# DATA STRUCTURES AND ALGORITHM



- To understand application of a graph theory
- To apply the concept of Depth First Search and Breadth First Search

GRAPH is a way of representing relationships that exist between pairs of objects.

Graphs Application

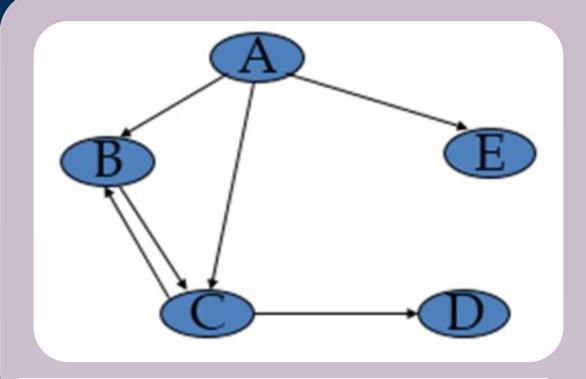
- Computer networks
- Electronic circuits
- Engineering
- Geography
- Solving games and puzzles
- Transportation networks

A graph is a set of objects, called **vertices**, together with a collection of pairwise connections between them.

- Any vertex may be connected to any other, these connections are called edges.
- Graph G is simply a set V of vertices and a collection E of pairs of vertices from V, called edges
   A graph G = (V,E) is composed of:
  - V → set of vertices
  - E -> set of edges connecting the vertices in V
- An edge e = (u, v) is a pair of vertices

DIRECTED GRAPH	UNDIRECTED GRAPH
An edge (u,v) is said to be directed from u to v if the pair (u,v) is ordered, with u preceding v.	<ul> <li>When the edges in a graph have no direction, the graph is called undirected</li> </ul>
When the edges in a graph have a direction, the graph is called directed graph / digraph.	<ul> <li>An edge (u,v) is said to be undirected if the pair (u,v) is not ordered.</li> </ul>
<ul> <li>This kind of graph contains ordered pair of vertices</li> </ul>	<ul> <li>Such edges are undirected because of a symmetric</li> </ul>

relation;



B

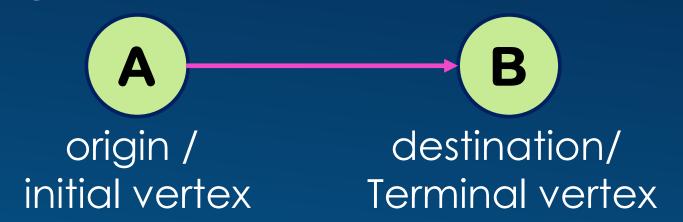
V = {A, B, C, D, E} E = {(A,B), (A,C), (A,E), (B,C), (C,B), (C,D)}

DIRECTED GRAPH

V = {A, B, C, D, E} E = {(A,B), (A,C), (A,E), (B,A), (B,C), (C,A),(C,B), (C,D), (D,C), (E,A) } UNDIRECTED GRAPH

#### **BASIC TERMINOLOGIES**

If an edge is directed, its first endpoint is its origin and the other is the destination of the edge.



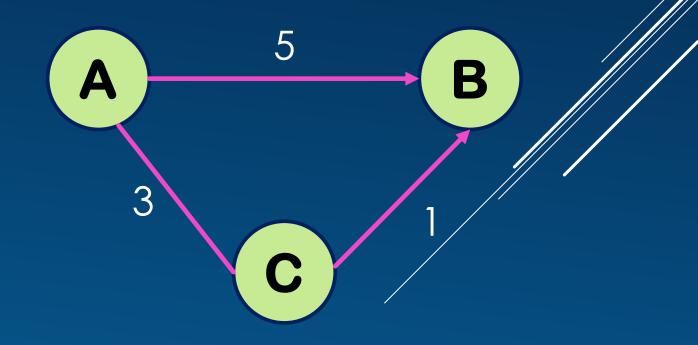
#### **BASIC TERMINOLOGIES**

### Weighted Graph

Every edge is assigned some value which is greater than or equal to zero.

