

# Summary of symmetry calculations

January 24, 2022



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# Chapter 1

## DBH\_model

Run 11\_09AM\_24\_January-2022

Degree in tangential ansätze: 2.  
The system of ODEs is given by:

$$\begin{aligned}\frac{dw_1}{dt} &= -w_1w_2 - w_1w_3 + w_2w_3, \\ \frac{dw_2}{dt} &= -w_1w_2 + w_1w_3 - w_2w_3, \\ \frac{dw_3}{dt} &= w_1w_2 - w_1w_3 - w_2w_3.\end{aligned}$$

The calculated generators are:

$$X_1 = (1) \partial t,$$

$$X_2 = (1) \partial t,$$

$$X_3 = (-t) \partial t + (w_1) \partial w_1 + (w_2) \partial w_2 + (w_3) \partial w_3,$$

$$\begin{aligned}X_4 &= (t^2) \partial t + (1 - 2tw_1) \partial w_1 + (1 - 2tw_2) \partial w_2 + (1 \\ &\quad + -2tw_3) \partial w_3\end{aligned}$$

$$\begin{aligned}X_5 &= (f_1(t)) \partial t + (w_2w_3 f_1(t) - w_1w_2 f_1(t) - w_1w_3 f_1(t)) \partial w_1 + (w_1w_3 f_1(t) - w_1w_2 f_1(t) \\ &\quad + -w_2w_3 f_1(t)) \partial w_2 + (w_1w_2 f_1(t) - w_1w_3 f_1(t) - w_2w_3 f_1(t)) \partial w_3.\end{aligned}$$

Some of the generators might contain the following arbitrary functions:

$$f_1$$

The execution time of the script was:

0 hours 5 minutes 7 seconds.

## Chapter 2

# SIR

### Run 11\_10AM\_24\_January-2022

Degree in tangential ansätze: 1.  
The system of ODEs is given by:

$$\begin{aligned}\frac{dS}{dt} &= -ISr, \\ \frac{dI}{dt} &= ISr - Ia, \\ \frac{dR}{dt} &= Ia.\end{aligned}$$

The calculated generators are:

$$X_1 = (1) \partial R,$$

$$X_2 = (I + R + S) \partial t$$

$$X_3 = (I + R + S) \partial R$$

$$X_4 = (1) \partial t.$$

The execution time of the script was:

0 hours 0 minutes 23 seconds.

### Run 11\_13AM\_24\_January-2022

Degree in tangential ansätze: 2.  
The system of ODEs is given by:

$$\begin{aligned}\frac{dS}{dt} &= -ISr, \\ \frac{dI}{dt} &= ISr - Ia, \\ \frac{dR}{dt} &= Ia.\end{aligned}$$

The calculated generators are:

$$X_1 = \left(-\frac{1}{r}\right) \partial t,$$

$$X_2 = (1) \partial R,$$

$$X_3 = (1) \partial t,$$

$$X_4 = (I + R + S) \partial t$$

$$X_5 = (I^2 + R^2 + S^2 + 2IR + 2IS + 2RS) \partial t$$

$$X_6 = \left(\frac{f_1(t)}{a}\right) \partial t + \left(-\frac{ISr f_1(t)}{a}\right) \partial S + \left(\frac{ISr f_1(t)}{a} - I f_1(t)\right) \partial I + (I f_1(t)) \partial R.$$

Some of the generators might contain the following arbitrary functions:

$$f_1$$

## WARNING:

*Some of the calculated generators did not satisfy the linearised symmetry conditions. Thus, the presented list here is not complete and consists exclusively of the calculated generators that satisfy the linearised symmetry conditions.*

The execution time of the script was:

0 hours 2 minutes 52 seconds.



## Chapter 3

# Brusselator

Run 11\_13AM\_24\_January-2022

Degree in tangential ansätze: 1.  
The system of ODEs is given by:

$$\begin{aligned}\frac{du}{dt} &= au^2v - u(b+1) + 1, \\ \frac{dv}{dt} &= -au^2v + bu.\end{aligned}$$

The calculated generators are:

$$X_1 = (1) \partial t.$$

The execution time of the script was:

0 hours 0 minutes 6 seconds.



