

ECMA31000: Introduction to Empirical Analysis

Asymptotics I

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Outline

- This week:
 - Uses of Asymptotic Theory
 - Convergence almost surely
 - Convergence in probability
 - Convergence in r -th moment
 - Convergence in distribution
 - Relations between modes of convergence

Use of Asymptotic Theory: Estimation

- Example: Want to learn population mean wage μ .
 - Observe an iid sample of wages $\{X_i\}_{i=1}^n$.
 - Form an estimator $S_n(\{X_i\}_{i=1}^n) = \frac{1}{n} \sum_{i=1}^n X_i := \bar{X}_n$ which estimates μ using sample $\{X_i\}_{i=1}^n$.
 - In what sense is S_n is close to μ ? How does this depend on n ?
- Two types of results:
 - Finite sample bounds (explicit dependence on n)
 - Asymptotic results (what would happen if we could keep increasing sample size: $n \rightarrow \infty$).
- Asymptotic results often easier to derive, but our sample is only ever finite.
- Takeaway: Asymptotic properties are an approximation to finite sample properties (but not always a good one).

Use of Asymptotic Theory: Testing

- Suppose a randomly drawn height, X , is distributed according to P_X , where

$$E(X) = \mu \text{ (unknown)}$$

$$Var(X) = \sigma^2 \text{ (unknown)}$$

- Suppose we wish to test $H_0 : \mu = 180cm$ vs. $H_1 : \mu > 180cm$.
- Let

$$T_n = \frac{\sqrt{n}(\bar{X}_n - 180)}{\sqrt{\frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X}_n)^2}}.$$

- Test function

$$\phi_n(T_n) = \mathbf{1}(T_n > t_{n-1, 1-\alpha}).$$

where $t_{n-1, 1-\alpha}$ is $1 - \alpha$ quantile of t_{n-1} distribution.

- Probability of rejecting H_0 is known for each μ if we also know $X \sim Normal$.

Use of Asymptotic Theory: Testing

- Difficult (or impossible) to compute if P_X non-normal.
- But: If $T_n \overset{d}{\approx} \mathcal{N}(0, 1)$, and $\mu = 180\text{cm}$ (H_0 true), then

$$\begin{aligned} P(T_n > t_{n-1, 1-\alpha}) &\approx \text{Prob}(\mathcal{N}(0, 1) > z_{1-\alpha}) \\ &= 1 - \Phi(z_{1-\alpha}) \\ &= \alpha, \end{aligned}$$

where $z_{1-\alpha}$ is the $1 - \alpha$ quantile of $\mathcal{N}(0, 1)$, because

$$t_{n-1, 1-\alpha} \rightarrow z_{1-\alpha}$$

for each α .

- Can approximate the rejection probability of ϕ_n by considering simpler experiment using $\mathcal{N}(0, 1)$ random variable in place of T_n and $z_{1-\alpha}$ in place of $t_{n-1, 1-\alpha}$.

Convergence almost surely

- We say a sequence of real numbers $\{x_n\}_{n \geq 1}$ converges to $x \in \mathbb{R}$ ($x_n \rightarrow x$) if, for each $\epsilon > 0$, there exists n_ϵ such that

$$|x_n - x| \leq \epsilon$$

for all $n > n_\epsilon$.

- Let $\{X_n\}_{n \geq 1}$ and X be random variables defined on a common probability space (Ω, \mathcal{F}, P) .
- If $\omega \in \Omega$ is fixed, $\{X_n(\omega)\}_{n \geq 1}$ forms a sequence of reals.
- $X_n \rightarrow X$ pointwise if $X_n(\omega) \rightarrow X(\omega)$ for all $\omega \in \Omega$.
- $X_n \xrightarrow{a.s.} X$ (" X_n converges almost surely to X ") if $P(\{\omega : X_n(\omega) \rightarrow X(\omega)\}) = 1$.