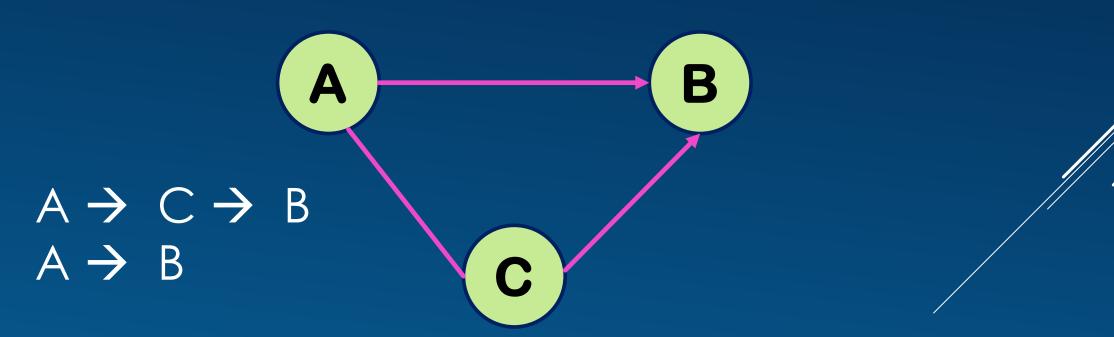
#### Examples:

- ✓ distance
- √ time
- ✓ cost
- ✓ capacity



#### **BASIC TERMINOLOGIES**

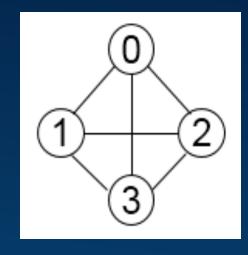
Path in a graph is a series of edges, none repeated, that can be traversed in order to travel from one vertex to another in a graph.



## BASIC TERMINOLOGIES

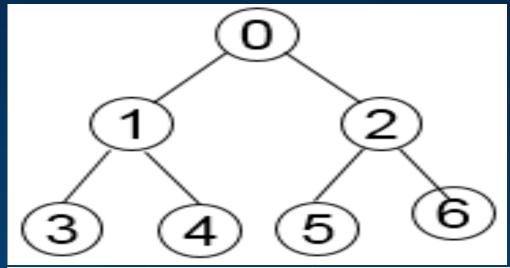
Degree of a vertex v, denoted deg(v), is the number of incident edges of v.

The *in-degree* and *out-degree* of a vertex v are the number of the incoming and outgoing edges of v, and are denoted indeg(v) and outdeg(v), respectively

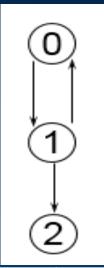


Vertices	In-	Out-		
vertices	Degree	Degree		
0	3	3		
1	3	3		
2	3	3		
3	3	3		

# BINARY SEARCH TREE (BST) acyclic



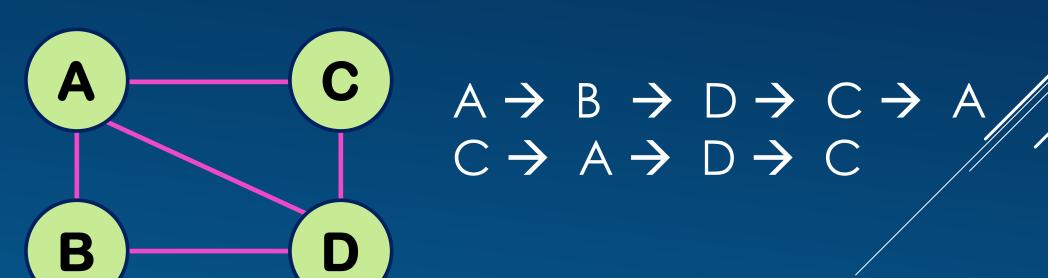
Vertices	In-	Out-
	Degree	Degree
0	2	2
1	3	3
2	3	3
3	1	1
4	1	1
5	1	1
6	1	1



Vertices	In-Degree	Out-Degree
0	1	1
1	1	2
2	1	0

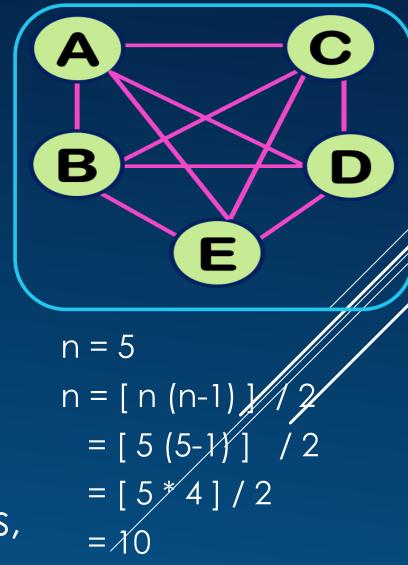
#### **BASIC TERMINOLOGIES**

- Acyclic Graph A graph without cycle
   Example: tree
- Cycle is a path with at least one edge that has the same start and end vertices.



