

Mathreex ICPC Team Notebook 2024

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1 Template

1.1 Template

```
#include <bits/stdc++.h>

#define mp make_pair
#define pb push_back
#define ppb pop_back
#define all(a) (a).begin(), (a).end()
#define sz(a) (int)a.size()
#define f first
#define s second
#define forn(i, n) for (int i = 0; i < n; i++)
#define forx(i, x, n) for (int i = x; i < n; i++)
#define each(a, x) for (auto &(a) : (x))

using namespace std;

typedef long long ll;
typedef vector<int> vi;
typedef vector<ll> vl;

void solve() {
    // code here
}

int main()
{
    ios::sync_with_stdio(0); cin.tie(0); cout.tie(0);
    solve();
    return 0;
}
```

2 Graph

2.1 BFS Algorithm

```
vector<int> bfs(vector<vector<int>>& g, int v) {
    vector<int> dis(g.size(), -1);
    queue<int> q;
    dis[v] = 0;
    q.push(v);
    while(!q.empty()) {
        int node = q.front();
        q.pop();
        for(int x : g[node]) {
            if(dis[x] == -1) {
                dis[x] = dis[node] + 1;
                q.push(x);
            }
        }
    }
    return dis;
}
```

2.2 DFS Algorithm

```
vector<bool> vis(tam);
```

```

void dfs(int node){
    vis[node] = 1;
    for(int x : g[node])
        if(!vis[x])
            dfs(x);
}

```

2.3 FloodFill Algorithm

```

int n, m;
int dir[2][4] = {{0,0,1,-1}, {1,-1,0,0}};

vector<vector<int>> tab, visi;

int floodfill(int x, int y) {
    if(x < 0 || y < 0 || x >= n || y >= m || visi[x][y] || tab[x][y] == 0)
        return;
    visi[x][y] = 1;
    int ret = 1;
    for(int i = 0; i < 4; i++)
        ret += floodfill(x + dir[0][i], y + dir[1][i]);
    return ret;
}

```

2.4 Dijkstra's Algorithm

```

typedef long long ll;

const long long INF = 4e18;

vector<ll> dijkstra(vector<vector<pair<ll, ll>>> graph, int n, int initial_node)
{
    vector<ll> dis(n + 1, INF);
    dis[initial_node] = 0;

    priority_queue<pair<ll, ll>, vector<pair<ll, ll>>, greater<pair<ll, ll>>> pq;
    pq.push({0, initial_node});
    while (!pq.empty())
    {
        pll minor = pq.top();
        pq.pop();
        ll actual_cost = minor.f;
        int node = minor.s;
        if (dis[node] < actual_cost)
            continue;

        for (auto to : graph[node])
        {
            int neighbor = to.f;
            ll cost = to.s;
            if (dis[node] + cost < dis[neighbor])
            {
                dis[neighbor] = dis[node] + cost;
                pq.push({dis[neighbor], neighbor});
            }
        }
    }
    return dis;
}

```

2.5 Floyd Warshall's Algorithm

```

typedef long long ll;

vector<vector<ll>> floydWarshall(vector<vector<pair<ll, ll>>> graph, int n)
{
    vector<vector<ll>> dis(n + 1, vl(n + 1, INF));
    forn(i, n) dis[i][i] = 0;

    forn(u, n)
    {
        for (auto to : graph[u])
        {
            ll v = to.f, w = to.s;
            dis[u][v] = min(dis[u][v], w);

```

```

        dis[v][u] = min(dis[v][u], w);
    }
}

forn(k, n)
{
    forn(u, n)
    {
        forn(v, n) dis[u][v] = min(dis[u][v], dis[u][k] + dis[k][v]);
    }
}

return dis;
}

```

2.6 MST (Kruskal's Algorithm)

```

typedef long long ll;

ll kruskal(vector<pair<ll, pair<int, int>>> edges, int n)
{
    sort(all(edges));
    UnionFind dsu(n + 1);
    int countEdges = 0;
    ll res = 0;
    for (auto edge : edges)
    {
        ll weight = edge.f;
        int u = edge.s.f;
        int v = edge.s.s;
        if (dsu.join(u, v))
        {
            countEdges++;
            res += weight;
        }
    }

    if (countEdges == n - 1)
        return res;

    if (countEdges < n - 1)
        return -1;

    return res;
}

```

2.7 Union Find Structure

```

struct UnionFind
{
    vector<int> p;
    UnionFind(int n) : p(n, -1) {}

    int find(int x)
    {
        if (p[x] == -1)
            return x;

        return p[x] = find(p[x]);
    }

    bool join(int x, int y)
    {
        x = find(x), y = find(y);
        if (x == y)
            return 0;

        p[y] = x;
        return 1;
    }
};

```

3 DFS

3.1 Coin Change

```

void solve() {
    ll n_coins, total;
    cin >> n_coins >> total;
    vl dp(total + 1, INT32_MAX - 1);
    vl coins(n_coins);
    forn(i, n_coins) cin >> coins[i];

    dp[0] = 0;
    for(i, n_coins) {
        each(coin, coins) {
            if (coin + i > x) continue;
            dp[coin + i] = min(dp[coin + i], dp[i] + 1);
        }
    }

    if (dp[total] + 1 == INT32_MAX) cout << "-1\n";
    else cout << dp[total] << '\n';
}

```

3.2 Knapsack

```

ll knapsack(ll W, vi weights, vi profits, int n) {
    vector<vi> dp(n + 1, vi(W + 1));
    forn(i, n + 1) {
        forn(w, W + 1) {
            if (i == 0 || w == 0) dp[i][w] = 0;
            else if (weights[i - 1] <= w)
                dp[i][w] = max(
                    profit[i - 1] + dp[i - 1][w - weights[i - 1]],
                    dp[i - 1][w]);
            else
                dp[i][w] = dp[i - 1][w];
        }
    }
    return dp[n][W];
}

```

3.3 Longest Common Subsequence

```

int lcs(string &s1, string &s2) {
    int m = sz(s1), n = sz(s2);

    vector<vi> dp(m + 1, vi(n + 1, 0));
    forx(i, 1, m + 1) {
        forx(j, 1, n + 1) {
            dp[i][j] = max(dp[i - 1][j], dp[i][j - 1]);
            if (s1[i - 1] == s2[j - 1]) dp[i][j] = max(dp[i][j], dp[i - 1][j - 1] + 1);
        }
    }
    return dp[m][n];
}

```

3.4 Longest Increasing Subsequences

```

int lis(vi &original) {
    vi aux;
    forn(i, sz(original)) {
        auto it = lower_bound(all(aux), original[i]);
        if (it == aux.end()) aux.pb(original[i]);
        else *it = original[i];
    }
    return sz(aux);
}

```

4 Query

4.1 Prefix sum

```

void solve() {
    ll n, q, x, y;
    cin >> n >> q;

    vl nums(n, prefix(n + 1));
    forn(i, n) cin >> nums[i], prefix[i + 1] = prefix[i] + nums[i];

    forn(i, q) {
        cin >> x >> y;
        cout << prefix[y] - prefix[x - 1] << '\n';
    }
}

```

4.2 Prefix sum 2D

```

void solve() {
    ll n, q;
    cin >> n >> q;
    vector<string> s(n); // 0-index

    vector<vl> prefix(n + 1, vl(n + 1)); // 1-index
    forn(i, n) {
        forn(j, n) {
            ll value = s[i][j] == '+';
            prefix[i + 1][j + 1] = (value
                                   + prefix[i][j + 1]
                                   + prefix[i + 1][j]
                                   - prefix[i][j]);
        }
    }

    while (q--) {
        ll x1, y1, x2, y2;
        cin >> x1 >> y1 >> x2 >> y2;
        x1--, y1--, x2--, y2--;

        ll sum = (prefix[x2 + 1][y2 + 1]
                  - prefix[x1][y2 + 1]
                  - prefix[x2 + 1][y1]
                  + prefix[x1][y1]); // 0-index query
        cout << sum << '\n';
    }
}

```

4.3 Fenwick Tree

```

struct BIT { // 1-index
    vl bit;
    ll n;

    BIT(int n) : bit(n + 1), n(n) {}

    ll lsb(int i) { return i & -i; }

    void add(int i, ll x) {
        for (; i <= n; i += lsb(i)) bit[i] += x;
    }

    ll sum(int r) {
        ll res = 0;
        for (; r > 0; r -= lsb(r)) res += bit[r];
        return res;
    }

    ll sum(int l, int r) {
        return sum(r) - sum(l - 1);
    }

    void set(int i, ll x) {
        add(i, x - sum(i, i));
    }
};

```

4.4 Fenwick Tree 2D

```

struct BIT2D {
    vector<vl> bit;
    ll n, m;

```

```

BIT2D(ll n, ll m) : bit(n + 1, vector<ll>(m + 1)), n(n), m(m) {}

ll lsb(ll i) {
    return i & -i;
}

void add(int row, int col, ll x) {
    for (int i = row; i <= n; i += lsb(i)) {
        for (int j = col; j <= m; j += lsb(j)) {
            bit[i][j] += x;
        }
    }
}

ll sum(int row, int col) {
    ll res = 0;
    for (int i = row; i > 0; i -= lsb(i)) {
        for (int j = col; j > 0; j -= lsb(j)) {
            res += bit[i][j];
        }
    }
    return res;
}

ll sum(int x1, int y1, int x2, int y2) {
    return (sum(x2, y2)
            - sum(x1 - 1, y2)
            - sum(x2, y1 - 1)
            + sum(x1 - 1, y1 - 1));
}

void set(int x, int y, ll val) {
    add(x, y, val - sum(x, y, x, y));
}
};

```

4.5 General Segtree

```

struct Node {
    ll a = 0;

    Node(ll val = 0) : a(val) {}
};

Node e() {
    Node node;
    return node;
}

Node op(Node a, Node b) {
    Node node;
    node.a = a.a ^ b.a;
    return node;
}

struct Segtree {
    vector<Node> nodes;
    ll n;

    void init(int n) {
        auto a = vector<Node>(n, e());
        init(a);
    }

    void init(vector<Node>& initial) {
        nodes.clear();
        n = initial.size();
        int size = 1;
        while (size < n) {
            size *= 2;
        }
        nodes.resize(size * 2);
        build(0, 0, n-1, initial);
    }

    void build(int i, int sl, int sr, vector<Node>& initial) {
        if (sl == sr) {
            nodes[i] = initial[sl];
        } else {
            ll mid = (sl + sr) >> 1;
            build(i*2+1, sl, mid, initial);
            build(i*2+2, mid+1, sr, initial);
            nodes[i] = op(nodes[i*2+1], nodes[i*2+2]);
        }
    }
};

```

```

void update(int i, int sl, int sr, int pos, Node node) {
    if (sl <= pos && pos <= sr) {
        if (sl == sr) {
            nodes[i] = node;
        } else {
            int mid = (sl + sr) >> 1;
            update(i * 2 + 1, sl, mid, pos, node);
            update(i * 2 + 2, mid + 1, sr, pos, node);
            nodes[i] = op(nodes[i*2+1], nodes[i*2+2]);
        }
    }
}

void update(int pos, Node node) {
    update(0, 0, n - 1, pos, node);
}

Node query(int i, int sl, int sr, int l, int r) {
    if (l <= sl && sr <= r) {
        return nodes[i];
    } else if (sr < l || r < sl) {
        return e();
    } else {
        int mid = (sl + sr) / 2;
        auto a = query(i * 2 + 1, sl, mid, l, r);
        auto b = query(i * 2 + 2, mid + 1, sr, l, r);
        return op(a, b);
    }
}

Node query(int l, int r) {
    return query(0, 0, n - 1, l, r);
}

Node get(int i) {
    return query(i, i);
}
};

```

4.6 Sum Lazytree

```

// 0-index
struct Lazytree {
    int n;
    vl sum;
    vl lazySum;

    void init(int nn) {
        sum.clear();
        n = nn;
        int size = 1;
        while (size < n) {
            size *= 2;
        }
        sum.resize(size * 2);
        lazySum.resize(size * 2);
    }

    void update(int i, int sl, int sr, int l, int r, ll diff) {
        if (lazySum[i]) {
            sum[i] += (sr - sl + 1) * lazySum[i];
            if (sl != sr) {
                lazySum[i * 2 + 1] += lazySum[i];
                lazySum[i * 2 + 2] += lazySum[i];
            }
            lazySum[i] = 0;
        }

        if (l <= sl && sr <= r) {
            sum[i] += (sr - sl + 1) * diff;
            if (sl != sr) {
                lazySum[i * 2 + 1] += diff;
                lazySum[i * 2 + 2] += diff;
            }
        } else if (sr < l || r < sl) {
        } else {
            int mid = (sl + sr) >> 1;
            update(i * 2 + 1, sl, mid, l, r, diff);
            update(i * 2 + 2, mid + 1, sr, l, r, diff);
            sum[i] = sum[i * 2 + 1] + sum[i * 2 + 2];
        }
    }

    void update(int l, int r, ll diff) {
        assert(l <= r);
    }
};

```

```

        assert(r < n);
        update(0, 0, n - 1, 1, r, diff);
    }

    ll query(int i, int sl, int sr, int l, int r) {
        if (lazySum[i]) {
            sum[i] += lazySum[i] * (sr - sl + 1);
            if (sl != sr) {
                lazySum[i * 2 + 1] += lazySum[i];
                lazySum[i * 2 + 2] += lazySum[i];
            }
            lazySum[i] = 0;
        }

        if (l <= sl && sr <= r) {
            return sum[i];
        } else if (sr < l || r < sl) {
            return 0;
        } else {
            int mid = (sl + sr) >> 1;
            return query(i * 2 + 1, sl, mid, l, r) + query(i * 2 + 2, mid + 1, sr, l, r);
        }
    }

    ll query(int l, int r)
    {
        assert(l <= r);
        assert(r < n);
        return query(0, 0, n - 1, 1, r);
    }
};

```

5 Geometry

5.1 2D Library

```

typedef long double lf;
const lf EPS = 1e-8L;
const lf E0 = 0.0L; //Keep = 0 for integer coordinates, otherwise = EPS
const lf INF = 5e9;

enum {OUT, IN, ON};

struct pt {
    lf x, y;
    pt() {}
    pt(lf a, lf b): x(a), y(b) {}

    pt operator - (const pt &q) const {
        return {x - q.x, y - q.y};
    }

    pt operator + (const pt &q) const {
        return {x + q.x, y + q.y};
    }

    pt operator * (const lf &t) const {
        return {x * t, y * t};
    }

    pt operator / (const lf &t) const {
        return {x / t, y / t};
    }

    bool operator < (const pt &q) const {
        if (fabsl(x - q.x) > E0) return x < q.x;
        return y < q.y;
    }

    void normalize() {
        lf norm = hypotl(x, y);
        if (fabsl(norm) > EPS)
            x /= norm, y /= norm;
    }
};

pt rot90(pt p) { return {-p.y, p.x}; }
pt rot(pt p, lf w) {
    return {cosl(w) * p.x - sinl(w) * p.y, sinl(w) * p.x + cosl(w) * p.y};
}

lf norm2(pt p) { return p.x * p.x + p.y * p.y; }
lf dis2(pt p, pt q) { return norm2(p-q); }

```

```

lf norm(pt p) { return hypotl(p.x, p.y); }
lf dis(pt p, pt q) { return norm(p - q); }

lf dot(pt p, pt q) { return p.x * q.x + p.y * q.y; }
lf cross(pt p, pt q) { return p.x * q.y - q.x * p.y; }

lf orient(pt a, pt b, pt c) { return cross(b - a, c - a); };

lf angle(pt a, pt b) { return atan2(cross(a, b), dot(a, b)); }
// rad => * 180.0 / M_PI
lf angle2(pt a, pt b) { return acos(dot(a, b) / abs(a) / abs(b)); }

lf abs(pt a) { return sqrt(a.x * a.x + a.y * a.y); }

lf proj(pt a, pt b) { return dot(a, b) / abs(b); }

bool in_angle(pt a, pt b, pt c, pt p) {
    //assert(fabsl(orient(a, b, c)) > E0);
    if (orient(a, b, c) < -E0)
        return orient(a, b, p) >= -E0 || orient(a, c, p) <= E0;
    return orient(a, b, p) >= -E0 && orient(a, c, p) <= E0;
}

struct line {
    pt nv;
    lf c;

    line(pt _nv, lf _c): nv(_nv), c(_c) {}

    line(lf _a, lf _b, lf _c): nv({_b, -_a}), c(_c) {}

    line(pt p, pt q) {
        nv = {p.y - q.y, q.x - p.x};
        c = -dot(p, nv);
    }

    lf eval(pt p) { return dot(nv, p) + c; }

    lf distance2(pt p) {
        return eval(p) / norm2(nv) * eval(p);
    }

    lf distance(pt p) {
        return fabsl(eval(p)) / norm(nv);
    }

    pt projection(pt p) {
        return p - nv * (eval(p) / norm2(nv));
    }

    bool contains(const pt& r) {
        return fabs(cross(nv, r) - c) < EPS;
    }
};

pt lines_intersection(line a, line b) {
    lf d = cross(a.nv, b.nv);
    //assert(fabsl(d) > E0);
    lf dx = a.nv.y * b.c - a.c * b.nv.y;
    lf dy = a.c * b.nv.x - a.nv.x * b.c;
    return {dx / d, dy / d};
}

line bisector(pt a, pt b) {
    pt nv = (b - a), p = (a + b) * 0.5L;
    lf c = -dot(nv, p);
    return line(nv, c);
}

struct Circle {
    pt center;
    lf r;

    Circle(pt p, lf rad): center(p), r(rad) {}

    Circle(pt p, pt q) {
        center = (p + q) * 0.5L;
        r = dis(p, q) * 0.5L;
    }

    Circle(pt a, pt b, pt c) {
        line lb = bisector(a, b), lc = bisector(a, c);
        center = lines_intersection(lb, lc);
        r = dis(a, center);
    }

    int contains(pt &p) {
        lf det = r * r - dis2(center, p);
        if (fabsl(det) <= E0) return ON;
        return (det > E0 ? IN : OUT);
    }
};

```

```

if part(pt a, pt b, lf r) {
    lf l = abs(a-b);
    pt p = (b-a)/l;
    lf c = dot(a, p), d = 4.0 * (c*c - dot(a, a) + r*r);
    if (d < EPS) return angle(a, b) * r * r * 0.5;
    d = sqrt(d) * 0.5;
    lf s = -c - d, t = -c + d;
    if (s < 0.0) s = 0.0; else if (s > 1) s = 1;
    if (t < 0.0) t = 0.0; else if (t > 1) t = 1;
    pt u = a + p*s, v = a + p*t;
    return (cross(u, v) + (angle(a, u) + angle(v, b)) * r * r) * 0.5;
}

if circle_poly_intersection( Circle c, vector<pt> p ){
    lf ans = 0;
    int n = p.size();
    for (int i = 0; i < n; i++) {
        ans += part(p[i]-c.center, p[(i+1)%n]-c.center, c.r);
    }
    return abs(ans);
}

vector< pt > circle_line_intersection( Circle c, line l ) {
    lf h2 = c.r * c.r - 1.distance2( c.center );
    if( fabs1( h2 ) < EPS ) return { 1.projection( c.center ) };
    if( h2 < 0.0L ) return {};

    pt dir = rot90( l.nv );
    pt p = 1.projection( c.center );
    lf t = sqrt1( h2 / norm2( dir ) );

    return { p + dir * t, p - dir * t };
}

vector< pt > circle_circle_intersection( Circle c1, Circle c2 ) {
    pt dir = c2.center - c1.center;
    lf d2 = dis2( c1.center, c2.center );

    if( d2 <= E0 ) {
        //assert( fabs1( c1.r - c2.r ) > E0 );
        return {};
    }

    lf td = 0.5L + ( d2 + c1.r * c1.r - c2.r * c2.r );
    lf h2 = c1.r * c1.r - td / d2 * td;

    pt p = c1.center + dir * ( td / d2 );
    if( fabs1( h2 ) < EPS ) return { p };
    if( h2 < 0.0L ) return {};

    pt dir_h = rot90(dir) * sqrt1( h2 / d2 );
    return { p + dir_h, p - dir_h };
}

vector< pt > convex_hull( vector< pt > v ) {
    sort( v.begin(), v.end() ); //remove repeated points if needed
    const int n = v.size();
    if( n < 3 ) return v;
    vector< pt > ch( 2 * n );

    int k = 0;
    for( int i = 0; i < n; ++ i ) {
        while( k > 1 && orient( ch[k-2], ch[k-1], v[i] ) <= E0 )
            --k;
        ch[k++] = v[i];
    }

    const int t = k;
    for( int i = n - 2; i >= 0; -- i ) {
        while( k > t && orient( ch[k-2], ch[k-1], v[i] ) <= E0 )
            --k;
        ch[k++] = v[i];
    }
    ch.resize( k - 1 );
    return ch;
}

vector<pt> minkowski( vector<pt> P, vector<pt> Q ) {
    rotate( P.begin(), min_element( P.begin(), P.end() ), P.end() );
    rotate( Q.begin(), min_element( Q.begin(), Q.end() ), Q.end() );

    P.push_back(P[0]), P.push_back(P[1]);
    Q.push_back(Q[0]), Q.push_back(Q[1]);

    vector<pt> ans;
    size_t i = 0, j = 0;
    while(i < P.size() - 2 || j < Q.size() - 2) {
        ans.push_back(P[i] + Q[j]);
        lf dt = cross( P[i + 1] - P[i], Q[j + 1] - Q[j] );
        if(dt >= E0 && i < P.size() - 2) ++i;
        if(dt <= E0 && j < Q.size() - 2) ++j;
    }
}