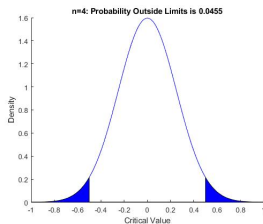
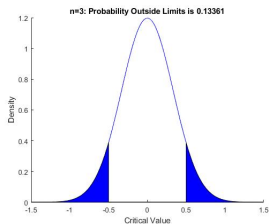
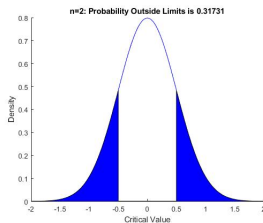
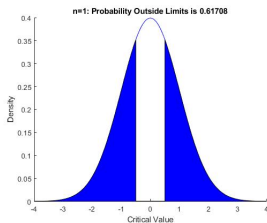
Example

- Probability Space: $([0, 1], \mathcal{F}, P)$ where $P(\{0\}) = 0$.
- Sequence

$$X_n(\omega) = 2^n \mathbf{1}\left(\omega \leq \frac{1}{n}\right).$$

Example: Normal distributions

- Suppose $\{X_n\}_{n \geq 1}$ is a sequence such that $X_n \sim \mathcal{N}(0, \frac{1}{n^2})$:



- As $n \rightarrow \infty$, a larger proportion of the density falls in the interval $(-\frac{1}{2}, \frac{1}{2})$, so

$$P\left(|X_n - 0| > \frac{1}{2}\right) \rightarrow 0.$$

Convergence in Probability

- X_n converges in probability to X ($X_n \xrightarrow{P} X$) if $\forall \epsilon > 0$:

$$P(\{\omega : |X_n(\omega) - X(\omega)| > \epsilon\}) \rightarrow 0.$$

- Example: Let

$$X_n = \begin{cases} 2^n & \text{with probability } \frac{1}{n} \\ 0 & \text{with probability } 1 - \frac{1}{n} \end{cases}.$$

Example: Weak LLN

- Suppose $\{X_i\}_{i \geq 1}$ are iid with $E(X_i) = \mu$ and $Var(X_i) = \sigma^2$.
Then $\bar{X}_n \xrightarrow{P} \mu$.

Proof.

Using Chebyshev's inequality, for any $\epsilon > 0$

$$\begin{aligned} P(|\bar{X}_n - \mu| > \epsilon) &\leq \frac{E(|\bar{X}_n - \mu|^2)}{\epsilon^2} \\ &= \frac{E\left(\sum_i (X_i - \mu)^2 + \sum_i \sum_{j \neq i} (X_i - \mu)(X_j - \mu)\right)}{n^2 \epsilon^2} \\ &= \frac{n Var(X_i)}{n^2 \epsilon^2} = \frac{\sigma^2}{n \epsilon^2} \rightarrow 0, \end{aligned}$$

where 2nd equality follows because X_i are iid and expectation is linear. Hence $\bar{X}_n \xrightarrow{P} \mu$. □

Example: Estimating the CDF

- Rather than estimating a feature of F_X , we can estimate the entire distribution:
- Let $\{X_i\}_{i \geq 1}$ be an iid sample drawn from F_X .
- Define the empirical distribution of F_X by

$$\hat{F}_X(x) := \frac{1}{n} \sum_{i=1}^n \mathbf{1}(X_i \leq x).$$

- $\hat{F}_X(x)$ is just the proportion of observations less than x , and is an estimate of

$$F_X(x) = \mathbb{P}(X \leq x).$$

Example: Estimating the CDF

- $\{\mathbf{1}(X_i \leq x)\}_{i \geq 1}$ is an independent sequence because the X_i are independent.
- Also identically distributed:

$$P(\mathbf{1}(X_i \leq x) = 1) = P(X_i \leq x) = F_X(x).$$

- Since

$$\begin{aligned} \text{Var}(\mathbf{1}(X_i \leq x)) &= E\left(\mathbf{1}(X_i \leq x)^2\right) - E(\mathbf{1}(X_i \leq x))^2 \\ &= F_X(x)(1 - F_X(x)) < \infty, \end{aligned}$$

we conclude that $\hat{F}_n(x) \xrightarrow{P} F(x)$.

