

A CPS Transformation for Gradual Programs with Evidence

CPSC 539B Final Project

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Source Language

e	$::=$	
	x	Variables
	b	Booleans
	n	Natural Numbers
	$\lambda x : T. e$	Functions
	$e_1 e_2$	Function Application
	$e_1 + e_2$	Addition
	$e_1 \stackrel{?}{=} e_2$	Number Equality Test
	if e_1 then e_2 else e_3	Conditionals
	$\langle e_1, e_2 \rangle$	Tuples
	$\pi_1 e$	Tuple First Projection
	$\pi_2 e$	Tuple Second Projection
	εe	Evidence Ascription
	error	Runtime Type Error

T	$::=$	Types
		Nat
		Bool
		$T_1 \rightarrow T_2$
		$T_1 \times T_2$
		?
ε	$::=$	
		$\{T\}$

HASTYPEASCR

$$\frac{\begin{array}{l} \Gamma \vdash e : T_2 \\ \varepsilon \vdash T_1 \cong T_2 \end{array}}{\Gamma \vdash \varepsilon e : T_1}$$

CONSISTENTEV

$$\frac{\begin{array}{l} T_3 \sqcap T_1 = T_3 \\ T_3 \sqcap T_2 = T_3 \end{array}}{\{T_3\} \vdash T_1 \cong T_2}$$

$$\boxed{T_1 \sqcap T_2 = T_3}$$

(Precision Meet)

MEETDYNL

$$\frac{}{? \sqcap T = T}$$

MEETDYNR

$$\frac{}{T \sqcap ? = T}$$

MEETREFL

$$\frac{}{T \sqcap T = T}$$

MEETFUN

$$\frac{\begin{array}{l} T_1 \sqcap T'_1 = T''_1 \\ T_2 \sqcap T'_2 = T''_2 \end{array}}{T_1 \rightarrow T_2 \sqcap T'_1 \rightarrow T'_2 = T''_1 \rightarrow T''_2}$$

MEETPROD

$$\frac{\begin{array}{l} T_1 \sqcap T'_1 = T''_1 \\ T_2 \sqcap T'_2 = T''_2 \end{array}}{T_1 \times T_2 \sqcap T'_1 \times T'_2 = T''_1 \times T''_2}$$

REDASCR

$$\frac{}{\varepsilon_1 (\varepsilon_2 e) \longrightarrow (\varepsilon_1 \sqcap \varepsilon_2) e}$$

REDASCRFAIL

$$\frac{\varepsilon_1 \sqcap \varepsilon_2 \text{ undefined}}{\varepsilon_1 (\varepsilon_2 e) \longrightarrow \text{error}}$$

REDAPPEV

$$\frac{}{(\varepsilon_1 (\lambda x : T. e)) (\varepsilon_2 r) \longrightarrow (\text{cod } \varepsilon_2) ([(\text{dom } \varepsilon_1 \sqcap \varepsilon_2) r/x] e)}$$

REDAPPEVFAIL

$$\frac{\text{dom } \varepsilon_1 \sqcap \varepsilon_2 \text{ undefined}}{(\varepsilon_1 (\lambda x : T. e)) (\varepsilon_2 r) \longrightarrow \text{error}}$$

$\{\text{Nat}\} (\{\text{Bool}\} \text{true}) + 0$ typechecks!

$\{\text{Bool}\} \vdash \text{Bool} \cong ?$ and $\{\text{Nat}\} \vdash ? \cong \text{Bool}$

But: fails at runtime!

$\text{Nat} \sqcap \text{Bool}$ undefined

The Target

u, k	$::=$		
		x	
		n	
		b	
		fix $x u$	
		$\lambda x_1 \dots x_j. t$	
		$\langle u_1, u_2 \rangle$	
d	$::=$		
		$x := u$	
		$x := \pi_1 u$	
		$x := \pi_2 u$	
		$x := u_1 + u_2$	
		$x := u_1 \stackrel{?}{=} u_2$	
		t	$::=$
			v
			let d in t
			$u(arg)$
			if u then t_1 else t_2
			halt $[u]$
			error
		arg	$::=$
			u_1, \dots, u_j

The Translation

Integer constants **BOOL**, **NAT**, **ARROW**, **PRODUCT**, **DYN**

$$\boxed{\llbracket \varepsilon \rrbracket = u}$$

(CPS Representation of Runtime Evidence)

EVTRANSFORMBOOL

$$\frac{}{\llbracket \{\text{Bool}\} \rrbracket = \langle \mathbf{BOOL}, 0 \rangle}$$

EVTRANSFORMNAT

$$\frac{}{\llbracket \{\text{Nat}\} \rrbracket = \langle \mathbf{NAT}, 0 \rangle}$$