#### **BASIC TERMINOLOGIES**

- Complete Graph
  - A graph in which all pairs of vertices are adjacent
  - A graph in which every vertex is directly connected to every other vertex
    - Let n = Number of vertices, and m = Number of edges
  - For a complete graph with n vertices, the number of edges is n(n-1)/2.

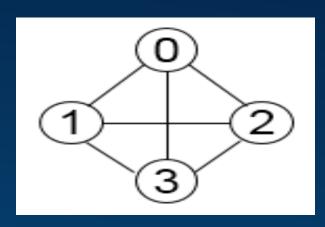


### **GRAPH REPRESENTATION**

## Adjacency Matrix (Array Implementation)

- Let G=(V,E) be a graph with n vertices.
- The adjacency matrix of G is a two-dimensional n by n array, adj\_mat If the edge (vi, vj) is in E(G), adj\_mat[i][j]=1 Else adj\_mat[i][j]=0
- The adjacency matrix for an undirected graph is symmetric; since adj\_mat[i][j]=adj\_mat[j]{[i]
- The adjacency matrix for a digraph máy not be symmetric

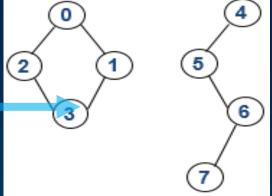
# Adjacency Matrix (Array Implementation)





1 (have connection)

V	0	1	2	3
0				
1				
2				
3				



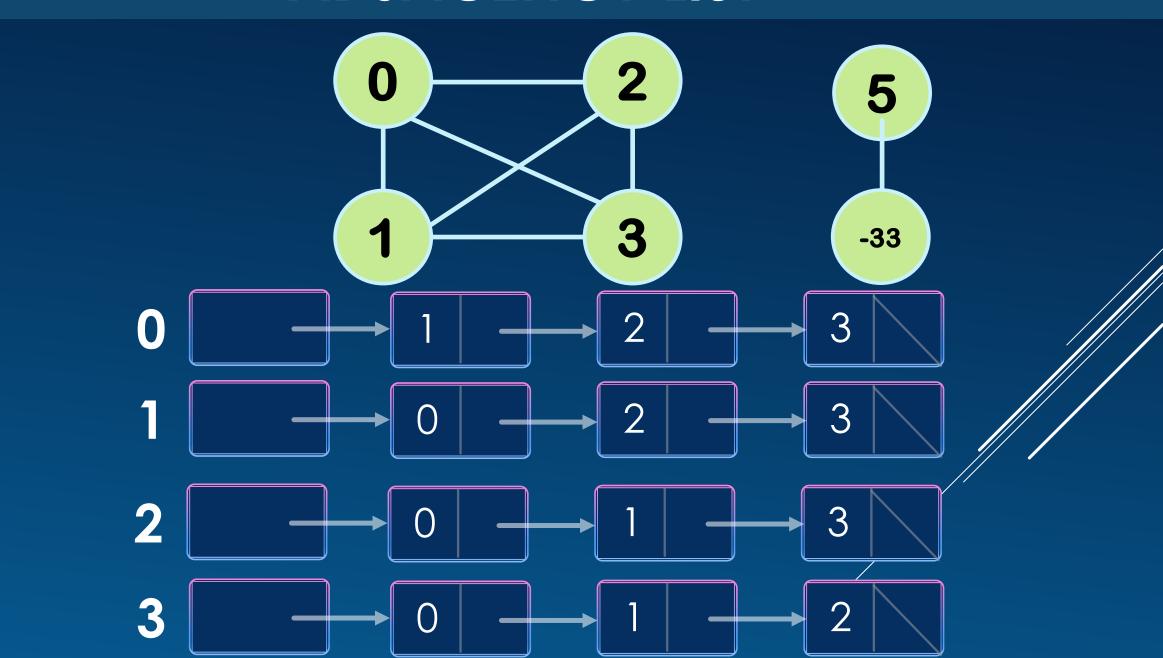
V	0	1	2	3	4	5	6	7
0								
1								
2 3								
3								
4								
5								
6								
7								

