

# Proyecto Final

## Código fuente

AirGPS

### Model > Converters > CoordinateCircleConverter.cs

```
class CoordinateCircleConverter
{
    static readonly double circumference = 40030.174;

    public static Circle CoordinateToCircle(Coordinate coordinate)
    {
        double y = circumference / 360 * Math.Cos(coordinate.Latitude * Math.PI / 180);
        double x = y * coordinate.Longitude;

        return new Circle { X = x, Y = y, R = coordinate.Distance };
    }

    public static Coordinate CircleToCoordinate(Circle circle) => new Coordinate
    {
        Latitude = (180 / Math.PI) * Math.Acos(circle.Y * 360 / circumference),
        Longitude = circle.X / circle.Y,
        Distance = circle.R
    };
}
```

### Model > Genetic > Genetics.cs

```
class Genetics
{
    // For random numbers
    static Random Rand;

    // Get the necessary bits for a certain variable
    public static int GetMj(double a, double b, int n)
    {
        if (b - a <= 0 || n <= 0)
            throw new ArgumentException($"El dominio de la variable es inválido: a = {a}, b = {b}, n = {n}.");

        double r = (Math.Log(b - a) + Math.Log(10) * n) / Math.Log(2);

        int integerPart = Convert.ToInt32(r);

        return r - integerPart <= 0 ? integerPart : integerPart + 1;
    }

    // Map a chromosome part that fits in 64 bits
```

```

private static double MapValueFast(char[] chromosome, int begin, int end, double a, double
b)
{
    ulong val = 0;
    ulong vmx = 0;
    for (int i = begin; i < end; ++i)
    {
        val = (val << 1) | ((ulong)chromosome[i] - '0');
        vmx = (vmx << 1) | 1ul;
    }

    return (ulong)((b - a) * val) / (double)vmx + a;
}

// Map a chromosome part that doesn't fit in 64 bits
private static double MapValueSlow(char[] chromosome, int begin, int end, double a, double
b)
{
    double val = 0;
    double vmx = 0;
    for (int i = begin; i < end; ++i)
    {
        val = val * 2 + (chromosome[i] - '0');
        vmx = vmx * 2 + 1;
    }

    return (b - a) * val / vmx + a;
}

// Get the mapped value of a chromosome's variable
// The variable occupies from chromosome[begin] to chromosome[end - 1]
public static double MapValue(char[] chromosome, int begin, int end, double a, double b)
{
    return end - begin > 64 ? MapValueSlow(chromosome, begin, end, a, b) :
MapValueFast(chromosome, begin, end, a, b);
}

// Generate a chromosome with n random bits
public static char[] GenerateRandomChromosome(int n)
{
    var r = new char[n];

    for (int i = 0; i < n; ++i)
        r[i] = Rand.Next(0, 2).ToString()[0];

    return r;
}

// Get the mapped values of a chromosome
public static double[] GetMappedValues(char[] chromosome, Limit[] limits)
{
    var mappedValues = new double[limits.Length];
    for (int i = 0, j = 0; i < mappedValues.Length; ++i)
    {

```

```

        mappedValues[i] = MapValue(chromosome, j, j + limits[i].M, limits[i].A,
limits[i].B);
        j += limits[i].M;
    }

    return mappedValues;
}

// Check if a chromosome is valid
public static bool CheckChromosome(char[] chromosome, Limit[] limits, Func<double, double,
bool>[] restrictions)
{
    var mappedValues = GetMappedValues(chromosome, limits);

    for (int i = 0; i < restrictions.Length; ++i)
        if (!restrictions[i](mappedValues[0], mappedValues[1]))
            return false;

    return true;
}

// Generate a valid chromosome
public static char[] GenerateChromosome(Limit[] limits, Func<double, double, bool>[]
restrictions, CancellationTokens timer)
{
    char[] chromosome = null;
    bool stay = true;

    while (stay && !timer.IsCancellationRequested)
    {
        int n = 0;
        foreach (var l in limits) n += l.M;

        chromosome = GenerateRandomChromosome(n);
        stay = !CheckChromosome(chromosome, limits, restrictions);
    }

    if (timer.IsCancellationRequested)
        throw new TimeoutException();

    return chromosome;
}

// Generate a population of n valid chromosomes
public static char[][] GeneratePopulation(Limit[] limits, Func<double, double, bool>[]
restrictions, int m, CancellationTokens timer)
{
    char[][] population = new char[m][];

    for (int i = 0; i < m; ++i)
        population[i] = GenerateChromosome(limits, restrictions, timer);

    return population;
}