## Chapter 4

# linear\_model

Run 11\_03AM\_24\_January-2022

Degree in tangential ansätze: 1.  
The system of ODEs is given by:

$$\begin{aligned}\frac{du}{dt} &= u + v, \\ \frac{dv}{dt} &= u + v.\end{aligned}$$

The calculated generators are:

$$X_1 = \left( \frac{v}{2} - \frac{u}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2} \right) \partial t$$

$$\begin{aligned}X_2 = & \left( \frac{e^{2t}}{4} - \frac{e^{-2t}}{4} \right) \partial t + \left( \frac{u}{2} + \frac{ve^{2t}}{2} - \frac{ue^{-2t}}{2} - \frac{ve^{-2t}}{2} \right) \partial u + \left( \frac{v}{2} \right. \\ & \left. + \frac{ve^{2t}}{2} \right) \partial v\end{aligned}$$

$$X_3 = \left( \frac{e^{2t}}{2} - \frac{1}{2} \right) \partial u + \left( \frac{1}{2} + \frac{e^{2t}}{2} \right) \partial v$$

$$X_4 = \left( \frac{1}{2} + \frac{e^{2t}}{2} \right) \partial u + \left( \frac{e^{2t}}{2} - \frac{1}{2} \right) \partial v,$$

$$X_5 = \left( -\frac{e^{2t}}{4} - \frac{1}{2} - \frac{e^{-2t}}{4} \right) \partial t + \left( -\frac{u}{2} - \frac{ue^{-2t}}{2} - \frac{ve^{2t}}{2} - \frac{ve^{-2t}}{2} \right) \partial u + \left( -\frac{ve^{2t}}{2} - \frac{v}{2} \right) \partial v,$$

$$X_6 = \left( -\frac{e^{2t}}{4} + \frac{e^{-2t}}{4} \right) \partial t + \left( \frac{u}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2} - \frac{ve^{2t}}{2} \right) \partial u \\ + \left( \frac{v}{2} - \frac{ve^{2t}}{2} \right) \partial v$$

$$X_7 = \left( -\frac{1}{2} + \frac{e^{-2t}}{4} + \frac{e^{2t}}{4} \right) \partial t + \left( -\frac{u}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2} \right. \\ \left. + \frac{ve^{2t}}{2} \right) \partial u + \left( \frac{ve^{2t}}{2} - \frac{v}{2} \right) \partial v,$$

$$X_8 = \left( \frac{u}{2} - \frac{v}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2} \right) \partial t$$

$$X_9 = (1) \partial t,$$

$$X_{10} = (f_1(t)) \partial t + (u f_1(t) + v f_1(t)) \partial u + (u f_1(t) + v f_1(t)) \partial v$$

Some of the generators might contain the following arbitrary functions:

$$f_1$$

The execution time of the script was:

0 hours 0 minutes 12 seconds.

## Run 11\_04AM\_24\_January-2022

Degree in tangential ansätze: 2.

The system of ODEs is given by:

$$\frac{du}{dt} = u + v, \\ \frac{dv}{dt} = u + v.$$

The calculated generators are:

$$X_1 = \left( -\frac{5v}{8} + \frac{3u}{8} - \frac{3ue^{-2t}}{8} - \frac{ue^{2t}}{8} + \frac{ue^{-4t}}{8} + \frac{ve^{-4t}}{8} \right. \\ \left. + \frac{ve^{-2t}}{8} + \frac{3ve^{2t}}{8} \right) \partial t + \left( -\frac{v^2}{4} + \frac{u^2}{4} + \frac{v^2e^{-2t}}{2} + \frac{v^2e^{2t}}{2} \right. \\ \left. + -\frac{uv}{2} - \frac{u^2e^{-2t}}{2} + \frac{u^2e^{-4t}}{4} + \frac{v^2e^{-4t}}{4} + \frac{uve^{-4t}}{2} \right) \partial u + \left( \frac{v^2e^{2t}}{2} - \frac{v^2}{2} \right) \partial v,$$

$$\begin{aligned}
X_2 = & \left( -\frac{u}{8} + \frac{3v}{8} - \frac{3ve^{2t}}{8} - \frac{ue^{-2t}}{8} - \frac{ve^{-2t}}{8} + \frac{ue^{-4t}}{8} \right. \\
& \left. + \frac{ue^{2t}}{8} + \frac{ve^{-4t}}{8} \right) \partial t + \left( -\frac{u^2}{4} + \frac{v^2}{4} + \frac{uv}{2} - \frac{v^2e^{2t}}{2} \right. \\
& \left. + \frac{u^2e^{-4t}}{4} + \frac{v^2e^{-4t}}{4} + \frac{uve^{-4t}}{2} \right) \partial u + \left( \frac{v^2}{2} - \frac{v^2e^{2t}}{2} \right) \partial v
\end{aligned}$$

$$\begin{aligned}
X_3 = & \left( \frac{e^{2t}}{4} - \frac{e^{-2t}}{4} \right) \partial t + \left( \frac{u}{2} + \frac{ve^{2t}}{2} - \frac{ue^{-2t}}{2} - \frac{ve^{-2t}}{2} \right) \partial u + \left( \frac{v}{2} \right. \\
& \left. + \frac{ve^{2t}}{2} \right) \partial v
\end{aligned}$$

