Summary of symmetry calculations

April 27, 2022

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DBH_{model}

$Run~01_27PM_01_February-2022$

Degree in tangential ansätze: 2. The system of ODEs is given by:

$$\begin{split} \frac{\mathrm{d}w_1}{\mathrm{d}t} &= -w_1w_2 - w_1w_3 + w_2w_3, \\ \frac{\mathrm{d}w_2}{\mathrm{d}t} &= -w_1w_2 + w_1w_3 - w_2w_3, \\ \frac{\mathrm{d}w_3}{\mathrm{d}t} &= w_1w_2 - w_1w_3 - w_2w_3. \end{split}$$

$$X_1 = (-t) \partial t + (w_1) \partial w_1 + (w_2) \partial w_2 + (w_3) \partial w_3,$$

$$X_2 = (1) \partial t$$
,

$$X_3 = (1) \partial t$$
,

$$X_4 = (t^2) \partial t + (1 - 2tw_1) \partial w_1 + (1 - 2tw_2) \partial w_2 + (1 + 2tw_3) \partial w_3$$

$$X_{5} = (f_{1}(t)) \partial t + (w_{2}w_{3} f_{1}(t) - w_{1}w_{2} f_{1}(t) - w_{1}w_{3} f_{1}(t)) \partial w_{1} + (w_{1}w_{3} f_{1}(t) - w_{1}w_{2} f_{1}(t) + -w_{2}w_{3} f_{1}(t)) \partial w_{2} + (w_{1}w_{2} f_{1}(t) - w_{1}w_{3} f_{1}(t) - w_{2}w_{3} f_{1}(t)) \partial w_{3}.$$

 f_1

The execution time of the script was:

0 hours 5 minutes 15 seconds.

Run 01_51PM_27_April-2022

Degree in tangential ansätze: 2. The system of ODEs is given by:

$$\frac{\mathrm{d}w_1}{\mathrm{d}t} = -w_1w_2 - w_1w_3 + w_2w_3,$$

$$\frac{\mathrm{d}w_2}{\mathrm{d}t} = -w_1w_2 + w_1w_3 - w_2w_3,$$

$$\frac{\mathrm{d}w_3}{\mathrm{d}t} = w_1w_2 - w_1w_3 - w_2w_3.$$

The calculated generators are:

$$X_1 = (1) \partial t$$
,

$$X_2 = (t^2) \partial t + (1 - 2tw_1) \partial w_1 + (1 - 2tw_2) \partial w_2 + (1 + 2tw_3) \partial w_3$$

$$X_3 = (-t) \partial t + (w_1) \partial w_1 + (w_2) \partial w_2 + (w_3) \partial w_3$$

$$X_4 = (1) \partial t$$
,

$$X_5 = (f_1(t)) \partial t + (w_2 w_3 f_1(t) - w_1 w_2 f_1(t) - w_1 w_3 f_1(t)) \partial w_1 + (w_1 w_3 f_1(t) - w_1 w_2 f_1(t) + -w_2 w_3 f_1(t)) \partial w_2 + (w_1 w_2 f_1(t) - w_1 w_3 f_1(t) - w_2 w_3 f_1(t)) \partial w_3.$$

Some of the generators might contain the following arbitrary functions:

 f_1

The execution time of the script was:

0 hours 3 minutes 34 seconds.

LV

$Run~01_28PM_01_February-2022$

Degree in tangential ansätze: 2. The system of ODEs is given by:

$$\frac{\mathrm{d}u}{\mathrm{d}t} = u (1 - v),$$

$$\frac{\mathrm{d}v}{\mathrm{d}t} = av (u - 1).$$

The calculated generators are:

$$X_1 = (1) \partial t$$
,

$$X_2 = (-1) \partial t$$
,

$$X_{3}=\left(\frac{\mathbf{f}_{1}\left(t\right)}{a}\right)\partial t+\left(\frac{u\,\mathbf{f}_{1}\left(t\right)}{a}-\frac{uv\,\mathbf{f}_{1}\left(t\right)}{a}\right)\partial u+\left(uv\,\mathbf{f}_{1}\left(t\right)-v\,\mathbf{f}_{1}\left(t\right)\right)\partial v.$$

Some of the generators might contain the following arbitrary functions:

 f_1

The execution time of the script was:

0 hours 0 minutes 41 seconds.

