view_frames Result

Recorded at time: 1770966152.7566037

odom

Broadcaster: default_authority
Average rate: 50.251
Buffer length: 3.98
Most recent transform: 67.284
Oldest transform: 63.304

robot_base_link

robot_base_footprint

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 60.279
Buffer length: 5.01
Most recent transform: 67.284
Oldest transform: 62.274

Broadcaster: default_authority
Average rate: 60.279
Buffer length: 5.01
Most recent transform: 67.284
Oldest transform: 62.274

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

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Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

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Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_elevator_base_link

robot_left_wheel_link

robot_right_wheel_link

robot_front_cover_link

robot_omni_backwheel_link

robot_omni_front_leftwheel_link

robot_omni_front_rightwheel_link

robot_top_cover_link

Broadcaster: default_authority
Average rate: 60.279
Buffer length: 5.01
Most recent transform: 67.284
Oldest transform: 62.274

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_elevator_platform_link

robot_base_docking_contact_link