```

```

}
return ans;
}

vector< pt > cut( const vector< pt > &pol, line l ) {
    vector< pt > ans;
    for( int i = 0, n = pol.size(); i < n; ++ i ) {
        lf s1 = 1.eval( pol[i] ), s2 = 1.eval( pol[(i+1)%n] );
        if( s1 >= -EPS ) ans.push_back( pol[i] );
        if( ( s1 < -EPS && s2 > EPS ) || ( s1 > EPS && s2 < -EPS ) ) {
            line li = line( pol[i], pol[(i+1)%n] );
            ans.push_back( lines_intersection( l, li ) );
        }
    }
    return ans;
}

int point_in_polygon( const vector< pt > &pol, const pt &p ) {
    int wn = 0;
    for( int i = 0, n = pol.size(); i < n; ++ i ) {
        lf c = orient( p, pol[i], pol[(i+1)%n] );
        if( fabs1( c ) <= E0 && dot( pol[i] - p, pol[(i+1)%n] - p ) <= E0 ) return ON;
        if( c > 0 && pol[i].y <= p.y + E0 && pol[(i+1)%n].y - p.y > E0 ) ++wn;
        if( c < 0 && pol[(i+1)%n].y <= p.y + E0 && pol[i].y - p.y > E0 ) --wn;
    }
    return wn ? IN : OUT;
}

int point_in_convex_polygon( const vector< pt > &pol, const pt &p ) {
    int low = 1, high = pol.size() - 1;
    while( high - low > 1 ) {
        int mid = ( low + high ) / 2;
        if( orient( pol[0], pol[mid], p ) >= -E0 ) low = mid;
        else high = mid;
    }
    if( orient( pol[0], pol[low], p ) < -E0 ) return OUT;
    if( orient( pol[low], pol[high], p ) < -E0 ) return OUT;
    if( orient( pol[high], pol[0], p ) < -E0 ) return OUT;

    if( low == 1 && orient( pol[0], pol[low], p ) <= E0 ) return ON;
    if( orient( pol[low], pol[high], p ) <= E0 ) return ON;
    if( high == (int) pol.size() - 1 && orient( pol[high], pol[0], p ) <= E0 ) return ON;
    return IN;
}

```

5.2 3D Library

```

typedef double T;
struct p3 {
    T x, y, z;
    // Basic vector operations
    p3 operator + (p3 p) { return {x+p.x, y+p.y, z+p.z }; }
    p3 operator - (p3 p) { return {x - p.x, y - p.y, z - p.z}; }
    p3 operator * (T d) { return {x*d, y*d, z*d}; }
    p3 operator / (T d) { return {x / d, y / d, z / d}; } // only for floating point
    // Some comparators
    bool operator == (p3 p) { return tie(x, y, z) == tie(p.x, p.y, p.z); }
    bool operator != (p3 p) { return !operator == (p); }
};

p3 zero {0, 0, 0 };
T operator | (p3 v, p3 w) { /// dot
    return v.x*w.x + v.y*w.y + v.z*w.z;
}

p3 operator * (p3 v, p3 w) { /// cross
    return { v.y*w.z - v.z*w.y, v.z*w.x - v.x*w.z, v.x*w.y - v.y*w.x };
}

T sq(p3 v) { return v | v; }
double abs(p3 v) { return sqrt(sq(v)); }
p3 unit(p3 v) { return v / abs(v); }
double angle(p3 v, p3 w) {
    double cos_theta = (v | w) / abs(v) / abs(w);
    return acos(max(-1.0, min(1.0, cos_theta)));
}

T orient(p3 p, p3 q, p3 r, p3 s) { /// orient s, pqr form a triangle
    return (q - p) * (r - p) | (s - p);
}

T orient_by_normal(p3 p, p3 q, p3 r, p3 n) { /// same as 2D but in n-normal direction
    return (q - p) * (r - p) | n;
}

struct plane {
    p3 n; T d;
    /// From normal n and offset d
    plane(p3 n, T d): n(n), d(d) {}
    /// From normal n and point P
    plane(p3 n, p3 p): n(n), d(n | p) {}
    /// From three non-collinear points P,Q,R
    plane(p3 p, p3 q, p3 r): plane((q - p) * (r - p), p) {}
}

```

```

/// - these work with T = int
T side(p3 p) { return (n | p) - d; }
double dist(p3 p) { return abs(side(p)) / abs(n); }
plane translate(p3 t) { return (n, d + (n | t)); }
/// - these require T = double
plane shift_up(double dist) { return {n, d + dist * abs(n)}; }
p3 proj(p3 p) { return p - n * side(p) / sq(n); }
p3 refl(p3 p) { return p - n * 2 * side(p) / sq(n); }
};

struct line3d {
    p3 d, o;
    /// From two points P, Q
    line3d(p3 p, p3 q): d(q - p), o(p) {}
    /// From two planes p1, p2 (requires T = double)
    line3d(plane p1, plane p2) {
        d = p1.n * p2.n;
        o = (p2.n * p1.d - p1.n * p2.d) * d / sq(d);
    }
    /// - these work with T = int
    double sq_dist(p3 p) { return sq(d * (p - o)) / sq(d); }
    double dist(p3 p) { return sqrt(sq_dist(p)); }
    bool cmp_proj(p3 p, p3 q) { return (d | p) < (d | q); }
    /// - these require T = double
    p3 proj(p3 p) { return o + d * (d | (p - o)) / sq(d); }
    p3 refl(p3 p) { return proj(p) * 2 - p; }
    p3 inter(plane p) { return o - d * p.side(o) / (p.n | d); }
};

double dist(line3d l1, line3d l2) {
    p3 n = l1.d * l2.d;
    if(n == zero) //parallel
        return l1.dist(l2.o);
    return abs((l2.o - l1.o) | n) / abs(n);
}

p3 closest_on_line1(line3d l1, line3d l2) { /// closest point on l1 to l2
    p3 n2 = l2.d * (l1.d * l2.d);
    return l1.o + l1.d * ((l2.o - l1.o) | n2) / (l1.d | n2);
}

double small_angle(p3 v, p3 w) { return acos(min(abs(v | w) / abs(v) / abs(w), 1.0)); }
double angle(plane p1, plane p2) { return small_angle(p1.n, p2.n); }
bool is_parallel(plane p1, plane p2) { return p1.n * p2.n == zero; }
bool is_perpendicular(plane p1, plane p2) { return (p1.n | p2.n) == 0; }
double angle(line3d l1, line3d l2) { return small_angle(l1.d, l2.d); }
bool is_parallel(line3d l1, line3d l2) { return l1.d * l2.d == zero; }
bool is_perpendicular(line3d l1, line3d l2) { return (l1.d | l2.d) == 0; }
double angle(plane p, line3d l) { return _p1 / 2 - small_angle(p.n, l.d); }
bool is_parallel(plane p, line3d l) { return (p.n | l.d) == 0; }
bool is_perpendicular(plane p, line3d l) { return p.n * l.d == zero; }
line3d perp_through(plane p, p3 o) { return line(o, o + p.n); }
plane perp_through(line3d l, p3 o) { return plane(l.d, o); }

```

5.3 Closest points

```

long long dist2(pair<int, int> a, pair<int, int> b) {
    return 1LL * (a.F - b.F) * (a.F - b.F) + 1LL * (a.S - b.S) * (a.S - b.S);
}

pair<int, int> closest_pair(vector<pair<int, int>> a) {
    int n = a.size();
    assert(n >= 2);
    vector<pair<int, int>, int>> p(n);
    for (int i = 0; i < n; i++) p[i] = {a[i], i};
    sort(p.begin(), p.end());
    int l = 0, r = 2;
    long long ans = dist2(p[0].F, p[1].F);
    pair<int, int> ret = {p[0].S, p[1].S};
    while (r < n) {
        while (l < r && 1LL * (p[r].F.F - p[l].F.F) * (p[r].F.F - p[l].F.F) >= ans) l++;
        for (int i = l; i < r; i++) {
            long long nw = dist2(p[i].F, p[r].F);
            if (nw < ans) {
                ans = nw;
                ret = {p[i].S, p[r].S};
            }
        }
        r++;
    }
    return ret;
}

```

5.4 Convex Hull

```

int orientation(pt a, pt b, pt c) {
    if v = a.x * (b.y - c.y) + b.x * (c.y - a.y) + c.x * (a.y - b.y);
    if (v < 0) return -1; // clockwise
    if (v > 0) return 1; // counter-clockwise
    return 0;
}

bool cw(pt a, pt b, pt c, bool include_collinear) {
    int o = orientation(a, b, c);
    return o < 0 || (include_collinear && o == 0);
}

bool collinear(pt a, pt b, pt c) { return orientation(a, b, c) == 0; }

void convex_hull(vector<pt>& a, bool include_collinear) {
    pt p0 = *min_element(all(a), [](pt a, pt b) {
        return make_pair(a.y, a.x) < make_pair(b.y, b.x);
    });
    sort(all(a), [&p0](const pt& a, const pt& b) {
        int o = orientation(p0, a, b);
        if (o == 0)
            return (p0.x - a.x) * (p0.x - a.x) + (p0.y - a.y) * (p0.y - a.y)
                < (p0.x - b.x) * (p0.x - b.x) + (p0.y - b.y) * (p0.y - b.y);
        return o < 0;
    });
    if (include_collinear) {
        int i = sz(a) - 1;
        while (i >= 0 && collinear(p0, a[i], a.back())) i--;
        reverse(a.begin() + i + 1, a.end());
    }

    vector<pt> st;
    for (int i = 0; i < sz(a); i++) {
        while (sz(st) > 1 && !cw(st[sz(st) - 2], st.back(), a[i], include_collinear))
            st.pop_back();
        st.push_back(a[i]);
    }

    a = st;
}

if area(const vector<pt>& fig) {
    if res = 0;
    for (unsigned i = 0; i < fig.size(); i++) {
        pt p = i ? fig[i - 1] : fig.back();
        pt q = fig[i];
        res += (p.x - q.x) * (p.y + q.y);
    }

    return fabs(res) / 2;
}

if areaPolygon(const vector<pt>& fig) {
    if area = 0;
    int n = fig.size();
    for (int i = 0; i < n; i++) {
        int j = (i + 1) % n;
        area += fig[i].x * fig[j].y;
        area -= fig[j].x * fig[i].y;
    }

    return fabs(area) / 2;
}

```

5.5 Point in convex polygon

```

struct pt {
    long long x, y;
    pt() {}
    pt(long long _x, long long _y): x(_x), y(_y) {}
    pt operator+(const pt &p) const { return pt(x + p.x, y + p.y); }
    pt operator-(const pt &p) const { return pt(x - p.x, y - p.y); }
    long long cross(const pt &p) const { return x * p.y - y * p.x; }
    long long dot(const pt &p) const { return x * p.x + y * p.y; }
    long long cross(const pt &a, const pt &b) const { return (a - *this).cross(b - *this); }
    long long dot(const pt &a, const pt &b) const { return (a - *this).dot(b - *this); }
    long long sqrlen() const { return this->dot(*this); }
};

bool lexComp(const pt &l, const pt &r) {
    return l.x < r.x || (l.x == r.x && l.y < r.y);
}

int sgn(long long val) { return val > 0 ? 1 : (val == 0 ? 0 : -1); }

```

```

vector<pt> seq;
pt translation;
int n;

bool pointInTriangle(pt a, pt b, pt c, pt point) {
    long long s1 = abs(a.cross(b, c));
    long long s2 = abs(point.cross(a, b)) + abs(point.cross(b, c)) + abs(point.cross(c, a));
    return s1 == s2;
}

void prepare(vector<pt> &points) {
    n = points.size();
    int pos = 0;
    for (int i = 1; i < n; i++) {
        if (lexComp(points[i], points[pos]))
            pos = i;
    }
    rotate(points.begin(), points.begin() + pos, points.end());

    n--;
    seq.resize(n);
    for (int i = 0; i < n; i++)
        seq[i] = points[i + 1] - points[0];
    translation = points[0];
}

bool pointInConvexPolygon(pt point) {
    point = point - translation;
    if (seq[0].cross(point) != 0 &&
        sgn(seq[0].cross(point)) != sgn(seq[0].cross(seq[n - 1])))
        return false;
    if (seq[n - 1].cross(point) != 0 &&
        sgn(seq[n - 1].cross(point)) != sgn(seq[n - 1].cross(seq[0])))
        return false;

    if (seq[0].cross(point) == 0)
        return seq[0].sqrLen() >= point.sqrLen();

    int l = 0, r = n - 1;
    while (r - l > 1) {
        int mid = (l + r) / 2;
        int pos = mid;
        if (seq[pos].cross(point) >= 0)
            l = mid;
        else
            r = mid;
    }
    int pos = l;
    return pointInTriangle(seq[pos], seq[pos + 1], pt(0, 0), point);
}

bool isIn(const vector<pt> &v, pt p) {
    int n = sz(v);
    if (n < 3) return false;

    if angleSum = 0;
    for (int i = 0; i < n; i++) {
        pt a = v[i];
        pt b = v[(i + 1) % n];
        double angle = atan2(b.y - a.y, b.x - a.x) - atan2(a.y - p.y, a.x - p.x);
        if (angle >= M_PI) angle -= 2 * M_PI;
        if (angle <= -M_PI) angle += 2 * M_PI;
        angleSum += angle;
    }

    return fabs(angleSum - 2 * M_PI) < 1e-9;
}

```

6 Math

6.1 Basics

```

// Greatest Common Divisor & Lowest Common Multiple
ll gcd(ll a, ll b) { return b ? gcd(b, a % b) : a; }
ll lcm(ll a, ll b) { return a / gcd(a, b) * b; }

// Multiply caring overflow
ll mulmod(ll a, ll b, ll m = MOD) {
    ll r = 0;
    for (a %= m; b; b >>= 1, a = (a * 2) % m) if (b & 1) r = (r + a) % m;
    return r;
}

// Another option for mulmod is using long double

```

```

ull mulmod(ull a, ull b, ull m = MOD) {
    ull q = (ld) a * (ld) b / (ld) m;
    ull r = a * b - q * m;
    return (r + m) % m;
}

// Fast exponential
ll fexp(ll a, ll b, ll m = MOD) {
    ll r = 1;
    for (a %= m; b; b >>= 1, a = (a * a) % m) if (b & 1) r = (r * a) % m;
    return r;
}

/* Line integral = integral(sqrt(1 + (dy/dx)^2)) dx */

/* Multiplicative Inverse over MOD for all 1..N - 1 < MOD in O(N)
   Only works for prime MOD. If all 1..MOD - 1 needed, use N = MOD */
ll inv[N];
inv[1] = 1;
for (int i = 2; i < N; ++i)
    inv[i] = MOD - (MOD / i) * inv[MOD % i] % MOD;

/* Catalan
   f(n) = sum(f(i) * f(n - i - 1)), i in [0, n - 1] = (2n)! / ((n+1)! * n!) = ...
   If you have any function f(n) (there are many) that follows this sequence (0-indexed):
   1, 1, 2, 5, 14, 42, 132, 429, 1430, 4862, 16796, 58786, 208012, 742900, 2674440
   than it's the Catalan function */
ll cat[N];
cat[0] = 1;
for (int i = 1; i + 1 < N; i++) // needs inv[i + 1] till inv[N - 1]
    cat[i] = 2 * i * (2 * i - 1) * inv[i + 1] % MOD * cat[i - 1] % MOD;

/* Floor(n / i), i = [1, n], has <= 2 * sqrt(n) diff values.
   Proof: i = [1, sqrt(n)] has sqrt(n) diff values.
   For i = [sqrt(n), n] we have that 1 <= n / i <= sqrt(n)
   and thus has <= sqrt(n) diff values.
   */
/* l = first number that has floor(N / l) = x
   r = last number that has floor(N / r) = x
   N / r >= floor(N / l)
   r <= N / floor(N / l) */
for (int l = 1, r; l <= n; l = r + 1) {
    r = n / (n / l);
    // floor(n / i) has the same value for l <= i <= r
}

/* Recurrence using matrix
   h[i + 2] = a1 * h[i + 1] + a0 * h[i]
   [h[i] h[i-1]] = [h[1] h[0]] * [a1 1] ^ (i - 1)

```

```

/* Fibonacci in O(log(N)) with memoization
   f(0) = f(1) = 1
   f(2+k) = f(k)^2 + f(k - 1)^2
   f(2+k + 1) = f(k) * [f(k) + 2 * f(k - 1)] */

/* Wilson's Theorem Extension
   B = b1 + b2 + ... + bm (mod n) = +-1, all bi <= n such that gcd(bi, n) = 1
   if (n <= 4 or n = (odd prime)^k or n = 2 * (odd prime)^k) B = -1; for any k
   else B = 1; */

```

```

/* Stirling numbers of the second kind
   S(n, k) = Number of ways to split n numbers into k non-empty sets
   S(n, 1) = S(n, n) = 1
   S(n, k) = k * S(n - 1, k) + S(n - 1, k - 1)
   Sr(n, k) = S(n, k) with at least r numbers in each set
   Sr(n, k) = k * Sr(n - 1, k) + (n - 1) * Sr(n - r, k - 1)
               (r - 1)
   S(n - d + 1, k - d + 1) = S(n, k) where if indexes i, j belong to the same set, then |i - j| >= d */

```

```

/* Burnside's Lemma
   |Classes| = 1 / |G| * sum(K ^ C(g)) for each g in G
   G = Different permutations possible
   C(g) = Number of cycles on the permutation g
   K = Number of states for each element

Different ways to paint a necklace with N beads and K colors:
G = {(1, 2, ... N), (2, 3, ... N, 1), ... (N, 1, ... N - 1)}

```



```

gi = (i, i + 1, ... i + N), (taking mod N to get it right) i = 1 ... N
i -> 21 -> 31 ..., Cycles in gi all have size n / gcd(i, n), so C(gi) = gcd(i, n)
Ans = 1 / N * sum(K ^ gcd(i, n)), i = 1 ... N
(For the brave, you can get to Ans = 1 / N * sum(euler_phi(N / d) * K ^ d), d | N) */

/* Mobius Inversion
Sum of gcd(i, j), 1 <= i, j <= N?
sum(k->N) k * sum(i->N) sum(j->N) [gcd(i, j) == k], i = a * k, j = b * k
= sum(k->N) k * sum(a->N/k) sum(b->N/k) [gcd(a, b) == 1]
= sum(k->N) k * sum(a->N/k) sum(b->N/k) sum(d->N/k) [d | a] * [d | b] * mi(d)
= sum(k->N) k * sum(d->N/k) mi(d) * floor(N / kd)^2, 1 = kd, 1 <= N, k | 1, d = 1 / k
= sum(l->N) floor(N / l)^2 * sum(k|l) k * mi(l / k)
If f(n) = sum(x|n) (g(x) * h(x)) with g(x) and h(x) multiplicative, then f(n) is multiplicative
Hence, g(1) = sum(k|1) k * mi(1 / k) is multiplicative
= sum(l->N) floor(N / l)^2 * g(1) */

/* Frobenius / Chicken McNugget
n, m given, gcd(n, m) = 1, we want to know if it's possible to create N = a * n + b * m
N, a, b >= 0
The greatest number NOT possible is n * m - n - m
We can NOT create (n - 1) * (m - 1) / 2 numbers */

```

6.3 Discrete log

```

// O(sqrt(m))
// Solve c * a^x = b mod(m) for integer x >= 0.
// Return the smallest x possible, or -1 if there is no solution
// If all solutions needed, solve c * a^x = b mod(m) and (a*b) * a^y = b mod(m)
// x + k * (y + 1) for k >= 0 are all solutions
// Works for any integer values of c, a, b and positive m

// Corner Cases:
// 0^x = 1 mod(m) returns x = 0, so you may want to change it to -1
// You also may want to change for 0^x = 0 mod(1) to return x = 1 instead
// We leave it like it is because you might be actually checking for m^x = 0^x mod(m)
// which would have x = 0 as the actual solution.
ll discrete_log(ll c, ll a, ll b, ll m){
    c = ((c % m) + m) % m, a = ((a % m) + m) % m, b = ((b % m) + m) % m;
    if(c == b)
        return 0;

    ll g = __gcd(a, m);
    if(b % g) return -1;

    if(g > 1){
        ll r = discrete_log(c * a / g, a, b / g, m / g);
        return r + (r >= 0);
    }

    unordered_map<ll, ll> babystep;
    ll n = 1, an = a % m;

    // set n to the ceil of sqrt(m):
    while(n * n < m) n++, an = (an * a) % m;

    // babysteps:
    ll bstep = b;
    for(ll i = 0; i <= n; i++){
        babystep[bstep] = i;
        bstep = (bstep * a) % m;
    }

    // giantsteps:
    ll gstep = c * an % m;
    for(ll i = 1; i <= n; i++){
        if(babystep.find(gstep) != babystep.end())
            return n * i - babystep[gstep];
        gstep = (gstep * an) % m;
    }
    return -1;
}