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$Run~01_52PM_27_April-2022$

Degree in tangential ansätze: 2. The system of ODEs is given by:

$$\frac{\mathrm{d}u}{\mathrm{d}t} = u (1 - v),$$

$$\frac{\mathrm{d}v}{\mathrm{d}t} = av (u - 1).$$

The calculated generators are:

$$X_1 = (1) \, \partial t,$$

$$X_2 = (1) \partial t$$
,

$$X_{3}=\left(\frac{\mathbf{f}_{1}\left(t\right)}{a}\right)\partial t+\left(\frac{u\,\mathbf{f}_{1}\left(t\right)}{a}-\frac{uv\,\mathbf{f}_{1}\left(t\right)}{a}\right)\partial u+\left(uv\,\mathbf{f}_{1}\left(t\right)-v\,\mathbf{f}_{1}\left(t\right)\right)\partial v.$$

Some of the generators might contain the following arbitrary functions:

 f_1

The execution time of the script was:

0 hours 0 minutes 27 seconds.

hydons_model

Run 01_20PM_01_February-2022

Degree in tangential ansätze: 2. The system of ODEs is given by:

$$\frac{\mathrm{d}y_1}{\mathrm{d}t} = \frac{ty_1 + y_2^2}{-t^2 + y_1 y_2},$$
$$\frac{\mathrm{d}y_2}{\mathrm{d}t} = \frac{ty_2 + y_1^2}{-t^2 + y_1 y_2}.$$

The calculated generators are:

$$X_1 = (t) \partial t + (y_1) \partial y_1 + (y_2) \partial y_2,$$

$$X_{2}=\left(-t^{2} \operatorname{f}_{1}\left(t\right)+y_{1} y_{2} \operatorname{f}_{1}\left(t\right)\right) \partial t+\left(y_{2}^{2} \operatorname{f}_{1}\left(t\right)+t y_{1} \operatorname{f}_{1}\left(t\right)\right) \partial y_{1}+\left(y_{1}^{2} \operatorname{f}_{1}\left(t\right)+t y_{2} \operatorname{f}_{1}\left(t\right)\right) \partial y_{2}$$

Some of the generators might contain the following arbitrary functions:

 f_1

The execution time of the script was:

0 hours 0 minutes 27 seconds.

Run 01_44PM_27_April-2022

Degree in tangential ansätze: 2. The system of ODEs is given by:

$$\frac{\mathrm{d}y_1}{\mathrm{d}t} = \frac{ty_1 + y_2^2}{-t^2 + y_1 y_2},$$
$$\frac{\mathrm{d}y_2}{\mathrm{d}t} = \frac{ty_2 + y_1^2}{-t^2 + y_1 y_2}.$$

The calculated generators are:

$$X_1 = (t) \partial t + (y_1) \partial y_1 + (y_2) \partial y_2,$$

$$X_{2} = \left(-t^{2} f_{1}\left(t\right) + y_{1} y_{2} f_{1}\left(t\right)\right) \partial t + \left(y_{2}^{2} f_{1}\left(t\right) + t y_{1} f_{1}\left(t\right)\right) \partial y_{1} + \left(y_{1}^{2} f_{1}\left(t\right) + t y_{2} f_{1}\left(t\right)\right) \partial y_{2}$$

Some of the generators might contain the following arbitrary functions:

 f_1

The execution time of the script was:

0 hours 0 minutes 41 seconds.

SIR

$Run~01_28PM_01_February-2022$

Degree in tangential ansätze: 1. The system of ODEs is given by:

$$\frac{\mathrm{d}S}{\mathrm{d}t} = -ISr,$$

$$\frac{\mathrm{d}I}{\mathrm{d}t} = ISr - Ia,$$

$$\frac{\mathrm{d}R}{\mathrm{d}t} = Ia.$$

The calculated generators are:

$$X_1 = (I + R + S) \partial t$$

$$X_2 = (1) \partial R$$
,

$$X_3 = (I + R + S) \partial R$$

$$X_4 = (1) \partial t$$
.

The execution time of the script was:

0 hours 0 minutes 24 seconds.

$Run~01_31PM_01_February-2022$

Degree in tangential ansätze: 2. The system of ODEs is given by:

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$$\frac{\mathrm{d}S}{\mathrm{d}t} = -ISr,$$

$$\frac{\mathrm{d}I}{\mathrm{d}t} = ISr - Ia,$$

$$\frac{\mathrm{d}R}{\mathrm{d}t} = Ia.$$

The calculated generators are:

$$X_1 = (1) \partial R,$$

$$X_2 = \left(\frac{I^2}{2} + \frac{R^2}{2} + \frac{S^2}{2} + IR + IS + RS\right)\partial t$$

$$X_3 = (I + R + S) \partial t$$

$$X_4 = (1) \partial t$$
,

$$X_5 = (IS) \partial S + \left(-IS + \frac{Ia}{r}\right) \partial I + \left(\frac{Ra}{r} + \frac{Sa}{r}\right) \partial R$$

$$X_6 = \left(-\frac{1}{a}\right)\partial t + \left(\frac{ISr}{a}\right)\partial S + \left(I - \frac{ISr}{a}\right)\partial I + (R+S)\,\partial R$$

$$X_{7} = \left(\frac{\mathbf{f}_{1}\left(t\right)}{a}\right)\partial t + \left(-\frac{ISr\,\mathbf{f}_{1}\left(t\right)}{a}\right)\partial S + \left(\frac{ISr\,\mathbf{f}_{1}\left(t\right)}{a} - I\,\mathbf{f}_{1}\left(t\right)\right)\partial I + \left(I\,\mathbf{f}_{1}\left(t\right)\right)\partial R.$$

