

a)

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b) Kolo bez postizymy ppranego i sredzinego

$$q = (x, y, \theta, \phi)^T$$

$$g_1 = (c\theta, s\theta, 0, 1)^T$$

$$g_2 = (0, 0, 1, 0)^T$$

- n - wymiar przestrzeni = 4
- m - l. generatorów = 2
- L - l. ograniczeń nichol = $n - m = 2$

$$D_0(q) = \begin{bmatrix} c\theta & 0 \\ s\theta & 0 \\ 0 & 1 \\ 1 & 0 \end{bmatrix} \quad \det D_0^{(2 \times 2)} \neq 0 \Rightarrow \dim D_0 = 2$$

$$D_1(q) = \text{span} \{g_1, g_2, g_{12}\}$$

$$g_{12} = [g_1, g_2] = \frac{g_2}{q} \cdot g_1 - \frac{g_1}{q} \cdot g_2 =$$

$$= \begin{bmatrix} 0 & 0 & -s\theta & 0 \\ 0 & 0 & c\theta & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} - \begin{bmatrix} s\theta & -c\theta & 0 & 0 \end{bmatrix} = \begin{bmatrix} s\theta \\ -c\theta \\ 0 \\ 0 \end{bmatrix}$$

$$D_1 = \begin{bmatrix} c\theta & 0 & s\theta \\ s\theta & 0 & -c\theta \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

$$\det D_1^{(3 \times 3)} \neq 0 \Rightarrow \dim D_1 = 3$$

(2b)

$$D_2 = \text{span}\{g_1, g_2, g_{12}, g_{112}, g_{212}\}$$

$$g_{112} = [g_1, g_{12}] = \frac{dg_{12}}{dq_1} g_1 - \frac{dg_1}{dq_1} g_{12} =$$

$$\begin{bmatrix} 0 & 0 & c\theta & 0 \\ 0 & 0 & s\theta & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} c\theta \\ s\theta \\ 0 \\ 1 \end{bmatrix} - \begin{bmatrix} 0 & 0 & -s\theta & 0 \\ 0 & 0 & c\theta & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} s\theta \\ -c\theta \\ 0 \\ 0 \end{bmatrix} =$$

$$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} - \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$g_{212} = [g_2, g_{12}] = \frac{dg_{12}}{dq_2} g_2 - \frac{dg_2}{dq_2} g_{12} =$$

$$\begin{bmatrix} 0 & 0 & c\theta & 0 \\ 0 & 0 & s\theta & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} - \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} s\theta \\ -c\theta \\ 0 \\ 0 \end{bmatrix} =$$

$$\begin{bmatrix} c\theta \\ s\theta \\ 0 \\ 0 \end{bmatrix}$$

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$$D_2 = \begin{bmatrix} c\theta & 0 & s\theta & c\theta \\ s\theta & 0 & -c\theta & s\theta \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

$$\det D_2 \neq 0 \Rightarrow$$

$$\dim D_2 = 4$$

$$g_1 \quad g_2 \quad g_{12} \quad g_{212}$$

Wektor wartości dyktynji

$$[2, 3, 4]$$

Stopień nieholonomii = 2, bo $\dim_2 = 4 = n$

$$A(q) \cdot \dot{q} = 0$$

Jeżeli $r_p(q) = 0$, to układ jest nieholonomiczny.
Stopień denszty powyżej (nieholonomii).

⑩ c) samochód kinematyzujący

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$$q = \begin{bmatrix} x \\ y \\ \theta \\ \phi \end{bmatrix}$$

$$g_1 = \begin{bmatrix} L \cos \theta \cos \phi \\ L \sin \theta \cos \phi \\ s \phi \\ 0 \end{bmatrix}$$

$$g_2 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

$$n = 4$$

$$m = 2$$

$$L = 4 - 2 = 2$$

$$D_0 = \begin{bmatrix} L \cos \theta \cos \phi & 0 \\ L \sin \theta \cos \phi & 0 \\ -s \phi & 0 \\ 0 & 1 \end{bmatrix}$$

$$\det D_0^{(2 \times 2)} \neq 0 \Rightarrow$$

$$\dim D_0 = 2$$

$$D_1 = \text{span}\{g_1, g_2, g_{12}\}$$

$$g_{12} = [g_1, g_2] =$$

$$\frac{dg_2}{q} \cdot g_1 - \frac{dg_1}{q} \cdot g_2 = - \begin{bmatrix} 0 & 0 & L \sin \theta \cos \phi & -L \sin \theta \sin \phi \\ 0 & 0 & L \cos \theta \cos \phi & -L \cos \theta \sin \phi \\ 0 & 0 & 0 & c \phi \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} =$$

