{\sigma^{2}}} \Big) \\ &= arg \max_{a} \sum_{i=1}^{N} \ln \Big( \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{1}{2}\frac{(y_{i}-ax_{i})^{2}}{\sigma^{2}}} \Big) \\ &= arg \max_{a} \sum_{i=1}^{N} \ln \frac{1}{\sqrt{2\pi}\sigma} - \frac{(y_{i}-ax_{i})^{2}}{2\sigma^{2}} \\ &= arg \max_{a} \sum_{i=1}^{N} -(y_{i}-ax_{i})^{2} \qquad \text{(remove constants)} \\ &= arg \min_{a} \sum_{i=1}^{N} (y_{i}-ax_{i})^{2} \end{split}$$

Deterministic Least Squares:

$$a_{LS} = arg \min_a R(a) = arg \min_a \sum_i (y_i - a x_i)^2$$

Probabilistic Maximum Likelihood:

$$a_{ML} = arg \, min_a \sum_i (y_i - a \, x_i)^2$$

- same answer, different view
- ▶ Note: ML answer here assumes uncertainty is normally distributed

In both cases,

$$a_{ML} = arg \, min_a \sum_i (y_i - a \, x_i)^2$$

To find the minimum, find the derivative

$$\frac{d}{da}\sum_{i}(y_{i}-ax_{i})^{2}=-2\sum_{i}x_{i}(y_{i}-ax_{i})$$

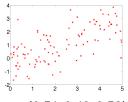
and equate it to zero

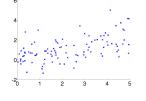
$$-2\sum_{i} x_{i}(y_{i} - a_{ML}x_{i}) = 0$$

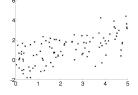
$$\sum_{i} x_{i}y_{i} - a_{ML}\sum_{i} x_{i}^{2} = 0$$

$$a_{ML} = \frac{\sum_{i} y_{i}x_{i}}{\sum_{i} x_{i}^{2}}$$

- so why to take the probabilistic approach?
- Probabilistic Models can tell us more
- For example: how much does  $a_{ML}$  vary if it is computed for many data samples? How reliable is it?

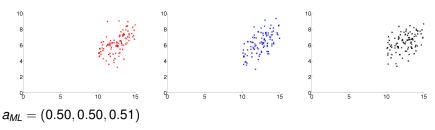






 $a_{ML} = (0.51, 0.49, 0.52)$ 

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- so why to take the probabilistic approach?
- Probabilistic Models can tell us more
- ► For example: how much does *a<sub>ML</sub>* vary if it is computed for many data samples? How reliable is it?
- ► For *M* different samples

$$Var(a_{ML}) = \frac{1}{M-1} \sum_{j=1}^{M} \left( a_{MLj} - \overline{a_{ML}} \right)$$

▶ If

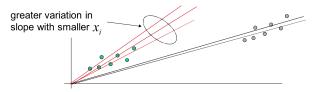
$$a_{ML} = \frac{\sum_{i} y_{i} x_{i}}{\sum_{i} x_{i}^{2}}$$

 $\triangleright$  Then for the same values  $x_i$ 

$$Var(a_{ML}) = \frac{\sigma^2}{\sum_i x_i^2}$$

$$Var(a_{ML}) = \frac{\sigma^2}{\sum_i x_i^2}$$

Variance is thus dependent on input variables



## Maximum Likelihood Estimation - General

 Maximum Likelihood Estimation (MLE) is a common method for solving such problems

```
	heta_{MLE} = arg \max_{\theta} p(D|\theta)
= arg \max_{\theta} \ln p(D|\theta)
= arg \min_{\theta} - \ln p(D|\theta)
```

## **MLE Recipe**

- 1. Determine  $\theta$ , D and expression for likelihood  $p(D|\theta)$
- 2. Take the natural logarithm of the likelihood
- 3. Take the derivative of  $\ln p(D|\theta)$  w.r.t.  $\theta$ . If  $\theta$  is a multi-dimensional vector, take partial derivatives
- 4. Set derivative(s) to 0 and solve for  $\theta$

## MLE Recipe - Ex1

1. Determine  $\theta$ , D and expression for likelihood  $p(D|\theta)$ 

$$p(D|a) = \prod_{i=1}^{N} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{1}{2} \frac{(y_i - ax_i)^2}{\sigma^2}}$$