#### **GRAPH REPRESENTATION**

## **Adjacency List**

- A single dimension array of structure is used to represent the vertices
- A Linked list is used for each vertex V which contains the vertices which are adjacent from V (adjacency list)

# **ADJACENCY LIST**



# **BREADTH FIRST SEARCH (BFS)**

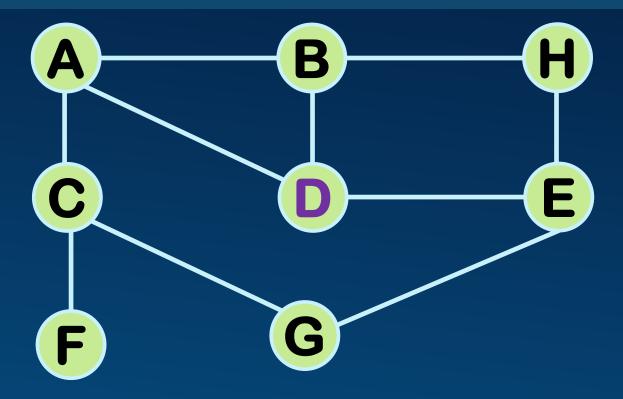
- This method visits all the vertices, beginning with a specified start vertex. It can be described roughly as "neighbours-first".
- No vertex is visited more than once, and vertices are visited only if they can be reached – that is, if there is a path from the start vertex.
- Use of a queue data structure (first-in first-out structure)
- Neighbours are not added to the queue if they are already in the queue, or have already been visited.

# **BREADTH FIRST SEARCH (BFS)**

#### **BREADTH-FIRST SEARCHING ALGORITHM:**

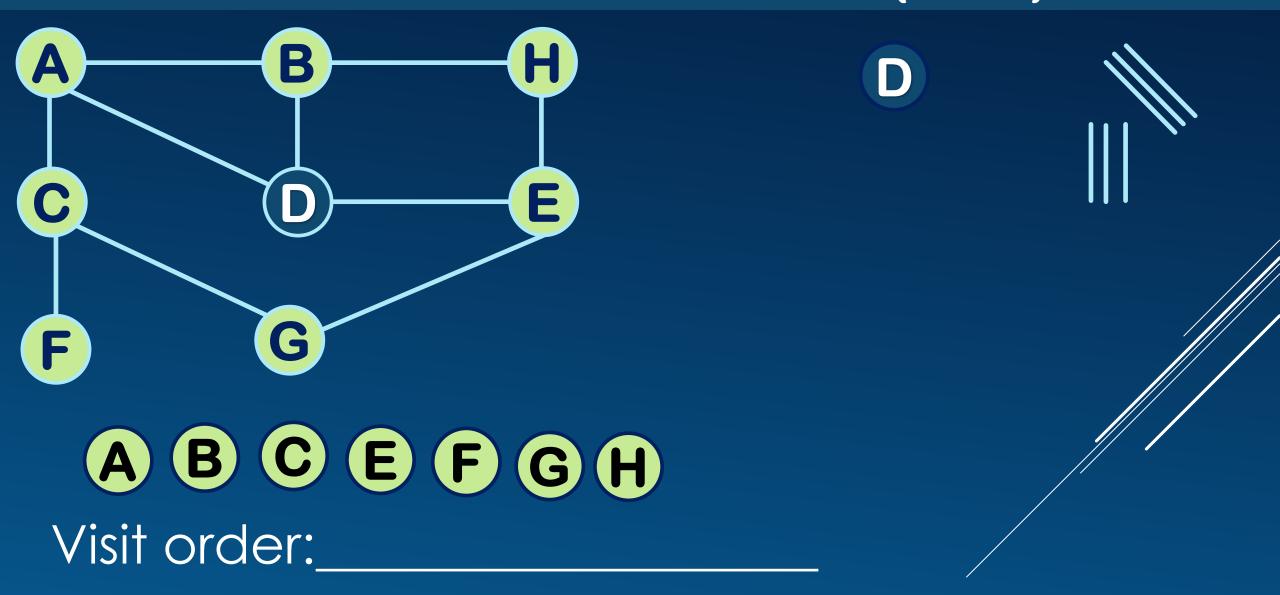
- 1. Push the starting vertex into a queue and then start a loop that will execute while the queue is not empty.
- 2. Once inside the loop, pop a vertex from the queue and make it the current vertex.
- 3. Place all unchecked vertices adjacent to the current vertex onto the queue and mark them as checked.
- 4. If there are no more vertices adjacent to the current vertex, check if the current vertex is the destination,
- 5. If the destination is found, the algorithm is done.
- 6. If the algorithm did not find the destination, repeat steps 2 through 5.