$$X_4 = \left( -\frac{u^2}{4} - \frac{v^2}{4} + \frac{uv}{2} + \frac{u^2e^{-4t}}{4} + \frac{v^2e^{-4t}}{4} + \frac{uve^{-4t}}{2} \right) \partial t$$

$$\begin{aligned}
X_5 = & \left( \frac{u^2}{4} + \frac{v^2}{4} + \frac{u^2e^{-2t}}{2} - \frac{uv}{2} - \frac{v^2e^{-2t}}{2} + \frac{u^2e^{-4t}}{4} \right. \\
& \left. + \frac{v^2e^{-4t}}{4} + \frac{uve^{-4t}}{2} \right) \partial t
\end{aligned}$$

$$X_6 = \left( \frac{1}{2} + \frac{e^{2t}}{2} \right) \partial u + \left( \frac{e^{2t}}{2} - \frac{1}{2} \right) \partial v,$$

$$X_7 = \left( \frac{e^{2t}}{2} - \frac{1}{2} \right) \partial u + \left( \frac{1}{2} + \frac{e^{2t}}{2} \right) \partial v$$

$$\begin{aligned}
X_8 = & \left( -\frac{e^{2t}}{4} + \frac{e^{-2t}}{4} \right) \partial t + \left( \frac{u}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2} - \frac{ve^{2t}}{2} \right) \partial u \\
& + \left( \frac{v}{2} - \frac{ve^{2t}}{2} \right) \partial v
\end{aligned}$$

$$\begin{aligned}
X_9 = & \left( -\frac{3v}{8} + \frac{u}{8} - \frac{3ve^{2t}}{8} - \frac{ue^{-4t}}{8} - \frac{ue^{-2t}}{8} - \frac{ve^{-4t}}{8} \right. \\
& \left. + -\frac{ve^{-2t}}{8} + \frac{ue^{2t}}{8} \right) \partial t + \left( \frac{u^2}{4} - \frac{u^2e^{-4t}}{4} - \frac{uv}{2} - \frac{uve^{-4t}}{2} - \frac{v^2e^{2t}}{2} - \frac{v^2}{4} - \frac{v^2e^{-4t}}{4} \right) \partial u + \left( -\frac{v^2e^{2t}}{2} - \frac{v^2}{2} \right) \partial v,
\end{aligned}$$

$$\begin{aligned}
X_{10} = & \left( -\frac{u}{8} - \frac{v}{8} - \frac{3ve^{-2t}}{8} - \frac{ue^{2t}}{8} + \frac{ue^{-4t}}{8} + \frac{ue^{-2t}}{8} \right. \\
& + \left. \frac{ve^{-4t}}{8} + \frac{3ve^{2t}}{8} \right) \partial t + \left( -\frac{v^2}{4} + \frac{u^2}{4} + \frac{u^2e^{-2t}}{2} + \frac{v^2e^{2t}}{2} \right. \\
& + \left. -\frac{uv}{2} - \frac{v^2e^{-2t}}{2} + \frac{u^2e^{-4t}}{4} + \frac{v^2e^{-4t}}{4} + \frac{uve^{-4t}}{2} \right) \partial u + \left( \frac{v^2e^{2t}}{2} - \frac{v^2}{2} \right) \partial v,
\end{aligned}$$

$$\begin{aligned}
X_{11} = & \left( -\frac{3u}{8} + \frac{5v}{8} - \frac{3ue^{-2t}}{8} - \frac{ue^{-4t}}{8} - \frac{ue^{2t}}{8} - \frac{ve^{-4t}}{8} \right. \\
& + \left. \frac{ve^{-2t}}{8} + \frac{3ve^{2t}}{8} \right) \partial t + \left( -\frac{u^2}{4} + \frac{v^2}{4} + \frac{uv}{2} + \frac{v^2e^{-2t}}{2} \right. \\
& + \left. \frac{v^2e^{2t}}{2} - \frac{u^2e^{-2t}}{2} - \frac{u^2e^{-4t}}{4} - \frac{v^2e^{-4t}}{4} - \frac{uve^{-4t}}{2} \right) \partial u + \left( \frac{v^2}{2} \right. \\
& + \left. \frac{v^2e^{2t}}{2} \right) \partial v
\end{aligned}$$

$$X_{12} = (1) \partial t,$$

$$X_{13} = \left( -\frac{e^{2t}}{4} - \frac{1}{2} - \frac{e^{-2t}}{4} \right) \partial t + \left( -\frac{u}{2} - \frac{ue^{-2t}}{2} - \frac{ve^{2t}}{2} - \frac{ve^{-2t}}{2} \right) \partial u + \left( -\frac{ve^{2t}}{2} - \frac{v}{2} \right) \partial v,$$