- 2. Take the natural logarithm of the likelihood  $a_{MI} = arg \min_{a} \sum_{i} (y_i a x_i)^2$
- 3. Take the derivative of  $\ln p(D|\theta)$  w.r.t.  $\theta$ . If  $\theta$  is a multi-dimensional vector, take partial derivatives

$$\frac{d}{da}\sum_{i}(y_{i}-ax_{i})^{2}=-2\sum_{i}x_{i}(y_{i}-ax_{i})$$

4. Set derivative(s) to 0 and solve for  $\theta$ 

$$a_{ML} = \frac{\sum_{i} y_{i} x_{i}}{\sum_{i} x_{i}^{2}}$$

## Example

Given a coin, you were assigned the task of figuring out whether the coin will land on its head or tails. You were asked to build a probabilistic model (i.e. with confidence)

- Data: head/tail binary attempts (of size N)
- Model: Binomial distribution
- Model Parameters: head probability α

#### Definition

The **binomial distribution** gives the probability distribution for a discrete variable to obtain exactly D successes out of N trials, where the probability of the success is  $\alpha$  and the probability of failure is  $(1 - \alpha)$  and  $0 \le \alpha \le 1$ 

The binomial distribution probability density function is given by

$$P(D|N) = {N \choose D} \alpha^{D} (1 - \alpha)^{N-D}$$
$$= \frac{N!}{D!(N-D)!} \alpha^{D} (1 - \alpha)^{N-D}$$

Accordingly, using the binomial probability distribution where D is the number of heads in N coin tosses and  $\theta$  is the probability of getting heads in a single toss,

$$P(D|\theta) = \binom{N}{D} \theta^{D} (1-\theta)^{N-D}$$

Maximum Likelihood Estimation (MLE) would then be looking for

$$\theta_{ML} = arg \max_{\theta} p(D|\theta)$$

Take the natural logarithm

$$P(D|\theta) = \binom{N}{D} \theta^{D} (1-\theta)^{N-D}$$

$$\ln P(D|\theta) = \ln \binom{N}{D} + D \ln \theta + (N-D) \ln(1-\theta)$$

Take the derivative w.r.t θ

$$\frac{d}{d\theta} \ln P(D|\theta) = D\frac{1}{\theta} + (N - D)\frac{1}{1 - \theta}(-1)$$
$$= \frac{D}{\theta} - \frac{N - D}{1 - \theta}$$

 $\blacktriangleright$  Set the derivative to 0 and solve for  $\theta$ 

$$\begin{split} \frac{D}{\theta_{ML}} - \frac{N - D}{1 - \theta_{ML}} &= 0\\ \frac{D(1 - \theta_{ML}) - (N - D)\theta_{ML}}{\theta_{ML}(1 - \theta_{ML})} &= 0\\ D - N\theta_{ML} &= 0\\ \theta_{ML} &= \frac{D}{N} \end{split}$$

In conclusion, the probability of heads is the relative frequency of heads to the sample

## Example

Given a coin, you were assigned the task of figuring out whether the coin will land on its head or tails. You were asked to build a probabilistic model (i.e. with confidence)

#### What if you chose another model?

- Data: head/tail binary attempts (of size N)
- Model: Normal distribution
- ▶ Model Parameters: mean  $\mu$  assume  $\sigma$  is a constant

Assume  $D = \{d_1, d_2, \cdots d_N\}$  are *noisy* measurements of an actual signal  $\theta = \mu$ , where noise is Gaussian,

$$p(D|\theta) = \prod_{i=1}^{N} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(d_i-\theta)^2}{2\sigma^2}}$$

i.e.  $D = \{0, 0, 1, 1, 1, \cdots\}$  where 0 represents tails and 1 represents heads...

