# Regular Research Meeting

22/03/2021

#### **Research Topic**

CFD application on natural ventilation design in a built environment

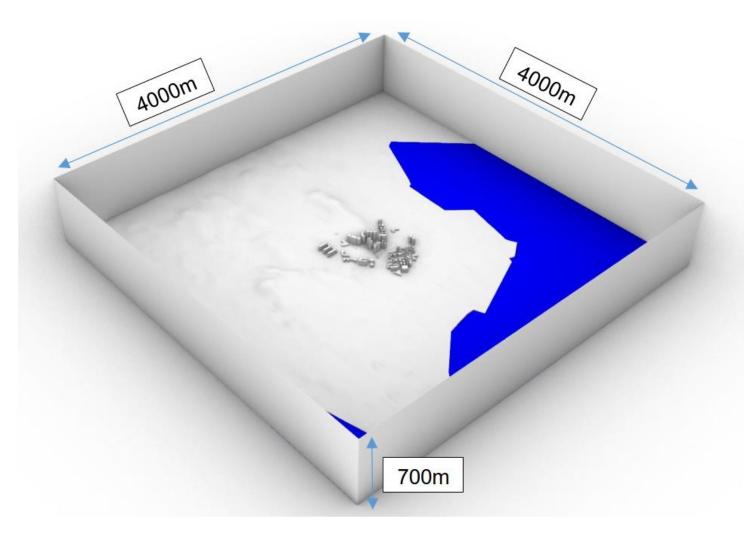
**CFD Simulation** Mesh Geometry Solver Postmodelling Generation Settings processing Boundary Condition Setting Turbulence Model Selection Numerical Scheme etc

Demands from practitioners in the building industry:

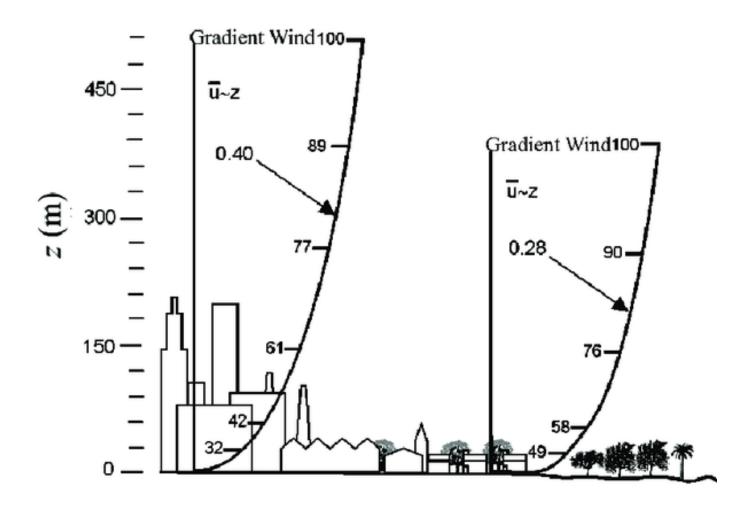
Building designers want reasonable CFD result and short simulation time to optimize design schemes.

Meshing is the most important part of the simulation process.

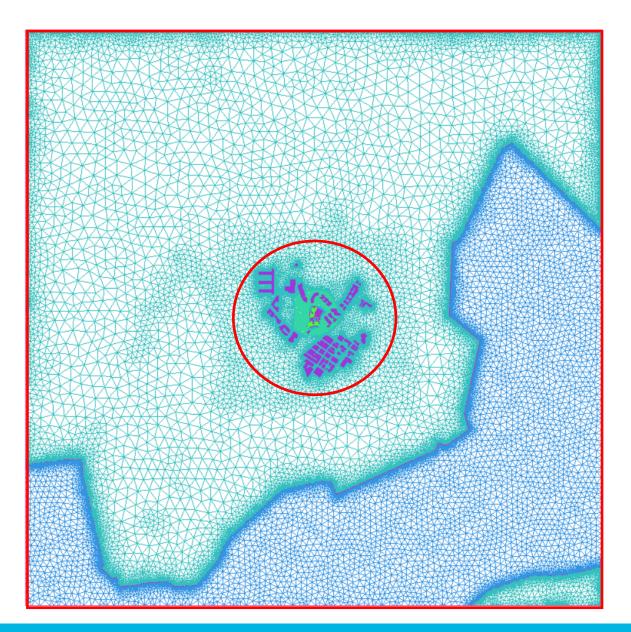
- Quality of mesh impacts the simulation accuracy.
- Number of mesh impacts the simulation time.