Some of the generators might contain the following arbitrary functions:

 f_1

WARNING: Some of the calculated generators did not satisfy the linearised symmetry conditions. Thus, the presented list here is not complete and consists exclusively of the calculated generators that satisfy the linearised symmetry conditions.

The execution time of the script was:

0 hours 2 minutes 58 seconds.

$Run~01_52PM_27_April-2022$

Degree in tangential ansätze: 1. The system of ODEs is given by:

$$\frac{\mathrm{d}S}{\mathrm{d}t} = -ISr,$$

$$\frac{\mathrm{d}I}{\mathrm{d}t} = ISr - Ia,$$

$$\frac{\mathrm{d}R}{\mathrm{d}t} = Ia.$$

The calculated generators are:

$$X_1 = (1) \, \partial R,$$

$$X_2 = (1) \partial t$$
,

$$X_3 = (I + R + S) \partial t$$

$$X_4 = (I + R + S) \partial R$$

The execution time of the script was:

0 hours 0 minutes 14 seconds.

$Run~01_54PM_27_April-2022$

Degree in tangential ansätze: 2. The system of ODEs is given by:

$$\frac{\mathrm{d}S}{\mathrm{d}t} = -ISr,$$

$$\frac{\mathrm{d}I}{\mathrm{d}t} = ISr - Ia,$$

$$\frac{\mathrm{d}R}{\mathrm{d}t} = Ia.$$

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$$X_1 = (1) \partial R$$
,

$$X_2 = \left(\frac{I^2}{2} + \frac{R^2}{2} + \frac{S^2}{2} + IR + IS + RS\right) \partial t$$

$$X_3 = \left(\frac{I^2}{2} + \frac{R^2}{2} + \frac{S^2}{2} + IR + IS + RS\right) \partial R$$

$$X_4 = (1) \partial t$$
,

$$X_5 = \left(-\frac{1}{r}\right) \partial t,$$

$$X_6 = (I + R + S) \partial t$$

$$X_{7} = \left(\frac{\mathbf{f}_{1}\left(t\right)}{a}\right)\partial t + \left(-\frac{ISr\,\mathbf{f}_{1}\left(t\right)}{a}\right)\partial S + \left(\frac{ISr\,\mathbf{f}_{1}\left(t\right)}{a} - I\,\mathbf{f}_{1}\left(t\right)\right)\partial I + \left(I\,\mathbf{f}_{1}\left(t\right)\right)\partial R.$$

Some of the generators might contain the following arbitrary functions:

 f_1

WARNING: Some of the calculated generators did not satisfy the linearised symmetry conditions. Thus, the presented list here is not complete and consists exclusively of the calculated generators that satisfy the linearised symmetry conditions.

The execution time of the script was:

0 hours 2 minutes 5 seconds.

linear_model

$Run~01_21PM_01_February-2022$

Degree in tangential ansätze: 1. The system of ODEs is given by:

$$\frac{\mathrm{d}u}{\mathrm{d}t} = u + v,$$
$$\frac{\mathrm{d}v}{\mathrm{d}t} = u + v.$$

$$X_1 = \left(\frac{1}{2} + \frac{e^{2t}}{2}\right)\partial u + \left(\frac{e^{2t}}{2} - \frac{1}{2}\right)\partial v,$$

$$X_{2} = \left(-\frac{e^{2t}}{4} + \frac{e^{-2t}}{4}\right) \partial t + \left(\frac{u}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2} - \frac{ve^{2t}}{2}\right) \partial u$$

$$+ \left(\frac{v}{2} - \frac{ve^{2t}}{2}\right) \partial v$$

$$X_{3} = \left(\frac{v}{2} - \frac{u}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2}\right) \partial t$$

$$X_{4} = \left(\frac{u}{2} - \frac{v}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2}\right) \partial t$$

$$X_{5} = (1) \partial t,$$

$$X_6 = \left(\frac{e^{2t}}{2} - \frac{1}{2}\right)\partial u + \left(\frac{1}{2} + \frac{e^{2t}}{2}\right)\partial v$$