- (Glivenko-Cantelli) Can in fact show that:

$$\sup_{x \in \mathbb{R}} \left| \hat{F}_n(x) - F(x) \right| \xrightarrow{P} 0.$$

Questions?

Convergence a.s.

- Recall: $X_n \xrightarrow{a.s.} X$ if $P(\{\omega : X_n(\omega) \rightarrow X(\omega)\}) = 1$.
- Suppose ω is such that $X_n(\omega) \rightarrow X(\omega)$. Then for any $\epsilon > 0$,

$$|X_n(\omega) - X(\omega)| \leq \epsilon$$

for $n > N(\epsilon, \omega)$. For such ω , $|X_n(\omega) - X(\omega)| > \epsilon$ only finitely many times.

- Thus, the set of ω for which $X_n(\omega) \rightarrow X(\omega)$ is the set of ω such that for any $\epsilon > 0$,

$$|X_n(\omega) - X(\omega)| > \epsilon$$

finitely many times.

- Now note:

$$A_k := \cup_{n \geq k} \{\omega : |X_n(\omega) - X(\omega)| > \epsilon\}$$

is the set of ω such that $|X_n(\omega) - X(\omega)| > \epsilon$ for some $n \geq k$.

Convergence a.s.

- Therefore,

$$\bigcap_{k \geq 1} \bigcup_{n \geq k} \{\omega : |X_n(\omega) - X(\omega)| > \epsilon\}$$

is the set of ω such that $|X_n(\omega) - X(\omega)| > \epsilon$ for some n , no matter how large k gets.

- This is equivalent to saying $|X_n(\omega) - X(\omega)| > \epsilon$ infinitely often.
- Since $X_n \xrightarrow{\text{a.s.}} X$,

$$P(\{\omega : |X_n(\omega) - X(\omega)| > \epsilon \text{ infinitely often}\}) = 0,$$

or

$$P(\bigcap_{k \geq 1} A_k) = 0.$$

Convergence a.s.

- By a similar argument to Exercise 2(b) of problem set 1:

$$\mathbb{P}(\cap_{k \geq 1} A_k) = \lim_{K \rightarrow \infty} \mathbb{P}(\cap_{k=1}^K A_k).$$

Finally, notice that

$$A_k = \cup_{n \geq k} \{\omega : |X_n(\omega) - X(\omega)| > \epsilon\}$$

is a decreasing sequence of sets: $A_k \supset A_{k+1} \supset A_{k+2} \dots$, so $\cap_{k=1}^K A_k = A_K$.

- In conclusion: $X_n \xrightarrow{\text{a.s.}} X$ iff

$$\lim_{K \rightarrow \infty} \mathbb{P}(\cup_{n \geq K} \{\omega : |X_n(\omega) - X(\omega)| > \epsilon\}) = 0.$$

Convergence a.s.

- Two equivalent definitions: $X_n \xrightarrow{a.s.} X$ if

$$P(\{\omega : X_n(\omega) \rightarrow X(\omega)\}) = 1$$

or

$$\forall \epsilon > 0, \lim_{n \rightarrow \infty} P(\cup_{k \geq n} \{\omega : |X_k(\omega) - X(\omega)| > \epsilon\}) = 0$$

- First definition not always helpful: What if we don't know the underlying probability space?
- 2nd definition doesn't require us to know which ω converge, just need to show overall fraction of ω converges to 0.
- For example, consider

$$X_n = \begin{cases} 2^n & \text{with prob. } \frac{1}{n^2} \\ 0 & \text{with prob. } 1 - \frac{1}{n^2}. \end{cases}$$

Example

- Showing that $X_n \xrightarrow{a.s.} 0$ much easier with 2nd definition:
- Let $\epsilon > 0$ be given. Then

$$\begin{aligned} P\left(\bigcup_{k \geq n} \{|X_k - 0| > \epsilon\}\right) &\leq \sum_{k=n}^{\infty} P(|X_k - 0| > \epsilon) \\ &\leq \sum_{k=n}^{\infty} P(X_k = 2^k) \\ &= \sum_{k=n}^{\infty} \frac{1}{k^2} \\ &= \sum_{k=1}^{\infty} \frac{1}{k^2} - \sum_{k=1}^{n-1} \frac{1}{k^2} \rightarrow 0 \end{aligned}$$

as $n \rightarrow \infty$.