# **BREADTH FIRST SEARCH (BFS)**



Start at Vertex D

# BREADTH FIRST SEARCH (BFS) A-Z



# DEPTH FIRST SEARCH (DFS)

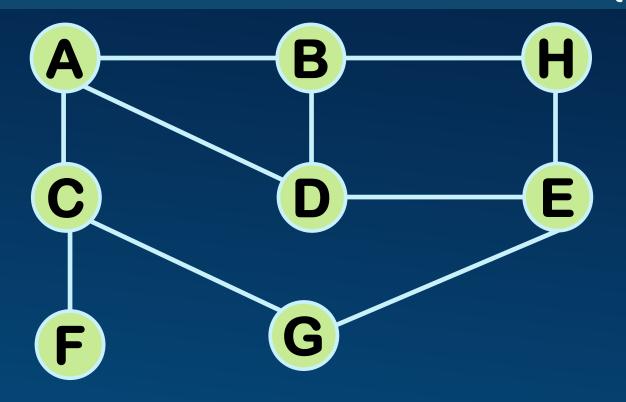
- This method visits all the vertices, beginning with a specified start vertex.
- This strategy proceeds along a path from vertex V as deeply into the graph as possible.
- This means that after visiting V, the algorithm tries to visit any unvisited vertex adjacent to V. When the traversal reaches a vertex which has no adjacent vertex, it back tracks and visits and unvisited adjacent vertex.
- Use of a Stack data structure.

# DEPTH FIRST SEARCH (DFS)

# Depth-first traversal of a graph:

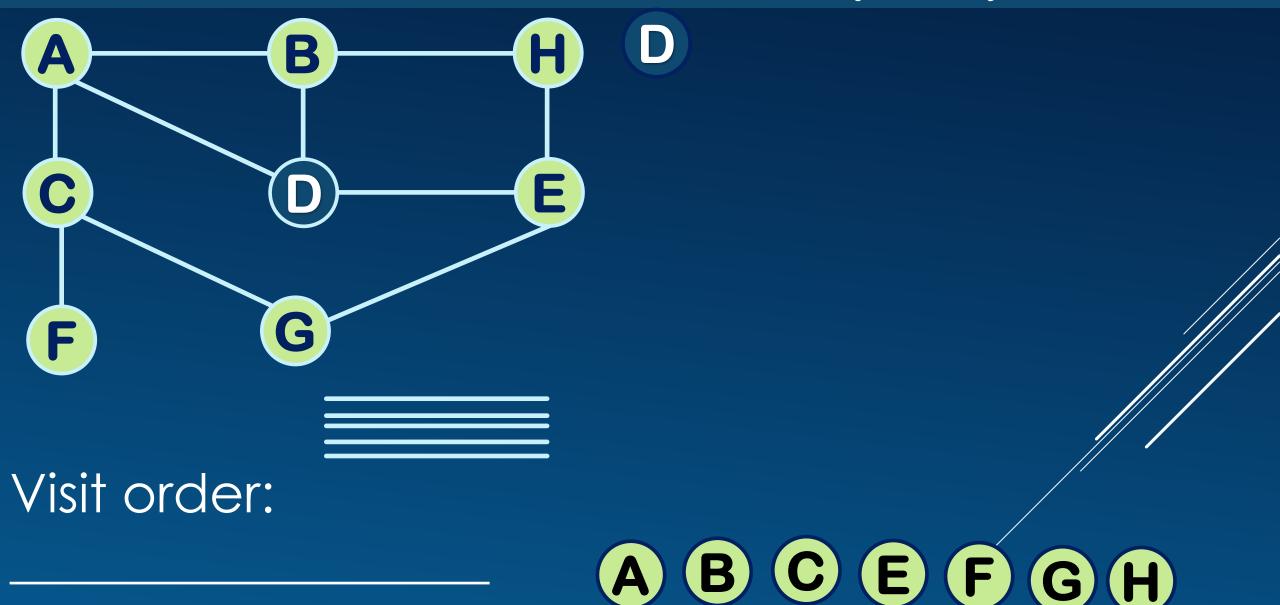
- 1. Start the traversal from an arbitrary vertex;
- 2. Apply depth-first search;
- 3. When the search terminates, backtrack to the previous vertex of the finishing point,
- 4. Repeat depth-first search on other adjacent vertices, then backtrack to one level up.
- 5. Continue the process until all the vertices that are reachable from the starting vertex are visited.
- 6. Repeat above processes until all vertiées are visited.

