

1 Source Language Syntax

2 Source Language Statics and Dynamics

3 The Target Language

4 The Translation

4.1 Translating Evidence

4.1.1 Helper Functions

With our evidence represented as tuples with integer tags, we must represent the partial functions on types in our target language. The implementation is given in Figure 7. Doing this is straightforward: if one argument is $?$, then we return the other argument. Otherwise, we check if we have simple or complex types. For simple types, either $\text{Bool} \sqcap \text{Bool} = \text{Bool}$, $\text{Nat} \sqcap \text{Nat} = \text{Nat}$. For complex types, we check that the tags agree, then recursively compute the meets of the sub-components. If neither argument is $?$, and there is a tag mismatch, then we must raise an exception, retuning the **error** continuation.

For the partial functions decomposing types, we first check if the input is $?$, in which case we return $?$. Otherwise, we check the tag, and if it is correct, we return the relevant sub-component of the type. In all other cases, we throw an error. We give an example implementation for **dom** in Figure 8: either we are given $?$ and return $?$, we are given $T_1 \rightarrow T_2$ and we return T_1 , or we raise an exception. We omit **cod**, **proj₁** and **proj₂**, but they are implemented similarly.

5 Correctness

Lemma 5.1 (Correctness of Evidence Translation). *Consider evidence $\varepsilon, \varepsilon'$. Then, for any k :*

- $\text{MEET}(\llbracket \varepsilon \rrbracket, \llbracket \varepsilon' \rrbracket, k) \longrightarrow^* k(\llbracket \varepsilon \sqcap \varepsilon' \rrbracket)$ if $\varepsilon \sqcap \varepsilon'$ is defined.
- If $\varepsilon \sqcap \varepsilon'$ is undefined, then $\text{MEET}(\llbracket \varepsilon \rrbracket, \llbracket \varepsilon' \rrbracket) \longrightarrow^* \text{error}$.

*The same property holds for **dom** ε , **cod** ε , and **Proj_i** ε .*

Lemma 5.2 (Canonical Forms for Translated Values). *For an irreducible v , $\llbracket v \rrbracket = \langle \llbracket \varepsilon \rrbracket, u \rangle$ for some evidence ε and CPS-value u . Moreover, if v is a raw irreducible, then $\varepsilon = \{?\}$.*

Proof. By inversion on the definition of $\llbracket v \rrbracket$. □

Lemma 5.3 (Value and Expression Translations Match). *Let v be an irreducible term. Then, for any k , $v, \llbracket v \rrbracket k \longrightarrow^* k(\llbracket v \rrbracket)$.*

Proof. By induction on v .

$n \in \mathbb{Z}, b \in \mathbb{B}$

e	$::=$	
		x Variables
		b Booleans
		n Natural Numbers
		$\lambda x : T. e$ Functions
		$e_1 e_2$ Function Application
		$e_1 + e_2$ Addition
		$e_1 \stackrel{?}{=} e_2$ Number Equality Test
		if e_1 then e_2 else e_3 Conditionals
		$\langle e_1, e_2 \rangle$ Tuples
		$\pi_1 e$ Tuple First Projection
		$\pi_2 e$ Tuple Second Projection
		εe Evidence Ascription
		error Runtime Type Error
O	$::=$	Observable values
		b
		n
v	$::=$	Irreducible (closed) terms
		εr
		b
		n
		$\lambda x : T. e$ Functions
		$\langle v_1, v_2 \rangle$
r	$::=$	Raw Irreducible (closed) terms (i.e. not ascribed with)
		b
		n
		$\lambda x : T. e$ Functions
		$\langle v_1, v_2 \rangle$

Figure 1: Source Language Syntax: Terms

T	$::=$	Types
		Nat
		Bool
		$T_1 \rightarrow T_2$
		$T_1 \times T_2$
		?
ε	$::=$	
		$\{T\}$
Γ	$::=$	Environments
		.
		$\Gamma, (x : T)$