Convergence a.s. \implies Convergence in Prob.

Theorem

Suppose $X_n \xrightarrow{\text{a.s.}} X$. Then $X_n \xrightarrow{P} X$.

Proof.

Note that $|X_K(\omega) - X(\omega)| > \epsilon$ implies that $|X_n(\omega) - X(\omega)| > \epsilon$ for some $n \geq K$:

$$\{\omega : |X_K(\omega) - X(\omega)| > \epsilon\} \subset \cup_{n \geq K} \{\omega : |X_n(\omega) - X(\omega)| > \epsilon\},$$

and so

$$P(\{\omega : |X_K(\omega) - X(\omega)| > \epsilon\}) \leq P(\cup_{n \geq K} \{\omega : |X_n(\omega) - X(\omega)| > \epsilon\}).$$

Therefore, if $X_n \xrightarrow{\text{a.s.}} X$, the RHS converges to 0 as $K \rightarrow \infty$, so

$$\lim_{K \rightarrow \infty} P(\{\omega : |X_K(\omega) - X(\omega)| > \epsilon\}) \leq 0.$$

Since probabilities are non-negative, conclude $X_n \xrightarrow{P} X$. □

Difference between $\xrightarrow{a.s.}$ and \xrightarrow{p}

- Convergence almost surely requires that for almost all ω , and any $\epsilon > 0$,

$$|X_n(\omega) - X(\omega)| > \epsilon$$

for finitely many n .

- Convergence in probability merely requires that the fraction of ω such that $|X_n(\omega) - X(\omega)| > \epsilon$ converges to 0 as $n \rightarrow \infty$. The actual ω for which the condition holds can change with n as long as the overall fraction decreases to 0.
- Because of this, $X_n(\omega) \rightarrow X(\omega)$ is not required for any ω , as next example demonstrates.

Counterexample: $\xrightarrow{P} \not\Rightarrow \xrightarrow{a.s.}$

- Consider the space $([0, 1], \mathcal{B}([0, 1]), P)$ and define:

$$X_1(\omega) = \begin{cases} 1 & \text{if } \omega \in [0, 1] ; \\ 0 & \text{otherwise} \end{cases} ;$$

$$X_2(\omega) = \begin{cases} 1 & \text{if } \omega \in [0, \frac{1}{2}] ; \\ 0 & \text{otherwise} \end{cases} ; \quad X_3(\omega) = \begin{cases} 1 & \text{if } \omega \in [\frac{1}{2}, 1] ; \\ 0 & \text{otherwise} \end{cases} ;$$

$$X_4(\omega) = \begin{cases} 1 & \text{if } \omega \in [0, \frac{1}{3}] ; \\ 0 & \text{otherwise} \end{cases} ; \quad X_5(\omega) = \begin{cases} 1 & \text{if } \omega \in [\frac{1}{3}, \frac{2}{3}] ; \\ 0 & \text{otherwise} \end{cases} ; \quad \dots$$

- If $[a, b]$ is an interval contained in $[0, 1]$, we set $P([a, b]) = b - a$.
- Then, for example, $P_{X_1}(X_1 = 1) = 1$ and $P_{X_5}(X_5 = 1) = \frac{1}{3}$.

Counterexample: $\xrightarrow{P} \not\xrightarrow{\text{a.s.}}$

- As n grows large, $P(\{\omega : X_n(\omega) = 0\}) \rightarrow 1$. Thus for any $\epsilon > 0$

$$\lim_{n \rightarrow \infty} P(\{\omega : |X_n(\omega) - 0| > \epsilon\}) = 0,$$

and so $X_n \xrightarrow{P} 0$.