```

6.4 Euler Phi

```

// Euler phi (totient)
int ind = 0, pf = primes[0], ans = n;
while (1ll*pf*pf <= n) {
    if (n%pf==0) ans -= ans/pf;
    while (n%pf==0) n /= pf;
    pf = primes[++ind];
}
if (n != 1) ans -= ans/n;

```

```

// IME2014
int phi[N];
void totient() {
    for (int i = 1; i < N; ++i) phi[i]=i;
    for (int i = 2; i < N; i+=2) phi[i]>>=1;
    for (int j = 3; j < N; j+=2) if (phi[j]==j) {
        phi[j]--;
        for (int i = 2*j; i < N; i+=j) phi[i]=phi[i]/j*(j-1);
    }
}

```

6.5 Extended euclid

```

// Extended Euclid:
void euclid(ll a, ll b, ll &x, ll &y) {
    if (b) euclid(b, a%b, y, x), y -= x*(a/b);
    else x = 1, y = 0;
}

// find (x, y) such that a*x + b*y = c or return false if it's not possible
// {x + k*b/gcd(a, b), y - k*a/gcd(a, b)} are also solutions
bool diof(ll a, ll b, ll c, ll &x, ll &y){
    euclid(abs(a), abs(b), x, y);
    ll g = abs(__gcd(a, b));
    if(c % g) return false;
    x *= c / g;
    y *= c / g;
    if(a < 0) x = -x;
    if(b < 0) y = -y;
    return true;
}

// auxiliar to find_all_solutions
void shift_solution (ll &x, ll &y, ll a, ll b, ll cnt) {
    x += cnt * b;
    y -= cnt * a;
}

// Find the amount of solutions of
// ax + by = c
// in given intervals for x and y
ll find_all_solutions (ll a, ll b, ll c, ll minx, ll maxx, ll miny, ll maxy) {
    ll x, y, g = __gcd(a, b);
    if(!diof(a, b, c, x, y)) return 0;
    a /= g; b /= g;

    int sign_a = a>0 ? +1 : -1;
    int sign_b = b>0 ? +1 : -1;

    shift_solution (x, y, a, b, (minx - x) / b);
    if (x < minx)
        shift_solution (x, y, a, b, sign_b);
    if (x > maxx)
        return 0;
    int lx1 = x;

    shift_solution (x, y, a, b, (maxx - x) / b);
    if (x > maxx)
        shift_solution (x, y, a, b, -sign_b);
    int rx1 = x;

    shift_solution (x, y, a, b, - (miny - y) / a);
    if (y < miny)
        shift_solution (x, y, a, b, -sign_a);
    if (y > maxy)
        return 0;
    int lx2 = x;

    shift_solution (x, y, a, b, - (maxy - y) / a);
    if (y > maxy)
        shift_solution (x, y, a, b, sign_a);
    int rx2 = x;

    if (lx2 > rx2)
        swap (lx2, rx2);
    int lx = max (lx1, lx2);
    int rx = min (rx1, rx2);

    if (lx > rx) return 0;
    return (rx - lx) / abs(b) + 1;
}

```

```

bool crt_auxiliar(ll a, ll b, ll m1, ll m2, ll &ans){
    ll x, y;
    if(!diof(m1, m2, b - a, x, y)) return false;
    ll lcm = m1 / __gcd(m1, m2) * m2;
    ans = ((a + x % (lcm / m1) * m1) % lcm + lcm) % lcm;
    return true;
}

```

```

}

// find ans such that ans = a[i] mod b[i] for all 0 <= i < n or return false if not possible
// ans + k * lcm(b[i]) are also solutions
bool crt(int n, ll a[], ll b[], ll &ans){
    if(!b[0]) return false;
    ans = a[0] % b[0];
    ll l = b[0];
    for(int i = 1; i < n; i++){
        if(!b[i]) return false;
        if(!crt_auxiliar(ans, a[i] % b[i], l, b[i], ans)) return false;
        l *= (b[i] / __gcd(b[i], l));
    }
    return true;
}

```

6.6 FFT

```

// Fast Fourier Transform - O(nlogn)

/*
// Use struct instead. Performance will be way better!
typedef complex<ld> T;
T a[N], b[N];
*/

struct T {
    ld x, y;
    T() : x(0), y(0) {}
    T(ld a, ld b=0) : x(a), y(b) {}

    T operator+=(ld k) { x/=k; y/=k; return (*this); }
    T operator+(T a) const { return T(x+a.x - y*a.y, x*a.y + y*a.x); }
    T operator+(T a) const { return T(x+a.x, y+a.y); }
    T operator-(T a) const { return T(x-a.x, y-a.y); }
} a[N], b[N];

// a: vector containing polynomial
// n: power of two greater or equal product size
/*
// Use iterative version!
void fft_recursive(T* a, int n, int s) {
    if (n == 1) return;
    T tmp[n];
    for (int i = 0; i < n/2; ++i)
        tmp[i] = a[2*i], tmp[i+n/2] = a[2*i+1];

    fft_recursive(&tmp[0], n/2, s);
    fft_recursive(&tmp[n/2], n/2, s);

    T wn = T(cos(s*2*PI/n), sin(s*2*PI/n)), w(1,0);
    for (int i = 0; i < n/2; i++, w=w*wn)
        a[i] = tmp[i] + w*tmp[i+n/2],
        a[i+n/2] = tmp[i] - w*tmp[i+n/2];
}
*/

void fft(T* a, int n, int s) {
    for (int i=0, j=0; i<n; i++) {
        if (i>j) swap(a[i], a[j]);
        for (int l=n/2; (j^=1) < 1; l>>=1);
    }

    for(int i = 1; (1<<i) <= n; i++){
        int M = 1 << i;
        int K = M >> 1;
        T wn = T(cos(s*2*PI/M), sin(s*2*PI/M));
        for(int j = 0; j < n; j += M) {
            T w = T(1, 0);
            for(int l = j; l < K + j; ++l){
                T t = w*a[l + K];
                a[l + K] = a[l]-t;
                a[l] = a[l] + t;
                w = wn*w;
            }
        }
    }
}

// assert n is a power of two greater or equal product size
// n = na + nb; while (n&(n-1)) n++;
void multiply(T* a, T* b, int n) {
    fft(a, n, 1);
    fft(b, n, 1);
    for (int i = 0; i < n; i++) a[i] = a[i]*b[i];
    fft(a, n, -1);
    for (int i = 0; i < n; i++) a[i] /= n;
}

```

```

// Convert to integers after multiplying:
// (int) (a[i].x + 0.5);

```

6.7 FFT Tourist

```

//
// FFT made by tourist. It is faster and more supportive, although it requires more lines of code.
// Also, it allows operations with MOD, which is usually an issue in FFT problems.
//
namespace fft {
    typedef double dbl;

    struct num {
        dbl x, y;
        num() { x = y = 0; }
        num(dbl x, dbl y) : x(x), y(y) {}
    };

    inline num operator+ (num a, num b) { return num(a.x + b.x, a.y + b.y); }
    inline num operator- (num a, num b) { return num(a.x - b.x, a.y - b.y); }
    inline num operator* (num a, num b) { return num(a.x * b.x - a.y * b.y, a.x * b.y + a.y * b.x); }
    inline num conj(num a) { return num(a.x, -a.y); }

    int base = 1;
    vector<num> roots = {{0, 0}, {1, 0}};
    vector<int> rev = {0, 1};

    const dbl PI = acos(-1.0);

    void ensure_base(int nbase) {
        if(nbase <= base) return;
        rev.resize(1 << nbase);
        for(int i=0; i < (1 << nbase); i++) {
            rev[i] = (rev[i >> 1] >> 1) + ((i & 1) << (nbase - 1));
        }
        roots.resize(1 << nbase);

        while(base < nbase) {
            dbl angle = 2*PI / (1 << (base + 1));
            for(int i = 1 << (base - 1); i < (1 << base); i++) {
                roots[i << 1] = roots[i];
                dbl angle_i = angle * (2 * i + 1 - (1 << base));
                roots[(i << 1) + 1] = num(cos(angle_i), sin(angle_i));
            }
            base++;
        }
    }

    void fft(vector<num> &a, int n = -1) {
        if(n == -1) {
            n = a.size();
        }
        assert((n & (n-1)) == 0);
        int zeros = __builtin_ctz(n);
        ensure_base(zeros);
        int shift = base - zeros;
        for(int i = 0; i < n; i++) {
            if(i < (rev[i] >> shift)) {
                swap(a[i], a[rev[i] >> shift]);
            }
        }
        for(int k = 1; k < n; k <= 1) {
            for(int i = 0; i < n; i += 2 * k) {
                for(int j = 0; j < k; j++) {
                    num z = a[i+j+k] * roots[j+k];
                    a[i+j+k] = a[i+j] - z;
                    a[i+j] = a[i+j] + z;
                }
            }
        }
    }

    vector<num> fa, fb;
    vector<int> multiply(vector<int> &a, vector<int> &b) {
        int need = a.size() + b.size() - 1;
        int nbase = 0;
        while((1 << nbase) < need) nbase++;
        ensure_base(nbase);
        int sz = 1 << nbase;
        if(sz > (int) fa.size()) {
            fa.resize(sz);
        }
        for(int i = 0; i < sz; i++) {
            int x = (i < (int) a.size() ? a[i] : 0);
            int y = (i < (int) b.size() ? b[i] : 0);
        }
    }
}

```

```

        fa[i] = num(x, y);
    }
    fft(fa, sz);
    num r(0, -0.25 / sz);
    for(int i = 0; i <= (sz >> 1); i++) {
        int j = (sz - i) & (sz - 1);
        num z = (fa[j] * fa[j] - conj(fa[i] * fa[i])) * r;
        if(i != j) {
            fa[j] = (fa[i] * fa[i] - conj(fa[j] * fa[j])) * r;
        }
        fa[i] = z;
    }
    fft(fa, sz);
    vector<int> res(need);
    for(int i = 0; i < need; i++) {
        res[i] = fa[i].x + 0.5;
    }
    return res;
}

vector<int> multiply_mod(vector<int> &a, vector<int> &b, int m, int eq = 0) {
    int need = a.size() + b.size() - 1;
    int nbase = 0;
    while ((1 << nbase) < need) nbase++;
    ensure_base(nbase);
    int sz = 1 << nbase;
    if (sz > (int) fa.size()) {
        fa.resize(sz);
    }
    for (int i = 0; i < (int) a.size(); i++) {
        int x = (a[i] % m + m) % m;
        fa[i] = num(x & ((1 << 15) - 1), x >> 15);
    }
    fill(fa.begin() + a.size(), fa.begin() + sz, num {0, 0});
    fft(fa, sz);
    if (sz > (int) fb.size()) {
        fb.resize(sz);
    }
    if (eq) {
        copy(fa.begin(), fa.begin() + sz, fb.begin());
    } else {
        for (int i = 0; i < (int) b.size(); i++) {
            int x = (b[i] % m + m) % m;
            fb[i] = num(x & ((1 << 15) - 1), x >> 15);
        }
        fill(fb.begin() + b.size(), fb.begin() + sz, num {0, 0});
        fft(fb, sz);
    }
    dbl ratio = 0.25 / sz;
    num r2(0, -1);
    num r3(ratio, 0);
    num r4(0, -ratio);
    num r5(0, 1);
    for (int i = 0; i <= (sz >> 1); i++) {
        int j = (sz - i) & (sz - 1);
        num a1 = (fa[i] + conj(fa[j]));
        num a2 = (fa[i] - conj(fa[j])) * r2;
        num b1 = (fb[i] + conj(fb[j]));
        num b2 = (fb[i] - conj(fb[j])) * r4;
        if (i != j) {
            num c1 = (fa[j] + conj(fa[i]));
            num c2 = (fa[j] - conj(fa[i])) * r2;
            num d1 = (fb[j] + conj(fb[i])) * r3;
            num d2 = (fb[j] - conj(fb[i])) * r4;
            fa[i] = c1 * d1 + c2 * d2 * r5;
            fb[i] = c1 * d2 + c2 * d1;
        }
        fa[j] = a1 + b1 + a2 * b2 * r5;
        fb[j] = a1 * b2 + a2 * b1;
    }
    fft(fa, sz);
    fft(fb, sz);
    vector<int> res(need);
    for (int i = 0; i < need; i++) {
        long long aa = fa[i].x + 0.5;
        long long bb = fb[i].x + 0.5;
        long long cc = fa[i].y + 0.5;
        res[i] = (aa + ((bb % m) << 15) + ((cc % m) << 30)) % m;
    }
    return res;
}

vector<int> square_mod(vector<int> &a, int m) {
    return multiply_mod(a, a, m, 1);
}
}

```

```

// Fast Walsh-Hadamard Transform - O(nlogn)
//
// Multiply two polynomials, but instead of x^a * x^b = x^(a+b)
// we have x^a * x^b = x^(a XOR b).
//
// WARNING: assert n is a power of two!
void fwht(ll* a, int n, bool inv) {
    for(int l=1; 2*l <= n; l<=<=1) {
        for(int i=0; i < n; i+=2*l) {
            for(int j=0; j < l; j++) {
                ll u = a[i+j], v = a[i+l+j];

                a[i+j] = (u+v) % MOD;
                a[i+l+j] = (u-v+MOD) % MOD;
                // % is kinda slow, you can use add() macro instead
                // #define add(x,y) (x+y >= MOD ? x+y-MOD : x+y)
            }
        }
    }

    if(inv) {
        for(int i=0; i < n; i++) {
            a[i] = a[i] / n;
        }
    }
}

/* FWHT AND
Matrix : Inverse
0 1   -1 1
1 1    1 0
*/
void fwht_and(vi &a, bool inv) {
    vi ret = a;
    ll u, v;
    int tam = a.size() / 2;
    for(int len = 1; 2 * len <= tam; len <=<= 1) {
        for(int i = 0; i < tam; i += 2 * len) {
            for(int j = 0; j < len; j++) {
                u = ret[i + j];
                v = ret[i + len + j];
                if(!inv) {
                    ret[i + j] = v;
                    ret[i + len + j] = u + v;
                } else {
                    ret[i + j] = -u + v;
                    ret[i + len + j] = u;
                }
            }
        }
    }
    a = ret;
}

/* FWHT OR
Matrix : Inverse
1 1    0 1
1 0    1 -1
*/
void fwht_or(vi &a, bool inv) {
    vi ret = a;
    ll u, v;
    int tam = a.size() / 2;
    for(int len = 1; 2 * len <= tam; len <=<= 1) {
        for(int i = 0; i < tam; i += 2 * len) {
            for(int j = 0; j < len; j++) {
                u = ret[i + j];
                v = ret[i + len + j];
                if(!inv) {
                    ret[i + j] = u + v;
                    ret[i + len + j] = u;
                } else {
                    ret[i + j] = v;
                    ret[i + len + j] = u - v;
                }
            }
        }
    }
    a = ret;
}

```

6.8 FWHT

6.9 Gauss elim

```
//Gaussian Elimination
```

```
//double A[N][M+1], X[M]

// if n < m, there's no solution
// column m holds the right side of the equation
// X holds the solutions

for(int j=0; j<m; j++) { //column to eliminate
    int l = j;
    for(int i=j+1; i<n; i++) //find largest pivot
        if(abs(A[i][j])>abs(A[l][j]))
            l=i;
    if(abs(A[l][j]) < EPS) continue;
    for(int k = 0; k < m+1; k++) { //Swap lines
        swap(A[l][k], A[j][k]);
    }
    for(int i = j+1; i < n; i++) { //eliminate column
        double t=A[i][j]/A[j][j];
        for(int k = j; k < m+1; k++)
            A[i][k]-=t*A[j][k];
    }
}

for(int i = m-1; i >= 0; i--) { //solve triangular system
    for(int j = m-1; j > i; j--)
        A[i][m] -= A[i][j]*X[j];
    X[i]=A[i][m]/A[i][i];
}
}
```

6.10 Gauss elim ext

```
// Gauss-Jordan Elimination with Scaled Partial Pivoting
// Extended to Calculate Inverses - O(n^3)
// To get more precision choose m[j][i] as pivot the element such that m[j][i] / mx[j] is maximized.
// mx[j] is the element with biggest absolute value of row j.

ld C[N][M]; // N = 1000, M = 2*N+1;
int row, col;

bool elim() {
    for(int i=0; i<row; ++i) {
        int p = i; // Choose the biggest pivot
        for(int j=1; j<row; ++j) if (abs(C[j][i]) > abs(C[p][i])) p = j;
        for(int j=1; j<col; ++j) swap(C[i][j], C[p][j]);

        if (!C[i][i]) return 0;

        ld c = 1/C[i][i]; // Normalize pivot line
        for(int j=0; j<col; ++j) C[i][j] *= c;

        for(int k=i+1; k<col; ++k) {
            ld c = -C[k][i]; // Remove pivot variable from other lines
            for(int j=0; j<col; ++j) C[k][j] += c*C[i][j];
        }
    }

    // Make triangular system a diagonal one
    for(int i=row-1; i>=0; --i) for(int j=i-1; j>=0; --j) {
        ld c = -C[j][i];
        for(int k=i; k<col; ++k) C[j][k] += c*C[i][k];
    }

    return 1;
}

// Finds inv, the inverse of matrix m of size n x n.
// Returns true if procedure was successful.
bool inverse(int n, ld m[N][N], ld inv[N][N]) {
    for(int i=0; i<n; ++i) for(int j=0; j<n; ++j)
        C[i][j] = m[i][j], C[i][j+n] = (i == j);

    row = n, col = 2*n;
    bool ok = elim();

    for(int i=0; i<n; ++i) for(int j=0; j<n; ++j) inv[i][j] = C[i][j+n];
    return ok;
}

// Solves linear system m*x = y, of size n x n
bool linear_system(int n, ld m[N][N], ld x, ld y) {
    for(int i = 0; i < n; ++i) for(int j = 0; j < n; ++j) C[i][j] = m[i][j];
    for(int j = 0; j < n; ++j) C[j][n] = x[j];

    row = n, col = n+1;
    bool ok = elim();

    for(int j=0; j<n; ++j) y[j] = C[j][n];
    return ok;
}
}
```

6.11 Gauss elim prime

```
//ll A[N][M+1], X[M]

for(int j=0; j<m; j++) { //column to eliminate
    int l = j;
    for(int i=j+1; i<n; i++) //find nonzero pivot
        if(A[i][j]%p)
            l=i;
    for(int k = 0; k < m+1; k++) { //Swap lines
        swap(A[l][k], A[j][k]);
    }
    for(int i = j+1; i < n; i++) { //eliminate column
        ll t=mulmod(A[i][j], inv(A[j][j],p),p);
        for(int k = j; k < m+1; k++)
            A[i][k]=(A[i][k]-mulmod(t,A[j][k],p)+p)%p;
    }
}

for(int i = m-1; i >= 0; i--) { //solve triangular system
    for(int j = m-1; j > i; j--)
        A[i][m] = (A[i][m] - mulmod(A[i][j],X[j],p)+p)%p;
    X[i] = mulmod(A[i][m], inv(A[i][i],p),p);
}
}
```

6.12 Gauss elim xor

```
// Gauss Elimination for xor boolean operations
// Return false if not possible to solve
// Use boolean matrixes 0-indexed
// n equations, m variables, O(n * m * m)
// eq[i][j] = coefficient of j-th element in i-th equation
// r[i] = result of i-th equation
// Return ans[j] = xj that gives the lexicographically greatest solution (if possible)
// (Can be changed to lexicographically least, follow the comments in the code)
// WARNING!! The arrays get changed during de algorithm

bool eq[N][M], r[N], ans[M];

bool gauss_xor(int n, int m){
    for(int i = 0; i < m; i++)
        ans[i] = true;
    int lid[N] = {0}; // id + 1 of last element present in i-th line of final matrix
    int l = 0;
    for(int i = m - 1; i >= 0; i--){
        for(int j = 1; j < n; j++){
            if(eq[j][i]){ // pivot
                swap(eq[l], eq[j]);
                swap(r[l], r[j]);
            }
        }
        if(l == n || !eq[l][i])
            continue;
        lid[l] = i + 1;
        for(int j = l + 1; j < n; j++){ // eliminate column
            if(!eq[j][i])
                continue;
            for(int k = 0; k <= i; k++)
                eq[j][k] ^= eq[l][k];
            r[j] ^= r[l];
        }
        l++;
    }
    for(int i = n - 1; i >= 0; i--){ // solve triangular matrix
        for(int j = 0; j < lid[i + 1]; j++)
            r[i] ^= (eq[i][j] && ans[j]);
        // for lexicographically least just delete the for bellow
        for(int j = lid[i + 1]; j + 1 < lid[i]; j++){
            ans[j] = true;
            r[i] ^= eq[i][j];
        }
        if(lid[i])
            ans[lid[i] - 1] = r[i];
        else if(r[i])
            return false;
    }
    return true;
}
}
```