Figure 2: Source Language Syntax: Types

$\boxed{\Gamma \vdash e : T}$					(Typability relation)
$\frac{\text{HASTYPEVAR} \quad (x : T) \in \Gamma}{\Gamma \vdash x : T}$	$\frac{\text{HASTYPEBOOL}}{\Gamma \vdash b : \text{Bool}}$	$\frac{\text{HASTYPENAT}}{\Gamma \vdash n : \text{Nat}}$	$\frac{\text{HASTYPEPLUS} \quad \Gamma \vdash e_1 : \text{Nat} \quad \Gamma \vdash e_2 : \text{Nat}}{\Gamma \vdash e_1 + e_2 : \text{Nat}}$	$\frac{\text{HASTYPEEQ} \quad \Gamma \vdash e_1 : \text{Nat} \quad \Gamma \vdash e_2 : \text{Nat}}{\Gamma \vdash e_1 \stackrel{?}{=} e_2 : \text{Nat}}$	
$\frac{\text{HASTYPELAM} \quad \Gamma, (x : T_1) \vdash e : T_2}{\Gamma \vdash \lambda x : T_1. e : T_1 \rightarrow T_2}$		$\frac{\text{HASTYPEAPP} \quad \Gamma \vdash e_1 : T_1 \rightarrow T_2 \quad \Gamma \vdash e_2 : T_1}{\Gamma \vdash e_1 e_2 : T_2}$		$\frac{\text{HASTYPEIF} \quad \Gamma \vdash e : \text{Bool} \quad \Gamma \vdash e_1 : T \quad \Gamma \vdash e_2 : T}{\Gamma \vdash \text{if } e \text{ then } e_1 \text{ else } e_2 : T}$	
$\frac{\text{HASTYPEPAIR} \quad \Gamma \vdash e_1 : T_1 \quad \Gamma \vdash e_2 : T_2}{\Gamma \vdash \langle e_1, e_2 \rangle : T_1 \times T_2}$		$\frac{\text{HASTYPEPROJ} \quad \Gamma \vdash e : T_1 \times T_2 \quad i \in \{1, 2\}}{\Gamma \vdash \text{p}_i e : T_1}$		$\frac{\text{HASTYPEASCR} \quad \Gamma \vdash e : T_2 \quad \varepsilon \vdash T_1 \cong T_2}{\Gamma \vdash \varepsilon e : T_1}$	

Figure 3: Source Language: Type Rules

$$\boxed{\varepsilon \vdash T_1 \cong T_2}$$

(Type Consistency relative to Evidence)

$$\frac{\text{CONSISTENTEV} \quad \begin{array}{l} T_3 \sqcap T_1 = T_3 \\ T_3 \sqcap T_2 = T_3 \end{array}}{\{T_3\} \vdash T_1 \cong T_2}$$

$$\boxed{T_1 \sqcap T_2 = T_3}$$

(Precision Meet)

$$\begin{array}{c} \text{MEETDYNL} \\ \hline ? \sqcap T = T \end{array} \quad \begin{array}{c} \text{MEETDYNR} \\ \hline T \sqcap ? = T \end{array} \quad \begin{array}{c} \text{MEETREFL} \\ \hline T \sqcap T = T \end{array} \quad \begin{array}{c} \text{MEETFUN} \\ \begin{array}{l} T_1 \sqcap T'_1 = T''_1 \\ T_2 \sqcap T'_2 = T''_2 \end{array} \\ \hline T_1 \rightarrow T_2 \sqcap T'_1 \rightarrow T'_2 = T''_1 \rightarrow T''_2 \end{array}$$

$$\begin{array}{c} \text{MEETPROD} \\ \begin{array}{l} T_1 \sqcap T'_1 = T''_1 \\ T_2 \sqcap T'_2 = T''_2 \end{array} \\ \hline T_1 \times T_2 \sqcap T'_1 \times T'_2 = T''_1 \times T''_2 \end{array}$$