$$X_7 = \left(-\frac{1}{2} + \frac{e^{-2t}}{4} + \frac{e^{2t}}{4}\right) \partial t + \left(-\frac{u}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2} + \frac{ve^{-2t}}{2}\right) \partial u + \left(\frac{ve^{2t}}{2} - \frac{v}{2}\right) \partial v,$$

$$X_8 = \left(-\frac{e^{2t}}{4} - \frac{1}{2} - \frac{e^{-2t}}{4}\right)\partial t + \left(-\frac{u}{2} - \frac{ue^{-2t}}{2} - \frac{ve^{2t}}{2} - \frac{ve^{-2t}}{2}\right)\partial u + \left(-\frac{ve^{2t}}{2} - \frac{v}{2}\right)\partial v,$$

$$X_{9} = \left(\frac{e^{2t}}{4} - \frac{e^{-2t}}{4}\right) \partial t + \left(\frac{u}{2} + \frac{ve^{2t}}{2} - \frac{ue^{-2t}}{2} - \frac{ve^{-2t}}{2}\right) \partial u + \left(\frac{v}{2} + \frac{ve^{2t}}{2}\right) \partial v$$

$$X_{10} = (f_1(t)) \partial t + (u f_1(t) + v f_1(t)) \partial u + (u f_1(t) + v f_1(t)) \partial v$$

 f_1

The execution time of the script was:

0 hours 0 minutes 14 seconds.

Run $01_22PM_01_February-2022$

Degree in tangential ansätze: 2. The system of ODEs is given by:

$$\frac{\mathrm{d}u}{\mathrm{d}t} = u + v,$$
$$\frac{\mathrm{d}v}{\mathrm{d}t} = u + v.$$

$$X_1 = \left(-\frac{e^{2t}}{4} + \frac{e^{-2t}}{4}\right)\partial t + \left(\frac{u}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2} - \frac{ve^{2t}}{2}\right)\partial u$$
$$+ \left(\frac{v}{2} - \frac{ve^{2t}}{2}\right)\partial v$$

$$X_2 = \left(\frac{1}{2} + \frac{e^{2t}}{2}\right)\partial u + \left(\frac{e^{2t}}{2} - \frac{1}{2}\right)\partial v,$$

$$X_3 = (1) \partial t$$

$$X_4 = \left(\frac{u}{2} - \frac{v}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2}\right)\partial t$$

$$X_5 = \left(-\frac{1}{2} + \frac{e^{-2t}}{4} + \frac{e^{2t}}{4}\right)\partial t + \left(-\frac{u}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2} + \frac{ve^{-2t}}{2} + \frac{ve^{-2t}}{2}\right)\partial u + \left(\frac{ve^{2t}}{2} - \frac{v}{2}\right)\partial v,$$

$$X_6 = \left(\frac{u^2}{4} + \frac{v^2}{4} + \frac{v^2 e^{-2t}}{2} - \frac{uv}{2} - \frac{u^2 e^{-2t}}{2} + \frac{u^2 e^{-4t}}{4} + \frac{v^2 e^{-4t}}{4} + \frac{uv e^{-4t}}{2}\right) \partial t$$

$$X_7 = \left(-\frac{3v}{8} + \frac{u}{8} - \frac{3ve^{2t}}{8} - \frac{ue^{-4t}}{8} - \frac{ue^{-2t}}{8} - \frac{ve^{-4t}}{8} + \frac{ve^{-4t}}{8}\right) + \left(\frac{u^2}{4} - \frac{u^2e^{-4t}}{4} - \frac{uv}{2} - \frac{uve^{-4t}}{2} - \frac{v^2e^{2t}}{2} - \frac{v^2}{4} - \frac{v^2e^{-4t}}{4}\right) \partial u + \left(-\frac{v^2e^{2t}}{2} - \frac{v^2}{2}\right) \partial v,$$

$$X_8 = \left(\frac{e^{2t}}{2} - \frac{1}{2}\right)\partial u + \left(\frac{1}{2} + \frac{e^{2t}}{2}\right)\partial v$$

$$\begin{split} X_9 &= \left(\frac{u}{8} + \frac{v}{8} - \frac{3ve^{-2t}}{8} - \frac{ue^{-4t}}{8} - \frac{ue^{2t}}{8} - \frac{ve^{-4t}}{8} \right. \\ &+ \frac{ue^{-2t}}{8} + \frac{3ve^{2t}}{8} \right) \partial t + \left(-\frac{u^2}{4} + \frac{v^2}{4} + \frac{uv}{2} + \frac{u^2e^{-2t}}{2} \right. \\ &+ \frac{v^2e^{2t}}{2} - \frac{v^2e^{-2t}}{2} - \frac{u^2e^{-4t}}{4} - \frac{v^2e^{-4t}}{4} - \frac{uve^{-4t}}{2} \right) \partial u + \left(\frac{v^2}{2} + \frac{v^2e^{2t}}{2} \right) \partial v \end{split}$$