(2c)

$$g_{12} = \begin{bmatrix} -Lc\theta s\phi \\ -Ls\theta s\phi \\ c\phi \\ 0 \end{bmatrix} = \begin{bmatrix} Lc\theta s\phi \\ Ls\theta s\phi \\ -c\phi \\ 0 \end{bmatrix}$$

$$D_1 = \begin{bmatrix} Lc\theta c\phi & 0 & Lc\theta s\phi \\ Ls\theta c\phi & 0 & Ls\theta s\phi \\ s\phi & 0 & -c\phi \\ 0 & 1 & 0 \end{bmatrix}$$

$$\det D_1^{(3 \times 3)} \neq 0 \Rightarrow$$

$$\underline{\underline{\dim D_1 = 3}}$$

$$D_2 = \text{span} \{ g_1, g_2, g_{12}, g_{112}, g_{212} \}$$

$$g_{212} = [g_2, g_{12}] = \begin{matrix} & x & y & \theta & \phi \end{matrix}$$

$$\frac{dg_{12}}{dq_1} g_2 - \frac{dg_2}{dq_1} g_{12} = \begin{bmatrix} 0 & 0 & -Ls\theta & Lc\theta c\phi \\ 0 & 0 & Lc\theta s\phi & Ls\theta c\phi \\ 0 & 0 & 0 & s\phi \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} =$$

$$\cancel{g_{112} = [g_1, g_{12}] =}$$

$$\begin{bmatrix} Lc\theta c\phi \\ Ls\theta c\phi \\ s\phi \\ 0 \end{bmatrix}$$

3c

$$g_{12} = [g_1, g_2] =$$

$$\frac{\partial g_1}{\partial q_1} q_1 - \frac{\partial g_2}{\partial q_1} q_2$$

$$\begin{array}{c|c|c|c|c} x & y & \theta & \phi & \\ \hline 0 & 0 & L\phi s\theta & Lc\theta c\phi & Lc\theta c\phi \\ 0 & 0 & L\phi c\theta & Ls\theta c\phi & Ls\theta c\phi \\ 0 & 0 & 0 & s\phi & s\phi \\ 0 & 0 & 0 & 0 & 0 \end{array}$$

$$\begin{array}{c|c|c|c|c} x & y & \theta & \phi & \\ \hline 0 & 0 & L\phi s\theta & Lc\theta s\phi & Lc\theta s\phi \\ 0 & 0 & L\phi c\theta & Ls\theta s\phi & Ls\theta s\phi \\ 0 & 0 & 0 & c\phi & -c\phi \\ 0 & 0 & 0 & 0 & 0 \end{array} = \begin{bmatrix} -Ls\phi s\theta s\phi - (Lc\phi s\theta) \\ Ls\phi c\theta s\phi + Lc\phi c\theta c\phi \\ 0 - 0 \\ 0 - 0 \end{bmatrix} =$$

$$\begin{bmatrix} -Ls\theta \\ Lc\theta \\ 0 \\ 0 \end{bmatrix}$$

4c)

$$D_2 = \begin{bmatrix} Lc\theta c\phi & 0 & Lc\theta s\phi & -Ls\theta \\ Ls\theta c\phi & 0 & Ls\theta s\phi & Lc\theta \\ s\phi & 0 & -c\phi & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

$$\det D_2 \neq 0 \Rightarrow \dim D_2 = 4$$

- wektor wartości: $[2, 3, 4]$
- stopień nieholonomiczności = 2, $\dim D_2 = n = 4$
- Sterowalny, nieholonomiczny

d) Jan Bronicki

$$a) \quad q = (q_1, q_2, q_3)^T$$

$$g_1 = \begin{pmatrix} 1 \\ 0 \\ q_2 \end{pmatrix} \quad g_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$1) \quad m=3 \quad l=1$$

$$m=2$$

$$2) \quad D_0 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ q_2 & 0 \end{bmatrix} = 1 \neq 0 \quad \dim D_0 = 2$$

$$D_1 = D_0 + [D_0, D_0] = \text{span}_{\mathbb{C}^\infty} [g_1, g_2, g_{12}]$$

$$g_{12} = [g_1, g_2] = \frac{\partial g_2}{\partial q} g_1 - \frac{\partial g_1}{\partial q} g_2 = - \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = - \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$= \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix}$$

$$D_1 = \det \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ q_2 & 0 & -1 \end{bmatrix} = -1 \neq 0 \quad \dim D_1 = 3$$

$$3), 4) \quad r_0(q) = 2 < r_1(q) = 3 = m$$

STOPIEŃ NIEHOLONOMICZNOŚCI = 1

Układ jest w pełni holonomiczny korzystając na poprzednich punktach

e)

f)