6.13 GSS

```
double gss(double l, double r) {
    double m1 = r-(r-1)/gr, m2 = 1+(r-1)/gr;
    double f1 = f(m1), f2 = f(m2);
    while(fabs(l-r)>EPS) {
        if(f1>f2) l=m1, f1=f2, m1=m2, m2=1+(r-1)/gr, f2=f(m2);
        else r=m2, f2=f1, m2=m1, m1=r-(r-1)/gr, f1=f(m1);
    }
    return l;
}
```

6.14 Josephus

```
/* UFMG
 * Josephus Problem - It returns the position to be, in order to not die. O(n)*/
 * With k=2, for instance, the game begins with 2 being killed and then n+2, n+4, ... */
ll josephus(ll n, ll k) {
    if(n==1) return 1;
    else return (josephus(n-1, k)+k-1)%n+1;
}

/* Another Way to compute the last position to be killed - O(d * log n) */
ll josephus(ll n, ll d) {
    ll K = 1;
    while (K <= (d - 1)*n) K = (d * K + d - 2) / (d - 1);
    return d * n + 1 - K;
}
```

6.15 Matrix

```
/*
 * This code assumes you are multiplying two matrices that can be multiplied: (A nxp * B pxm)
 * Matrix fexp assumes square matrices
 */

const int MOD = 1e9 + 7;
typedef long long ll;
typedef long long type;

struct matrix{
    //matrix n x m
    vector<vector<type>> a;
    int n, m;
    matrix() = default;

    matrix(int _n, int _m) : n(_n), m(_m){
        a.resize(n, vector<type>(m));
    }

    matrix operator *(matrix other){
        matrix result(this->n, other.m);
        for(int i = 0; i < result.n; i++){
            for(int j = 0; j < result.m; j++){
                for(int k = 0; k < this->m; k++){
                    result.a[i][j] = (result.a[i][j] + a[i][k] * other.a[k][j]);
                    //result.a[i][j] = (result.a[i][j] + (a[i][k] * other.a[k][j])
                    // % MOD) % MOD;
                }
            }
        }
        return result;
    }

    matrix identity(int n){
        matrix id(n, n);
        for(int i = 0; i < n; i++) id.a[i][i] = 1;
        return id;
    }

    matrix fexp(matrix b, ll e){
        matrix ans = identity(b.n);
        while(e){
            if(e & 1) ans = (ans * b);
            b = b * b;
            e >>= 1;
        }
        return ans;
    }
}
```

6.16 Mobius

```
// 1 if n == 1
// 0 if exists x | n%(x^2) == 0
// else (-1)^k, k = #(p) | p is prime and n%p == 0

//Calculate Mobius for all integers using sieve
//O(n*log(log(n)))
void mobius() {
    for(int i = 1; i < N; i++) mob[i] = 1;

    for(ll i = 2; i < N; i++) if(!sieve[i]){
        for(ll j = i; j < N; j += i) sieve[j] = i, mob[j] *= -1;
        for(ll j = i*i; j < N; j += i*i) mob[j] = 0;
    }

    /*
    //Calculate Mobius for 1 integer
    //O(sqrt(n))
    int mobius(int n){
        if(n == 1) return 1;
        int p = 0;
        for(int i = 2; i*i <= n; i++){
            if(n%i == 0){
                n /= i;
                p++;
                if(n%i == 0) return 0;
            }
        }
        if(n > 1) p++;
        return p%2 ? -1 : 1;
    }
    */
}
```

6.17 Mobius inversion

```
// multiplicative function calculator
// euler_phi and mobius are multiplicative
// if another f[N] needed just remove comments
// O(N)

bool p[N];
vector<ll> primes;
ll g[N];
// ll f[N];

void mfc(){
    // if g(1) != 1 than it's not multiplicative
    g[1] = 1;
    // f[1] = 1;
    primes.clear();
    primes.reserve(N / 10);
    for(ll i = 2; i < N; i++){
        if(!p[i]){
            primes.push_back(i);
            for(ll j = i; j < N; j += i){
                g[j] = // g(p^k) you found
                // f[j] = f(p^k) you found
                p[j] = (j != i);
            }
        }
        for(ll j : primes){
            if(i * j >= N || i % j == 0)
                break;
            for(ll k = j; i * k < N; k *= j){
                g[i * k] = g[i] * g[k];
                // f[i * k] = f[i] * f[k];
                p[i * k] = true;
            }
        }
    }
}
```

6.18 NTT

```
// Number Theoretic Transform - O(nlogn)

// if long long is not necessary, use int instead to improve performance
const int mod = 20*(1<<23)+1;
const int root = 3;

ll w[N];

// a: vector containing polynomial
// n: power of two greater or equal product size
```

```

void ntt(ll* a, int n, bool inv) {
    for (int i=0, j=0; i<n; i++) {
        if (i>j) swap(a[i], a[j]);
        for (int l=n/2; (j^=1) < 1; l>>=1);
    }

    // TODO: Rewrite this loop using FFT version
    ll k, t, nrev;
    w[0] = 1;
    k = exp(root, (mod-1) / n, mod);
    for (int i=1; i<=n; i++) w[i] = w[i-1] * k % mod;
    for (int i=2; i<=n; i<=1) for (int j=0; j<n; j+=i) for (int l=0; l<(i/2); l++) {
        int x = j+l, y = j+l+(i/2), z = (n/i)+1;
        t = a[y] * w[inv ? (n-z) : z] % mod;
        a[y] = (a[x] - t + mod) % mod;
        a[x] = (a[j+l] + t) % mod;
    }

    nrev = exp(n, mod-2, mod);
    if (inv) for (int i=0; i<n; ++i) a[i] = a[i] * nrev % mod;
}

// assert n is a power of two greater or equal product size
// n = na + nb; while (n&(n-1)) n++;
void multiply(ll* a, ll* b, int n) {
    ntt(a, n, 0);
    ntt(b, n, 0);
    for (int i = 0; i < n; i++) a[i] = a[i]*b[i] % mod;
    ntt(a, n, 1);
}

```

6.19 Pollard rho

```

// factor(N, v) to get N factorized in vector v
// O(N^(1/4)) on average
// Miller-Rabin - Primarily Test O((base*(logn)^2))
ll addmod(ll a, ll b, ll m) {
    if (a >= m - b) return a + b - m;
    return a + b;
}

ll mulmod(ll a, ll b, ll m) {
    ll ans = 0;
    while (b) {
        if (b & 1) ans = addmod(ans, a, m);
        a = addmod(a, a, m);
        b >>= 1;
    }
    return ans;
}

ll fexp(ll a, ll b, ll n) {
    ll r = 1;
    while (b) {
        if (b & 1) r = mulmod(r, a, n);
        a = mulmod(a, a, n);
        b >>= 1;
    }
    return r;
}

bool miller(ll a, ll n) {
    if (a >= n) return true;
    ll s = 0, d = n - 1;
    while (d % 2 == 0) d >>= 1, s++;
    ll x = fexp(a, d, n);
    if (x == 1 || x == n - 1) return true;
    for (int r = 0; r < s; r++) x = mulmod(x, x, n);
    if (x == 1) return false;
    if (x == n - 1) return true;
    return false;
}

bool isprime(ll n) {
    if (n == 1) return false;
    int base[] = {2, 3, 5, 7, 11, 13, 17, 19, 23, 29, 31, 37};
    for (int i = 0; i < 12; ++i) if (!miller(base[i], n)) return false;
    return true;
}

ll pollard(ll n) {
    ll x, y, d, c = 1;
    if (n % 2 == 0) return 2;
    while (true) {
        y = x = 2;
        while (true) {
            x = addmod(mulmod(x, x, n), c, n);

```

```

        y = addmod(mulmod(y, y, n), c, n);
        y = addmod(mulmod(y, y, n), c, n);
        if (x == y) break;
        d = __gcd(abs(x-y), n);
        if (d > 1) return d;
    }
    c++;
}

vector<ll> factor(ll n) {
    if (n == 1 || isprime(n)) return {n};
    ll f = pollard(n);
    vector<ll> l = factor(f), r = factor(n / f);
    l.insert(l.end(), r.begin(), r.end());
    sort(l.begin(), l.end());
    return l;
}

//n < 2,047 base = {2};
//n < 9,080,191 base = {31, 73};
//n < 2,152,302,898,747 base = {2, 3, 5, 7, 11};
//n < 318,665,857,834,031,151,167,461 base = {2, 3, 5, 7, 11, 13, 17, 19, 23, 29, 31, 37};
//n < 3,317,044,064,679,887,385,961,981 base = {2, 3, 5, 7, 11, 13, 17, 19, 23, 29, 31, 37, 41};

```

6.20 Pollard rho optimization

```

// We recomend you to use pollard-rho.cpp! I've never needed this code, but here it is.
// This uses Brent's algorithm for cycle detection
//
std::mt19937 rng((int) std::chrono::steady_clock::now().time_since_epoch().count());

ull func(ull x, ull n, ull c) { return (mulmod(x, x, n) + c) % n; // f(x) = (x^2 + c) % n; }

ull pollard(ull n) {
    // Finds a positive divisor of n
    ull x, y, d, c;
    ull pot, lam;
    if (n % 2 == 0) return 2;
    if (isprime(n)) return n;

    while (1) {
        y = x = 2; d = 1;
        pot = lam = 1;
        while (1) {
            c = rng() % n;
            if (c != 0 and (c+2)%n != 0) break;
        }
        while (1) {
            if (pot == lam) {
                x = y;
                pot <= 1;
                lam = 0;
            }
            y = func(y, n, c);
            lam++;
            d = gcd(x >= y ? x-y : y-x, n);
            if (d > 1) {
                if (d == n) break;
                else return d;
            }
        }
    }
}

void fator(ull n, vector<ull> &v) {
    // prime factorization of n, put into a vector v.
    //
    // for each prime factor of n, it is repeated the amount of times
    // that it divides n
    //
    // ex : n = 120, v = {2, 2, 2, 3, 5};
    //
    if (isprime(n)) { v.pb(n); return; }
    vector<ull> w, t; w.pb(n); t.pb(1);

    while (!w.empty()) {
        ull bck = w.back();
        ull div = pollard(bck);

        if (div == w.back()) {
            int amt = 0;
            for (int i=0; i < (int) w.size(); i++) {
                int cur = 0;
                while (w[i] % div == 0) {
                    w[i] /= div;

```

```

        cur++;
    }
    amt += cur * t[i];
    if(w[i] == 1) {
        swap(w[i], w.back());
        swap(t[i], t.back());
        w.pop_back();
        t.pop_back();
    }
    while(amt--> v.pb(div);
}
else {
    int amt = 0;
    while(w.back() % div == 0) {
        w.back() /= div;
        amt++;
    }
    amt *= t.back();
    if(w.back() == 1) {
        w.pop_back();
        t.pop_back();
    }
    w.pb(div);
    t.pb(amt);
}
}

// the divisors will not be sorted, so you need to sort it afterwards
sort(v.begin(), v.end());
}
}

```

6.21 Prime factors

```

// Prime factors (up to 9*10^13. For greater see Pollard Rho)
vi factors;
int ind=0, pf = primes[0];
while (pf*pf <= n) {
    while (n%pf == 0) n /= pf, factors.pb(pf);
    pf = primes[++ind];
}
if (n != 1) factors.pb(n);

```

6.22 Primitive root

```

// Finds a primitive root modulo p
// To make it works for any value of p, we must add calculation of phi(p)
// n is 1, 2, 4 or p^k or 2*p^k (p odd in both cases)
ll root(ll p) {
    ll n = p-1;
    vector<ll> fact;

    for (int i=2; i*i<=n; ++i) if (n % i == 0) {
        fact.push_back(i);
        while (n % i == 0) n /= i;
    }

    if (n > 1) fact.push_back(n);

    for (int res=2; res<=p; ++res) {
        bool ok = true;
        for (size_t i=0; i<fact.size(); ++i)
            ok &= exp(res, (p-1) / fact[i], p) != 1;
        if (ok) return res;
    }

    return -1;
}

```

6.23 Sieve

```

// Sieve of Erasthotenes
int p[N]; vi primes;

for (ll i = 2; i < N; ++i) if (!p[i]) {
    for (ll j = i*i; j < N; j+=i) p[j]=1;
    primes.pb(i);
}

```

6.24 Simpson rule

```

// Simpson Integration Rule
// define the function f
double f(double x) {
    // ...
}

double simpson(double a, double b, int n = 1e6) {
    double h = (b - a) / n;
    double s = f(a) + f(b);
    for (int i = 1; i < n; i += 2) s += 4 * f(a + h*i);
    for (int i = 2; i < n; i += 2) s += 2 * f(a + h*i);
    return s*h/3;
}

```

6.25 Stanford simplex

```

// Two-phase simplex algorithm for solving linear programs of the form
//
//      maximize    c^T x
//      subject to   Ax <= b
//                  x >= 0
//
// INPUT: A -- an m x n matrix
//        b -- an m-dimensional vector
//        c -- an n-dimensional vector
//        x -- a vector where the optimal solution will be stored
//
// OUTPUT: value of the optimal solution (infinity if unbounded
//         above, nan if infeasible)
//
// To use this code, create an LPSolver object with A, b, and c as
// arguments. Then, call Solve(x).

#include <iostream>
#include <iomanip>
#include <vector>
#include <cmath>
#include <limits>

using namespace std;
typedef long double DOUBLE;
typedef vector<DOUBLE> VD;
typedef vector<VD> VVD;
typedef vector<int> VI;
const DOUBLE EPS = 1e-9;

struct LPSolver {
    int m, n;
    VI B, N;
    VVD D;

    LPSolver(const VVD &A, const VD &b, const VD &c) :
        m(b.size()), n(c.size()), N(n + 1), B(m), D(m + 2, VD(n + 2)) {
        for (int i = 0; i < m; i++) for (int j = 0; j < n; j++) D[i][j] = A[i][j];
        for (int i = 0; i < m; i++) { B[i] = n + 1; D[i][n] = -1; D[i][n + 1] = b[i]; }
        for (int j = 0; j < n; j++) { N[j] = j; D[m][j] = -c[j]; }
        N[n] = -1; D[m + 1][n] = 1;
    }

    void Pivot(int r, int s) {
        for (int i = 0; i < m + 2; i++) if (i != r)
            for (int j = 0; j < n + 2; j++) if (j != s)
                D[i][j] -= D[r][j] * D[i][s] / D[r][s];

        for (int j = 0; j < n + 2; j++) if (j != s) D[r][j] /= D[r][s];
        for (int i = 0; i < m + 2; i++) if (i != r) D[i][s] /= -D[r][s];
        D[r][s] = 1.0 / D[r][s];
        swap(B[r], N[s]);
    }

    bool Simplex(int phase) {
        int x = phase == 1 ? m + 1 : m;
        while (true) {
            int s = -1;
            for (int j = 0; j <= n; j++) {
                if (phase == 2 && N[j] == -1) continue;
                if (s == -1 || D[x][j] < D[x][s] || D[x][j] == D[x][s] && N[j] < N[s])
                    s = j;
            }
            if (D[x][s] > -EPS) return true;
            int r = -1;
            for (int i = 0; i < m; i++) {
                if (D[i][s] < EPS) continue;

```

```

        if (r == -1 || D[i][n + 1] / D[i][s] < D[r][n + 1] / D[r][s] ||
            (D[i][n + 1] / D[i][s]) == (D[r][n + 1] / D[r][s]) && B[i] < B
            [r]) r = i;
    }
    if (r == -1) return false;
    Pivot(r, s);
}

}

DOUBLE Solve(VD &x) {
    int r = 0;
    for (int i = 1; i < m; i++) if (D[i][n + 1] < D[r][n + 1]) r = i;
    if (D[r][n + 1] < -EPS) {
        Pivot(r, n);
        if (!Simplex(1) || D[m + 1][n + 1] < -EPS) return -numeric_limits<DOUBLE>::
            infinity();
        for (int i = 0; i < m; i++) if (B[i] == -1) {
            int s = -1;
            for (int j = 0; j <= n; j++)
                if (s == -1 || D[i][j] < D[i][s] || D[i][j] == D[i][s] && N[j]
                    < N[s]) s = j;
            Pivot(i, s);
        }
    }
    if (!Simplex(2)) return numeric_limits<DOUBLE>::infinity();
    x = VD(n);
    for (int i = 0; i < m; i++) if (B[i] < n) x[B[i]] = D[i][n + 1];
    return D[m][n + 1];
}

};

int main() {
    const int m = 4;
    const int n = 3;
    DOUBLE _A[m][n] = {
        { 6, -1, 0 },
        { -1, -5, 0 },
        { 1, 5, 1 },
        { -1, -5, -1 }
    };
    DOUBLE _b[m] = { 10, -4, 5, -5 };
    DOUBLE _c[n] = { 1, -1, 0 };

    VVD A(m);
    VD b(_b, _b + m);
    VD c(_c, _c + n);
    for (int i = 0; i < m; i++) A[i] = VD(_A[i], _A[i] + n);

    LPSolver solver(A, b, c);
    VD x;
    DOUBLE value = solver.Solve(x);

    cerr << "VALUE: " << value << endl; // VALUE: 1.29032
    cerr << "SOLUTION:"; // SOLUTION: 1.74194 0.451613 1
    for (size_t i = 0; i < x.size(); i++) cerr << " " << x[i];
    cerr << endl;
    return 0;
}

```

7 Strings

7.1 KMP

```

vi kmp_builder(string &s, int n) {
    vi dp(n, 0);
    int j = 0;
    forx(i, 1, n) {
        while (j && s[i] != s[j]) j = dp[j - 1];

        if (s[i] == s[j]) dp[i] = ++j;
        else dp[i] = 0;
    }

    return dp;
}

// Return all occurrences of the pattern in the text
vi kmp(string &t, string &p) {
    string q = p + "#";
    vi v = kmp_builder(q, sz(q));
    vi res;
    forn(i, sz(q)) if (v[i] == sz(p)) res.pb(i - 2 * sz(p) + 1);

    return res;
}

```

7.2 Algorithm Z

```

// Example answer aabb#aaxnaabba -> 01000210041001
vi alz(const string &s) // pattern#where_to_look
{
    int n = s.size();
    vi z(n, 0);
    for (int i = 1, l = 0, r = 0; i < n; i++)
    {
        if (i <= r)
            z[i] = min(z[i - l], r - i + 1);
        while (i + z[i] < n && s[z[i]] == s[i + z[i]])
            z[i]++;
        if (r < i + z[i] - 1)
            l = i, r = i + z[i] - 1;
    }
    return z;
}

```

7.3 Rabin Karp

```

const ll mod[2] = {10000000007, 998244353};
const ll px[2] = {29, 31};

vl rabin_karp(string &s, string &p) {
    vl ss[2], pp[2], ppx[2];
    for (ll i = 0; i < 2; i++)
        ss[i] = rolling_hash(s, px[i], mod[i]),
        pp[i] = rolling_hash(p, px[i], mod[i]);

    vi res;
    for (int i = 0; i + sz(p) - 1 < sz(s); i++) {
        ll ok = 1;
        for (ll j = 0; j < 2; j++) {
            int fh = fast_hash(ss[j], px[j], mod[j], i, i + sz(p) - 1) % mod[j];
            ok &= (fh == pp[j].back());
        }
        if (ok) res.pb(i + 1);
    }

    return res;
}

```

7.4 Aho-Corasick

```

const int K = 26;

struct Vertex {
    int next[K];
    bool output = false;
    int p = -1;
    char pch;
    int link = -1;
    int go[K];

    Vertex(int p=-1, char ch='§') : p(p), pch(ch) {
        fill(begin(next), end(next), -1);
        fill(begin(go), end(go), -1);
    }
};

vector<Vertex> t(1);

void aho_init() {
    t.clear();
    t.pb(Vertex());
}

void add_string(string const& s) {
    int v = 0;
    for (char ch : s) {
        int c = ch - 'a';
        if (t[v].next[c] == -1) {
            t[v].next[c] = t.size();
            t.emplace_back(v, ch);
        }
        v = t[v].next[c];
    }
}

