view_frames Result

Recorded at time: 1770964388.3314273

odom

Broadcaster: default_authority
Average rate: 50.201
Buffer length: 4.98
Most recent transform: 418.262
Oldest transform: 413.282

robot_base_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 60.12
Buffer length: 4.99
Most recent transform: 418.262
Oldest transform: 413.272

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Average rate: 60.12
Buffer length: 4.99
Most recent transform: 418.262
Oldest transform: 413.272

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

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Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

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Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_base_footprint

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_elevator_base_link

robot_left_wheel_link

robot_right_wheel_link

robot_front_cover_link

robot_omni_backwheel_link

robot_omni_front_leftwheel_link

robot_omni_front_rightwheel_link

robot_top_cover_link

Broadcaster: default_authority
Average rate: 60.12
Buffer length: 4.99
Most recent transform: 418.262
Oldest transform: 413.272

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_elevator_platform_link

robot_base_docking_contact_link