```

```

// Mutate a random chromosome's gen and return a new one
public static char[] Mutate(char[] chromosome)
{
    var r = new char[chromosome.Length];

    for (int i = 0; i < r.Length; ++i)
        r[i] = chromosome[i];

    int index = Rand.Next(0, r.Length);
    r[index] = r[index] == '1' ? '0' : '1';

    return r;
}

// Cross two chromosome in a random position
public static char[] Cross(char[] parent1, char[] parent2)
{
    int chromosomeSize = parent1.Length;
    var child = new char[chromosomeSize];
    int n = Rand.Next(0, chromosomeSize);

    for (int i = 0; i < n; ++i)
        child[i] = parent1[i];

    for (int i = n; i < chromosomeSize; ++i)
        child[i] = parent2[i];

    return child;
}

```

its sum

```

// Calculate the z values associated with each chromosome and return an array with them and
public static (double[], double) CalculateZValues(char[][] population, Limit[] limits)
{
    double total = 0;
    var values = new double[population.Length];

    for (int i = 0; i < values.Length; ++i)
    {
        var mappedValues = GetMappedValues(population[i], limits);
        values[i] = -Restriction.Z(mappedValues[0], mappedValues[1]);
        total += values[i];
    }

    return (values, total);
}

```

them

```

// Calculate the percentages associated and the accumulates with each z value and return
public static (double[], double[]) CalculatePercentages(double[] values, double total)
{
    var percentages = new double[values.Length];
    var accumulates = new double[values.Length];
    double accumulate = 0.0;

```

```

        for (int i = 0; i < values.Length; ++i)
        {
            percentages[i] = values[i] / total;
            accumulate += percentages[i];
            accumulates[i] = accumulate;
        }

        return (percentages, accumulates);
    }

    // Get the best chromosomes of a population
    public static char[][] GetTheBest(char[][] population, double[] values, double[]
accumulates)
    {
        var best = new PriorityQueue();
        for (int i = 0; i < values.Length; ++i)
        {
            double r = Rand.NextDouble();
            for (int j = 0; j < values.Length; ++j)
            {
                if (r < accumulates[j])
                {
                    best.Push(population[j], values[j]);
                    break;
                }
            }
        }

        return best.GetOnlyValues();
    }

    // Genetic round
    public static char[][] Round(char[][] population, Limit[] limits)
    {
        var (values, total) = CalculateZValues(population, limits);
        var (percentages, accumulates) = CalculatePercentages(values, total);

        return GetTheBest(population, percentages, accumulates);
    }

    // Regenerate the given population with best chromosomes, and mutation and crossover of
best chromosomes
    public static void RegeneratePopulation(char[][] population, char[][] best, Limit[] limits,
Func<double, double, bool>[] restrictions, CancellationToken timer)
    {
        int i;
        for (i = 0; i < best.Length; ++i)
            population[i] = best[i];

        for (int j = i; j < population.Length; ++j)
        {
            while (!timer.IsCancellationRequested)
            {
                population[j] = Rand.Next(0, 2) == 0 ? Mutate(best[Rand.Next(0, i)]) :
Cross(best[Rand.Next(0, i)], best[Rand.Next(0, i)]);
            }
        }
    }

