

a)

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b) Kąt bez pośredniego poprzedniego i następnego

$$q = (x, y, \theta, \dot{\theta})^T$$

$$g_1 = (c\theta, s\theta, 0, 1)^T$$

$$g_2 = (0, 0, 1, 0)^T$$

n - wymiar przestrzeni = 4

m - l. generatorów = 2

l - l. ograniczeń nichol = n - m = 2

$$\cdot D_0(q) = \begin{bmatrix} c\theta & 0 \\ s\theta & 0 \\ 0 & 1 \\ 1 & 0 \end{bmatrix} \quad \det D_0^{(2 \times 2)} \neq 0 \Rightarrow \dim D_0 = 2$$

$$D_1(q) = \underset{\text{span}}{\text{span}} \{ g_1, g_2, g_{12} \}$$

$$\left\{ \begin{array}{l} g_{12} = [g_1 \ g_2] = \frac{g_2 - g_1}{q} = \\ - \begin{bmatrix} 0 & 0 & -s\theta & 0 \\ 0 & 0 & c\theta & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} s\theta \\ -c\theta \\ 0 \\ 0 \end{bmatrix} \end{array} \right.$$

$$D_2 = \begin{bmatrix} c\theta & 0 & s\theta \\ s\theta & 0 & -c\theta \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \quad \det D_2^{(3 \times 3)} \neq 0 \Rightarrow \dim D_2 = 3$$

(26)

$$D_2 = \text{span} \{ f_1, g_2, g_{12}, g_{112}, g_{212} \}$$

$$g_{112} = [g_1, g_{12}] = \frac{dg_{12}}{dq} g_1 - \frac{dg_1}{dq} g_{12} =$$

$$\begin{bmatrix} 0 & 0 & c\theta & 0 \\ 0 & 0 & s\theta & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} c\theta \\ s\theta \\ 0 \\ 1 \end{bmatrix} - \begin{bmatrix} 0 & 0 & -s\theta & 0 \\ 0 & 0 & c\theta & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} s\theta \\ -c\theta \\ 0 \\ 0 \end{bmatrix} =$$

$$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} - \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$g_{212} = [g_2, g_{12}] = \frac{dg_{12}}{dq} g_2 - \frac{dg_{12}}{dq} g_{12} =$$

$$\begin{bmatrix} 0 & 0 & c\theta & 0 \\ 0 & 0 & s\theta & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} - \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} s\theta \\ -c\theta \\ 0 \\ 0 \end{bmatrix} =$$

$$\begin{bmatrix} c\theta \\ s\theta \\ 0 \\ 0 \end{bmatrix}$$

(3b)

$$D_2 = \begin{bmatrix} c\theta & 0 & s\theta & c\theta \\ s\theta & 0 & -c\theta & s\theta \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

$$\det D_2 \neq 0 \Rightarrow \\ \dim D_2 = 4$$

$$g_1 \quad g_2 \quad g_{12} \quad g_{112}$$

Wektor wektoru skróty lengi

$$[2, 3, 4]$$

Stopień niehdonomiczności = 2, bo  $\dim_2 = 4 = n$

$$A(q) \cdot \dot{q} = 0$$

Jezeli  $r_p(q) = 0$ , to wektor jest niehdonomiczny.  
stopień określony powyżej (niehdonomiczności).



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⑩ c) samochód kinetyczny

$$q = \begin{bmatrix} x \\ y \\ \dot{x} \\ \dot{\phi} \end{bmatrix}$$

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$$\varphi_1 = \begin{bmatrix} Lc\theta c\phi \\ Ls\theta c\phi \\ s\phi \\ 0 \end{bmatrix}$$

$$g_2 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\bullet n = 4$$

$$m = 2$$

$$l = 4 - 2 = 2$$

$$\bullet D_0 = \begin{bmatrix} Lc\theta c\phi & 0 \\ Ls\theta c\phi & 0 \\ -s\phi & 0 \\ 0 & 1 \end{bmatrix} \quad \det D_0^{(2 \times 2)} \neq 0 \Rightarrow \\ \underline{\dim D_0 = 2}$$

$$D_1 = \text{span} \{ g_1, g_2, \varphi_2 \}$$

$$\varphi_{12} = [g_1, g_2] =$$

$$\frac{dg_2}{q} \cdot g_1 - \frac{dg_1}{q} \cdot g_2 = - \begin{bmatrix} 0 & 0 & Lc\theta s\phi & -Ls\theta \\ 0 & 0 & Ls\theta c\phi & Lc\theta \\ 0 & 0 & 0 & c\phi \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} =$$