Take the natural logarithm and derivate

$$p(D|\theta) = \prod_{i=1}^{N} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(d_i - \theta)^2}{2\sigma^2}}$$

$$\ln p(D|\theta) = N \ln \frac{1}{\sqrt{2\pi}\sigma} + \sum_{i=1}^{N} -\frac{(d_i - \theta)^2}{2\sigma^2}$$

$$\frac{d}{d\theta} \ln p(D|\theta) = \sum_{i=1}^{N} -\frac{2(d_i - \theta)(-1)}{2\sigma^2}$$

▶ Set the derivative to 0 and solve for  $\theta$ 

$$\sum_{i=1}^{N} \frac{(d_i - \theta_{ML})}{\sigma^2} = 0$$

$$\sum_{i=1}^{N} d_i - N\theta_{ML} = 0$$

$$\theta_{ML} = \frac{1}{N} \sum_{i=1}^{N} d_i$$

$$\theta_{ML} = \overline{d}$$

## Example

Given a coin, you were assigned the task of figuring out whether the coin will land on its head or tails. You were asked to build a probabilistic model (i.e. with confidence)

Use binomial distribution for likelihood.

$$\theta_{ML} = \frac{D}{N}$$

where D is the number of success (i.e. heads)

Use Gaussian distribution for likelihood

$$\theta_{ML} = \frac{1}{N} \sum_{i=1}^{N} d_i$$

where  $d_i = 1$  if success (i.e. heads) or  $d_i = 0$  if failure (i.e. tails)

same answer, different view

#### Probabilistic Model - Likelihood and Prior

- MLE ignores any prior knowledge we may have about θ
- If we have prior knowledge about values that  $\theta$  is likely to have, then we can built this into MLE

$$\theta_{ML} = arg \max_{\theta} p(D|\theta) p(\theta)$$

This is known as Maximum a Posteriori (MAP) estimation

## Example

Given a coin, you were assigned the task of figuring out whether the coin will land on its head or tails. You were asked to build a probabilistic model (i.e. with confidence)

- Suppose we want to utilise our prior belief that coins are typically fair
- ▶  $p(\theta)$  would peak around  $\theta = 0.5$
- Let's use

$$p(\theta) = \frac{b}{\theta} (1 - \theta)$$

where *b* is a normalising factor so the area under the curve is equal to 1

Likelihood:

$$p(D|\theta) = \binom{N}{D} \theta^D (1-\theta)^{N-D}$$

▶ Prior:

$$p(\theta) = b\theta(1-\theta)$$

Posterior:

$$p(D|\theta) p(\theta) = \binom{N}{D} \theta^{D} (1-\theta)^{N-D} b \theta (1-\theta)$$

Take the natural logarithm and derivate

$$p(D|\theta) p(\theta) = \binom{N}{D} \theta^{D} (1-\theta)^{N-D} b \theta (1-\theta)$$

$$\ln p(D|\theta) p(\theta) = \ln \binom{N}{D} + D \ln \theta + (N-D) \ln(1-\theta) + \ln b + \ln \theta + \ln(1-\theta)$$

$$\frac{d}{d\theta}\ln p(D|\theta)\,p(\theta) = D\frac{1}{\theta} - (N-D)\frac{1}{1-\theta} + \frac{1}{\theta} - \frac{1}{(1-\theta)}$$

▶ Set the derivative to 0 and solve for  $\theta_{MAP}$ 

$$\begin{split} & D \frac{1}{\theta_{MAP}} - (N - D) \frac{1}{1 - \theta_{MAP}} + \frac{1}{\theta_{MAP}} - \frac{1}{(1 - \theta_{MAP})} = 0 \\ & \frac{D + 1}{\theta_{MAP}} - (N - D + 1) \frac{1}{1 - \theta_{MAP}} = 0 \\ & \frac{(D + 1)(1 - \theta_{MAP}) - (N - D + 1)\theta_{MAP}}{\theta_{MAP}(1 - \theta_{MAP})} = 0 \\ & \theta_{MAP} = \frac{D + 1}{N + 2} \end{split}$$

 The prior added two 'virtual' coin tosses, one with heads and one with tails

#### Conclusion

- Probabilistic models encode randomness in the data
- They enable predicting confidence (as a probability)
- Parameters of the model are tuned
- Maximum Likelihood Estimation (MLE) is a recipe used for training model parameters
- MLE does not encode our prior knowledge of possible parameters
- Maximum a Posteriori (MAP) maximises likelihood along with prior

# **Further Reading**

- Probability and Statistics for Engineers and Scientists
   Walpole et al (2007)
  - Section 3.1
  - Section 3.2
  - Section 4.1
  - Section 4.2
- Statistical Learning Methods Russell and Norvig (2003)
  - Chapter 20 (p. 712 720)