

HW Jan 31, Johannes Byle

$$\mathbf{3.14} \quad m\dot{v} = -\dot{m}v_{ex} + F^{ext}$$

$$\dot{v} = \frac{kv_{ex}}{m} - \frac{b}{m}v$$

$$v = e^{-\frac{b}{m}t} \left(\int e^{\frac{b}{m}t} \frac{kv_{ex}}{m} dt + C \right)$$

$$v = \frac{kv_{ex}}{m} e^{-\frac{b}{m}t} \left(\int e^{\frac{b}{m}t} dt + C \right)$$

$$v = \frac{kv_{ex}}{m} e^{-\frac{b}{m}t} \left(\frac{m}{b} e^{\frac{b}{m}t} + C \right)$$

$$v(0) = \frac{kv_{ex}}{m} \left(\frac{m}{b} + C \right) = 0$$

$$C = -\frac{m}{b}$$

$$v = \frac{kv_{ex}}{m} e^{-\frac{b}{m}t} \left(\frac{m}{b} e^{\frac{b}{m}t} - \frac{m}{b} \right)$$

$$v = \frac{kv_{ex}}{b} \left(1 - e^{-\frac{b}{m}t} \right)$$

$$v = \frac{kv_{ex}}{b} \left(1 - \left(\frac{m}{m_0} \right)^{\frac{b}{m}} \right)$$

$$\mathbf{3.21} \quad \theta = \frac{\pi}{2}$$

$$r = \frac{1}{M} \int_0^\theta \int_0^R r \sin\theta r dr d\theta$$

$$r = \frac{4}{3\pi} R$$

$$\mathbf{3.25} \quad L = mr^2\omega$$

$$L_1 = L_2 = mr_1^2\omega_1 = mr_2^2\omega_2$$

$$\omega_2 = \frac{r_1^2\omega_1}{r_2^2}$$

$$\mathbf{3.34} \quad t = \frac{2v_0}{g} = \frac{n2\pi}{\omega_0}$$

$$v_0 = \frac{n\pi g}{\omega_0}$$