# **SmartCar C++ Coding Style Guideline**

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This guideline is written in reference to C++ Coding Standards and Style Guide by NASA in 2005.

# Introduction

This guideline is aimed to provide a recommendation in C++ code writing which is

- Organized
- Easy to read
- Easy to understand
- Maintainable
- Extendable
- Efficient

### **Names**

In general, choose names that are meaningful and readable.

• If abbreviations can be used, do so. The abbreviations should be all in the same case.

```
1 class PIDController;
2 BTComm btComm;
```

Avoid underscores

#### Struct/Class Names

• Capitalize the first letter of each word.

```
1 class FeatureExtraction;
2 struct Edge;
```

#### **Method/Function Names**

• Capitalize the first letter of each word except first word. The function name should start with a verb if possible.

```
1 | findOneLeftEdge();
```

Some examples of prefix verbs.

Verbs	Meaning
ls/Has/Can	Asking questions about something and return bool type
Set	Setters
Get	Getters
Init	Inititialization
Calc/Find/Compute	Computation
Print	Print

Use 'on' for interrupt functions, for example onButtonClick().

• The name of the class should not be duplicated in a method name.

```
1 | Edge push(); // not Edge PushEdge();
```

# **Namespace Names**

• Each subpart of your project should be contained in one namespace, with the first letter of each word capitalized.

```
1    namespace Algorithm;
2    namespace Utility;
3    namespace ControlSys;
```

#### **Variable Names**

• Variables should be in camelCase, i.e. the first letter of the each word capitalized except the first.

```
1 | Edge leftEdge;
```

• Variable names should be concise at its purpose. If it is not possible, add a comment along with it.

#### **Method/Function Parameters**

• Parameter names can have the same name as its type, but with the first letter not capitalized,

```
void genPath(Feature feature);
```

• The parameter name can also be the initial of its type.

```
void genPath(Feature f);
```

#### **Pointers**

• Names of pointers should start with p.

• Place the \* operator with the name instead of type.

```
1 | Motor *pMotor = &motor;
```

#### Reference

• Place the & operator with the name instead of type.

```
1 | Coord findFirstCorner(const Edge &edge);
```

• For operator overloads, put the & with the type.

```
1 | Coord& operator+=(const Coord &coord);
```

# **Type Names**

• Type name should have the first letter of each word capitalized.

```
1 | typedef uint16_t Byte;
```

#### **Enum Struct Names**

- The enum struct name should follow the one in *Class Name*.
- The members of the enum struct should start with k and follow its name with first letter of each word capitalized.

```
1  enum struct Feature {
2    kStraight = 0,
3    kRoundroad,
4    kCrossroad
5  };
```

• If the enum struct is used with the purpose of flag, name it with the word 'Type'.

```
1   enum struct RoundaboutStatusType {
2    kDetectedEntry = 0,
3    kInside,
4    kDetectedExit,
5    kOutside
6  };
```

The variable with that type then should have the name camelCase without the word 'Type'.

```
1 RoundaboutStatusType roundaboutStatus = RoudaboutStatusType::kOutside;
```

#### **Constant Names**

• Constant names should be in all CAPS with underscores between words.

```
1 const uint16_t MAX_NUMBER_OF_EDGE_ENTRY = 200;
```

#### C++ File Names

- All header files should end with .h type.
- All source files should end with .cpp type.
- File names of both header and source should match and are put in \inc and \src folders respectively.

### **Variables and Constants**

• Declarations of temporary variables should just be above the scope it is used.

```
uint16_t blackCount = 0;
for (uint16_t i = 0; i < leftEdge.size(); i++)
blackCount += leftEdge.at(i)</pre>
```

- Beware of the placement of variables, prevent frequent construction and destruction for temporary variables.
- Avoid the use of global variables, rather provide them through the use of class API/namespace.
- Always provide an initialized value for variables.
  - Use nullptr instead of NULL for initialization of pointers.
- Avoid #define, use const instead.
- If constant references can be used instead of pointers, use them.

# **Formatting**

#### **Variables**

• It is preferable to declare variables with similar purpose in the same line, one per line if not applicable.

```
1 | int leftCount = 0, rightCount = 0;
```

#### **Indentation**

• Use 4 spaces instead of a tab for indentation since indentation maybe different for different editors and environments,

#### **Space**

• Put one space after a comma/semicolon.

```
pow(2, 3);
for (i = 0; i < n; i++);</pre>
```

• Put one space around = .

```
1 | c1 = c2;
```

• Put space between keyword and parentheses.

```
1 | if ( ... );
2 | while ( ... );
```

• Put space between parentheses and braces.

```
1 | for (i = 0; i < n; i++) {
2 | ...
3 |}
```

• No space between function name parentheses.

```
1 | x = pow(2, 3);
```

• No space between unary/primary operators and the operands.

```
1    p->m;
2    s.m;
3    a[i];
4    a(i);
5    ++i;
6    -n;
7    *p;
8    &r;
```

#### **Blank Lines**

• Use blank lines to separate different sections of your code to make it more understandable.