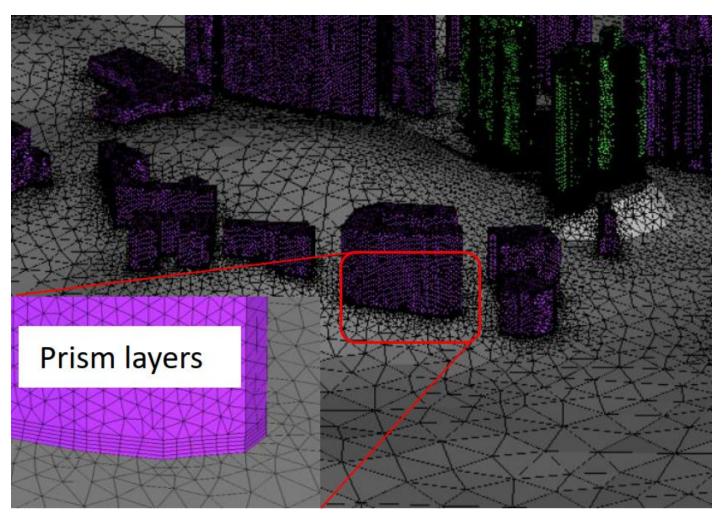
- Computational domain is very large in length, width and height;
- Wind profile of the atmosphere boundary condition is required;
- Coarse mesh is allowable for outer zone while fine mesh is required near building surfaces and ground surfaces;
- Boundary layer is required when studying the wind performance at the pedestrian level.



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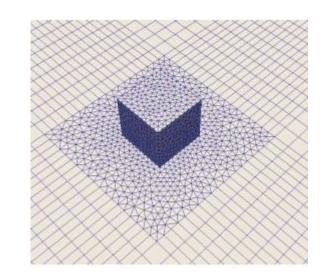
## **Hybrid mesh**

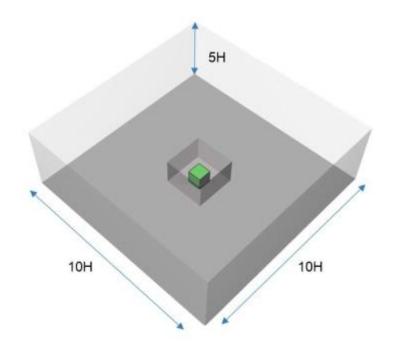
A Solution to the problem:

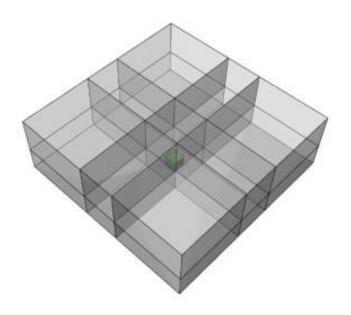
Hybrid mesh – reduce the number of mesh and keep mesh quality

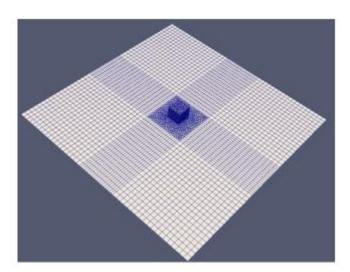
Outer zone – multiblock and structured grid

