

*Backtrace* ( $k, v_k$ )

*/\* map objective into PI assignment \*/*

**begin**

$v = v_k$

**while**  $k$  is a gate output

**begin**

$i$  = inversion of  $k$

select an input ( $j$ ) of  $k$  with value  $x$

$v = v \oplus i$

$k = j$

**end**

*/\*  $k$  is a PI \*/*

**return** ( $k, v$ )

**end**