Figure 4: Source Language: Type Consistency and Precision

$e_1 \longrightarrow e_2$		(Reduction Relation on terms)	
$\frac{\text{REDIfTRUE}}{\text{if true then } e_1 \text{ else } e_2 \longrightarrow e_1}$		$\frac{\text{REDIfFALSE}}{\text{if false then } e_1 \text{ else } e_2 \longrightarrow e_2}$	
$\frac{\text{REDIfEv}}{\text{if } b \text{ then } e_1 \text{ else } e_2 \longrightarrow e}$		$\frac{\text{REDAPP}}{(\lambda x : T. e) v \longrightarrow [v/x]e}$	
$\frac{\text{REDAppEv}}{(\varepsilon_1 (\lambda x : T. e)) (\varepsilon_2 r) \longrightarrow (\text{cod } \varepsilon_2) ([(\text{dom } \varepsilon_1 \sqcap \varepsilon_2) r/x]e)}$			
$\frac{\text{REDAppEvFail}}{\text{dom } \varepsilon_1 \sqcap \varepsilon_2 \text{ undefined}}{\varepsilon_1 (\lambda x : T. e)) (\varepsilon_2 r) \longrightarrow \text{error}}$		$\frac{\text{REDAppEvPartial}}{(\varepsilon (\lambda x : T. e_1)) r \longrightarrow (\text{cod } \varepsilon) ([(\text{dom } \varepsilon) e_2/x]e_1)}$	
$\frac{\text{REDPLUS}}{n_1 + n_2 \longrightarrow n_1 + n_2}$	$\frac{\text{REDPLUSEvL}}{n_1 + v \longrightarrow e}{\varepsilon n_1 + v \longrightarrow e}$	$\frac{\text{REDPLUSEvR}}{n_1 + n_2 \longrightarrow e}{n_1 + \varepsilon n_2 \longrightarrow e}$	$\frac{\text{REDEQT}}{n \stackrel{?}{=} n \longrightarrow \text{true}}$
$\frac{\text{REDEQF}}{n_1 \neq n_2}{n_1 \stackrel{?}{=} n_2 \longrightarrow \text{false}}$	$\frac{\text{REDEQEvL}}{n_1 \stackrel{?}{=} v \longrightarrow e}{\varepsilon n_1 \stackrel{?}{=} v \longrightarrow e}$	$\frac{\text{REDEQEvR}}{n_1 \stackrel{?}{=} n_2 \longrightarrow e}{n_1 \stackrel{?}{=} \varepsilon n_2 \longrightarrow e}$	$\frac{\text{REDPROJ}}{i \in \{1, 2\}}{\pi_i \langle e_1, e_2 \rangle \longrightarrow e_i}$
$\frac{\text{REDPROJEv}}{i \in \{1, 2\}}{\pi_i (\varepsilon \langle e_1, e_2 \rangle) \longrightarrow \text{Proj}_i \varepsilon e_i}$	$\frac{\text{REDASCR}}{\varepsilon_1 (\varepsilon_2 e) \longrightarrow (\varepsilon_1 \sqcap \varepsilon_2) e}$	$\frac{\text{REDASCRFail}}{\varepsilon_1 \sqcap \varepsilon_2 \text{ undefined}}{\varepsilon_1 (\varepsilon_2 e) \longrightarrow \text{error}}$	
$\frac{\text{REDCONTEXT}}{e_1 \longrightarrow e_2}{C[e_1] \longrightarrow C[e_2]}$		$\frac{\text{REDCONTEXTFail}}{e \longrightarrow \text{error}}{C[e] \longrightarrow C[\text{error}]}$	

Figure 5: Source Language: Small-Step Operational Semantics

$$\begin{array}{lcl}
u, k & ::= & \\
& | & x \\
& | & n \\
& | & b \\
& | & \mathbf{fix} \, x \, u \\
& | & \lambda x_1 \dots x_i. t \\
& | & \langle u_1, u_2 \rangle \\
\\
d & ::= & \\
& | & x := u \\
& | & x := \pi_1 u \\
& | & x := \pi_2 u \\
& | & x := u_1 + u_2 \\
& | & x := u_1 \stackrel{?}{=} u_2 \\
\\
t & ::= & \\
& | & v \\
& | & \mathbf{let} \, d \, \mathbf{in} \, t \\
& | & u(arg) \\
& | & \mathbf{if} \, u \, \mathbf{then} \, t_1 \, \mathbf{else} \, t_2 \\
& | & \mathbf{halt} \, [u] \\
& | & \mathbf{error}
\end{array}$$