$$\begin{split} X_{10} &= \left(-\frac{u}{8} + \frac{3v}{8} - \frac{3ve^{2t}}{8} - \frac{ue^{-2t}}{8} - \frac{ve^{-2t}}{8} + \frac{ue^{-4t}}{8} \right. \\ &+ \left. \frac{ue^{2t}}{8} + \frac{ve^{-4t}}{8} \right) \partial t + \left(-\frac{u^2}{4} + \frac{v^2}{4} + \frac{uv}{2} - \frac{v^2e^{2t}}{2} \right. \\ &+ \left. \frac{u^2e^{-4t}}{4} + \frac{v^2e^{-4t}}{4} + \frac{uve^{-4t}}{2} \right) \partial u + \left(\frac{v^2}{2} - \frac{v^2e^{2t}}{2} \right) \partial v \end{split}$$

$$\begin{split} X_{11} &= \left(-\frac{3u}{8} + \frac{5v}{8} - \frac{3ue^{-2t}}{8} - \frac{ue^{-4t}}{8} - \frac{ue^{2t}}{8} - \frac{ve^{-4t}}{8} \right. \\ &+ \left. \frac{ve^{-2t}}{8} + \frac{3ve^{2t}}{8} \right) \partial t + \left(-\frac{u^2}{4} + \frac{v^2}{4} + \frac{uv}{2} + \frac{v^2e^{-2t}}{2} \right. \\ &+ \left. \frac{v^2e^{2t}}{2} - \frac{u^2e^{-2t}}{2} - \frac{u^2e^{-4t}}{4} - \frac{v^2e^{-4t}}{4} - \frac{uve^{-4t}}{2} \right) \partial u + \left(\frac{v^2}{2} + \frac{v^2e^{2t}}{2} \right) \partial v \end{split}$$

$$X_{12} = \left(\frac{e^{2t}}{4} - \frac{e^{-2t}}{4}\right) \partial t + \left(\frac{u}{2} + \frac{ve^{2t}}{2} - \frac{ue^{-2t}}{2} - \frac{ve^{-2t}}{2}\right) \partial u + \left(\frac{v}{2} + \frac{ve^{2t}}{2}\right) \partial v$$

$$X_{13} = \left(-\frac{5v}{8} + \frac{3u}{8} - \frac{3ue^{-2t}}{8} - \frac{ue^{2t}}{8} + \frac{ue^{-4t}}{8} + \frac{ve^{-4t}}{8} + \frac{ve^{-2t}}{8} + \frac{3ve^{2t}}{8}\right) \partial t + \left(-\frac{v^2}{4} + \frac{u^2}{4} + \frac{v^2e^{-2t}}{2} + \frac{v^2e^{2t}}{2} + \frac{v^2e^{-2t}}{2} + \frac{u^2e^{-2t}}{2} + \frac{u^2e^{-4t}}{4} + \frac{v^2e^{-4t}}{4} + \frac{uve^{-4t}}{2}\right) \partial u + \left(\frac{v^2e^{2t}}{2} - \frac{v^2}{2}\right) \partial v,$$

$$X_{14} = \left(\frac{u^2}{4} + \frac{v^2}{4} + \frac{u^2 e^{-2t}}{2} - \frac{uv}{2} - \frac{v^2 e^{-2t}}{2} + \frac{u^2 e^{-4t}}{4} + \frac{v^2 e^{-4t}}{4} + \frac{uv e^{-4t}}{2}\right) \partial t$$

$$X_{15} = \left(-\frac{e^{2t}}{4} - \frac{1}{2} - \frac{e^{-2t}}{4}\right)\partial t + \left(-\frac{u}{2} - \frac{ue^{-2t}}{2} - \frac{ve^{2t}}{2} - \frac{ve^{-2t}}{2}\right)\partial u + \left(-\frac{ve^{2t}}{2} - \frac{v}{2}\right)\partial v,$$

$$X_{16} = \left(-\frac{u^2}{4} - \frac{v^2}{4} + \frac{uv}{2} + \frac{u^2e^{-4t}}{4} + \frac{v^2e^{-4t}}{4} + \frac{uve^{-4t}}{2}\right)\partial t$$

$$\begin{split} X_{17} &= \left(-\frac{u}{8} - \frac{v}{8} - \frac{3ve^{-2t}}{8} - \frac{ue^{2t}}{8} + \frac{ue^{-4t}}{8} + \frac{ue^{-2t}}{8} \right. \\ &+ \left. \frac{ve^{-4t}}{8} + \frac{3ve^{2t}}{8} \right) \partial t + \left(-\frac{v^2}{4} + \frac{u^2}{4} + \frac{u^2e^{-2t}}{2} + \frac{v^2e^{2t}}{2} \right. \\ &+ \left. -\frac{uv}{2} - \frac{v^2e^{-2t}}{2} + \frac{u^2e^{-4t}}{4} + \frac{v^2e^{-4t}}{4} + \frac{uve^{-4t}}{2} \right) \partial u + \left(\frac{v^2e^{2t}}{2} - \frac{v^2}{2} \right) \partial v, \end{split}$$