```

```

        if (CheckChromosome(population[j], limits, restrictions))
            break;
    }

    if (timer.IsCancellationRequested)
        throw new TimeoutException();
}

}

// Genetic Algorithm
public static (int, double, double, double) Calculate(Circle[] circles, int n, int rounds,
int size, double e, bool rel, Action<(int, double, double, double)> loggerTuple, Action<string>
logger, Cancellation token timer)
{
    Rand = new Random();

    var answer = (0, 0.0, 0.0, 0.0);

    Restriction.InitializeZ(circles);

    double error = Restriction.CalculateError(e, circles.Length, rel);
    logger($"Usando error: {error}");
    var restrictions = Restriction.Generate(circles, error);
    var limits = Limit.Generate(circles, n, error, logger);

    logger($"Generando población de {size} individuos...");
    var population = GeneratePopulation(limits, restrictions, size, timer);
    logger($"Población generada de {size} individuos...");

    for (int i = 0; i < rounds && i < 100; ++i)
    {
        var best = Round(population, limits);
        RegeneratePopulation(population, best, limits, restrictions, timer);

        var values = GetMappedValues(population[0], limits);

        answer = (i, values[0], values[1], Restriction.Z(values[0], values[1]));
        loggerTuple(answer);
    }

    return answer;
}
}

```

## Model › Genetic › Limit.cs

```
class Limit
{
    public double A { set; get; }
    public double B { set; get; }
    private int m;
    public int M
    {
        get => m;
        set { m = value < 0 ? -value : value; }
    }

    // Generar limites
    public static Limit[] Generate(Circle[] circles, int n, double error, Action<string>
logger)
    {
        try
        {
            // Hot fix
            var original = new double[circles.Length];

            for (int i = 0; i < circles.Length; ++i) {
                original[i] = circles[i].R;
                circles[i].R = Math.Sqrt(Help.Square(circles[i].R) + error);
            }

            var commonArea = Circle.GetIntersectionArea(new List<Circle>(circles));

            for (int i = 0; i < circles.Length; ++i)
                circles[i].R = original[i];

            // ---

            double ax = commonArea.LeftDown.X;
            double ay = commonArea.LeftDown.Y;

            double bx = commonArea.RightUp.X;
            double by = commonArea.RightUp.Y;

            logger($"Límites en X: ({ax}, {bx}).");
            logger($"Límites en Y: ({ay}, {by}).");

            int mx = Genetics.GetMj(ax, bx, n);
            int my = Genetics.GetMj(ay, by, n);

            Limit[] limits = {
                new Limit() { A = ax, B = bx, M = mx },
                new Limit() { A = ay, B = by, M = my }
            };

            return limits;
        }
        catch (Exception e)
```

```

        {
            logger(e.Message);
            throw e;
        }
    }
}

```

## Model > Genetic > Restriction.cs

```

class Restriction
{
    // Represents the objective function
    public static Func<double, double, double> Z = null;

    // Create a new objective function
    public static void InitializeZ(Circle[] circles)
    {
        Z = (double x, double y) => {
            double result = 0;

            foreach(var circle in circles)
                result += Help.Square(Help.Square(x - circle.X) + Help.Square(y - circle.Y) -
Help.Square(circle.R));

            return result;
        };
    }

    // Create a new restriction
    static Func<double, double, bool> CreateCircleRestriction(Circle circle, double error) =>
        (double x, double y) => Help.Square(x - circle.X) + Help.Square(y - circle.Y) -
Help.Square(circle.R) <= error;

    // Error calculation (Modified to meters)
    public static double AbsoluteError(double e, int numOfRestrictions) => Math.Sqrt(Z(0, 0)) *
e / (numOfRestrictions * 10E+6);
    public static double RelativeError(double e, int numOfRestrictions) => Z(0, 0) * e /
(numOfRestrictions * 10E+6);
    public static double CalculateError(double e, int length, bool rel) => rel ?
RelativeError(e, length) : AbsoluteError(e, length);

    // Generate all restrictions
    public static Func<double, double, bool>[] Generate(Circle[] circles, double error)
    {
        var restrictions = new Func<double, double, bool>[circles.Length];
        for (int i = 0; i < restrictions.Length; ++i)
        {
            restrictions[i] = CreateCircleRestriction(circles[i], error);
        }
        return restrictions;
    }
}