Inner zone – tetrahedral grid to capture building features









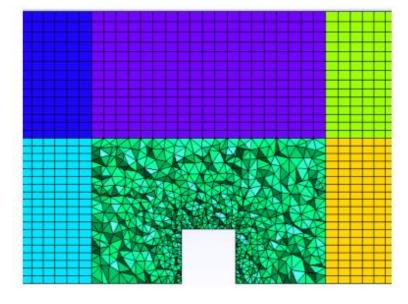
### **Hybrid mesh**

A Solution to the problem:

Hybrid mesh – reduce the number of mesh and keep mesh quality Outer zone – multiblock and structured grid Inner zone – tetrahedral grid to capture building features

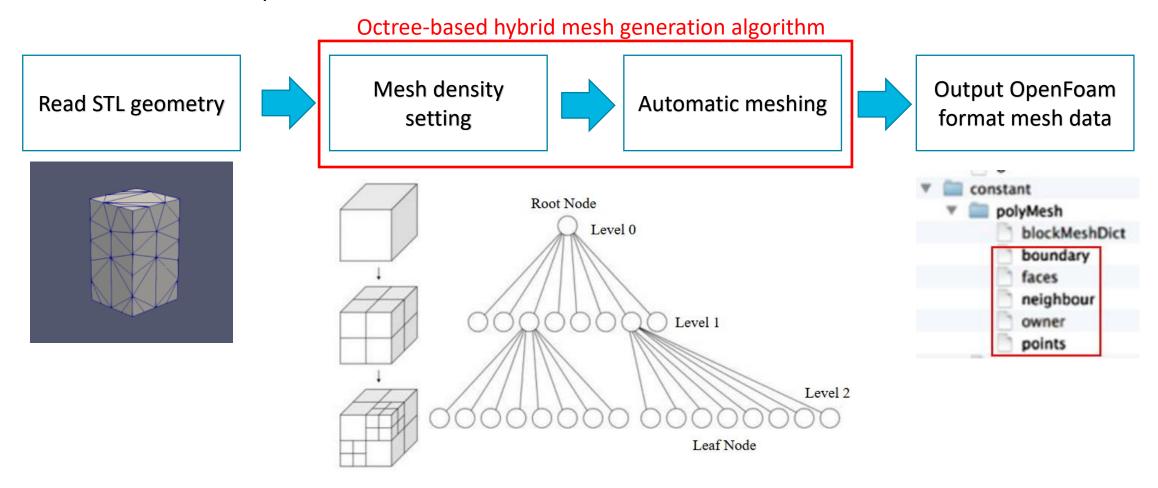
	Unstructured Mesh Scheme	Hybrid Mesh Scheme
Number of Tetrahedron	378,624	81,893
Number of Hexahedron	0	66,038
Number of Pyramid	0	1,805
Total Number of Mesh Element	378,624	149,736
Reduction of Mesh Elements	60.5%	
Total Computational Time	1,947 s (equivalent to 32 min)	403 s (equivalent to 6.7 min)
Reduction of Time	79.3%	





Further improvement on the hybrid mesh:

- Fully automatic meshing process
- Flexible mesh density control

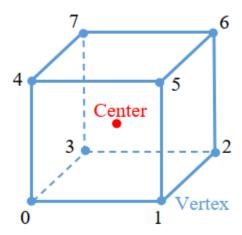


#### Algorithm Development in C++

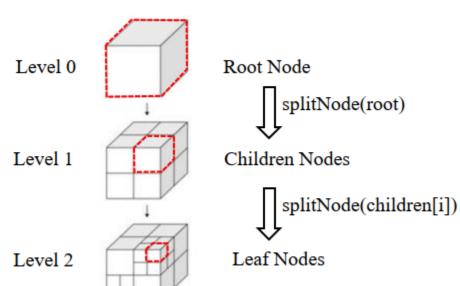
```
Class OctNode
string nid;
vector<double> center;
int level;
OctNode* parent;
vector<OctNode*> children;
void addChildNode(string nid, int
_level, vector<double> _center);
```

```
Class Octree
OctNode* root;
void define root();
void splitNode (OctNode* node);
};
```