# DEPTH FIRST SEARCH (DFS)

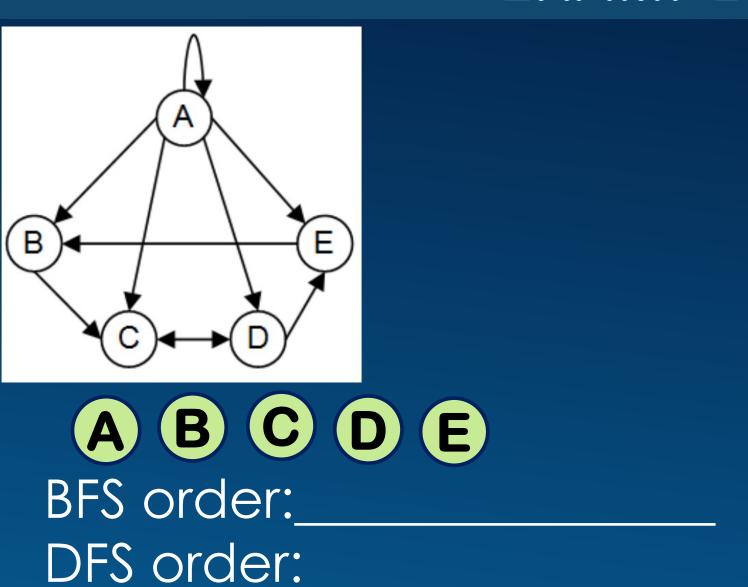


Start at Vertex D

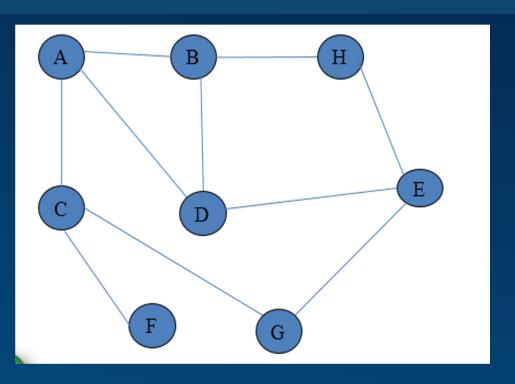
# DEPTH FIRST SEARCH (DFS) A-Z



# **EXAMPLE**



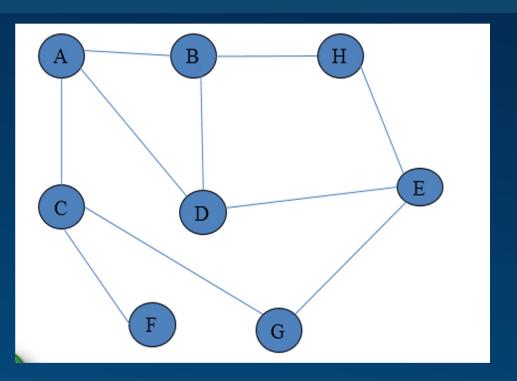
## **BFS and DFS**



BFS



## **BFS and DFS**



**DFS** 