```



## Model > Data > Area.cs

```
public class Area
{
    public Point LeftDown { get; set; }
    public Point RightUp { get; set; }

    /// Static methods

    // Calculate a rectangular area that enclose all the points
    public static Area CalculateArea(List<Point> points)
    {
        double minX = points[0].X;
        double maxX = points[0].X;

        double minY = points[0].Y;
        double maxY = points[0].Y;

        foreach (var p in points)
        {
            if (minX > p.X)
                minX = p.X;

            if (maxX < p.X)
                maxX = p.X;

            if (minY > p.Y)
                minY = p.Y;

            if (maxY < p.Y)
                maxY = p.Y;
        }

        return new Area
        {
            LeftDown = new Point(minX, minY),
            RightUp = new Point(maxX, maxY)
        };
    }

    // Get the limits of the intersection in an axis
    // Throws Exception if there are not intersection
    static (double, double) GetLimitsOfAxis(List<Area> areas, string axis)
    {
        var end = axis == "X" ? areas[0].RightUp.X : areas[0].RightUp.Y;
        for (int i = 1; i < areas.Count; ++i)
        {
            var aux = axis == "X" ? areas[i].RightUp.X : areas[i].RightUp.Y;
            if (aux < end)
                end = aux;
        }

        var begin = axis == "X" ? areas[0].LeftDown.X : areas[0].LeftDown.Y;
        for (int i = 1; i < areas.Count; ++i)
```

```

        {
            var aux = axis == "X" ? areas[i].LeftDown.X : areas[i].LeftDown.Y;
            if (aux > begin)
                begin = aux;
        }

        if (begin >= end)
            throw new Exception($"No existe una intersección común en las áreas a lo largo de {axis}");

        return (begin, end);
    }

    // Get the intersection of all areas
    // Throw Exception if there are not intersection
    public static Area GetIntersectionOfAllAreas(List<Area> areas)
    {
        var (xBegin, xEnd) = GetLimitsOfAxis(areas, "X");
        var (yBegin, yEnd) = GetLimitsOfAxis(areas, "Y");

        return new Area
        {
            LeftDown = new Point(xBegin, yBegin),
            RightUp = new Point(xEnd, yEnd)
        };
    }
}

```

## Model > Data > Circle.cs

```

public class Circle
{
    // Properties
    public Point Center { get; set; }
    public double X
    {
        get => Center.X;
        set { Center.X = value; }
    }
    public double Y
    {
        get => Center.Y;
        set { Center.Y = value; }
    }
    private double r;
    public double R
    {
        get => r;
        set { r = value < 0 ? -value : value; }
    }

    // Constructors
    public Circle()

```

```

{
    Center = new Point(0, 0);
}

// Check if the given points are contained in the circle
public bool ContainsAll(List<Point> points)
{
    foreach (Point p in points)
        if (!Contains(p))
            return false;

    return true;
}

// Check if the point is contained in the circle
public bool Contains(Point p) => Help.Square(p.X - X) + Help.Square(p.Y - Y) <=
Help.Square(R);

public List<Point> GetCardinalPoints()
{
    return new List<Point>
    {
        new Point(X, Y + R),
        new Point(X, Y - R),
        new Point(X + R, Y),
        new Point(X - R, Y)
    };
}

/// Static methods

// Computes the distance between two circles' centers
public static double DistanceBetweenTwoCenters(Circle c1, Circle c2)
    => Point.DistanceBetweenTwoPoints(c1.X, c1.Y, c2.X, c2.Y);

// Check if inner circle is enclosed in outer circle
static bool IsEnclosedIn(Circle ic, Circle oc) => oc.R >=
Circle.DistanceBetweenTwoCenters(ic, oc) + ic.R;

// Remove all enclosing circles
static List<Circle> RemoveEnclosingCircles(List<Circle> circles)
{
    // De-duplicate list and order it by radius
    var orderedList = new List<Circle>(new HashSet<Circle>(circles, new
CircleHashComparer())).OrderBy(circle => circle.R).ToList();
    var smallest = orderedList[0];
    orderedList.RemoveAt(0);

    // Quit all circles enclosing smallest
    var r = orderedList.Where(circle => !IsEnclosedIn(smallest, circle)).ToList();
    r.Insert(0, smallest);

    return r;
}