$$X_{18} = \left(\frac{v}{2} - \frac{u}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2}\right)\partial t$$

$$X_{19} = (u f_2(t) + v f_1(t) - v f_2(t) + f_3(t)) \partial t + (u f_3(t) + v f_3(t) + u^2 f_2(t) + v^2 f_1(t) - v^2 f_2(t) + uv f_1(t)) \partial u + (u f_3(t) + v f_3(t) + u^2 f_2(t) + v^2 f_1(t) - v^2 f_2(t) + uv f_1(t)) \partial v$$

 f_1 f_2 f_3

The execution time of the script was:

0 hours 1 minutes 10 seconds.

Run 01_44PM_27_April-2022

Degree in tangential ansätze: 1. The system of ODEs is given by:

$$\frac{\mathrm{d}u}{\mathrm{d}t} = u + v,$$
$$\frac{\mathrm{d}v}{\mathrm{d}t} = u + v.$$

$$X_{1} = \left(\frac{u}{2} - \frac{v}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2}\right) \partial t$$

$$X_{2} = \left(-\frac{1}{2} + \frac{e^{-2t}}{4} + \frac{e^{2t}}{4}\right) \partial t + \left(-\frac{u}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2} + \frac{ve^{-2t}}{2}\right) \partial u + \left(\frac{ve^{2t}}{2} - \frac{v}{2}\right) \partial v,$$

$$X_3 = \left(-\frac{e^{2t}}{4} - \frac{1}{2} - \frac{e^{-2t}}{4}\right)\partial t + \left(-\frac{u}{2} - \frac{ue^{-2t}}{2} - \frac{ve^{2t}}{2} - \frac{ve^{-2t}}{2}\right)\partial u + \left(-\frac{ve^{2t}}{2} - \frac{v}{2}\right)\partial v,$$

$$X_4 = \left(\frac{e^{2t}}{2} - \frac{1}{2}\right)\partial u + \left(\frac{1}{2} + \frac{e^{2t}}{2}\right)\partial v$$

$$X_5 = (1) \partial t$$
,

$$X_6 = \left(\frac{v}{2} - \frac{u}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2}\right)\partial t$$

$$X_7 = \left(\frac{e^{2t}}{4} - \frac{e^{-2t}}{4}\right) \partial t + \left(\frac{u}{2} + \frac{ve^{2t}}{2} - \frac{ue^{-2t}}{2} - \frac{ve^{-2t}}{2}\right) \partial u + \left(\frac{v}{2} + \frac{ve^{2t}}{2}\right) \partial v$$

$$X_{8} = \left(-\frac{e^{2t}}{4} + \frac{e^{-2t}}{4}\right) \partial t + \left(\frac{u}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2} - \frac{ve^{2t}}{2}\right) \partial u + \left(\frac{v}{2} - \frac{ve^{2t}}{2}\right) \partial v$$

$$X_9 = \left(\frac{1}{2} + \frac{e^{2t}}{2}\right)\partial u + \left(\frac{e^{2t}}{2} - \frac{1}{2}\right)\partial v,$$

$$X_{10} = (f_1(t)) \partial t + (u f_1(t) + v f_1(t)) \partial u + (u f_1(t) + v f_1(t)) \partial v$$

 f_1

The execution time of the script was:

0 hours 0 minutes 11 seconds.

$Run~01_48PM_27_April-2022$

Degree in tangential ansätze: 2. The system of ODEs is given by:

$$\frac{\mathrm{d}u}{\mathrm{d}t} = u + v,$$
$$\frac{\mathrm{d}v}{\mathrm{d}t} = u + v.$$

$$\begin{split} X_1 &= \left(-\frac{5v}{8} + \frac{3u}{8} - \frac{3ue^{-2t}}{8} - \frac{ue^{2t}}{8} + \frac{ue^{-4t}}{8} + \frac{ve^{-4t}}{8} \right. \\ &+ \left. \frac{ve^{-2t}}{8} + \frac{3ve^{2t}}{8} \right) \partial t + \left(-\frac{v^2}{4} + \frac{u^2}{4} + \frac{v^2e^{-2t}}{2} + \frac{v^2e^{2t}}{2} \right. \\ &+ \left. -\frac{uv}{2} - \frac{u^2e^{-2t}}{2} + \frac{u^2e^{-4t}}{4} + \frac{v^2e^{-4t}}{4} + \frac{uve^{-4t}}{2} \right) \partial u + \left(\frac{v^2e^{2t}}{2} - \frac{v^2}{2} \right) \partial v, \end{split}$$