Figure 6: Target Language: Syntax

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MEET =fix self λty1 ty2 c. let tag1 := π1ty1 in let sub1 := π2ty1 in let isDyn1 := tag1 ? DYN in
  if isDyn1 then c(ty2) else
    let tag2 := π1ty2 in let sub2 := π2ty2 in let isDyn2 := tag2 ? DYN in
      if isDyn2 then c(ty1) else
        let isNat1 := tag1 ? NAT in let isNat2 := tag2 ? NAT in
          if isNat1 then (if isNat2 then k(NAT) else error) else
            let isBool1 := tag1 ? BOOL in let isBool2 := tag2 ? BOOL in
              if isBool1 then (if isBool2 then k(BOOL) else error) else
                let isArrow1 := tag1 ? ARROW in let isArrow2 := tag2 ? ARROW in
                  if isArrow1 then
                    let dom1 := π1sub1 in let cod1 := π2sub1 in
                      if isArrow2 then
                        let dom2 := π1sub2 in let cod2 := π2sub2 in
                          self(dom1, dom2, (λmeet1. self(cod1, cod2, (λmeet2. k(⟨ARROW, ⟨meet1, meet2⟩⟩))))))
                        else error
                      else error
                    let isProduct1 := tag1 ? PRODUCT in let isProduct2 := tag2 ? PRODUCT in
                      if isProduct1 then
                        let lhs1 := π1sub1 in let rhs1 := π2sub1 in
                          if isProduct2 then
                            let lhs2 := π1sub2 in let rhs2 := π2sub2 in
                              self(lhs1, lhs2, (λmeet1. self(rhs1, rhs2, (λmeet2. k(⟨PRODUCT, ⟨meet1, meet2⟩⟩))))))
                              else error
                          else error
                        else error
                      else error
                    else error
                  else error
                else error
              else error
            else error
          else error
        else error
      else error
    else error
  else error

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Figure 7: CPS implementation of meet

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DOM    =  $\lambda \text{ty } c. \text{let tag} := \pi_1 \text{ty1 in let sub} := \pi_2 \text{ty1 in let isDyn} := \text{tag} \stackrel{?}{=} \text{DYN in}$ 
         $\text{if isDyn then } c(\langle \text{DYN}, 0 \rangle) \text{ else}$ 
         $\text{let isArrow} := \text{tag} \stackrel{?}{=} \text{ARROW in}$ 
         $\text{if isArrow then (let ret} := \pi_1 \text{sub in } k(\text{ret})) \text{ else error}$ 

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Figure 8: CPS implementation of domain

- Case $v = b, v = n$, or $v = \lambda x : T. e$: trivial.
- Case $v = \langle v_1, v_2 \rangle$. So $\llbracket \langle v_1, v_2 \rangle \rrbracket k = \llbracket v_1 \rrbracket (\lambda x_1. \llbracket v_2 \rrbracket (\lambda x_2. k(\langle \text{DYN}, \langle x_1, x_2 \rangle \rangle)))$, which, by our hypothesis, reduces to $t_1 \longrightarrow^* (\lambda x_1. (\lambda x_2. k(\langle \text{DYN}, \langle x_1, x_2 \rangle \rangle)))(\llbracket v_2 \rrbracket)(\llbracket v_1 \rrbracket)$, which we can then reduce to $k(\langle \text{DYN}, \langle \llbracket v_1 \rrbracket, \llbracket v_2 \rrbracket \rangle \rangle)$.
- Case $v = \varepsilon r$. Since all raw irreducibles are themselves irreducible, our inductive hypothesis gives that $\llbracket r \rrbracket (\lambda x. \text{let } x_1 := \pi_1 x \text{ in let } x_2 := \pi_2 x \text{ in MEET}(\llbracket \varepsilon \rrbracket, x_1, (\lambda y. k(\langle y, x_2 \rangle \rangle)))$ steps to $(\lambda x. \text{let } x_1 := \pi_1 x \text{ in let } x_2 := \pi_2 x \text{ in MEET}(\llbracket \varepsilon \rrbracket, x_1, (\lambda y. k(\langle y, x_2 \rangle \rangle)))(\llbracket r \rrbracket)$. By Lemma 5.2, $\llbracket r \rrbracket$ is of the form $\langle \text{DYN}, u \rangle$ for some u . So we can then β -reduce and apply the let-substitutions to reach $\text{MEET}(\llbracket \varepsilon \rrbracket, \text{DYN}, u)$. By Lemma 5.1, this steps to $\langle \llbracket \varepsilon \rrbracket, u \rangle$. By the rule **TRANSFORMEV**, this means that $\llbracket \varepsilon r \rrbracket$ also steps to this value.