```

```

// Get the intersection points between a line and a circle
// Throws Exception if line doesn't intersect with circle
static List<Point> IntersectionLineCircle(Line line, Circle circle)
{
    double cprime = line.C - line.A * circle.X - line.B * circle.Y;

    var aa = Help.Square(line.A) + Help.Square(line.B);
    Func<double, double> bb = n => -2 * n * cprime;
    Func<double, double> cc = n => cprime * cprime - Help.Square(circle.R * n);

    var (e1, e2) = Help.QuadraticEquation(aa, bb(line.A), cc(line.B));
    var (n1, n2) = Help.QuadraticEquation(aa, bb(line.B), cc(line.A));

    var x1 = e1 + circle.X;
    var x2 = e2 + circle.X;
    var y1 = n1 + circle.Y;
    var y2 = n2 + circle.Y;

    if (x1 == x2 && y1 == y2)
        return new List<Point> { new Point(x1, y2) };

    return new List<Point>
    {
        new Point(x1, y1),
        new Point(x2, y2)
    };
}

// Get the intersection point(s) between two circles
// Throws Exception if the circles don't intersect themselves
static List<Point> IntersectionCircleCircle(Circle c1, Circle c2)
{
    var line = new Line
    {
        A = 2 * (c2.X - c1.X),
        B = 2 * (c2.Y - c1.Y),
        C = (Help.Square(c1.R) - Help.Square(c2.R)) - (Help.Square(c1.X) -
Help.Square(c2.X)) - (Help.Square(c1.Y) - Help.Square(c2.Y))
    };

    return IntersectionLineCircle(line, c1);
}

// Calculate the intersection area of two circles
// Throws ArgumentOutOfRangeException if the circles don't intersect themselves
static Area GetAreaFromCircles(Circle c1, Circle c2)
{
    try
    {
        var points = new List<Point>();

        points.AddRange(c1.GetCardinalPoints().Where(point =>
c2.Contains(point)).ToList());
        points.AddRange(c2.GetCardinalPoints().Where(point =>
c1.Contains(point)).ToList());
    }
}

```

```

        points.AddRange(IntersectionCircleCircle(c1, c2));

        return Area.CalculateArea(points);
    }
    catch (Exception)
    {
        throw new ArgumentOutOfRangeException($"Los círculos: {{{{c1.X}, {c1.Y}, {c1.R}}}, {{{c2.X}, {c2.Y}, {c2.R}}}}} no se intersectan en ningún punto.");
    }
}

// Get all intersections areas of the circles
// Throws ArgumentOutOfRangeException if any pair of circles don't intersect themselves
static List<Area> GetIntersectionAreas(List<Circle> circles)
{
    var areas = new List<Area>();

    for (int i = 0; i < circles.Count; ++i)
        for (int j = i + 1; j < circles.Count; ++j)
            areas.Add(GetAreaFromCircles(circles[i], circles[j]));

    return areas;
}

// Get the rectangle intersection area of circles
// Throw Exception if a pair of circles don't intersect or doesn't exists an area of
intersection
public static Area GetIntersectionArea(List<Circle> circles)
{
    Point leftDown, rightUp;

    var noEnclosingCircles = RemoveEnclosingCircles(circles);

    if (noEnclosingCircles.Count == 1)
    {
        var final = noEnclosingCircles[0];

        leftDown = new Point(final.X - final.R, final.Y - final.R);
        rightUp = new Point(final.X + final.R, final.Y + final.R);

        return new Area { LeftDown = leftDown, RightUp = rightUp };
    }

    var areas = GetIntersectionAreas(noEnclosingCircles);

    return Area.GetIntersectionOfAllAreas(areas);
}
}

```

## Model › Data › Coordinate.cs

```
public class Coordinate
{
    public double Latitude { get; set; }
    public double Longitude { get; set; }

    private double distance;
    public double Distance
    {
        get => distance;
        set
        {
            distance = value < 0.0 ? -value : value;
        }
    }

    public Coordinate() { Latitude = 0; Longitude = 0; Distance = 0; }
    public Coordinate(double latitude, double longitude, double distance) { Latitude = latitude; Longitude = longitude; Distance = distance; }
}
```