$$\begin{split} X_2 = & \left(\frac{u^2}{4} + \frac{v^2}{4} + \frac{u^2 e^{-2t}}{2} - \frac{uv}{2} - \frac{v^2 e^{-2t}}{2} + \frac{u^2 e^{-4t}}{4} \right. \\ & + \left. \frac{v^2 e^{-4t}}{4} + \frac{uv e^{-4t}}{2} \right) \partial t \end{split}$$

$$\begin{split} X_3 &= \left(-\frac{3u}{8} + \frac{5v}{8} - \frac{3ue^{-2t}}{8} - \frac{ue^{-4t}}{8} - \frac{ue^{2t}}{8} - \frac{ve^{-4t}}{8} \right. \\ &+ \frac{ve^{-2t}}{8} + \frac{3ve^{2t}}{8}\right) \partial t + \left(-\frac{u^2}{4} + \frac{v^2}{4} + \frac{uv}{2} + \frac{v^2e^{-2t}}{2} \right. \\ &+ \frac{v^2e^{2t}}{2} - \frac{u^2e^{-2t}}{2} - \frac{u^2e^{-4t}}{4} - \frac{v^2e^{-4t}}{4} - \frac{uve^{-4t}}{2}\right) \partial u + \left(\frac{v^2}{2} + \frac{v^2e^{2t}}{2}\right) \partial v \end{split}$$

$$\begin{split} X_4 &= \left(\frac{u}{8} + \frac{v}{8} - \frac{3ve^{-2t}}{8} - \frac{ue^{-4t}}{8} - \frac{ue^{2t}}{8} - \frac{ve^{-4t}}{8} \right. \\ &\quad + \frac{ue^{-2t}}{8} + \frac{3ve^{2t}}{8} \left. \right) \partial t + \left(-\frac{u^2}{4} + \frac{v^2}{4} + \frac{uv}{2} + \frac{u^2e^{-2t}}{2} \right. \\ &\quad + \frac{v^2e^{2t}}{2} - \frac{v^2e^{-2t}}{2} - \frac{u^2e^{-4t}}{4} - \frac{v^2e^{-4t}}{4} - \frac{uve^{-4t}}{2} \right) \partial u + \left(\frac{v^2}{2} + \frac{v^2e^{-2t}}{2} \right) \partial v \end{split}$$

$$X_5 = \left(\frac{v}{2} - \frac{u}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2}\right)\partial t$$

$$\begin{split} X_6 &= \left(-\frac{u}{8} - \frac{v}{8} - \frac{3ve^{-2t}}{8} - \frac{ue^{2t}}{8} + \frac{ue^{-4t}}{8} + \frac{ue^{-2t}}{8} \right. \\ &+ \left. \frac{ve^{-4t}}{8} + \frac{3ve^{2t}}{8} \right) \partial t + \left(-\frac{v^2}{4} + \frac{u^2}{4} + \frac{u^2e^{-2t}}{2} + \frac{v^2e^{2t}}{2} \right. \\ &+ \left. -\frac{uv}{2} - \frac{v^2e^{-2t}}{2} + \frac{u^2e^{-4t}}{4} + \frac{v^2e^{-4t}}{4} + \frac{uve^{-4t}}{2} \right) \partial u + \left(\frac{v^2e^{2t}}{2} - \frac{v^2}{2} \right) \partial v, \end{split}$$

$$X_7 = \left(\frac{u}{2} - \frac{v}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2}\right) \partial t$$

$$X_8 = \left(-\frac{1}{2} + \frac{e^{-2t}}{4} + \frac{e^{2t}}{4}\right) \partial t + \left(-\frac{u}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2} + \frac{ve^{-2t}}{2}\right) \partial u + \left(\frac{ve^{2t}}{2} - \frac{v}{2}\right) \partial v,$$

$$X_{9} = \left(-\frac{3v}{8} + \frac{u}{8} - \frac{3ve^{2t}}{8} - \frac{ue^{-4t}}{8} - \frac{ue^{-2t}}{8} - \frac{ve^{-4t}}{8}\right) + \left(-\frac{ve^{-2t}}{8} + \frac{ue^{2t}}{8}\right) \partial t + \left(\frac{u^{2}}{4} - \frac{u^{2}e^{-4t}}{4} - \frac{uv}{2} - \frac{uve^{-4t}}{2} - \frac{v^{2}e^{2t}}{2} - \frac{v^{2}e^{-4t}}{4}\right) \partial u + \left(-\frac{v^{2}e^{2t}}{2} - \frac{v^{2}}{2}\right) \partial v,$$