```



```

    t[v].output = true;
}

int go(int v, char ch);

int get_link(int v) {
    if (t[v].link == -1) {
        if (v == 0 || t[v].p == 0)
            t[v].link = 0;
        else
            t[v].link = go(get_link(t[v].p), t[v].pch);
    }
    return t[v].link;
}

int go(int v, char ch) {
    int c = ch - 'a';
    if (t[v].go[c] == -1) {
        if (t[v].next[c] != -1)
            t[v].go[c] = t[v].next[c];
        else
            t[v].go[c] = v == 0 ? 0 : go(get_link(v), ch);
    }
    return t[v].go[c];
}

vector<int> search_in_text(const string& text) {
    vector<int> occurrences;
    int v = 0;
    for (int i = 0; i < text.size(); i++) {
        char ch = text[i];
        v = go(v, ch);

        for (int u = v; u != 0; u = get_link(u)) {
            if (t[u].output) {
                occurrences.push_back(i);
            }
        }
    }
    return occurrences;
}

```

7.5 Hashing

```

const int K = 2;
struct Hash {
    const ll MOD[K] = {999727999, 1070777777};
    const ll P = 17777771;
    vector<ll> h[K], p[K];
    Hash(string &s) {
        int n = s.size();
        for (int k = 0; k < K; k++) {
            h[k].resize(n + 1, 0);
            p[k].resize(n + 1, 1);
            for (int i = 1; i <= n; i++) {
                h[k][i] = (h[k][i - 1] * P + s[i - 1]) % MOD[k];
                p[k][i] = (p[k][i - 1] * P) % MOD[k];
            }
        }
    }
    vector<ll> get(int i, int j) { // hash [i, j]
        j++;
        vector<ll> r(K);
        for (int k = 0; k < K; k++) {
            r[k] = (h[k][j] - h[k][i] * p[k][j - i]) % MOD[k];
            r[k] = (r[k] + MOD[k]) % MOD[k];
        }
        return r;
    }
};

// Other
ll pow(ll b, ll e, ll m) {
    ll res = 1;
    for (; e >= 1; b = (b * b) % m)
        if (e & 1) res = (res * b) % m;
    return res;
}

ll inv(ll b, ll e, ll m) {
    return pow(pow(b, e, m), m - 2, m);
}

vl rolling_hash(string &s, ll p, ll m) {
    ll n = sz(s);
    vl v(n, 0);

```

```

v[0] = (s[0]) % m;
for (ll i = 1; i < n; i++)
    v[i] = (v[i - 1] + (s[i] * pow(p, i, m)) % m) % m;

return v;
}

ll fast_hash(vl &v, ll p, ll m, ll i, ll j) {
    return ((v[j] - (i ? v[i - 1] : 0) + m) % m * inv(p, i, m)) % m;
}

// Hash 128
#define bint __int128
struct Hash {
    bint MOD=212345678987654321LL,P=1777771,PI=106955741089659571LL;
    vector<bint> h,pi;
    Hash(string& s) {
        assert((P*PI)%MOD==1);
        h.resize(s.size()+1);pi.resize(s.size()+1);
        h[0]=0;pi[0]=1;
        bint p=1;
        forx(i,1,s.size()+1){
            h[i]=(h[i-1]+p*s[i-1])%MOD;
            pi[i]=(pi[i-1]*PI)%MOD;
            p=(p*P)%MOD;
        }
    }
    ll get(int s, int e){
        return (((h[e]-h[s]+MOD)%MOD)*pi[s])%MOD;
    }
};

```

7.6 Manacher

```

/* Find palindromes in a string
f = 1 para pares, 0 impar
a a a a a
1 2 3 3 2 1    f = 0 impar
0 1 2 3 2 1    f = 1 par centrado entre [i-1,i]
Time: O(n)
*/
void manacher(string &s, int f, vi &d) {
    int l = 0, r = -1, n = s.size();
    d.assign(n, 0);
    for (int i = 0; i < n; i++) {
        int k = (i > r ? (1 - f) : min(d[l + r - i + f], r - i + f)) + f;
        while (i + k - f < n && i - k >= 0 && s[i + k - f] == s[i - k]) ++k;
        d[i] = k - f; --k;
        if (i + k - f > r) l = i - k, r = i + k - f;
    }
}

```

7.7 Suffix Array

```

struct suffix {
    int index;
    int rank[2];
};

int cmp(struct suffix a, struct suffix b) {
    return (a.rank[0] == b.rank[0]) ? (a.rank[1] < b.rank[1] ? 1 : 0) :
        (a.rank[0] < b.rank[0] ? 1 : 0);
}

int *buildSuffixArray(char *txt, int n) {
    struct suffix suffixes[n];

    for (int i = 0; i < n; i++) {
        suffixes[i].index = i;
        suffixes[i].rank[0] = txt[i] - 'a';
        suffixes[i].rank[1] = ((i+1) < n) ? (txt[i + 1] - 'a') - 1;
    }

    sort(suffixes, suffixes+n, cmp);

    int ind[n];
    for (int k = 4; k < 2*n; k = k*2) {
        int rank = 0;
        int prev_rank = suffixes[0].rank[0];
        suffixes[0].rank[0] = rank;
        ind[suffixes[0].index] = 0;

        for (int i = 1; i < n; i++) {

```

```

        if (suffixes[i].rank[0] == prev_rank &&
            suffixes[i].rank[1] == suffixes[i-1].rank[1]) {
            prev_rank = suffixes[i].rank[0];
            suffixes[i].rank[0] = rank;
        } else {
            prev_rank = suffixes[i].rank[0];
            suffixes[i].rank[0] = ++rank;
        }
        ind[suffixes[i].index] = i;

    for (int i = 0; i < n; i++) {
        int nextindex = suffixes[i].index + k/2;
        suffixes[i].rank[1] = (nextindex < n)?
                                suffixes[ind[nextindex]].rank[0] : -1;
    }

    sort(suffixes, suffixes+n, cmp);
}

int *suffixArr = new int[n];
for (int i = 0; i < n; i++)
    suffixArr[i] = suffixes[i].index;

return suffixArr;
}

void printArr(int arr[], int n)
{
    for (int i = 0; i < n; i++)
        cout << arr[i] << " ";
    cout << endl;
}

void solve() {
    char txt[] = "banana";
    int n = strlen(txt);
    int *suffixArr = buildSuffixArray(txt, n);
    cout << "Following is suffix array for " << txt << endl;
    printArr(suffixArr, n);
}

```

8 Others

8.1 Grundy (Nim Game)

```

#define PLAYER1 1
#define PLAYER2 2

```

```

int calculate_mex(unordered_set<int> my_set) {
    int mex = 0;
    while (my_set.find(mex) != my_set.end()) mex++;
    return mex;
}

int calculate_grundy(int n, int grundy[]) {
    grundy[0] = 0;
    if (grundy[n] != -1) return (grundy[n]);

    unordered_set<int> my_set
    for (int i = 3; i <= 5; i++) // Range of numbers of items we can take
        my_set.insert(calculate_grundy(n - i, grundy));

    grundy[n] = calculate_mex(my_set);
    return grundy[n];
}

void declare_winner(int whoseTurn, int piles[],
                    int grundy[], int n) {
    int xorValue = grundy[piles[0]];
    for (int i = 1; i <= n - 1; i++)
        xorValue = xorValue ^ grundy[piles[i]];

    if (xorValue != 0) {
        if (whoseTurn == PLAYER1)
            printf("Player 1 will win\n");
        else
            printf("Player 2 will win\n");
    } else {
        if (whoseTurn == PLAYER1)
            printf("Player 2 will win\n");
        else
            printf("Player 1 will win\n");
    }
}

void solve() {
    // Each of the piles is a sub game
    int piles[] = {12 + 34 + 11 + 1 + 23};
    int n = sizeof(piles) / sizeof(piles[0]);

    int maximum = *max_element(piles, piles + n);
    int grundy[maximum + 1];
    memset(grundy, -1, sizeof(grundy));

    for (int i = 0; i <= n - 1; i++)
        calculate_grundy(piles[i], grundy);

    declareWinner(PLAYER1, piles, Grundy, n);
}

```

$f(n) = O(g(n))$	iff \exists positive c, n_0 such that $0 \leq f(n) \leq cg(n) \forall n \geq n_0$.	$\sum_{i=1}^n i = \frac{n(n+1)}{2}, \quad \sum_{i=1}^n i^2 = \frac{n(n+1)(2n+1)}{6}, \quad \sum_{i=1}^n i^3 = \frac{n^2(n+1)^2}{4}.$
$f(n) = \Omega(g(n))$	iff \exists positive c, n_0 such that $f(n) \geq cg(n) \geq 0 \forall n \geq n_0$.	In general:
$f(n) = \Theta(g(n))$	iff $f(n) = O(g(n))$ and $f(n) = \Omega(g(n))$.	$\sum_{i=1}^n i^m = \frac{1}{m+1} \left[(n+1)^{m+1} - 1 - \sum_{i=1}^n ((i+1)^{m+1} - i^{m+1} - (m+1)i^m) \right]$
$f(n) = o(g(n))$	iff $\lim_{n \rightarrow \infty} f(n)/g(n) = 0$.	$\sum_{i=1}^{n-1} i^m = \frac{1}{m+1} \sum_{k=0}^m \binom{m+1}{k} B_k n^{m+1-k}.$
$\lim_{n \rightarrow \infty} a_n = a$	iff $\forall \epsilon > 0, \exists n_0$ such that $ a_n - a < \epsilon, \forall n \geq n_0$.	Geometric series:
$\sup S$	least $b \in \mathbb{R}$ such that $b \geq s, \forall s \in S$.	$\sum_{i=0}^n c^i = \frac{c^{n+1} - 1}{c - 1}, \quad c \neq 1, \quad \sum_{i=0}^{\infty} c^i = \frac{1}{1 - c}, \quad \sum_{i=1}^{\infty} c^i = \frac{c}{1 - c}, \quad c < 1,$
$\inf S$	greatest $b \in \mathbb{R}$ such that $b \leq s, \forall s \in S$.	$\sum_{i=0}^n i c^i = \frac{nc^{n+2} - (n+1)c^{n+1} + c}{(c-1)^2}, \quad c \neq 1, \quad \sum_{i=0}^{\infty} i c^i = \frac{c}{(1-c)^2}, \quad c < 1.$
$\liminf_{n \rightarrow \infty} a_n$	$\lim_{n \rightarrow \infty} \inf \{a_i \mid i \geq n, i \in \mathbb{N}\}.$	Harmonic series:
$\limsup_{n \rightarrow \infty} a_n$	$\lim_{n \rightarrow \infty} \sup \{a_i \mid i \geq n, i \in \mathbb{N}\}.$	$H_n = \sum_{i=1}^n \frac{1}{i}, \quad \sum_{i=1}^n i H_i = \frac{n(n+1)}{2} H_n - \frac{n(n-1)}{4}.$
$\binom{n}{k}$	Combinations: Size k subsets of a size n set.	$\sum_{i=1}^n H_i = (n+1)H_n - n, \quad \sum_{i=1}^n \binom{i}{m} H_i = \binom{n+1}{m+1} \left(H_{n+1} - \frac{1}{m+1} \right).$
$[n]$	Stirling numbers (1st kind): Arrangements of an n element set into k cycles.	1. $\binom{n}{k} = \frac{n!}{(n-k)!k!}, \quad 2. \sum_{k=0}^n \binom{n}{k} = 2^n, \quad 3. \binom{n}{k} = \binom{n}{n-k},$
$\left\{ \begin{matrix} n \\ k \end{matrix} \right\}$	Stirling numbers (2nd kind): Partitions of an n element set into k non-empty sets.	4. $\binom{n}{k} = \frac{n}{k} \binom{n-1}{k-1}, \quad 5. \binom{n}{k} = \binom{n-1}{k} + \binom{n-1}{k-1},$
$\langle \begin{matrix} n \\ k \end{matrix} \rangle$	1st order Eulerian numbers: Permutations $\pi_1 \pi_2 \dots \pi_n$ on $\{1, 2, \dots, n\}$ with k ascents.	6. $\binom{n}{m} \binom{m}{k} = \binom{n}{k} \binom{n-k}{m-k}, \quad 7. \sum_{k=0}^n \binom{r+k}{k} = \binom{r+n+1}{n},$
$\langle \langle \begin{matrix} n \\ k \end{matrix} \rangle \rangle$	2nd order Eulerian numbers.	8. $\sum_{k=0}^n \binom{k}{m} = \binom{n+1}{m+1}, \quad 9. \sum_{k=0}^n \binom{r}{k} \binom{s}{n-k} = \binom{r+s}{n},$
C_n	Catalan Numbers: Binary trees with $n+1$ vertices.	10. $\binom{n}{k} = (-1)^k \binom{k-n-1}{k}, \quad 11. \left\{ \begin{matrix} n \\ 1 \end{matrix} \right\} = \left\{ \begin{matrix} n \\ n \end{matrix} \right\} = 1,$
14. $\begin{bmatrix} n \\ 1 \end{bmatrix} = (n-1)!,$	15. $\begin{bmatrix} n \\ 2 \end{bmatrix} = (n-1)!H_{n-1},$	16. $\begin{bmatrix} n \\ n \end{bmatrix} = 1, \quad 17. \begin{bmatrix} n \\ k \end{bmatrix} \geq \left\{ \begin{matrix} n \\ k \end{matrix} \right\},$
18. $\begin{bmatrix} n \\ k \end{bmatrix} = (n-1) \begin{bmatrix} n-1 \\ k \end{bmatrix} + \begin{bmatrix} n-1 \\ k-1 \end{bmatrix},$	19. $\left\{ \begin{matrix} n \\ n-1 \end{matrix} \right\} = \begin{bmatrix} n \\ n-1 \end{bmatrix} = \binom{n}{2},$	20. $\sum_{k=0}^n \begin{bmatrix} n \\ k \end{bmatrix} = n!, \quad 21. C_n = \frac{1}{n+1} \binom{2n}{n},$
22. $\langle \begin{matrix} n \\ 0 \end{matrix} \rangle = \langle \begin{matrix} n \\ n-1 \end{matrix} \rangle = 1,$	23. $\langle \begin{matrix} n \\ k \end{matrix} \rangle = \langle \begin{matrix} n \\ n-1-k \end{matrix} \rangle,$	24. $\langle \begin{matrix} n \\ k \end{matrix} \rangle = (k+1) \langle \begin{matrix} n-1 \\ k \end{matrix} \rangle + (n-k) \langle \begin{matrix} n-1 \\ k-1 \end{matrix} \rangle,$
25. $\langle \begin{matrix} 0 \\ k \end{matrix} \rangle = \begin{cases} 1 & \text{if } k=0, \\ 0 & \text{otherwise} \end{cases}$	26. $\langle \begin{matrix} n \\ 1 \end{matrix} \rangle = 2^n - n - 1,$	27. $\langle \begin{matrix} n \\ 2 \end{matrix} \rangle = 3^n - (n+1)2^n + \binom{n+1}{2},$
28. $x^n = \sum_{k=0}^n \langle \begin{matrix} n \\ k \end{matrix} \rangle \binom{x+k}{n},$	29. $\langle \begin{matrix} n \\ m \end{matrix} \rangle = \sum_{k=0}^m \binom{n+1}{k} (m+1-k)^n (-1)^k,$	30. $m! \left\{ \begin{matrix} n \\ m \end{matrix} \right\} = \sum_{k=0}^n \langle \begin{matrix} n \\ k \end{matrix} \rangle \binom{k}{n-m},$
31. $\langle \begin{matrix} n \\ m \end{matrix} \rangle = \sum_{k=0}^n \left\{ \begin{matrix} n \\ k \end{matrix} \right\} \binom{n-k}{m} (-1)^{n-k-m} k!,$	32. $\langle \langle \begin{matrix} n \\ 0 \end{matrix} \rangle \rangle = 1,$	33. $\langle \langle \begin{matrix} n \\ n \end{matrix} \rangle \rangle = 0 \quad \text{for } n \neq 0,$
34. $\langle \langle \begin{matrix} n \\ k \end{matrix} \rangle \rangle = (k+1) \langle \langle \begin{matrix} n-1 \\ k \end{matrix} \rangle \rangle + (2n-1-k) \langle \langle \begin{matrix} n-1 \\ k-1 \end{matrix} \rangle \rangle,$	35. $\sum_{k=0}^n \langle \langle \begin{matrix} n \\ k \end{matrix} \rangle \rangle = \frac{(2n)n}{2^n},$	36. $\left\{ \begin{matrix} x \\ x-n \end{matrix} \right\} = \sum_{k=0}^n \langle \langle \begin{matrix} n \\ k \end{matrix} \rangle \rangle \binom{x+n-1-k}{2n},$
37. $\left\{ \begin{matrix} n+1 \\ m+1 \end{matrix} \right\} = \sum_k \binom{n}{k} \left\{ \begin{matrix} k \\ m \end{matrix} \right\} = \sum_{k=0}^n \left\{ \begin{matrix} k \\ m \end{matrix} \right\} (m+1)^{n-k},$		

<p>38. $\begin{bmatrix} n+1 \\ m+1 \end{bmatrix} = \sum_k \begin{bmatrix} n \\ k \end{bmatrix} \begin{bmatrix} k \\ m \end{bmatrix} = \sum_{k=0}^n \begin{bmatrix} k \\ m \end{bmatrix} n^{n-k} = n! \sum_{k=0}^n \frac{1}{k!} \begin{bmatrix} k \\ m \end{bmatrix},$</p> <p>40. $\left\{ \begin{matrix} n \\ m \end{matrix} \right\} = \sum_k \binom{n}{k} \left\{ \begin{matrix} k+1 \\ m+1 \end{matrix} \right\} (-1)^{n-k},$</p> <p>42. $\left\{ \begin{matrix} m+n+1 \\ m \end{matrix} \right\} = \sum_{k=0}^m k \left\{ \begin{matrix} n+k \\ k \end{matrix} \right\},$</p> <p>44. $\binom{n}{m} = \sum_k \left\{ \begin{matrix} n+1 \\ k+1 \end{matrix} \right\} \begin{bmatrix} k \\ m \end{bmatrix} (-1)^{m-k},$</p> <p>46. $\left\{ \begin{matrix} n \\ n-m \end{matrix} \right\} = \sum_k \binom{m-n}{m+k} \binom{m+n}{n+k} \begin{bmatrix} m+k \\ k \end{bmatrix},$</p> <p>48. $\left\{ \begin{matrix} n \\ \ell+m \end{matrix} \right\} \binom{\ell+m}{\ell} = \sum_k \left\{ \begin{matrix} k \\ \ell \end{matrix} \right\} \left\{ \begin{matrix} n-k \\ m \end{matrix} \right\} \binom{n}{k},$</p>	<p>39. $\begin{bmatrix} x \\ x-n \end{bmatrix} = \sum_{k=0}^n \left\langle \begin{matrix} n \\ k \end{matrix} \right\rangle \begin{bmatrix} x+k \\ 2n \end{bmatrix},$</p> <p>41. $\begin{bmatrix} n \\ m \end{bmatrix} = \sum_k \begin{bmatrix} n+1 \\ k+1 \end{bmatrix} \binom{k}{m} (-1)^{m-k},$</p> <p>43. $\begin{bmatrix} m+n+1 \\ m \end{bmatrix} = \sum_{k=0}^m k(n+k) \begin{bmatrix} n+k \\ k \end{bmatrix},$</p> <p>45. $(n-m)! \binom{n}{m} = \sum_k \begin{bmatrix} n+1 \\ k+1 \end{bmatrix} \left\{ \begin{matrix} k \\ m \end{matrix} \right\} (-1)^{m-k},$ for $n \geq m,$</p> <p>47. $\begin{bmatrix} n \\ n-m \end{bmatrix} = \sum_k \binom{m-n}{m+k} \binom{m+n}{n+k} \left\{ \begin{matrix} m+k \\ k \end{matrix} \right\},$</p> <p>49. $\begin{bmatrix} n \\ \ell+m \end{bmatrix} \binom{\ell+m}{\ell} = \sum_k \begin{bmatrix} k \\ \ell \end{bmatrix} \begin{bmatrix} n-k \\ m \end{bmatrix} \binom{n}{k}.$</p>	<p>Every tree with n vertices has $n-1$ edges.</p> <p>Kraft inequality: If the depths of the leaves of a binary tree are d_1, \dots, d_n:</p> $\sum_{i=1}^n 2^{-d_i} \leq 1,$ <p>and equality holds only if every internal node has 2 sons.</p>
--	--	--

Recurrences

Master method:

$$T(n) = aT(n/b) + f(n), \quad a \geq 1, b > 1$$

If $\exists \epsilon > 0$ such that $f(n) = O(n^{\log_b a - \epsilon})$ then

$$T(n) = \Theta(n^{\log_b a}).$$

If $f(n) = \Theta(n^{\log_b a})$ then

$$T(n) = \Theta(n^{\log_b a} \log_2 n).$$

If $\exists \epsilon > 0$ such that $f(n) = \Omega(n^{\log_b a + \epsilon})$, and $\exists c < 1$ such that $af(n/b) \leq cf(n)$ for large n , then

$$T(n) = \Theta(f(n)).$$

Substitution (example): Consider the following recurrence

$$T_{i+1} = 2^{2^i} \cdot T_i^2, \quad T_1 = 2.$$

Note that T_i is always a power of two.