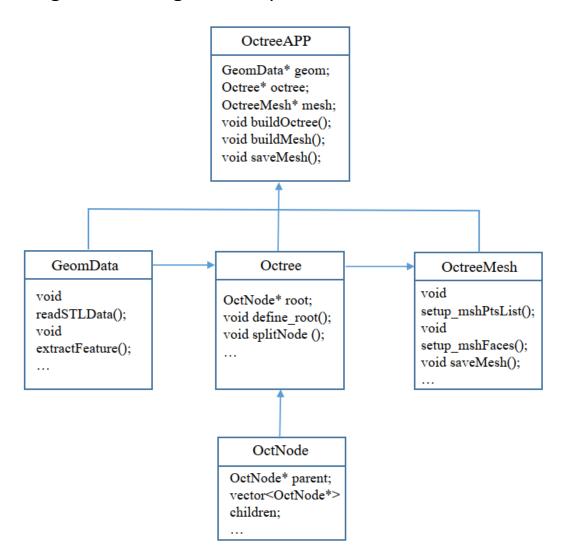
#### OctNode Structure



#### Octree Structure

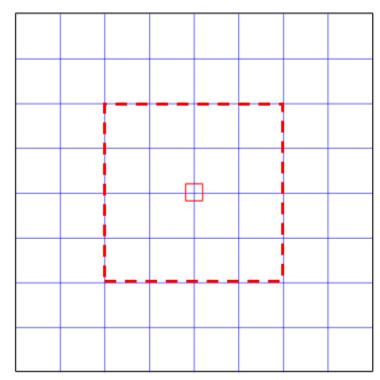


Algorithm design and implementation

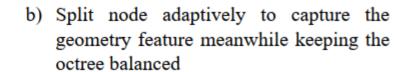


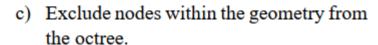
C++ Class	Function	
OctreeAPP	Initiate the mesh generation application and control the operation process	
GeomData	Read, process and store the input geometry data, e.g. the list of points and triangles from the STL file	
Octree	Initiate root node and split nodes to generate required octree data structure	
OctreeMesh	Convert the octree data structure to a specific CFD mesh format and output the mesh data for a CFD solver.	

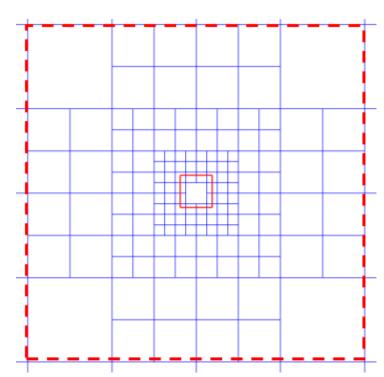
#### Example



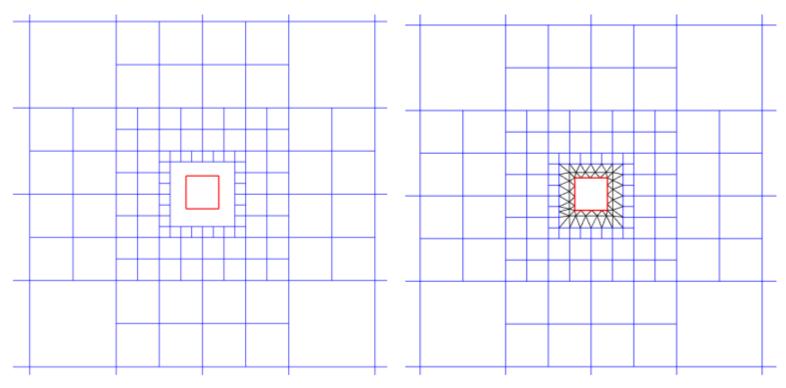
a) Root node defined first to cover the whole domain and then split node until reaching the minimum node level.







The way forward



- d) Delete nodes within the buffer zone offset from the geometry surfaces.
- e) Reconstruct with tetrahedral mesh element