# **Method/Function Arguments**

• If the arguments are too long to be put in one single line, you may line the arguments up with the first argument.

```
Clamp(servoBounds.kLeft,
pidController.Calc(error),
servoBounds.kRight);
```

### **Scopes**

• Indent statements if they are in a scope.

```
while (condition) {
   statement;
}
```

### Control/Loop

- Same rule with Scopes.
- If the inner statement contains only one line, you may write the whole control in one line, or two line with indentation (without braces).

```
if (condition) statement;
//OR
if (condition)
statement;
```

• It is recommended to use explicit comparisons.

```
if (leftEdge.size() != 0);
//instead of
if (leftEdge.size());
```

# **Conditional Statements**

• Put space around conditional operators.

```
1 | x = (a > b) ? a : b;
```

• Align the ? and : operators in new lines if the statement is too long to be put in one line.

```
1 (condition)
2 ? statement1
3 : statement2;
```

#### **Switch**

- Always have default case, which is put after all other cases and should have break; as well for consistency. If it should not be triggered, write a comment to specify it.
- If certain cases are meant to not have break; , specify them with a comment.
- You may have a scope declared inside certain case.

```
1
    switch (expression) {
2
     case a:
3
        statement;
4
        break;
5
      case b: // fall through
6
        statement;
7
      case c:
8
        {
9
          statement;
10
          break;
11
        }
12
      default:
13
        // not handled
```

```
14 | break;
15 |}
```

#### **Statements**

- Prevent the use of goto. Only use it if you believe the control loop would look better with goto instead of use of flags.
- You may use ? : if you believe the statements involved are not too complex.
- Use constexpr if you wish the compiler resolve the expression before compilation.

```
constexpr const float SERVO_MODEL_CONST = 120 / 0.5 + 0.6 * std::sin(0.2);
```

## **Functions**

• Use inline keyword if the functions are very short.

```
template <class T>
inline T max(T a, T b) { return (a > b) ? a : b; }
```

• Use boolean functions if applicable.

```
bool findOneLeftEdge() {
   // find one left edge, return false if failed
   return true;
4 }
```

# **Documentations**

• Always write documentations for class interface (declaration) and function prototypes.

```
/**
 1
 2
     * PIDController Class
 3
 4
     * <brief description>
 5
     */
 6
    class PIDController {
    public:
 8
 9
       * @brief Constructor
       * @param kP P constant
10
11
       * @param kI I constant
       * @param kD D constant
12
13
14
      PIDController(float kP, float kD, float kD) { ... }
15
16
       * @brief Next control value getter
17
18
       * @return Control value
19
```

```
float getNextVal() { return ...; }
}
```

• Always write the meaning of each constants, specify the unit if necessary.

```
1 const uint16_t MAX_DISTANCE 400; // Max distance the sensor can detect, in km
```

• Always specify the namespace/preprocessor directives that are being closed at the end.

```
namespace algorithm {
    /* ... */
} // namespace algorithm

#ifdef USE_MOTOR
/* ... */
#endif // USE_MOTOR
```

# **Classes**

- Class declaration should be purely prototypes and attribute declarations.
  - Any implementations should be put outside the class declaration
  - Use inline if appropriate
- Sections of public , protected and private should be declared in said order.
- The parameters in class constructors and the member attributes should have different names. Use m\_ to indicate the variable is a member attribute.

```
class Motor {
public:
    Motor(int pow) : m_pow(pow) {}

private:
    int m_pow;
}
```

• Inherited class should have the name of the base class as part of its name.

```
1 | class AlternateMotor : public Motor;
```

• Abstract class should have the function-to-be-overridden declared as pure virtual function, and the inherited class should override the function with override keyword.

```
class Motor {
private:
    virtual void onSetPower(uint16_t power) = 0;
};

class AlternateMotor : public Motor {
private:
    void onSetPower(uint16_t power) override;
};
```

• Member functions should be declared const if it does not change any class attributes.

```
class Motor {
public:
    int getPower() const;
    void setPower();

private:
    int m_power;
}
```

• All getter should return by copy. If it is necessary to return by reference, you may consider making the member attribute public.

# **Templates**

- Generic type should have name T, U, V, etc.
- For safety concern, you can include library <type\_traits> to make sure only certain types are usable.

```
#includfe <type_traits>
template <class T, class = typename std::enable_if<std::is_arithmetic<T>::value>::type>
...
```

# **Namespace**

• Avoid using namespace, use using instead.

```
using std::math;
// instead of
using namespace std;
```

# **Files**

#### **Headers**

• Preprocessor directive (#ifndef - #define - #endif) should be used in every header.

#### **Includes**

- Included libraries should be arranged from top to bottom, low-level to high-level.
- Included C++ libraries should be put around <> brackets.
- Do not include C libraries, include their C++ counterparts.
- Included libsccc/self-made libraries should be put around " ".

```
#include <cmath> // not "math.h"
#include <string>
#include "libsc/motor.h" // libsccc
#include "BTComm.h" // self-made
```