Let $t_i = \log_2 T_i$. Then we have

$$t_{i+1} = 2^i + 2t_i, \quad t_1 = 1.$$

Let $u_i = t_i/2^i$. Dividing both sides of the previous equation by 2^{i+1} we get

$$\frac{t_{i+1}}{2^{i+1}} = \frac{2^i}{2^{i+1}} + \frac{t_i}{2^i}.$$

Substituting we find

$$u_{i+1} = \frac{1}{2} + u_i, \quad u_1 = \frac{1}{2},$$

which is simply $u_i = i/2$. So we find that T_i has the closed form $T_i = 2^{i2^{i-1}}$.

Summing factors (example): Consider the following recurrence

$$T(n) = 3T(n/2) + n, \quad T(1) = 1.$$

Rewrite so that all terms involving T are on the left side

$$T(n) - 3T(n/2) = n.$$

Now expand the recurrence, and choose a factor which makes the left side “telescope”

$$1(T(n) - 3T(n/2)) = n$$

$$3(T(n/2) - 3T(n/4)) = n/2$$

$$\vdots \quad \vdots \quad \vdots$$

$$3^{\log_2 n - 1} (T(2) - 3T(1)) = 2$$

Let $m = \log_2 n$. Summing the left side we get $T(n) - 3^m T(1) = T(n) - 3^m = T(n) - n^k$ where $k = \log_2 3 \approx 1.58496$. Summing the right side we get

$$\sum_{i=0}^{m-1} \frac{n}{2^i} 3^i = n \sum_{i=0}^{m-1} \left(\frac{3}{2}\right)^i.$$

Let $c = \frac{3}{2}$. Then we have

$$\begin{aligned} n \sum_{i=0}^{m-1} c^i &= n \left(\frac{c^m - 1}{c - 1} \right) \\ &= 2n(c^{\log_2 n} - 1) \\ &= 2n(c^{(k-1)\log_2 n} - 1) \\ &= 2n^k - 2n, \end{aligned}$$

and so $T(n) = 3n^k - 2n$. Full history recurrences can often be changed to limited history ones (example): Consider

$$T_i = 1 + \sum_{j=0}^{i-1} T_j, \quad T_0 = 1.$$

Note that

$$T_{i+1} = 1 + \sum_{j=0}^i T_j.$$

Subtracting we find

$$\begin{aligned} T_{i+1} - T_i &= 1 + \sum_{j=0}^i T_j - 1 - \sum_{j=0}^{i-1} T_j \\ &= T_i. \end{aligned}$$

And so $T_{i+1} = 2T_i = 2^{i+1}$.

Generating functions:

1. Multiply both sides of the equation by x^i .
2. Sum both sides over all i for which the equation is valid.
3. Choose a generating function $G(x)$. Usually $G(x) = \sum_{i=0}^{\infty} x^i g_i$.
3. Rewrite the equation in terms of the generating function $G(x)$.
4. Solve for $G(x)$.
5. The coefficient of x^i in $G(x)$ is g_i .

Example:

$$g_{i+1} = 2g_i + 1, \quad g_0 = 0.$$

Multiply and sum:

$$\sum_{i \geq 0} g_{i+1} x^i = \sum_{i \geq 0} 2g_i x^i + \sum_{i \geq 0} x^i.$$

We choose $G(x) = \sum_{i \geq 0} x^i g_i$. Rewrite in terms of $G(x)$:

$$\frac{G(x) - g_0}{x} = 2G(x) + \sum_{i \geq 0} x^i.$$

Simplify:

$$\frac{G(x)}{x} = 2G(x) + \frac{1}{1-x}.$$

Solve for $G(x)$:

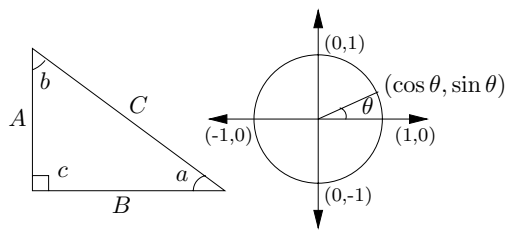
$$G(x) = \frac{x}{(1-x)(1-2x)}.$$

Expand this using partial fractions:

$$\begin{aligned} G(x) &= x \left(\frac{2}{1-2x} - \frac{1}{1-x} \right) \\ &= x \left(2 \sum_{i \geq 0} 2^i x^i - \sum_{i \geq 0} x^i \right) \\ &= \sum_{i \geq 0} (2^{i+1} - 1) x^{i+1}. \end{aligned}$$

So $g_i = 2^i - 1$.

$n \sim 0.11109,$			$\psi = 2 \sim 1.01009,$		
$\psi = 2 \sim 1.01009,$			$\psi = 2 \sim 1.01009,$		
i	2^i	p_i	General		Probability
1	2	2	Bernoulli Numbers ($B_i = 0$, odd $i \neq 1$):		Continuous distributions: If
2	4	3	$B_0 = 1, B_1 = -\frac{1}{2}, B_2 = \frac{1}{6}, B_4 = -\frac{1}{30},$		$\Pr[a < X < b] = \int_a^b p(x) dx,$
3	8	5	$B_6 = \frac{1}{42}, B_8 = -\frac{1}{30}, B_{10} = \frac{5}{66}.$		then p is the probability density function of X . If
4	16	7	Change of base, quadratic formula:		$\Pr[X < a] = P(a),$
5	32	11	$\log_b x = \frac{\log_a x}{\log_a b}, \quad \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}.$		then P is the distribution function of X . If P and p both exist then
6	64	13	Euler's number e :		$P(a) = \int_{-\infty}^a p(x) dx.$
7	128	17	$e = 1 + \frac{1}{2} + \frac{1}{6} + \frac{1}{24} + \frac{1}{120} + \dots$		Expectation: If X is discrete
8	256	19	$\lim_{n \rightarrow \infty} \left(1 + \frac{x}{n}\right)^n = e^x.$		$E[g(X)] = \sum_x g(x) \Pr[X = x].$
9	512	23	$\left(1 + \frac{1}{n}\right)^n < e < \left(1 + \frac{1}{n}\right)^{n+1}.$		If X continuous then
10	1,024	29	$\left(1 + \frac{1}{n}\right)^n = e - \frac{e}{2n} + \frac{11e}{24n^2} - O\left(\frac{1}{n^3}\right).$		$E[g(X)] = \int_{-\infty}^{\infty} g(x)p(x) dx = \int_{-\infty}^{\infty} g(x) dP(x).$
11	2,048	31	Harmonic numbers:		Variance, standard deviation:
12	4,096	37	$1, \frac{3}{2}, \frac{11}{6}, \frac{25}{12}, \frac{137}{60}, \frac{49}{20}, \frac{363}{140}, \frac{761}{280}, \frac{7129}{2520}, \dots$		$\text{VAR}[X] = E[X^2] - E[X]^2,$
13	8,192	41	$\ln n < H_n < \ln n + 1,$		$\sigma = \sqrt{\text{VAR}[X]}.$
14	16,384	43	$H_n = \ln n + \gamma + O\left(\frac{1}{n}\right).$		For events A and B :
15	32,768	47	Factorial, Stirling's approximation:		$\Pr[A \vee B] = \Pr[A] + \Pr[B] - \Pr[A \wedge B]$
16	65,536	53	$1, 2, 6, 24, 120, 720, 5040, 40320, 362880, \dots$		$\Pr[A \wedge B] = \Pr[A] \cdot \Pr[B],$
17	131,072	59	$n! = \sqrt{2\pi n} \left(\frac{n}{e}\right)^n \left(1 + \Theta\left(\frac{1}{n}\right)\right).$		iff A and B are independent.
18	262,144	61	Ackermann's function and inverse:		$\Pr[A B] = \frac{\Pr[A \wedge B]}{\Pr[B]}$
19	524,288	67	$a(i, j) = \begin{cases} 2^j & i = 1 \\ a(i-1, 2) & j = 1 \\ a(i-1, a(i, j-1)) & i, j \geq 2 \end{cases}$		For random variables X and Y :
20	1,048,576	71	$\alpha(i) = \min\{j \mid a(j, j) \geq i\}.$		$E[X \cdot Y] = E[X] \cdot E[Y],$
21	2,097,152	73	Binomial distribution:		if X and Y are independent.
22	4,194,304	79	$\Pr[X = k] = \binom{n}{k} p^k q^{n-k}, \quad q = 1 - p,$		$E[X + Y] = E[X] + E[Y],$
23	8,388,608	83	$E[X] = \sum_{k=1}^n k \binom{n}{k} p^k q^{n-k} = np.$		$E[cX] = cE[X].$
24	16,777,216	89	Poisson distribution:		Bayes' theorem:
25	33,554,432	97	$\Pr[X = k] = \frac{e^{-\lambda} \lambda^k}{k!}, \quad E[X] = \lambda.$		$\Pr[A_i B] = \frac{\Pr[B A_i] \Pr[A_i]}{\sum_{j=1}^n \Pr[A_j] \Pr[B A_j]}.$
26	67,108,864	101	Normal (Gaussian) distribution:		Inclusion-exclusion:
27	134,217,728	103	$p(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-(x-\mu)^2/2\sigma^2}, \quad E[X] = \mu.$		$\Pr\left[\bigvee_{i=1}^n X_i\right] = \sum_{i=1}^n \Pr[X_i] +$
28	268,435,456	107	The "coupon collector": We are given a random coupon each day, and there are n different types of coupons. The distribution of coupons is uniform. The expected number of days to pass before we to collect all n types is		$\sum_{k=2}^n (-1)^{k+1} \sum_{i_1 < \dots < i_k} \Pr\left[\bigwedge_{j=1}^k X_{i_j}\right].$
29	536,870,912	109	$nH_n.$		Moment inequalities:
30	1,073,741,824	113			$\Pr[X \geq \lambda E[X]] \leq \frac{1}{\lambda},$
31	2,147,483,648	127			$\Pr[X - E[X] \geq \lambda \cdot \sigma] \leq \frac{1}{\lambda^2}.$
32	4,294,967,296	131			Geometric distribution:
Pascal's Triangle					$\Pr[X = k] = pq^{k-1}, \quad q = 1 - p,$
1					$E[X] = \sum_{k=1}^{\infty} kpq^{k-1} = \frac{1}{p}.$
1 1					
1 2 1					
1 3 3 1					
1 4 6 4 1					
1 5 10 10 5 1					
1 6 15 20 15 6 1					
1 7 21 35 35 21 7 1					
1 8 28 56 70 56 28 8 1					
1 9 36 84 126 126 84 36 9 1					
1 10 45 120 210 252 210 120 45 10 1					



Pythagorean theorem:

$$C^2 = A^2 + B^2.$$

Definitions:

$$\begin{aligned} \sin a &= A/C, & \cos a &= B/C, \\ \csc a &= C/A, & \sec a &= C/B, \\ \tan a &= \frac{\sin a}{\cos a} = \frac{A}{B}, & \cot a &= \frac{\cos a}{\sin a} = \frac{B}{A}. \end{aligned}$$

Area, radius of inscribed circle:

$$\frac{1}{2}AB, \quad \frac{AB}{A+B+C}.$$

Identities:

$$\begin{aligned} \sin x &= \frac{1}{\csc x}, & \cos x &= \frac{1}{\sec x}, \\ \tan x &= \frac{1}{\cot x}, & \sin^2 x + \cos^2 x &= 1, \\ 1 + \tan^2 x &= \sec^2 x, & 1 + \cot^2 x &= \csc^2 x, \\ \sin x &= \cos\left(\frac{\pi}{2} - x\right), & \sin x &= \sin(\pi - x), \\ \cos x &= -\cos(\pi - x), & \tan x &= \cot\left(\frac{\pi}{2} - x\right), \\ \cot x &= -\cot(\pi - x), & \csc x &= \cot\frac{x}{2} - \cot x, \end{aligned}$$

$$\sin(x \pm y) = \sin x \cos y \pm \cos x \sin y,$$

$$\cos(x \pm y) = \cos x \cos y \mp \sin x \sin y,$$

$$\tan(x \pm y) = \frac{\tan x \pm \tan y}{1 \mp \tan x \tan y},$$

$$\cot(x \pm y) = \frac{\cot x \cot y \mp 1}{\cot x \pm \cot y},$$

$$\sin 2x = 2 \sin x \cos x, \quad \sin 2x = \frac{2 \tan x}{1 + \tan^2 x},$$

$$\cos 2x = \cos^2 x - \sin^2 x, \quad \cos 2x = 2 \cos^2 x - 1,$$

$$\cos 2x = 1 - 2 \sin^2 x, \quad \cos 2x = \frac{1 - \tan^2 x}{1 + \tan^2 x},$$

$$\tan 2x = \frac{2 \tan x}{1 - \tan^2 x}, \quad \cot 2x = \frac{\cot^2 x - 1}{2 \cot x},$$

$$\sin(x+y) \sin(x-y) = \sin^2 x - \sin^2 y,$$

$$\cos(x+y) \cos(x-y) = \cos^2 x - \sin^2 y.$$

Euler's equation:

$$e^{ix} = \cos x + i \sin x, \quad e^{i\pi} = -1.$$

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sseiden@acm.org
<http://www.csc.lsu.edu/~seiden>

Multiplication:

$$C = A \cdot B, \quad c_{i,j} = \sum_{k=1}^n a_{i,k} b_{k,j}.$$

Determinants: $\det A \neq 0$ iff A is non-singular.

$$\det A \cdot B = \det A \cdot \det B,$$

$$\det A = \sum_{\pi} \prod_{i=1}^n \text{sign}(\pi) a_{i,\pi(i)}.$$

2×2 and 3×3 determinant:

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc,$$

$$\begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = g \begin{vmatrix} b & c \\ e & f \end{vmatrix} - h \begin{vmatrix} a & c \\ d & f \end{vmatrix} + i \begin{vmatrix} a & b \\ d & e \end{vmatrix}$$

$$= aei + bfg + cdh - ceg - fha - ibd.$$

Permanents:

$$\text{perm } A = \sum_{\pi} \prod_{i=1}^n a_{i,\pi(i)}.$$

Hyperbolic Functions

Definitions:

$$\sinh x = \frac{e^x - e^{-x}}{2}, \quad \cosh x = \frac{e^x + e^{-x}}{2},$$

$$\tanh x = \frac{e^x - e^{-x}}{e^x + e^{-x}}, \quad \text{csch } x = \frac{1}{\sinh x},$$

$$\text{sech } x = \frac{1}{\cosh x}, \quad \coth x = \frac{1}{\tanh x}.$$

Identities:

$$\cosh^2 x - \sinh^2 x = 1, \quad \tanh^2 x + \text{sech}^2 x = 1,$$

$$\coth^2 x - \text{csch}^2 x = 1, \quad \sinh(-x) = -\sinh x,$$

$$\cosh(-x) = \cosh x, \quad \tanh(-x) = -\tanh x,$$

$$\sinh(x+y) = \sinh x \cosh y + \cosh x \sinh y,$$

$$\cosh(x+y) = \cosh x \cosh y + \sinh x \sinh y,$$

$$\sinh 2x = 2 \sinh x \cosh x,$$

$$\cosh 2x = \cosh^2 x + \sinh^2 x,$$

$$\cosh x + \sinh x = e^x, \quad \cosh x - \sinh x = e^{-x},$$

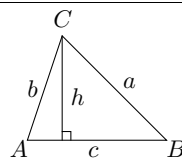
$$(\cosh x + \sinh x)^n = \cosh nx + \sinh nx, \quad n \in \mathbb{Z},$$

$$2 \sinh^2 \frac{x}{2} = \cosh x - 1, \quad 2 \cosh^2 \frac{x}{2} = \cosh x + 1.$$

θ	$\sin \theta$	$\cos \theta$	$\tan \theta$
0	0	1	0
$\frac{\pi}{6}$	$\frac{1}{2}$	$\frac{\sqrt{3}}{2}$	$\frac{\sqrt{3}}{3}$
$\frac{\pi}{4}$	$\frac{\sqrt{2}}{2}$	$\frac{\sqrt{2}}{2}$	1
$\frac{\pi}{3}$	$\frac{\sqrt{3}}{2}$	$\frac{1}{2}$	$\sqrt{3}$
$\frac{\pi}{2}$	1	0	∞

... in mathematics
you don't under-
stand things, you
just get used to
them.

– J. von Neumann



Law of cosines:

$$c^2 = a^2 + b^2 - 2ab \cos C.$$

Area:

$$\begin{aligned} A &= \frac{1}{2}hc, \\ &= \frac{1}{2}ab \sin C, \\ &= \frac{c^2 \sin A \sin B}{2 \sin C}. \end{aligned}$$

Heron's formula:

$$\begin{aligned} A &= \sqrt{s \cdot s_a \cdot s_b \cdot s_c}, \\ s &= \frac{1}{2}(a + b + c), \\ s_a &= s - a, \\ s_b &= s - b, \\ s_c &= s - c. \end{aligned}$$

More identities:

$$\sin \frac{x}{2} = \sqrt{\frac{1 - \cos x}{2}},$$

$$\cos \frac{x}{2} = \sqrt{\frac{1 + \cos x}{2}},$$

$$\tan \frac{x}{2} = \sqrt{\frac{1 - \cos x}{1 + \cos x}},$$

$$= \frac{1 - \cos x}{\sin x},$$

$$= \frac{\sin x}{1 + \cos x},$$

$$\cot \frac{x}{2} = \sqrt{\frac{1 + \cos x}{1 - \cos x}},$$

$$= \frac{1 + \cos x}{\sin x},$$

$$= \frac{\sin x}{1 - \cos x},$$

$$\sin x = \frac{e^{ix} - e^{-ix}}{2i},$$

$$\cos x = \frac{e^{ix} + e^{-ix}}{2},$$

$$\tan x = -i \frac{e^{ix} - e^{-ix}}{e^{ix} + e^{-ix}},$$

$$= -i \frac{e^{2ix} - 1}{e^{2ix} + 1},$$

$$\sin x = \frac{\sinh ix}{i},$$

$$\cos x = \cosh ix,$$

$$\tan x = \frac{\tanh ix}{i}.$$

The Chinese remainder theorem: There exists a number C such that:

$$C \equiv r_1 \pmod{m_1}$$

$$\vdots \quad \vdots \quad \vdots$$

$$C \equiv r_n \pmod{m_n}$$

if m_i and m_j are relatively prime for $i \neq j$.

Euler's function: $\phi(x)$ is the number of positive integers less than x relatively prime to x . If $\prod_{i=1}^n p_i^{e_i}$ is the prime factorization of x then

$$\phi(x) = \prod_{i=1}^n p_i^{e_i-1} (p_i - 1).$$

Euler's theorem: If a and b are relatively prime then

$$1 \equiv a^{\phi(b)} \pmod{b}.$$

Fermat's theorem:

$$1 \equiv a^{p-1} \pmod{p}.$$

The Euclidean algorithm: if $a > b$ are integers then

$$\gcd(a, b) = \gcd(a \bmod b, b).$$

If $\prod_{i=1}^n p_i^{e_i}$ is the prime factorization of x then

$$S(x) = \sum_{d|x} d = \prod_{i=1}^n \frac{p_i^{e_i+1} - 1}{p_i - 1}.$$

Perfect Numbers: x is an even perfect number iff $x = 2^{n-1}(2^n - 1)$ and $2^n - 1$ is prime.

Wilson's theorem: n is a prime iff

$$(n-1)! \equiv -1 \pmod{n}.$$

Möbius inversion:

$$\mu(i) = \begin{cases} 1 & \text{if } i = 1. \\ 0 & \text{if } i \text{ is not square-free.} \\ (-1)^r & \text{if } i \text{ is the product of } r \text{ distinct primes.} \end{cases}$$

If

$$G(a) = \sum_{d|a} F(d),$$

then

$$F(a) = \sum_{d|a} \mu(d) G\left(\frac{a}{d}\right).$$

Prime numbers:

$$p_n = n \ln n + n \ln \ln n - n + n \frac{\ln \ln n}{\ln n}$$

$$+ O\left(\frac{n}{\ln n}\right),$$

$$\pi(n) = \frac{n}{\ln n} + \frac{n}{(\ln n)^2} + \frac{2!n}{(\ln n)^3}$$

$$+ O\left(\frac{n}{(\ln n)^4}\right).$$

Definitions:

Loop An edge connecting a vertex to itself.

Directed Each edge has a direction.

Simple Graph with no loops or multi-edges.

Walk A sequence $v_0 e_1 v_1 \dots e_\ell v_\ell$.

Trail A walk with distinct edges.

Path A trail with distinct vertices.

Connected A graph where there exists a path between any two vertices.

Component A maximal connected subgraph.

Tree A connected acyclic graph.

Free tree A tree with no root.

DAG Directed acyclic graph.

Eulerian Graph with a trail visiting each edge exactly once.

Hamiltonian Graph with a cycle visiting each vertex exactly once.

Cut A set of edges whose removal increases the number of components.

