Newton's Second Law in Polar Coordinate

Acceleration in polar coordinate expressed as

$$\ddot{\mathbf{r}} = \left(\ddot{r} - r\dot{\phi}^2 \right) \,\, \hat{\mathbf{r}} + \left(r\ddot{\phi} + 2\dot{r}\dot{\phi} \right) \,\, \hat{\boldsymbol{\phi}}$$

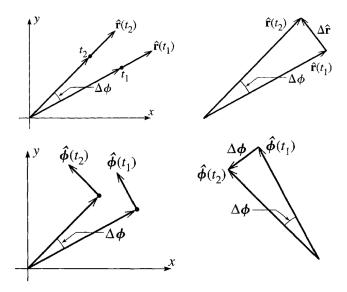
and velocity as

$$\mathbf{v} = \dot{r} \; \hat{\mathbf{r}} + r \dot{\phi} \; \hat{\boldsymbol{\phi}}$$

Hence Newton's law transform into

$$\mathbf{F} = m\mathbf{a} = \begin{cases} F_r &= m\left(\ddot{r} - r\dot{\phi}^2\right) \\ F_{\phi} &= m\left(r\ddot{\phi} + 2\dot{r}\dot{\phi}\right) \end{cases}$$

Derivation



The value of $d\hat{\mathbf{r}}$ and $d\hat{\boldsymbol{\phi}}$.

From the figure, we have

$$d\hat{\mathbf{r}} = d\phi \,\hat{\boldsymbol{\phi}}, \quad d\hat{\boldsymbol{\phi}} = -d\phi \,\hat{\mathbf{r}}$$

or equivalently

$$\frac{d\hat{\mathbf{r}}}{dt} = \dot{\phi} \ \hat{\boldsymbol{\phi}}, \quad \frac{d\hat{\boldsymbol{\phi}}}{dt} = -\dot{\phi} \ \hat{\mathbf{r}}$$

Using these we can now proceed to derive the Newton's law in polar coordinate. In cartesian coordinate, position vector can be writen as

$$\mathbf{r} = x \, \hat{\mathbf{x}} + y \, \hat{\mathbf{v}}$$

converting it into polar

$$\mathbf{r} = r \; \hat{\mathbf{r}}$$

Next, we determine the velocity as

$$\dot{\mathbf{r}} = \frac{d}{dt}r\;\hat{\mathbf{r}} = \dot{r}\;\hat{\mathbf{r}} + r\frac{d\hat{\mathbf{r}}}{dt} = \dot{r}\;\hat{\mathbf{r}} + r\dot{\phi}\;\hat{\boldsymbol{\phi}}$$

and acceleration as

$$\ddot{r} = \frac{d}{dt} \left(\dot{r} \ \hat{\mathbf{r}} + r \dot{\phi} \ \hat{\boldsymbol{\phi}} \right) = \ddot{r} \ \hat{\mathbf{r}} + \dot{r} \dot{\phi} \ \hat{\boldsymbol{\phi}} + r \frac{d}{dt} \left(\dot{\phi} \ \hat{\boldsymbol{\phi}} \right)$$

$$= \ddot{r} \hat{\mathbf{r}} + 2\dot{r} \dot{\phi} \ \hat{\boldsymbol{\phi}} + r \left(\ddot{\phi} \ \hat{\boldsymbol{\phi}} - \dot{\phi} \hat{\mathbf{r}} \right)$$

$$= \left(\ddot{r} - r \dot{\phi}^2 \right) \ \hat{\mathbf{r}} + \left(r \ddot{\phi} + 2\dot{r} \dot{\phi} \right) \ \hat{\boldsymbol{\phi}}$$

Finally

$$F = F_r \; \hat{\mathbf{r}} + F_\phi \; \hat{\boldsymbol{\phi}} \begin{cases} F_r &= m \left(\ddot{r} - r \dot{\phi}^2 \right) \\ F_\phi &= m \left(r \ddot{\phi} + 2 \dot{r} \dot{\phi} \right) \end{cases}$$