

23/12/2020

LAB PROGRAM-12

- Q. Drive a Stepper Motor interface to rotate the motor in clockwise by N steps. Introduce suitable delay between successive steps.

A.

```
#include <stdio.h>
#include <reg51.h>
char xdata port_a = 0x803;
char xdata port_at = 0x800;
char xdata acc_at = 0x30;

delay()
{
    int j;
    for(j=0; j<800; j++) {}
}

void main() { port = 0x80; while(1) {
    acc = 0x88;
    port_a = acc;
    delay();
    acc = 0x44;
    port_a = acc;
    delay();
    acc = 0x22;
    port_a = acc;
    delay();
    acc = 0x11;
    port_a = acc;
    delay();
}
```