(2c)

$$g_{12} = \begin{bmatrix} -Lc\theta s\phi \\ -Ls\theta s\phi \\ c\phi \\ 0 \end{bmatrix} = \begin{bmatrix} Lc\theta s\phi \\ Ls\theta s\phi \\ -c\phi \\ 0 \end{bmatrix}$$

$$D_1 = \begin{bmatrix} Lc\theta c\phi & 0 & Lc\theta s\phi \\ Ls\theta c\phi & 0 & Ls\theta s\phi \\ s\phi & 0 & -c\phi \\ 0 & 1 & 0 \end{bmatrix} \quad \det D_1^{(3 \times 3)} \neq 0 \Rightarrow \underline{\dim D_1 = 3}$$

$$D_2 = \text{span} \{ g_1, g_2, g_{12}, g_{112}, g_{212} \}$$

$$g_{212} = [g_2, g_{12}] = \begin{bmatrix} x & y & c & \phi \end{bmatrix}$$

$$\frac{dg_{12}}{dq} g_2 - \frac{g_2}{\frac{dg_{12}}{dq}} g_{12} = \left[ \begin{array}{c|cc|c} 0 & 0 & \text{wise krok} & 0 \\ \hline 0 & 0 & Lc\theta s\phi & Ls\theta s\phi \\ \hline 0 & 0 & 0 & s\phi \\ \hline 0 & 0 & 0 & 0 \end{array} \right] = 1$$

~~g<sub>112</sub>, g<sub>212</sub>~~

$$\begin{bmatrix} Lc\theta c\phi \\ Ls\theta c\phi \\ s\phi \\ 0 \end{bmatrix} \quad \begin{bmatrix} x \\ y \\ c \\ \phi \end{bmatrix}$$

3.C

$$\delta_{112} = \begin{bmatrix} g_{11} & g_{12} \end{bmatrix} =$$

$$\frac{\partial g_{12}}{\partial q_1} q_{12} - \frac{\partial g_{11}}{\partial q_2} q_{12}$$

$$\begin{array}{c|ccccc} x & y & \theta & \phi \\ \hline 0 & 0 & Ls\theta & Lc\theta & \\ 0 & 0 & Ls\theta & Lc\theta & \\ 0 & 0 & \textcircled{0} & S\phi & \\ \hline 0 & 0 & 0 & 0 & \\ x & y & \theta & \phi \end{array} = \begin{bmatrix} Lc\theta & \phi \\ Ls\theta & c\phi \\ S\phi & 0 \end{bmatrix}$$

$$\begin{array}{c|ccccc} x & y & \theta & \phi \\ \hline 0 & 0 & Lc\theta & Ls\theta & \\ 0 & 0 & Lc\theta & Ls\theta & \\ 0 & 0 & 0 & c\phi & \\ \hline 0 & 0 & 0 & 0 & \\ x & y & \theta & \phi \end{array} = \begin{bmatrix} Lc\theta & \phi \\ Ls\theta & c\phi \\ -c\phi & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} -Ls\theta s\theta s\phi - (Lc\theta s\phi) \\ Ls\theta c\theta s\phi + Lc\theta c\theta c\phi \\ 0 \\ 0 \end{bmatrix} =$$

$$\begin{bmatrix} -Ls\theta \\ Lc\theta \\ 0 \\ 0 \end{bmatrix}$$

4c

$$D_2 = \begin{bmatrix} L_c \theta c\phi & 0 & L_c \theta s\phi & -L_s \theta \\ L_s \theta c\phi & 0 & L_s \theta s\phi & L_c \theta \\ s\phi & 0 & -c\phi & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

$$\det D_2 \neq 0 \Rightarrow \dim D_2 = 4$$

- Wektor wartości:  $[2, 3, 4]$
- stopień nieholonomiczności = 2,  $\dim D_2 = n = 4$
- Sterowalny, nieholonomiczny

d) Jan Bronicki

$$c) \quad q = (q_1, q_2, q_3)^T$$

$$g_1 = \begin{pmatrix} 1 \\ 0 \\ q_2 \end{pmatrix} \quad g_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$1) \quad m=3 \quad l=1$$

$$m=2$$

$$2) \quad D_0 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ q_2 & 0 \end{bmatrix} = 1 \neq 0 \quad \text{odim } D_0 = 2$$

$$D_1 = D_0 + [D_0, D_0] = \text{span}_{\mathbb{C}^\infty} [g_1, g_2, g_{12}]$$

$$g_{12} = [g_1, g_2] = \frac{\partial g_2}{\partial q} g_1 - \frac{\partial g_1}{\partial q} g_2 = - \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = - \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$= \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix}$$

$$D_1 = \det \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ q_2 & 0 & -1 \end{bmatrix} = -1 \neq 0 \quad \dim D_1 = 3$$

$$3), 4) \quad n_0(q) = 2 < n_1(q) = 3 = m$$

STOPIEŃ NIEHOLONOMICZNOŚCI = 1

Witac! jest w pełni holonomiczny, bo zawsze ma pochodną punktową

e)

f)