- Notice that the elements ω which satisfy the condition $|X_n(\omega) - 0| > \epsilon$ change with n .
- For every element $\omega \in [0, 1]$, $X_n(\omega) = 1$ infinitely many times.
So:

$$P(\{\omega : X_n(\omega) \rightarrow 0\}) = 0.$$

Questions?

Difference between $\xrightarrow{a.s.}$ and \xrightarrow{P}

- Another way to describe difference: $X_n \xrightarrow{a.s.} X$ if

$$\forall \epsilon > 0, \lim_{n \rightarrow \infty} P(\cup_{k \geq n} \{\omega : |X_k(\omega) - X(\omega)| > \epsilon\}) = 0.$$

- P refers to the probability measure on the underlying probability space, but the condition inside says “at least one X_k ($k \geq n$) is far from X ”.
- So we can rewrite this using the distribution $P_{\{X_k\}_{k \geq n}, X}$ induced by $\{X_k\}_{k \geq n}, X$:

$$\forall \epsilon > 0, \lim_{n \rightarrow \infty} P_{\{X_k\}_{k \geq n}, X}(\cup_{k \geq n} \{|X_k - X| > \epsilon\}) = 0.$$

This no longer requires us to verify statements pointwise in $\omega \in \Omega$. It is a requirement on the joint distribution of $(\{X_k\}_{k \geq n}, X)$, as $n \rightarrow \infty$.

Difference between $\xrightarrow{a.s.}$ and \xrightarrow{p}

- Convergence in probability is simpler: $X_n \xrightarrow{p} X$ if

$$\forall \epsilon > 0, \lim_{n \rightarrow \infty} P(\{\omega : |X_n(\omega) - X(\omega)| > \epsilon\}) = 0.$$

- This can be rewritten as

$$\forall \epsilon > 0, \lim_{n \rightarrow \infty} P_{X_n, X}(\{|X_n - X| > \epsilon\}) = 0.$$

- It is a requirement on the (bivariate) joint distribution of (X_n, X) as $n \rightarrow \infty$.

Example

- Consider again

$$X_n = \begin{cases} 2^n & \text{with probability } \frac{1}{n} \\ 0 & \text{with probability } 1 - \frac{1}{n} \end{cases}.$$

- Previously established $X_n \xrightarrow{P} 0$ always, but $X_n \xrightarrow{a.s.} 0$ only for some underlying probability spaces.
 - Note: Since $X_n \xrightarrow{P} 0$, if $X_n \xrightarrow{a.s.} X$ then $X = 0$ (almost surely).
- Can also break $X_n \xrightarrow{a.s.} 0$ by putting conditions on $P_{\{X_k\}_{k \geq n}, X}$:
- Suppose $\{X_k\}_{k \geq n}$ is an independent sequence of random variables.

Example

- Adding this condition does nothing to $P_{X_n, X}$ for any n ($X_n \xrightarrow{P} 0$), but $X_n \not\xrightarrow{a.s.} 0$:

$$\begin{aligned} & P_{\{X_k\}_{k \geq n}, X}(\cup_{k \geq n} \{|X_k - X| > \epsilon\}) \\ &= 1 - P_{\{X_k\}_{k \geq n}}(\cap_{k \geq n} \{|X_k - 0| \leq \epsilon\}) \\ &= 1 - \prod_{k=n}^{\infty} P_{X_k}(X_k = 0) \\ &= 1 - \prod_{k=n}^{\infty} \left(\frac{k-1}{k} \right) \\ &= 1 - \lim_{N \rightarrow \infty} \prod_{k=n}^N \left(\frac{k-1}{k} \right) \\ &= 1 - \lim_{N \rightarrow \infty} \left(\frac{n-1}{N} \right) = 1 \end{aligned}$$

for all n . So we do not get convergence a.s.!

Questions?