$$\begin{aligned}
X_{14} = & \left( \frac{u}{8} + \frac{v}{8} - \frac{3ve^{-2t}}{8} - \frac{ue^{-4t}}{8} - \frac{ue^{2t}}{8} - \frac{ve^{-4t}}{8} \right. \\
& + \left. \frac{ue^{-2t}}{8} + \frac{3ve^{2t}}{8} \right) \partial t + \left( -\frac{u^2}{4} + \frac{v^2}{4} + \frac{uv}{2} + \frac{u^2e^{-2t}}{2} \right. \\
& + \left. \frac{v^2e^{2t}}{2} - \frac{v^2e^{-2t}}{2} - \frac{u^2e^{-4t}}{4} - \frac{v^2e^{-4t}}{4} - \frac{uve^{-4t}}{2} \right) \partial u + \left( \frac{v^2}{2} \right. \\
& + \left. \frac{v^2e^{2t}}{2} \right) \partial v
\end{aligned}$$

$$X_{15} = \left( \frac{u}{2} - \frac{v}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2} \right) \partial t$$

$$\begin{aligned}
X_{16} = & \left( \frac{u^2}{4} + \frac{v^2}{4} + \frac{v^2e^{-2t}}{2} - \frac{uv}{2} - \frac{u^2e^{-2t}}{2} + \frac{u^2e^{-4t}}{4} \right. \\
& + \left. \frac{v^2e^{-4t}}{4} + \frac{uve^{-4t}}{2} \right) \partial t
\end{aligned}$$

$$X_{17} = \left( -\frac{1}{2} + \frac{e^{-2t}}{4} + \frac{e^{2t}}{4} \right) \partial t + \left( -\frac{u}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2} + \frac{ve^{2t}}{2} \right) \partial u + \left( \frac{ve^{2t}}{2} - \frac{v}{2} \right) \partial v,$$

$$X_{18} = \left( \frac{v}{2} - \frac{u}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2} \right) \partial t$$

$$\begin{aligned} X_{19} = & (u f_2(t) + v f_1(t) - v f_2(t) + f_3(t)) \partial t + (u f_3(t) + v f_3(t) \\ & + u^2 f_2(t) + v^2 f_1(t) - v^2 f_2(t) + uv f_1(t)) \partial u + (u f_3(t) + v f_3(t) \\ & + u^2 f_2(t) + v^2 f_1(t) - v^2 f_2(t) + uv f_1(t)) \partial v \end{aligned}$$

Some of the generators might contain the following arbitrary functions:

$$\begin{aligned} & f_1 \\ & f_2 \\ & f_3 \end{aligned}$$

The execution time of the script was:

0 hours 1 minutes 7 seconds.





## Chapter 5

# hydons\_model

Run 11\_03AM\_24\_January-2022

Degree in tangential ansätze: 2.  
The system of ODEs is given by:

$$\begin{aligned}\frac{dy_1}{dt} &= \frac{ty_1 + y_2^2}{-t^2 + y_1y_2}, \\ \frac{dy_2}{dt} &= \frac{ty_2 + y_1^2}{-t^2 + y_1y_2}.\end{aligned}$$

The calculated generators are:

$$X_1 = (t) \partial t + (y_1) \partial y_1 + (y_2) \partial y_2,$$

$$X_2 = (-t^2 f_1(t) + y_1 y_2 f_1(t)) \partial t + (y_2^2 f_1(t) + t y_1 f_1(t)) \partial y_1 + (y_1^2 f_1(t) + t y_2 f_1(t)) \partial y_2$$

Some of the generators might contain the following arbitrary functions:

$$f_1$$

The execution time of the script was:

0 hours 0 minutes 25 seconds.



# Chapter 6

## LV

Run 11\_10AM\_24\_January-2022

Degree in tangential ansätze: 2.  
The system of ODEs is given by:

$$\begin{aligned}\frac{du}{dt} &= u(1-v), \\ \frac{dv}{dt} &= av(u-1).\end{aligned}$$

The calculated generators are:

$$X_1 = (1) \partial t,$$

$$X_2 = \left(-\frac{1}{a}\right) \partial t,$$

$$X_3 = \left(\frac{f_1(t)}{a}\right) \partial t + \left(\frac{u f_1(t)}{a} - \frac{uv f_1(t)}{a}\right) \partial u + (uv f_1(t) - v f_1(t)) \partial v.$$

Some of the generators might contain the following arbitrary functions:

$$f_1$$

The execution time of the script was:

0 hours 0 minutes 36 seconds.