

M.E.Sc. Software Engineer with a Collaborative Specialization in Artificial Intelligence. Passionate about leveraging data-driven technology to build machines and applications designed for people, with hands-on experience in industry research and development.

WORK EXPERIENCE:

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| R&D Aerospace Software Engineer | ITPS Canada | London, Ontario | Feb 2024 – Present |
| <ul style="list-style-type: none">Built a helmet mounted display project from scratch, including an outside-in optical tracking pipeline, and co-designing in-house display.Designed all software for head tracking and sensor-fusion algorithms, achieving ~2° spatial accuracy in cockpit environments.Implemented a Kalman filter to correct IMU drift and maintain stable, long-duration tracking under high-motion and vibration conditions.Architected and implemented the distributed system enabling fully wireless operation suitable for aircraft with ejection seats.Engineered/optimized UDP networking layer, to ensure high-frequency, low-jitter pose transmission. Achieving ~3 ms end-to-end latency.Designed and executed calibration workflows to align helmet, optical, and aircraft coordinate frames for consistent head-pose reconstruction.Collaborated directly with pilots, test engineers, program stakeholders, and leadership to translate operational needs into clear technical requirements and deliverables. | | | |
| R&D Engineering Intern | National Research Council Canada | London, Ontario | Sept 2023 – Dec 2023 |
| <ul style="list-style-type: none">Researched and designed a pipeline to transform real-world sensor data (LiDAR, camera, GPS) collected from a vehicle to simulated environments for autonomous vehicle development and testing. | | | |
| Software Engineer/DevOps Intern | IBM | Markham, Ontario | May 2021 – Sept 2022 |
| <ul style="list-style-type: none">Developed automated testing frameworks for IBM's Order Management System, reducing testing time, enhancing efficiency and ensuring system reliability; Setup a Dockerized virtual machine integrated with a web application, to execute and monitor automated test cases; Mentored/onboarded interns; Developed frontend components, to improve the user's interaction and experience. | | | |

EDUCATION:

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| M.E.Sc Software Engineering with Collaborative Specialization in Artificial Intelligence | Western University | 2023 – 2024 |
| <ul style="list-style-type: none">Submitted research findings to three journals for publishing, completing program four months early with a 4.0 GPA.Worked towards human-centered autonomous vehicles by researching conditionally autonomous takeover requests.Employed signal processing, data fusion, time series analysis, and deep learning to model and understand driver's cognitive behaviour through their physiological signals (ECG, EDA, RSP). | | |
| B.E.Sc Software Engineering with Co-op | Western University | 2018 – 2023 |
| <ul style="list-style-type: none">Achieved Dean's Honor list and completed a 16 month internship @ IBM between my 3rd and 4th year of study. | | |

PROJECTS and LEADERSHIP:

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| Peer Reviewed Studies |
| <ul style="list-style-type: none">Published: “<i>Navigating the Handover: Reviewing Takeover Requests in Level 3 Autonomous Vehicles</i>” (IEEE Open Journal of Vehicular Technology): A comprehensive review of Takeover Requests (TORs) in autonomous vehicles, emphasizing safe human-centered transitions from automation to manual control.Published: “<i>At the Heart of Intersections: Analyzing Their Influence on Driver Heart Behaviour</i>” (Springer Data Science for Transportation): Investigated intersections' impact on driver heart rates to inform safer urban traffic designs and autonomous vehicle technologies.Under Review: “<i>Modelling Takeover Requests in Conditional Autonomy Using Machine Learning and Driver Physiological Signals</i>” (IEEE Transactions Intelligent Transportation Systems): Developed adaptive machine learning models using physiological data to enhance driver takeover quality during autonomous transitions. |
| CARLA Reinforcement Learning Agent (Masters Project) |
| <ul style="list-style-type: none">Designed and implemented a reinforcement learning agent for autonomous vehicle navigation in the CARLA simulation environment, leveraging Deep Q-Learning and PPO algorithms.Fine-tuned reward functions to balance efficiency and exploitation, improving learning rates and decision-making accuracy. |
| FoodSnap (Capstone Project) |
| <ul style="list-style-type: none">Engineered a machine learning application to analyze the nutritional content of meals from single images, integrating image segmentation, depth estimation networks, and the USDA API.Achieved accurate identification of food types and volume estimation, enabling precise calorie and macronutrient calculations.Demonstrated the project's scalability and potential impact in nutrition tracking through real-world testing scenarios. |
| Western AI Club (Project Manager) |
| <ul style="list-style-type: none">Led a team of five developers to design, train, and deploy an iOS image classification app for waste categorization, promoting sustainable disposal practices.Implemented transfer learning techniques to optimize the model, achieving 98% accuracy in classifying waste types.Oversaw project milestones, ensuring timely delivery and seamless integration of app features. |

Skills: python, OpenCV, PyTorch, Kalman filtering, sensor fusion, optical tracking, IMU processing, camera calibration, real-time systems, UDP networking, distributed systems, signal processing, reinforcement learning, Docker, Git, human-machine interfaces, biometric data, machine learning, computer vision, image processing.