EVTRANSFORMDYN

$$\frac{}{\llbracket \{?\} \rrbracket = \langle \mathbf{DYN}, 0 \rangle}$$

EVTRANSFORMARR

$$\frac{}{\llbracket \{T_1 \rightarrow T_2\} \rrbracket = \langle \mathbf{ARROW}, \langle \llbracket \{T_1\} \rrbracket, \llbracket \{T_2\} \rrbracket \rangle \rangle}$$

EVTRANSFORMPROD

$$\frac{}{\llbracket \{T_1 \rightarrow T_2\} \rrbracket = \langle \mathbf{PRODUCT}, \langle \llbracket \{T_1\} \rrbracket, \llbracket \{T_2\} \rrbracket \rangle \rangle}$$

$\text{MEET}(u_1, u_2, k)$

Combines evidence representation u_1 and u_2 , gives result to k

Passes control **error** continuation if meet undefined

Similar for **DOM**, **COD** to decompose function types

$$\boxed{\llbracket v \rrbracket = u}$$

(CPS Translation of Closed Values)

VALTRANSFORMBOOL

$$\frac{}{\llbracket b \rrbracket = \langle \text{DYN}, b \rangle}$$

VALTRANSFORMNUM

$$\frac{}{\llbracket n \rrbracket = \langle \text{DYN}, n \rangle}$$

VALTRANSFORMFUN

$$\frac{\llbracket e \rrbracket c = t}{\llbracket \lambda x : T. e \rrbracket = \langle \text{DYN}, \lambda x c. t \rangle}$$

VALTRANSFORMPAIR

$$\frac{}{\llbracket \langle v_1, v_2 \rangle \rrbracket = \langle \text{DYN}, \langle \llbracket v_1 \rrbracket, \llbracket v_2 \rrbracket \rangle \rangle}$$

VALTRANSFORMEV

$$\frac{\llbracket r \rrbracket = \langle \text{DYN}, u \rangle}{\llbracket \varepsilon r \rrbracket = \langle \llbracket \varepsilon \rrbracket, u \rangle}$$

TRANSFORMAPP

$$k_1 := (\lambda x_2. \text{let } y_1 := \pi_1 x_1 \text{ in let } z_1 := \pi_2 x_1 \text{ in let } y_2 := \pi_1 x_2 \text{ in let } z_2 := \pi_2 x_2 \text{ in } t_1)$$

$$t_1 := \text{DOM}(y_1, \lambda y'_1. \text{COD}(y_1, \lambda y''_1. \text{MEET}(y'_1, y_2, (\lambda y_3. z_1(\langle y_3, z_2 \rangle, (\lambda z_3. t_2))))))$$

$$t_2 := \text{let } z'_3 := \pi_1 z_3 \text{ in let } z''_3 := \pi_2 z_3 \text{ in MEET}(y''_1, z'_3, (\lambda z_4. k(\langle z_4, z''_3 \rangle)))$$

$$\llbracket e_2 \rrbracket k_1 = t'$$

$$\llbracket e_1 \rrbracket (\lambda x_1. t') = t$$

$$\llbracket e_1 e_2 \rrbracket k = t$$

Correctness

$\text{MEET}(\llbracket \varepsilon_1 \rrbracket, \llbracket \varepsilon_2 \rrbracket, k) \longrightarrow^* k(\llbracket \varepsilon_1 \sqcap \varepsilon_2 \rrbracket)$

If $\varepsilon_1 \sqcap \varepsilon_2$ undefined, then $\text{MEET}(\llbracket \varepsilon_1 \rrbracket, \llbracket \varepsilon_2 \rrbracket, k) \longrightarrow^* \text{error}$

$\llbracket v \rrbracket k \longrightarrow^* k(\llbracket v \rrbracket)$

$\llbracket [v/x]e \rrbracket k \longrightarrow^* \llbracket [v]/x \rrbracket \llbracket e \rrbracket k$

If $e_1 \longrightarrow e_2$, then for any k , $\llbracket e_1 \rrbracket k \equiv \llbracket e_2 \rrbracket k$

Defined in terms of equivalence \equiv , symmetric closure of \longrightarrow^*

Simulation proved by induction on derivation of $e_1 \longrightarrow e_2$

Corollary: if $eval(e_1) = v$, then $eval(\llbracket e \rrbracket (\lambda x. \mathbf{halt} [x])) = \mathbf{halt} [\llbracket v \rrbracket]$.

Incorrectness

No notion of consistency in target language

$(\lambda x : ?.xx)$ typeable in source

Translation has no type in target

Possibly solved by combination of sum and recursive types

$(\lambda x : \text{Nat}. x + 0) \approx (\lambda x : \text{Nat}. (\{\text{Nat}\} x) + 0)$

Distinguish by target context $(\Box \langle n, 0 \rangle)$ where $n \neq \text{DYN}, n \neq \text{NAT}$

Only causes **error** in second case