$$X_{10} = \left(\frac{1}{2} + \frac{e^{2t}}{2}\right)\partial u + \left(\frac{e^{2t}}{2} - \frac{1}{2}\right)\partial v,$$

$$X_{11} = (1) \partial t$$
,

$$\begin{split} X_{12} = & \left(\frac{e^{2t}}{4} - \frac{e^{-2t}}{4}\right) \partial t + \left(\frac{u}{2} + \frac{ve^{2t}}{2} - \frac{ue^{-2t}}{2} - \frac{ve^{-2t}}{2}\right) \partial u + \left(\frac{v}{2} + \frac{ve^{2t}}{2}\right) \partial v \end{split}$$

$$X_{13} = \left(\frac{e^{2t}}{2} - \frac{1}{2}\right)\partial u + \left(\frac{1}{2} + \frac{e^{2t}}{2}\right)\partial v$$

$$X_{14} = \left(-\frac{e^{2t}}{4} - \frac{1}{2} - \frac{e^{-2t}}{4}\right)\partial t + \left(-\frac{u}{2} - \frac{ue^{-2t}}{2} - \frac{ve^{2t}}{2} - \frac{ve^{-2t}}{2}\right)\partial u + \left(-\frac{ve^{2t}}{2} - \frac{v}{2}\right)\partial v,$$

$$X_{15} = \left(-\frac{e^{2t}}{4} + \frac{e^{-2t}}{4}\right)\partial t + \left(\frac{u}{2} + \frac{ue^{-2t}}{2} + \frac{ve^{-2t}}{2} - \frac{ve^{2t}}{2}\right)\partial u + \left(\frac{v}{2} - \frac{ve^{2t}}{2}\right)\partial v$$

$$\begin{split} X_{16} &= \left(-\frac{u}{8} + \frac{3v}{8} - \frac{3ve^{2t}}{8} - \frac{ue^{-2t}}{8} - \frac{ve^{-2t}}{8} + \frac{ue^{-4t}}{8} \right. \\ &+ \left. \frac{ue^{2t}}{8} + \frac{ve^{-4t}}{8} \right) \partial t + \left(-\frac{u^2}{4} + \frac{v^2}{4} + \frac{uv}{2} - \frac{v^2e^{2t}}{2} \right. \\ &+ \left. \frac{u^2e^{-4t}}{4} + \frac{v^2e^{-4t}}{4} + \frac{uve^{-4t}}{2} \right) \partial u + \left(\frac{v^2}{2} - \frac{v^2e^{2t}}{2} \right) \partial v \end{split}$$

$$\begin{split} X_{17} = & \left(\frac{u^2}{4} + \frac{v^2}{4} + \frac{v^2 e^{-2t}}{2} - \frac{uv}{2} - \frac{u^2 e^{-2t}}{2} + \frac{u^2 e^{-4t}}{4} + \frac{v^2 e^{-4t}}{4} + \frac{uv e^{-4t}}{2} \right) \partial t \end{split}$$

$$X_{18} = \left(-\frac{u^2}{4} - \frac{v^2}{4} + \frac{uv}{2} + \frac{u^2e^{-4t}}{4} + \frac{v^2e^{-4t}}{4} + \frac{uve^{-4t}}{2}\right)\partial t$$

$$X_{19} = (u f_2(t) + v f_1(t) - v f_2(t) + f_3(t)) \partial t + (u f_3(t) + v f_3(t) + u^2 f_2(t) + v^2 f_1(t) - v^2 f_2(t) + uv f_1(t)) \partial u + (u f_3(t) + v f_3(t) + u^2 f_2(t) + v^2 f_1(t) - v^2 f_2(t) + uv f_1(t)) \partial v$$

 f_1 f_2 f_3

The execution time of the script was:

0 hours 3 minutes 19 seconds.

Brusselator

Run $01_31PM_01_February-2022$

Degree in tangential ansätze: 1. The system of ODEs is given by:

$$\frac{\mathrm{d}u}{\mathrm{d}t} = au^2v - u(b+1) + 1,$$

$$\frac{\mathrm{d}v}{\mathrm{d}t} = -au^2v + bu.$$

The calculated generators are:

$$X_1 = (1) \partial t$$
.

The execution time of the script was:

0 hours 0 minutes 6 seconds.

$Run~01_54PM_27_April-2022$

Degree in tangential ansätze: 1. The system of ODEs is given by:

$$\frac{\mathrm{d}u}{\mathrm{d}t} = au^2v - u(b+1) + 1,$$

$$\frac{\mathrm{d}v}{\mathrm{d}t} = -au^2v + bu.$$

$$X_1 = (1) \partial t$$
.

The execution time of the script was:

0 hours 0 minutes 4 seconds.