TODO

□

Lemma 5.4 (Translation Commutes With Substitution). $\llbracket [v/x]e \rrbracket k \longrightarrow^* \llbracket [v]/x \rrbracket \llbracket e \rrbracket k$.

Proof. Follows from straightforward induction on e , combined with Lemma 5.3 for the case where $e = x$. □

Theorem 5.1 (Weak Simulation). *If $e_1 \longrightarrow e_2$, then for all k , $\llbracket e_1 \rrbracket k \equiv \llbracket e_2 \rrbracket k$.*

Proof. We perform induction on the derivation tree of $e_1 \longrightarrow e_2$.

- **REDIFTRUE**: then $e_1 = \text{if true then } e_2 \text{ else } e_3$. The translation $\llbracket \text{true} \rrbracket k' = k'(\langle \text{DYN}, \text{true} \rangle)$ for any k' , so $\llbracket \text{if true then } e_2 \text{ else } e_3 \rrbracket k$ is $(\lambda x_0. \text{let } x := \pi_2 x_0 \text{ in if } x \text{ then } (\llbracket e_2 \rrbracket k) \text{ else } (\llbracket e_3 \rrbracket k))(\langle \text{DYN}, \text{true} \rangle)$. We can β -reduce to get $\text{let } x := \pi_2 \langle \text{DYN}, \text{true} \rangle \text{ in if } x \text{ then } \llbracket e_2 \rrbracket k \text{ else } \llbracket e_3 \rrbracket k$, and we can substitute **true** for x and reduce the **if** to get $\llbracket e_2 \rrbracket k$.
- **REDIFFALSE**: symmetric to **RedIfTrue**

$$\boxed{\llbracket e \rrbracket k = t}$$

(CPS Translation of Expressions)

TRANSFORMVAR

$$\frac{}{\llbracket x \rrbracket k = k(x)}$$

TRANSFORMBOOL

$$\frac{}{\llbracket b \rrbracket k = k(\langle \text{DYN}, b \rangle)}$$

TRANSFORMNUM

$$\frac{}{\llbracket n \rrbracket k = k(\langle \text{DYN}, n \rangle)}$$

TRANSFORMFUN

$$\frac{\llbracket e \rrbracket c = t}{\llbracket (\lambda x : T. e) \rrbracket k = k(\langle \text{DYN}, \lambda x c. t \rangle)}$$

TRANSFORMAPP

$$\frac{\begin{array}{l} k_1 := (\lambda x_2. \mathbf{let} \ y_1 := \pi_1 x_1 \mathbf{in} \mathbf{let} \ z_1 := \pi_2 x_1 \mathbf{in} \mathbf{let} \ y_2 := \pi_1 x_2 \mathbf{in} \mathbf{let} \ z_2 := \pi_2 x_2 \mathbf{in} \ t_1) \\ t_1 := \text{DOM}(y_1, \lambda y_1'. \text{COD}(y_1, \lambda y_1''. \text{MEET}(y_1', y_2, (\lambda y_3. z_1(\langle y_3, z_2 \rangle), (\lambda z_3. \mathbf{let} \ z_3' := \pi_1 z_3 \mathbf{in} \mathbf{let} \ z_3'' := \pi_2 z_3 \mathbf{in} \text{MEET}(y_1'', z_3', (\lambda x_1. t')) \\ \llbracket e_2 \rrbracket k_1 = t' \\ \llbracket e_1 \rrbracket (\lambda x_1. t') = t \end{array}}{\llbracket e_1 \ e_2 \rrbracket k = t}$$