## Model › Data › Line.cs

```
class Line
{
    public double A { get; set; }
    public double B { get; set; }
    public double C { get; set; }
}
```

## Model › Data › Point.cs

```
public class Point
{
    public double X { get; set; }
    public double Y { get; set; }

    public Point(double x, double y) { X = x; Y = y; }

    public static double DistanceBetweenTwoPoints(double px, double py, double qx, double qy)
        => Math.Sqrt(Help.Square(px - qx) + Help.Square(py - qy));

    public static double DistanceBetweenTwoPoints(Point p, Point q)
        => Math.Sqrt(Help.Square(p.X - q.X) + Help.Square(p.Y - q.Y));
}
```

## Model > Helpers > Help.cs

```
class Help
{
    // Simplification of a * a
    public static double Square(double a) => a * a;

    // Resolves ax^2 + bx + c = 0
    public static (double, double) QuadraticEquation(double a, double b, double c)
    {
        double discriminant = b * b - 4 * a * c;
        if (discriminante < 0)
            throw new Exception("El discriminante no es positivo.");

        double x1 = ((-b) + Math.Sqrt(discriminant)) / (2 * a);
        double x2 = ((-b) - Math.Sqrt(discriminant)) / (2 * a);

        return (x1, x2);
    }
}
```

## Model > Helpers > Pair.cs

```
public struct Pair
{
    public char[] Item { get; set; }
    public int Repetitions { get; set; }
    public double Weight { get; set; }

    public bool EqualsTo(char[] item)
    {
        if (Item.Length != item.Length) return false;

        for (int i = 0; i < item.Length; ++i)
            if (Item[i] != item[i])
                return false;

        return true;
    }
}
```

## Model > Helpers > PriorityQueue.cs

```
public class PriorityQueue
{
    public List<Pair> queue;

    // Get each Pair.Item of each queue element and return them
    public char[][] GetOnlyValues()
    {
        char[][] result = new char[queue.Count][];
    }
}
```

```

        for (int i = 0; i < result.Length; ++i)
            result[i] = queue[i].Item;

        return result;
    }

    // Constructor
    public PriorityQueue()
    {
        queue = new List<Pair>();
    }

    // Push an element, ordering first by repetitions, then by weight
    public void Push(char[] item, double weight)
    {
        // First element to be inserted
        if (queue.Count == 0)
        {
            queue.Add(new Pair { Item = item, Repetitions = 1, Weight = weight});
            return;
        }

        // Search the element in the queue
        int i = SearchFor(item);

        // If exists, update the repetitions or add a new element if not
        if (i >= 0)
            queue[i] = new Pair { Item = queue[i].Item, Repetitions = queue[i].Repetitions + 1,
Weight = queue[i].Weight };
        else
        {
            queue.Add(new Pair { Item = item, Repetitions = 1, Weight = weight });
            i = queue.Count - 1;
        }

        Shift(i);
    }

    // Search for the item inside the queue and returns its index
    // Return -1 if not
    public int SearchFor(char[] item) => queue.FindIndex(e => e.EqualsTo(item));

    // Shift the queue starting from i
    void Shift(int i)
    {
        for (int j = i - 1; j >= 0; --j)
        {
            if (queue[i].Repetitions < queue[j].Repetitions)
                break;

            if (queue[i].Repetitions > queue[j].Repetitions)
            {
                Swap(i, j);
                i = j;
                continue;
            }
        }
    }

```



```

    }

    if (queue[i].Weight <= queue[j].Weight)
        continue;

    Swap(i, j);
    i = j;
}

// Swap i with j elements in the queue
void Swap(int i, int j)
{
    Pair aux = queue[i];
    queue[i] = queue[j];
    queue[j] = aux;
}
}

```

Integrantes:

- Joel Harim Hernandez Javier (3CM8)
- Eli Sanchez Martinez (3CM8)
- Brenda Mariana Hernández Morales (3CM7)
- Diana Laura Jiménez López (3CM7)

El código completo se puede encontrar en Github:

<https://github.com/JoelHernandez343/TrilateracionGpsGeneticos>