Cut-set A minimal cut.

Cut edge A size 1 cut.

k-Connected A graph connected with the removal of any $k-1$ vertices.

k-Tough $\forall S \subseteq V, S \neq \emptyset$ we have $k \cdot c(G-S) \leq |S|$.

k-Regular A graph where all vertices have degree k .

k-Factor A k -regular spanning subgraph.

Matching A set of edges, no two of which are adjacent.

Clique A set of vertices, all of which are adjacent.

Ind. set A set of vertices, none of which are adjacent.

Vertex cover A set of vertices which cover all edges.

Planar graph A graph which can be embedded in the plane.

Plane graph An embedding of a planar graph.

$$\sum_{v \in V} \deg(v) = 2m.$$

If G is planar then $n - m + f = 2$, so

$$f \leq 2n - 4, \quad m \leq 3n - 6.$$

Any planar graph has a vertex with degree ≤ 5 .

Notation:

$E(G)$ Edge set

$V(G)$ Vertex set

$c(G)$ Number of components

$G[S]$ Induced subgraph

$\deg(v)$ Degree of v

$\Delta(G)$ Maximum degree

$\delta(G)$ Minimum degree

$\chi(G)$ Chromatic number

$\chi_E(G)$ Edge chromatic number

G^c Complement graph

K_n Complete graph

K_{n_1, n_2} Complete bipartite graph

$r(k, \ell)$ Ramsey number

Geometry

Projective coordinates: triples (x, y, z) , not all x, y and z zero.

$$(x, y, z) = (cx, cy, cz) \quad \forall c \neq 0.$$

Cartesian Projective

$$(x, y) \quad (x, y, 1)$$

$$y = mx + b \quad (m, -1, b)$$

$$x = c \quad (1, 0, -c)$$

Distance formula, L_p and L_∞ metric:

$$\sqrt{(x_1 - x_0)^2 + (y_1 - y_0)^2},$$

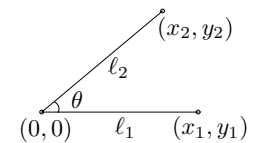
$$[|x_1 - x_0|^p + |y_1 - y_0|^p]^{1/p},$$

$$\lim_{p \rightarrow \infty} [|x_1 - x_0|^p + |y_1 - y_0|^p]^{1/p}.$$

Area of triangle $(x_0, y_0), (x_1, y_1)$ and (x_2, y_2) :

$$\frac{1}{2} \text{abs} \begin{vmatrix} x_1 - x_0 & y_1 - y_0 \\ x_2 - x_0 & y_2 - y_0 \end{vmatrix}.$$

Angle formed by three points:



$$\cos \theta = \frac{(x_1, y_1) \cdot (x_2, y_2)}{l_1 l_2}.$$

Line through two points (x_0, y_0) and (x_1, y_1) :

$$\begin{vmatrix} x & y & 1 \\ x_0 & y_0 & 1 \\ x_1 & y_1 & 1 \end{vmatrix} = 0.$$

Area of circle, volume of sphere:

$$A = \pi r^2, \quad V = \frac{4}{3} \pi r^3.$$

If I have seen farther than others, it is because I have stood on the shoulders of giants.

– Issac Newton

Wallis' identity:

$$\pi = 2 \cdot \frac{2 \cdot 2 \cdot 4 \cdot 4 \cdot 6 \cdot 6 \cdots}{1 \cdot 3 \cdot 3 \cdot 5 \cdot 5 \cdot 7 \cdots}$$

Brouncker's continued fraction expansion:

$$\frac{\pi}{4} = 1 + \frac{1^2}{2 + \frac{3^2}{2 + \frac{5^2}{2 + \frac{7^2}{2 + \cdots}}}}$$

Gregory's series:

$$\frac{\pi}{4} = 1 - \frac{1}{3} + \frac{1}{5} - \frac{1}{7} + \frac{1}{9} - \cdots$$

Newton's series:

$$\frac{\pi}{6} = \frac{1}{2} + \frac{1}{2 \cdot 3 \cdot 2^3} + \frac{1 \cdot 3}{2 \cdot 4 \cdot 5 \cdot 2^5} + \cdots$$

Sharp's series:

$$\frac{\pi}{6} = \frac{1}{\sqrt{3}} \left(1 - \frac{1}{3^1 \cdot 3} + \frac{1}{3^2 \cdot 5} - \frac{1}{3^3 \cdot 7} + \cdots \right)$$

Euler's series:

$$\frac{\pi^2}{6} = \frac{1}{1^2} + \frac{1}{2^2} + \frac{1}{3^2} + \frac{1}{4^2} + \frac{1}{5^2} + \cdots$$

$$\frac{\pi^2}{8} = \frac{1}{1^2} + \frac{1}{3^2} + \frac{1}{5^2} + \frac{1}{7^2} + \frac{1}{9^2} + \cdots$$

$$\frac{\pi^2}{12} = \frac{1}{1^2} - \frac{1}{2^2} + \frac{1}{3^2} - \frac{1}{4^2} + \frac{1}{5^2} - \cdots$$

Partial Fractions

Let $N(x)$ and $D(x)$ be polynomial functions of x . We can break down $N(x)/D(x)$ using partial fraction expansion. First, if the degree of N is greater than or equal to the degree of D , divide N by D , obtaining

$$\frac{N(x)}{D(x)} = Q(x) + \frac{N'(x)}{D(x)},$$

where the degree of N' is less than that of D . Second, factor $D(x)$. Use the following rules: For a non-repeated factor:

$$\frac{N(x)}{(x-a)D(x)} = \frac{A}{x-a} + \frac{N'(x)}{D(x)},$$

where

$$A = \left[\frac{N(x)}{D(x)} \right]_{x=a}.$$

For a repeated factor:

$$\frac{N(x)}{(x-a)^m D(x)} = \sum_{k=0}^{m-1} \frac{A_k}{(x-a)^{m-k}} + \frac{N'(x)}{D(x)},$$

where

$$A_k = \frac{1}{k!} \left[\frac{d^k}{dx^k} \left(\frac{N(x)}{D(x)} \right) \right]_{x=a}.$$

The reasonable man adapts himself to the world; the unreasonable persists in trying to adapt the world to himself. Therefore all progress depends on the unreasonable.
– George Bernard Shaw

Derivatives:

$$1. \frac{d(cu)}{dx} = c \frac{du}{dx}, \quad 2. \frac{d(u+v)}{dx} = \frac{du}{dx} + \frac{dv}{dx}, \quad 3. \frac{d(uv)}{dx} = u \frac{dv}{dx} + v \frac{du}{dx},$$

$$4. \frac{d(u^n)}{dx} = nu^{n-1} \frac{du}{dx}, \quad 5. \frac{d(u/v)}{dx} = \frac{v \left(\frac{du}{dx} \right) - u \left(\frac{dv}{dx} \right)}{v^2}, \quad 6. \frac{d(e^{cu})}{dx} = ce^{cu} \frac{du}{dx},$$

$$7. \frac{d(c^u)}{dx} = (\ln c) c^u \frac{du}{dx}, \quad 8. \frac{d(\ln u)}{dx} = \frac{1}{u} \frac{du}{dx},$$

$$9. \frac{d(\sin u)}{dx} = \cos u \frac{du}{dx}, \quad 10. \frac{d(\cos u)}{dx} = -\sin u \frac{du}{dx},$$

$$11. \frac{d(\tan u)}{dx} = \sec^2 u \frac{du}{dx}, \quad 12. \frac{d(\cot u)}{dx} = -\csc^2 u \frac{du}{dx},$$

$$13. \frac{d(\sec u)}{dx} = \tan u \sec u \frac{du}{dx}, \quad 14. \frac{d(\csc u)}{dx} = -\cot u \csc u \frac{du}{dx},$$

$$15. \frac{d(\arcsin u)}{dx} = \frac{1}{\sqrt{1-u^2}} \frac{du}{dx}, \quad 16. \frac{d(\arccos u)}{dx} = \frac{-1}{\sqrt{1-u^2}} \frac{du}{dx},$$

$$17. \frac{d(\arctan u)}{dx} = \frac{1}{1+u^2} \frac{du}{dx}, \quad 18. \frac{d(\operatorname{arccot} u)}{dx} = \frac{-1}{1+u^2} \frac{du}{dx},$$

$$19. \frac{d(\operatorname{arcsec} u)}{dx} = \frac{1}{u\sqrt{1-u^2}} \frac{du}{dx}, \quad 20. \frac{d(\operatorname{arccsc} u)}{dx} = \frac{-1}{u\sqrt{1-u^2}} \frac{du}{dx},$$

$$21. \frac{d(\sinh u)}{dx} = \cosh u \frac{du}{dx}, \quad 22. \frac{d(\cosh u)}{dx} = \sinh u \frac{du}{dx},$$

$$23. \frac{d(\tanh u)}{dx} = \operatorname{sech}^2 u \frac{du}{dx}, \quad 24. \frac{d(\coth u)}{dx} = -\operatorname{csch}^2 u \frac{du}{dx},$$

$$25. \frac{d(\operatorname{sech} u)}{dx} = -\operatorname{sech} u \tanh u \frac{du}{dx}, \quad 26. \frac{d(\operatorname{csch} u)}{dx} = -\operatorname{csch} u \coth u \frac{du}{dx},$$

$$27. \frac{d(\operatorname{arcsinh} u)}{dx} = \frac{1}{\sqrt{1+u^2}} \frac{du}{dx}, \quad 28. \frac{d(\operatorname{arccosh} u)}{dx} = \frac{1}{\sqrt{u^2-1}} \frac{du}{dx},$$

$$29. \frac{d(\operatorname{arctanh} u)}{dx} = \frac{1}{1-u^2} \frac{du}{dx}, \quad 30. \frac{d(\operatorname{arcoth} u)}{dx} = \frac{1}{u^2-1} \frac{du}{dx},$$

$$31. \frac{d(\operatorname{arcsech} u)}{dx} = \frac{-1}{u\sqrt{1-u^2}} \frac{du}{dx}, \quad 32. \frac{d(\operatorname{arccsch} u)}{dx} = \frac{-1}{|u|\sqrt{1+u^2}} \frac{du}{dx}.$$

Integrals:

$$1. \int cu \, dx = c \int u \, dx, \quad 2. \int (u+v) \, dx = \int u \, dx + \int v \, dx,$$

$$3. \int x^n \, dx = \frac{1}{n+1} x^{n+1}, \quad n \neq -1, \quad 4. \int \frac{1}{x} \, dx = \ln x, \quad 5. \int e^x \, dx = e^x,$$

$$6. \int \frac{dx}{1+x^2} = \arctan x, \quad 7. \int u \frac{dv}{dx} \, dx = uv - \int v \frac{du}{dx} \, dx,$$

$$8. \int \sin x \, dx = -\cos x, \quad 9. \int \cos x \, dx = \sin x,$$

$$10. \int \tan x \, dx = -\ln |\cos x|, \quad 11. \int \cot x \, dx = \ln |\cos x|,$$

$$12. \int \sec x \, dx = \ln |\sec x + \tan x|, \quad 13. \int \csc x \, dx = \ln |\csc x + \cot x|,$$

$$14. \int \arcsin \frac{x}{a} \, dx = \arcsin \frac{x}{a} + \sqrt{a^2 - x^2}, \quad a > 0,$$

15. $\int \arccos \frac{x}{a} dx = \arccos \frac{x}{a} - \sqrt{a^2 - x^2}, \quad a > 0,$
16. $\int \arctan \frac{x}{a} dx = x \arctan \frac{x}{a} - \frac{a}{2} \ln(a^2 + x^2), \quad a > 0,$
17. $\int \sin^2(ax) dx = \frac{1}{2a}(ax - \sin(ax) \cos(ax)),$
18. $\int \cos^2(ax) dx = \frac{1}{2a}(ax + \sin(ax) \cos(ax)),$
19. $\int \sec^2 x dx = \tan x,$
20. $\int \csc^2 x dx = -\cot x,$
21. $\int \sin^n x dx = -\frac{\sin^{n-1} x \cos x}{n} + \frac{n-1}{n} \int \sin^{n-2} x dx,$
22. $\int \cos^n x dx = \frac{\cos^{n-1} x \sin x}{n} + \frac{n-1}{n} \int \cos^{n-2} x dx,$
23. $\int \tan^n x dx = \frac{\tan^{n-1} x}{n-1} - \int \tan^{n-2} x dx, \quad n \neq 1,$
24. $\int \cot^n x dx = -\frac{\cot^{n-1} x}{n-1} - \int \cot^{n-2} x dx, \quad n \neq 1,$
25. $\int \sec^n x dx = \frac{\tan x \sec^{n-1} x}{n-1} + \frac{n-2}{n-1} \int \sec^{n-2} x dx, \quad n \neq 1,$
26. $\int \csc^n x dx = -\frac{\cot x \csc^{n-1} x}{n-1} + \frac{n-2}{n-1} \int \csc^{n-2} x dx, \quad n \neq 1,$
27. $\int \sinh x dx = \cosh x,$
28. $\int \cosh x dx = \sinh x,$
29. $\int \tanh x dx = \ln |\cosh x|,$
30. $\int \coth x dx = \ln |\sinh x|,$
31. $\int \operatorname{sech} x dx = \arctan \sinh x,$
32. $\int \operatorname{csch} x dx = \ln \left| \tanh \frac{x}{2} \right|,$
33. $\int \sinh^2 x dx = \frac{1}{4} \sinh(2x) - \frac{1}{2} x,$
34. $\int \cosh^2 x dx = \frac{1}{4} \sinh(2x) + \frac{1}{2} x,$
35. $\int \operatorname{sech}^2 x dx = \tanh x,$
36. $\int \operatorname{arcsinh} \frac{x}{a} dx = x \operatorname{arcsinh} \frac{x}{a} - \sqrt{x^2 + a^2}, \quad a > 0,$
37. $\int \operatorname{arctanh} \frac{x}{a} dx = x \operatorname{arctanh} \frac{x}{a} + \frac{a}{2} \ln |a^2 - x^2|,$
38. $\int \operatorname{arccosh} \frac{x}{a} dx = \begin{cases} x \operatorname{arccosh} \frac{x}{a} - \sqrt{x^2 + a^2}, & \text{if } \operatorname{arccosh} \frac{x}{a} > 0 \text{ and } a > 0, \\ x \operatorname{arccosh} \frac{x}{a} + \sqrt{x^2 + a^2}, & \text{if } \operatorname{arccosh} \frac{x}{a} < 0 \text{ and } a > 0, \end{cases}$
39. $\int \frac{dx}{\sqrt{a^2 + x^2}} = \ln \left(x + \sqrt{a^2 + x^2} \right), \quad a > 0,$
40. $\int \frac{dx}{a^2 + x^2} = \frac{1}{a} \arctan \frac{x}{a}, \quad a > 0,$
41. $\int \sqrt{a^2 - x^2} dx = \frac{x}{2} \sqrt{a^2 - x^2} + \frac{a^2}{2} \arcsin \frac{x}{a}, \quad a > 0,$
42. $\int (a^2 - x^2)^{3/2} dx = \frac{x}{8} (5a^2 - 2x^2) \sqrt{a^2 - x^2} + \frac{3a^4}{8} \arcsin \frac{x}{a}, \quad a > 0,$
43. $\int \frac{dx}{\sqrt{a^2 - x^2}} = \arcsin \frac{x}{a}, \quad a > 0,$
44. $\int \frac{dx}{a^2 - x^2} = \frac{1}{2a} \ln \left| \frac{a+x}{a-x} \right|,$
45. $\int \frac{dx}{(a^2 - x^2)^{3/2}} = \frac{x}{a^2 \sqrt{a^2 - x^2}},$
46. $\int \sqrt{a^2 \pm x^2} dx = \frac{x}{2} \sqrt{a^2 \pm x^2} \pm \frac{a^2}{2} \ln \left| x + \sqrt{a^2 \pm x^2} \right|,$
47. $\int \frac{dx}{\sqrt{x^2 - a^2}} = \ln \left| x + \sqrt{x^2 - a^2} \right|, \quad a > 0,$
48. $\int \frac{dx}{ax^2 + bx} = \frac{1}{a} \ln \left| \frac{x}{a+bx} \right|,$
49. $\int x \sqrt{a+bx} dx = \frac{2(3bx-2a)(a+bx)^{3/2}}{15b^2},$
50. $\int \frac{\sqrt{a+bx}}{x} dx = 2\sqrt{a+bx} + a \int \frac{1}{x\sqrt{a+bx}} dx,$
51. $\int \frac{x}{\sqrt{a+bx}} dx = \frac{1}{\sqrt{2}} \ln \left| \frac{\sqrt{a+bx} - \sqrt{a}}{\sqrt{a+bx} + \sqrt{a}} \right|, \quad a > 0,$
52. $\int \frac{\sqrt{a^2 - x^2}}{x} dx = \sqrt{a^2 - x^2} - a \ln \left| \frac{a + \sqrt{a^2 - x^2}}{x} \right|,$
53. $\int x \sqrt{a^2 - x^2} dx = -\frac{1}{3} (a^2 - x^2)^{3/2},$
54. $\int x^2 \sqrt{a^2 - x^2} dx = \frac{x}{8} (2x^2 - a^2) \sqrt{a^2 - x^2} + \frac{a^4}{8} \arcsin \frac{x}{a}, \quad a > 0,$
55. $\int \frac{dx}{\sqrt{a^2 - x^2}} = -\frac{1}{a} \ln \left| \frac{a + \sqrt{a^2 - x^2}}{x} \right|,$
56. $\int \frac{x dx}{\sqrt{a^2 - x^2}} = -\sqrt{a^2 - x^2},$
57. $\int \frac{x^2 dx}{\sqrt{a^2 - x^2}} = -\frac{x}{2} \sqrt{a^2 - x^2} + \frac{a^2}{2} \arcsin \frac{x}{a}, \quad a > 0,$
58. $\int \frac{\sqrt{a^2 + x^2}}{x} dx = \sqrt{a^2 + x^2} - a \ln \left| \frac{a + \sqrt{a^2 + x^2}}{x} \right|,$
59. $\int \frac{\sqrt{x^2 - a^2}}{x} dx = \sqrt{x^2 - a^2} - a \arccos \frac{a}{|x|}, \quad a > 0,$
60. $\int x \sqrt{x^2 \pm a^2} dx = \frac{1}{3} (x^2 \pm a^2)^{3/2},$
61. $\int \frac{dx}{x \sqrt{x^2 + a^2}} = \frac{1}{a} \ln \left| \frac{x}{a + \sqrt{a^2 + x^2}} \right|,$

$$\begin{aligned}
62. \int \frac{dx}{x\sqrt{x^2 - a^2}} &= \frac{1}{a} \arccos \frac{a}{|x|}, \quad a > 0, & 63. \int \frac{dx}{x^2\sqrt{x^2 \pm a^2}} &= \mp \frac{\sqrt{x^2 \pm a^2}}{a^2 x}, \\
64. \int \frac{x dx}{\sqrt{x^2 \pm a^2}} &= \sqrt{x^2 \pm a^2}, & 65. \int \frac{\sqrt{x^2 \pm a^2}}{x^4} dx &= \mp \frac{(x^2 + a^2)^{3/2}}{3a^2 x^3}, \\
66. \int \frac{dx}{ax^2 + bx + c} &= \begin{cases} \frac{1}{\sqrt{b^2 - 4ac}} \ln \left| \frac{2ax + b - \sqrt{b^2 - 4ac}}{2ax + b + \sqrt{b^2 - 4ac}} \right|, & \text{if } b^2 > 4ac, \\ \frac{2}{\sqrt{4ac - b^2}} \arctan \frac{2ax + b}{\sqrt{4ac - b^2}}, & \text{if } b^2 < 4ac, \end{cases} \\
67. \int \frac{dx}{\sqrt{ax^2 + bx + c}} &= \begin{cases} \frac{1}{\sqrt{a}} \ln \left| 2ax + b + 2\sqrt{a}\sqrt{ax^2 + bx + c} \right|, & \text{if } a > 0, \\ \frac{1}{\sqrt{-a}} \arcsin \frac{-2ax - b}{\sqrt{b^2 - 4ac}}, & \text{if } a < 0, \end{cases} \\
68. \int \sqrt{ax^2 + bx + c} dx &= \frac{2ax + b}{4a} \sqrt{ax^2 + bx + c} + \frac{4ac - b^2}{8a} \int \frac{dx}{\sqrt{ax^2 + bx + c}}, \\
69. \int \frac{x dx}{\sqrt{ax^2 + bx + c}} &= \frac{\sqrt{ax^2 + bx + c}}{a} - \frac{b}{2a} \int \frac{dx}{\sqrt{ax^2 + bx + c}}, \\
70. \int \frac{dx}{x\sqrt{ax^2 + bx + c}} &= \begin{cases} \frac{-1}{\sqrt{c}} \ln \left| \frac{2\sqrt{c}\sqrt{ax^2 + bx + c} + bx + 2c}{x} \right|, & \text{if } c > 0, \\ \frac{1}{\sqrt{-c}} \arcsin \frac{bx + 2c}{|x|\sqrt{b^2 - 4ac}}, & \text{if } c < 0, \end{cases} \\
71. \int x^3 \sqrt{x^2 + a^2} dx &= \left(\frac{1}{3}x^2 - \frac{2}{15}a^2\right)(x^2 + a^2)^{3/2}, \\
72. \int x^n \sin(ax) dx &= -\frac{1}{a}x^n \cos(ax) + \frac{n}{a} \int x^{n-1} \cos(ax) dx, \\
73. \int x^n \cos(ax) dx &= \frac{1}{a}x^n \sin(ax) - \frac{n}{a} \int x^{n-1} \sin(ax) dx, \\
74. \int x^n e^{ax} dx &= \frac{x^n e^{ax}}{a} - \frac{n}{a} \int x^{n-1} e^{ax} dx, \\
75. \int x^n \ln(ax) dx &= x^{n+1} \left(\frac{\ln(ax)}{n+1} - \frac{1}{(n+1)^2} \right), \\
76. \int x^n (\ln ax)^m dx &= \frac{x^{n+1}}{n+1} (\ln ax)^m - \frac{m}{n+1} \int x^n (\ln ax)^{m-1} dx.
\end{aligned}$$

$$\begin{aligned}
x^1 &= x^1 & x^{\bar{1}} &= x^{\bar{1}} \\
x^2 &= x^2 + x^1 & x^{\bar{2}} &= x^{\bar{2}} - x^{\bar{1}} \\
x^3 &= x^3 + 3x^2 + x^1 & x^{\bar{3}} &= x^{\bar{3}} - 3x^{\bar{2}} + x^{\bar{1}} \\
x^4 &= x^4 + 6x^3 + 7x^2 + x^1 & x^{\bar{4}} &= x^{\bar{4}} - 6x^{\bar{3}} + 7x^{\bar{2}} - x^{\bar{1}} \\
x^5 &= x^5 + 15x^4 + 25x^3 + 10x^2 + x^1 & x^{\bar{5}} &= x^{\bar{5}} - 15x^{\bar{4}} + 25x^{\bar{3}} - 10x^{\bar{2}} + x^{\bar{1}} \\
x^{\bar{1}} &= x^1 & x^1 &= x^1 \\
x^{\bar{2}} &= x^2 + x^1 & x^2 &= x^2 - x^1 \\
x^{\bar{3}} &= x^3 + 3x^2 + 2x^1 & x^3 &= x^3 - 3x^2 + 2x^1 \\
x^{\bar{4}} &= x^4 + 6x^3 + 11x^2 + 6x^1 & x^4 &= x^4 - 6x^3 + 11x^2 - 6x^1 \\
x^{\bar{5}} &= x^5 + 10x^4 + 35x^3 + 50x^2 + 24x^1 & x^{\bar{5}} &= x^5 - 10x^4 + 35x^3 - 50x^2 + 24x^1
\end{aligned}$$