TRANSFORMPLUS

$$\frac{\begin{array}{l} k_1 := (\lambda x_2. \mathbf{let} \ z_1 := \pi_2 x_1 \mathbf{in} \mathbf{let} \ z_2 := \pi_2 x_2 \mathbf{in} \mathbf{let} \ z_3 := z_1 + z_2 \mathbf{in} \ k(z_3)) \\ \llbracket e_2 \rrbracket k_1 = t' \\ \llbracket e_1 \rrbracket (\lambda x_1. t') = t \end{array}}{\llbracket e_1 + e_2 \rrbracket k = t}$$

TRANSFORMEQ

$$\frac{\begin{array}{l} k_1 := (\lambda x_2. \mathbf{let} \ z_1 := \pi_2 x_1 \mathbf{in} \mathbf{let} \ z_2 := \pi_2 x_2 \mathbf{in} \mathbf{let} \ z_3 := z_1 \stackrel{?}{=} z_2 \mathbf{in} \ k(z_3)) \\ \llbracket e_2 \rrbracket k_1 = t' \\ \llbracket e_1 \rrbracket (\lambda x_1. t') = t \end{array}}{\llbracket e_1 + e_2 \rrbracket k = t}$$

TRANSFORMPAIR

$$\frac{\begin{array}{l} \llbracket e_2 \rrbracket (\lambda x_2. k(\langle \text{DYN}, \langle x_1, x_2 \rangle \rangle)) = t' \\ \llbracket e_1 \rrbracket (\lambda x_1. t') = t \end{array}}{\llbracket \langle e_1, e_2 \rangle \rrbracket k = t}$$

TRANSFORMIF

$$\frac{\begin{array}{l} \llbracket e_1 \rrbracket k = t_1 \quad \llbracket e_2 \rrbracket k = t_2 \\ \llbracket e_0 \rrbracket (\lambda x_0. \mathbf{let} \ x := \pi_2 x_0 \mathbf{in} \mathbf{if} \ x \mathbf{then} \ t_1 \mathbf{else} \ t_2) = t \end{array}}{\llbracket \mathbf{if} \ e_0 \mathbf{then} \ e_1 \mathbf{else} \ e_2 \rrbracket k = t}$$

TRANSFORMPROJ

$$\frac{\llbracket e \rrbracket (\lambda x. \mathbf{let} \ x' := \pi @ i \ x \mathbf{in} \ k(x')) = t}{\llbracket \pi_i e \rrbracket k = t}$$

TRANSFORMEV

$$\frac{\llbracket e \rrbracket (\lambda x. \mathbf{let} \ x_1 := \pi_1 x \mathbf{in} \mathbf{let} \ x_2 := \pi_2 x \mathbf{in} \text{MEET}(\llbracket \varepsilon \rrbracket, x_1, (\lambda y. k(\langle y, x_2 \rangle)))) = t}{\llbracket \varepsilon \ e \rrbracket k = t}$$

TRANSFORMERR

$$\frac{}{\llbracket \mathbf{error} \rrbracket k_9 = \mathbf{error}}$$

Translation: Terms and Programs

$$\boxed{\llbracket \varepsilon \rrbracket = u}$$

()

EvTRANSFORMBOOL

$$\frac{}{\llbracket \{\text{Bool}\} \rrbracket = \langle \text{BOOL}, 0 \rangle}$$

EvTRANSFORMNAT

$$\frac{}{\llbracket \{\text{Nat}\} \rrbracket = \langle \text{NAT}, 0 \rangle}$$

EvTRANSFORMDYN

$$\frac{}{\llbracket \{?\} \rrbracket = \langle \text{DYN}, 0 \rangle}$$

EvTRANSFORMARR

$$\frac{}{\llbracket \{T_1 \rightarrow T_2\} \rrbracket = \langle \text{ARROW}, \langle \llbracket \{T_1\} \rrbracket, \llbracket \{T_2\} \rrbracket \rangle \rangle}$$

EvTRANSFORMPROD

$$\frac{}{\llbracket \{T_1 \rightarrow T_2\} \rrbracket = \langle \text{PRODUCT}, \langle \llbracket \{T_1\} \rrbracket, \llbracket \{T_2\} \rrbracket \rangle \rangle}$$

Translation: Evidence

$$\boxed{\llbracket v \rrbracket = u}$$

(CPS Translation of Closed Values)

VALTRANSFORMBOOL

$$\frac{}{\llbracket b \rrbracket = \langle \text{DYN}, b \rangle}$$

VALTRANSFORMNUM

$$\frac{}{\llbracket n \rrbracket = \langle \text{DYN}, n \rangle}$$

VALTRANSFORMFUN

$$\frac{\llbracket e \rrbracket c = t}{\llbracket \lambda x : T. e \rrbracket = \langle \text{DYN}, \lambda x c. t \rangle}$$

VALTRANSFORMPAIR

$$\frac{}{\llbracket \langle v_1, v_2 \rangle \rrbracket = \langle \text{DYN}, \langle \llbracket v_1 \rrbracket, \llbracket v_2 \rrbracket \rangle \rangle}$$

VALTRANSFORMEV

$$\frac{\llbracket r \rrbracket = \langle \text{DYN}, u \rangle}{\llbracket \varepsilon r \rrbracket = \langle \llbracket \varepsilon \rrbracket, u \rangle}$$