Difference, shift operators:

$$\Delta f(x) = f(x+1) - f(x),$$

$$\mathbb{E} f(x) = f(x+1).$$

Fundamental Theorem:

$$f(x) = \Delta F(x) \Leftrightarrow \sum f(x) \delta x = F(x) + C.$$

$$\sum_a^b f(x) \delta x = \sum_{i=a}^{b-1} f(i).$$

Differences:

$$\Delta(cu) = c\Delta u, \quad \Delta(u+v) = \Delta u + \Delta v,$$

$$\Delta(uv) = u\Delta v + \mathbb{E} v \Delta u,$$

$$\Delta(x^n) = nx^{n-1},$$

$$\Delta(H_x) = x^{-1}, \quad \Delta(2^x) = 2^x,$$

$$\Delta(c^x) = (c-1)c^x, \quad \Delta\binom{x}{m} = \binom{x}{m-1}.$$

Sums:

$$\sum cu \delta x = c \sum u \delta x,$$

$$\sum (u+v) \delta x = \sum u \delta x + \sum v \delta x,$$

$$\sum u \Delta v \delta x = uv - \sum \mathbb{E} v \Delta u \delta x,$$

$$\sum x^n \delta x = \frac{x^{n+1}}{n+1}, \quad \sum x^{-1} \delta x = H_x,$$

$$\sum c^x \delta x = \frac{c^x}{c-1}, \quad \sum \binom{x}{m} \delta x = \binom{x}{m+1}.$$

Falling Factorial Powers:

$$x^{\underline{n}} = x(x-1) \cdots (x-n+1), \quad n > 0,$$

$$x^{\underline{0}} = 1,$$

$$x^{\underline{n}} = \frac{1}{(x+1) \cdots (x+|n|)}, \quad n < 0,$$

$$x^{\underline{n+m}} = x^{\underline{m}}(x-m)^{\underline{n}}.$$

Rising Factorial Powers:

$$x^{\overline{n}} = x(x+1) \cdots (x+n-1), \quad n > 0,$$

$$x^{\overline{0}} = 1,$$

$$x^{\overline{n}} = \frac{1}{(x-1) \cdots (x-|n|)}, \quad n < 0,$$

$$x^{\overline{n+m}} = x^{\overline{m}}(x+m)^{\overline{n}}.$$

Conversion:

$$x^{\underline{n}} = (-1)^n (-x)^{\overline{n}} = (x-n+1)^{\overline{n}}$$

$$= 1/(x+1)^{-n},$$

$$x^{\overline{n}} = (-1)^n (-x)^{\underline{n}} = (x+n-1)^{\underline{n}}$$

$$= 1/(x-1)^{-n},$$

$$x^n = \sum_{k=1}^n \left\{ \begin{matrix} n \\ k \end{matrix} \right\} x^{\underline{k}} = \sum_{k=1}^n \left\{ \begin{matrix} n \\ k \end{matrix} \right\} (-1)^{n-k} x^{\overline{k}},$$

$$x^{\underline{n}} = \sum_{k=1}^n \left[\begin{matrix} n \\ k \end{matrix} \right] (-1)^{n-k} x^k,$$

$$x^{\overline{n}} = \sum_{k=1}^n \left[\begin{matrix} n \\ k \end{matrix} \right] x^k.$$

Taylor's series:

$$f(x) = f(a) + (x-a)f'(a) + \frac{(x-a)^2}{2}f''(a) + \dots = \sum_{i=0}^{\infty} \frac{(x-a)^i}{i!} f^{(i)}(a).$$

Expansions:

$$\begin{aligned} \frac{1}{1-x} &= 1 + x + x^2 + x^3 + x^4 + \dots = \sum_{i=0}^{\infty} x^i, \\ \frac{1}{1-cx} &= 1 + cx + c^2x^2 + c^3x^3 + \dots = \sum_{i=0}^{\infty} c^i x^i, \\ \frac{1}{1-x^n} &= 1 + x^n + x^{2n} + x^{3n} + \dots = \sum_{i=0}^{\infty} x^{ni}, \\ \frac{x}{(1-x)^2} &= x + 2x^2 + 3x^3 + 4x^4 + \dots = \sum_{i=0}^{\infty} ix^i, \\ x^k \frac{d^n}{dx^n} \left(\frac{1}{1-x} \right) &= x + 2^n x^2 + 3^n x^3 + 4^n x^4 + \dots = \sum_{i=0}^{\infty} i^n x^i, \\ e^x &= 1 + x + \frac{1}{2}x^2 + \frac{1}{6}x^3 + \dots = \sum_{i=0}^{\infty} \frac{x^i}{i!}, \\ \ln(1+x) &= x - \frac{1}{2}x^2 + \frac{1}{3}x^3 - \frac{1}{4}x^4 + \dots = \sum_{i=1}^{\infty} (-1)^{i+1} \frac{x^i}{i}, \\ \ln \frac{1}{1-x} &= x + \frac{1}{2}x^2 + \frac{1}{3}x^3 + \frac{1}{4}x^4 + \dots = \sum_{i=1}^{\infty} \frac{x^i}{i}, \\ \sin x &= x - \frac{1}{3!}x^3 + \frac{1}{5!}x^5 - \frac{1}{7!}x^7 + \dots = \sum_{i=0}^{\infty} (-1)^i \frac{x^{2i+1}}{(2i+1)!}, \\ \cos x &= 1 - \frac{1}{2!}x^2 + \frac{1}{4!}x^4 - \frac{1}{6!}x^6 + \dots = \sum_{i=0}^{\infty} (-1)^i \frac{x^{2i}}{(2i)!}, \\ \tan^{-1} x &= x - \frac{1}{3}x^3 + \frac{1}{5}x^5 - \frac{1}{7}x^7 + \dots = \sum_{i=0}^{\infty} (-1)^i \frac{x^{2i+1}}{(2i+1)}, \\ (1+x)^n &= 1 + nx + \frac{n(n-1)}{2}x^2 + \dots = \sum_{i=0}^{\infty} \binom{n}{i} x^i, \\ \frac{1}{(1-x)^{n+1}} &= 1 + (n+1)x + \binom{n+2}{2}x^2 + \dots = \sum_{i=0}^{\infty} \binom{i+n}{i} x^i, \\ \frac{x}{e^x - 1} &= 1 - \frac{1}{2}x + \frac{1}{12}x^2 - \frac{1}{720}x^4 + \dots = \sum_{i=0}^{\infty} \frac{B_i x^i}{i!}, \\ \frac{1}{2x}(1 - \sqrt{1-4x}) &= 1 + x + 2x^2 + 5x^3 + \dots = \sum_{i=0}^{\infty} \frac{1}{i+1} \binom{2i}{i} x^i, \\ \frac{1}{\sqrt{1-4x}} &= 1 + x + 2x^2 + 6x^3 + \dots = \sum_{i=0}^{\infty} \binom{2i}{i} x^i, \\ \frac{1}{\sqrt{1-4x}} \left(\frac{1 - \sqrt{1-4x}}{2x} \right)^n &= 1 + (2+n)x + \binom{4+n}{2}x^2 + \dots = \sum_{i=0}^{\infty} \binom{2i+n}{i} x^i, \\ \frac{1}{1-x} \ln \frac{1}{1-x} &= x + \frac{3}{2}x^2 + \frac{11}{6}x^3 + \frac{25}{12}x^4 + \dots = \sum_{i=1}^{\infty} H_i x^i, \\ \frac{1}{2} \left(\ln \frac{1}{1-x} \right)^2 &= \frac{1}{2}x^2 + \frac{3}{4}x^3 + \frac{11}{24}x^4 + \dots = \sum_{i=2}^{\infty} \frac{H_{i-1} x^i}{i}, \\ \frac{x}{1-x-x^2} &= x + x^2 + 2x^3 + 3x^4 + \dots = \sum_{i=0}^{\infty} F_i x^i, \\ \frac{F_n x}{1 - (F_{n-1} + F_{n+1})x - (-1)^n x^2} &= F_n x + F_{2n} x^2 + F_{3n} x^3 + \dots = \sum_{i=0}^{\infty} F_{ni} x^i. \end{aligned}$$

Ordinary power series:

$$A(x) = \sum_{i=0}^{\infty} a_i x^i.$$

Exponential power series:

$$A(x) = \sum_{i=0}^{\infty} a_i \frac{x^i}{i!}.$$

Dirichlet power series:

$$A(x) = \sum_{i=1}^{\infty} \frac{a_i}{i^x}.$$

Binomial theorem:

$$(x+y)^n = \sum_{k=0}^n \binom{n}{k} x^{n-k} y^k.$$

Difference of like powers:

$$x^n - y^n = (x-y) \sum_{k=0}^{n-1} x^{n-1-k} y^k.$$

For ordinary power series:

$$\alpha A(x) + \beta B(x) = \sum_{i=0}^{\infty} (\alpha a_i + \beta b_i) x^i,$$

$$x^k A(x) = \sum_{i=k}^{\infty} a_{i-k} x^i,$$

$$\frac{A(x) - \sum_{i=0}^{k-1} a_i x^i}{x^k} = \sum_{i=0}^{\infty} a_{i+k} x^i,$$

$$A(cx) = \sum_{i=0}^{\infty} c^i a_i x^i,$$

$$A'(x) = \sum_{i=0}^{\infty} (i+1) a_{i+1} x^i,$$

$$xA'(x) = \sum_{i=1}^{\infty} i a_i x^i,$$

$$\int A(x) dx = \sum_{i=1}^{\infty} \frac{a_{i-1}}{i} x^i,$$

$$\frac{A(x) + A(-x)}{2} = \sum_{i=0}^{\infty} a_{2i} x^{2i},$$

$$\frac{A(x) - A(-x)}{2} = \sum_{i=0}^{\infty} a_{2i+1} x^{2i+1}.$$

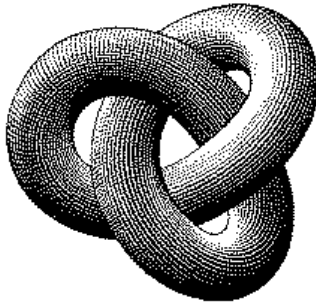
Summation: If $b_i = \sum_{j=0}^i a_j$ then

$$B(x) = \frac{1}{1-x} A(x).$$

Convolution:

$$A(x)B(x) = \sum_{i=0}^{\infty} \left(\sum_{j=0}^i a_j b_{i-j} \right) x^i.$$

God made the natural numbers;
all the rest is the work of man.
– Leopold Kronecker

Expansions:																																																																																																						
$\frac{1}{(1-x)^{n+1}} \ln \frac{1}{1-x}$ $x^{\overline{n}}$ $\left(\ln \frac{1}{1-x}\right)^n$ $\tan x$ $\frac{1}{\zeta(x)}$ $\zeta(x)$ $\zeta^2(x)$ $\zeta(x)\zeta(x-1)$ $\zeta(2n)$ $\frac{x}{\sin x}$ $\left(\frac{1-\sqrt{1-4x}}{2x}\right)^n$ $e^x \sin x$ $\sqrt{\frac{1-\sqrt{1-x}}{x}}$ $\left(\frac{\arcsin x}{x}\right)^2$	$= \sum_{i=0}^{\infty} (H_{n+i} - H_n) \binom{n+i}{i} x^i,$ $= \sum_{i=0}^{\infty} \left[\begin{matrix} n \\ i \end{matrix} \right] x^i,$ $= \sum_{i=0}^{\infty} \left[\begin{matrix} i \\ n \end{matrix} \right] \frac{n! x^i}{i!},$ $= \sum_{i=1}^{\infty} (-1)^{i-1} \frac{2^{2i} (2^{2i} - 1) B_{2i} x^{2i-1}}{(2i)!},$ $= \sum_{i=1}^{\infty} \frac{\mu(i)}{i^x},$ $= \prod_p \frac{1}{1 - p^{-x}},$ $= \sum_{i=1}^{\infty} \frac{d(i)}{x^i} \quad \text{where } d(n) = \sum_{d n} 1,$ $= \sum_{i=1}^{\infty} \frac{S(i)}{x^i} \quad \text{where } S(n) = \sum_{d n} d,$ $= \frac{2^{2n-1} B_{2n} }{(2n)!} \pi^{2n}, \quad n \in \mathbb{N},$ $= \sum_{i=0}^{\infty} (-1)^{i-1} \frac{(4^i - 2) B_{2i} x^{2i}}{(2i)!},$ $= \sum_{i=0}^{\infty} \frac{n(2i+n-1)!}{i!(n+i)!} x^i,$ $= \sum_{i=1}^{\infty} \frac{2^{i/2} \sin \frac{i\pi}{4}}{i!} x^i,$ $= \sum_{i=0}^{\infty} \frac{(4i)!}{16^i \sqrt{2} (2i)! (2i+1)!} x^i,$ $= \sum_{i=0}^{\infty} \frac{4^i i!^2}{(i+1)(2i+1)!} x^{2i}.$																																																																																																					
		<div>Stieltjes Integration</div> <div>If G is continuous in the interval $[a, b]$ and F is nondecreasing then $\int_a^b G(x) dF(x)$ exists. If $a \leq b \leq c$ then $\int_a^c G(x) dF(x) = \int_a^b G(x) dF(x) + \int_b^c G(x) dF(x).$ If the integrals involved exist $\int_a^b (G(x) + H(x)) dF(x) = \int_a^b G(x) dF(x) + \int_a^b H(x) dF(x),$ $\int_a^b G(x) d(F(x) + H(x)) = \int_a^b G(x) dF(x) + \int_a^b G(x) dH(x),$ $\int_a^b c \cdot G(x) dF(x) = \int_a^b G(x) d(c \cdot F(x)) = c \int_a^b G(x) dF(x),$ $\int_a^b G(x) dF(x) = G(b)F(b) - G(a)F(a) - \int_a^b F(x) dG(x).$ If the integrals involved exist, and F possesses a derivative F' at every point in $[a, b]$ then $\int_a^b G(x) dF(x) = \int_a^b G(x) F'(x) dx.$</div>																																																																																																				
<div>Cramer's Rule</div> <div>If we have equations: $a_{1,1}x_1 + a_{1,2}x_2 + \cdots + a_{1,n}x_n = b_1$$a_{2,1}x_1 + a_{2,2}x_2 + \cdots + a_{2,n}x_n = b_2$$\vdots \quad \quad \quad \vdots$$a_{n,1}x_1 + a_{n,2}x_2 + \cdots + a_{n,n}x_n = b_n$ Let $A = (a_{i,j})$ and B be the column matrix (b_i). Then there is a unique solution iff $\det A \neq 0$. Let A_i be A with column i replaced by B. Then $x_i = \frac{\det A_i}{\det A}.$</div>	<table><tr><td>00</td><td>47</td><td>18</td><td>76</td><td>29</td><td>93</td><td>85</td><td>34</td><td>61</td><td>52</td></tr><tr><td>86</td><td>11</td><td>57</td><td>28</td><td>70</td><td>39</td><td>94</td><td>45</td><td>02</td><td>63</td></tr><tr><td>95</td><td>80</td><td>22</td><td>67</td><td>38</td><td>71</td><td>49</td><td>56</td><td>13</td><td>04</td></tr><tr><td>59</td><td>96</td><td>81</td><td>33</td><td>07</td><td>48</td><td>72</td><td>60</td><td>24</td><td>15</td></tr><tr><td>73</td><td>69</td><td>90</td><td>82</td><td>44</td><td>17</td><td>58</td><td>01</td><td>35</td><td>26</td></tr><tr><td>68</td><td>74</td><td>09</td><td>91</td><td>83</td><td>55</td><td>27</td><td>12</td><td>46</td><td>30</td></tr><tr><td>37</td><td>08</td><td>75</td><td>19</td><td>92</td><td>84</td><td>66</td><td>23</td><td>50</td><td>41</td></tr><tr><td>14</td><td>25</td><td>36</td><td>40</td><td>51</td><td>62</td><td>03</td><td>77</td><td>88</td><td>99</td></tr><tr><td>21</td><td>32</td><td>43</td><td>54</td><td>65</td><td>06</td><td>10</td><td>89</td><td>97</td><td>78</td></tr><tr><td>42</td><td>53</td><td>64</td><td>05</td><td>16</td><td>20</td><td>31</td><td>98</td><td>79</td><td>87</td></tr></table>	00	47	18	76	29	93	85	34	61	52	86	11	57	28	70	39	94	45	02	63	95	80	22	67	38	71	49	56	13	04	59	96	81	33	07	48	72	60	24	15	73	69	90	82	44	17	58	01	35	26	68	74	09	91	83	55	27	12	46	30	37	08	75	19	92	84	66	23	50	41	14	25	36	40	51	62	03	77	88	99	21	32	43	54	65	06	10	89	97	78	42	53	64	05	16	20	31	98	79	87	<div>Fibonacci Numbers</div> <div>1, 1, 2, 3, 5, 8, 13, 21, 34, 55, 89, ...</div> <div>Definitions: $F_i = F_{i-1} + F_{i-2}, \quad F_0 = F_1 = 1,$$F_{-i} = (-1)^{i-1} F_i,$$F_i = \frac{1}{\sqrt{5}} \left(\phi^i - \hat{\phi}^i \right),$ Cassini's identity: for $i > 0$: $F_{i+1}F_{i-1} - F_i^2 = (-1)^i.$ Additive rule: $F_{n+k} = F_k F_{n+1} + F_{k-1} F_n,$$F_{2n} = F_n F_{n+1} + F_{n-1} F_n.$ Calculation by matrices: $\begin{pmatrix} F_{n-2} & F_{n-1} \\ F_{n-1} & F_n \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix}^n.$</div>
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Improvement makes strait roads, but the crooked roads without Improvement, are roads of Genius. – William Blake (The Marriage of Heaven and Hell)		<div>The Fibonacci number system:</div> <div>Every integer n has a unique representation $n = F_{k_1} + F_{k_2} + \cdots + F_{k_m},$ where $k_i \geq k_{i+1} + 2$ for all i, $1 \leq i < m$ and $k_m \geq 2$.</div>																																																																																																				