Translation: Evidence

- **REDIFEV**: $e_1 = \text{if } \varepsilon b \text{ then } e'_2 \text{ else } e'_3$. We know that $\llbracket b \rrbracket k' = k'(\langle \text{DYN}, b \rangle)$, so $\llbracket \varepsilon b \rrbracket k'' = (\lambda x. \text{let } x_1 := \pi_1 x \text{ in let } x_2 := \pi_2 x \text{ in MEET}(\llbracket \varepsilon \rrbracket, x_1, (\lambda y. k''(\langle y, x_2 \rangle)))(\langle \text{DYN}, b \rangle))$. We can β -reduce, and substitute with the let-expressions, to get $(\lambda x. \text{MEET}(\llbracket \varepsilon \rrbracket, \text{DYN}, (\lambda y. k''(\langle y, b \rangle))))$. However, $\varepsilon \sqcap \{?\} = \{?\}$, so by Lemma 5.1 this steps to $k''(\langle \llbracket \varepsilon \rrbracket, b \rangle)$. Since the translation of if ignores any evidence in the condition, we can use the same reasoning from RedIfTrue to show that it steps to e_2 if b is true, and e_3 if b is false.
- **REDAPP**: then $e_1 = (\lambda x : T. e') v$ and $e_2 = [v/x]e'$. Let $\langle \llbracket \varepsilon \rrbracket, u \rangle = \llbracket v \rrbracket$ (by Lemma 5.2). If we apply Lemma 5.3, we can see that $\llbracket (\lambda x : T. e') v \rrbracket k$ steps to $(\lambda x_1 x_2. \text{let } y_1 := \pi_1 x_1 \text{ in } \dots)(\langle \text{DYN}, (\lambda x c. \llbracket e' \rrbracket c) \rangle, \langle \llbracket \varepsilon \rrbracket, u \rangle)$. We can β -reduce and apply the let-substitutions to then step to $\text{DOM}(\text{DYN}, \lambda y'_1. \text{COD}(\text{DYN}, \lambda y''_1. \text{MEET}(y'_1, \llbracket \varepsilon \rrbracket, (\lambda y_3. (\lambda x c. \llbracket e' \rrbracket c)(\langle y_3, u \rangle), (\lambda z_3. \text{let } z'_3 := \pi_1 z_3 \text{ in let } z''_3 := \pi_2 z_3 \text{ in MEET}(y''_1, z'_3, (\lambda z_4. k(\langle z_4, z''_3 \rangle))))))))$. By applying Lemma 5.1 for DOM, COD and MEET of ? respectively, we can step to $(\lambda x c. \llbracket e' \rrbracket c)(\langle \llbracket \varepsilon \rrbracket, u \rangle, (\lambda z_3. \text{let } z'_3 := \pi_1 z_3 \text{ in let } z''_3 := \pi_2 z_3 \text{ in MEET}(\text{DYN}, z'_3, (\lambda z_4. k(\langle z_4, z''_3 \rangle))))$. This then β -reduces to $\llbracket \langle \llbracket \varepsilon \rrbracket, u \rangle / x \rrbracket \llbracket e' \rrbracket (\lambda z_3. \text{let } z'_3 := \pi_1 z_3 \text{ in let } z''_3 := \pi_2 z_3 \text{ in MEET}(\text{DYN}, z'_3, (\lambda z_4. k(\langle z_4, z''_3 \rangle))))$. But, then, by Lemma 5.1 and η -equivalence, this is equivalent to $\llbracket \langle \llbracket \varepsilon \rrbracket, u \rangle / x \rrbracket \llbracket e' \rrbracket k$. But we know that this is $\llbracket [v]/x \rrbracket \llbracket e' \rrbracket k$. Finally, Lemma 5.4 gives us that this is equivalent to $\llbracket [v/x]e' \rrbracket k$.
- **REDAPPEV**: then $e_1 = \varepsilon_1 (\lambda x : T. e') \varepsilon_2 v$ and $e_2 = \text{cod } \varepsilon_1 ([(\text{dom } \varepsilon_1 \sqcap \varepsilon_2) v/x]e')$. Let $\langle \llbracket \varepsilon_2 \rrbracket, u \rangle = \llbracket v \rrbracket$ (by Lemma 5.2). If we apply Lemma 5.3, we can see that $\llbracket \varepsilon_1 (\lambda x : T. e') \varepsilon_2 v \rrbracket k$ steps to $(\lambda x_1 x_2. \text{let } y_1 := \pi_1 x_1 \text{ in } \dots)(\langle \llbracket \varepsilon_1 \rrbracket, (\lambda x c. \llbracket e' \rrbracket c) \rangle, \langle \llbracket \varepsilon_2 \rrbracket, u \rangle)$. We can β -reduce and apply the let-substitutions to then step to $\text{DOM}(\llbracket \varepsilon_1 \rrbracket, \lambda y'_1. \text{COD}(\llbracket \varepsilon_1 \rrbracket, \lambda y''_1. \text{MEET}(y'_1, \llbracket \varepsilon_2 \rrbracket, (\lambda y_3. (\lambda x c. \llbracket e' \rrbracket c)(\langle y_3, u \rangle), (\lambda z_3. \text{let } z'_3 := \pi_1 z_3 \text{ in let } z''_3 := \pi_2 z_3 \text{ in MEET}(y''_1, z'_3, (\lambda z_4. k(\langle z_4, z''_3 \rangle))))))))$. By applying Lemma 5.1 for DOM, COD and MEET of ? respectively, we can step to $(\lambda x c. \llbracket e' \rrbracket c)(\langle \llbracket \text{dom } \varepsilon_1 \sqcap \varepsilon_2 \rrbracket, u \rangle, (\lambda z_3. \text{let } z'_3 := \pi_1 z_3 \text{ in let } z''_3 := \pi_2 z_3 \text{ in MEET}(\llbracket \text{cod } \varepsilon_1 \rrbracket, z'_3, (\lambda z_4. k(\langle z_4, z''_3 \rangle))))$. This then β -reduces to $\llbracket \llbracket \text{dom } \varepsilon_1 \sqcap \varepsilon_2 \rrbracket, u \rrbracket / x \rrbracket \llbracket e' \rrbracket (\lambda z_3. \text{let } z'_3 := \pi_1 z_3 \text{ in let } z''_3 := \pi_2 z_3 \text{ in MEET}(\llbracket \text{cod } \varepsilon_1 \rrbracket, z'_3, (\lambda z_4. k(\langle z_4, z''_3 \rangle))))$. But, by the rule TRANSFORMEV, this is α -equivalent to $\llbracket \text{cod } \varepsilon_1 ([(\text{dom } \varepsilon_1 \sqcap \varepsilon_2) v/x]e') \rrbracket k$, giving us our result.

□

6 Incorrectness