Convergence in r -th moment

- Let $\{X_n\}_{n \geq 1}, X$ be random variables on some probability space (Ω, \mathcal{F}, P) .
- X_n converges in r -th mean to X $\left(X_n \xrightarrow{r\text{-th}} X\right)$ for some $r > 0$ if

$$E(|X_n - X|^r) \rightarrow 0.$$

- Follows from Chebyshev's inequality that $X_n \xrightarrow{r\text{-th}} X$ implies $X_n \xrightarrow{P} X$:

$$P(|X_n - X| > \epsilon) \leq \frac{E(|X_n - X|^r)}{\epsilon^r} \rightarrow 0.$$

Convergence in r -th moment

- Converse is false. Consider again:

$$X_n = \begin{cases} 2^n & \text{with prob. } \frac{1}{n^2}; \\ 0 & \text{with prob. } 1 - \frac{1}{n^2}. \end{cases}$$

Then $X_n \xrightarrow{a.s.} 0$ ($\implies X_n \xrightarrow{P} 0$), but

$$E(|X_n - 0|^r) = \frac{2^{nr}}{n^2} \rightarrow \infty.$$

- So $\xrightarrow{a.s.}$ does not imply $\xrightarrow{r\text{-th}}$ for any $r > 0$.
- Note: In this example X_n is unbounded. $\xrightarrow{a.s.}$ does imply $\xrightarrow{r\text{-th}}$ under additional conditions, e.g. dominated/bounded convergence theorem.

Convergence in r -th moment

- To show $\xrightarrow{r\text{-th}}$ does not imply $\xrightarrow{\text{a.s.}}$, consider a function $f(n)$ satisfying $f(n) \in [0, 1]$ for all n and $\lim_{n \rightarrow \infty} f(n) = 0$. Let

$$X_n = \begin{cases} 1 & \text{with prob. } f(n); \\ 0 & \text{with prob. } 1 - f(n). \end{cases}$$

- We have:

$$\mathbb{E}(|X_n - 0|^r) = f(n) \rightarrow 0,$$

but (see e.g. slides 21+22) X_n does not necessarily converge a.s. to 0.

Convergence of Random Vectors

- A sequence of $(K \times 1)$ random vectors $X_n \xrightarrow{P} X$ if $\forall \epsilon > 0$:

$$P(\|X_n - X\| > \epsilon) \rightarrow 0$$

as $n \rightarrow \infty$, where $\|\cdot\|$ is the euclidean norm on \mathbb{R}^K :

$$\|X\| = \sqrt{\sum_{i=1}^K X_i^2},$$

where X_i is the i -th component of X .

- $X_n \xrightarrow{a.s.} X$ if:

$$P(\{\omega : \|X_n(\omega) - X(\omega)\| \rightarrow 0\}) = 1.$$

- $X_n \xrightarrow{r\text{-th}} X$ if

$$\lim_{n \rightarrow \infty} E(\|X_n - X\|^r) = 0.$$

Convergence of Random Vectors

- ① $X_n \xrightarrow{p} X \iff X_{n,i} \xrightarrow{p} X_i \text{ for } i = 1, \dots, k;$
- ② $X_n \xrightarrow{a.s.} X \iff X_{n,i} \xrightarrow{a.s.} X_i \text{ for } i = 1, \dots, k;$
- ③ $X_n \xrightarrow{r-th} X \iff X_{n,i} \xrightarrow{r-th} X_i \text{ for } i = 1, \dots, k.$

Proof.

Part 1: Note $|X_{n,i} - X_i| \leq \|X_n - X\| \leq \sqrt{K} \max_{i \leq K} |X_{n,i} - X_i|$.

If $X_{n,i} \xrightarrow{p} X_i$ for all i , then

$$\begin{aligned} P(\|X_n - X\| > \epsilon) &\leq P\left(\sqrt{K} \max_i |X_{n,i} - X_i| > \epsilon\right) \\ &= P\left(\cup_{i=1}^K \left\{\sqrt{K} |X_{n,i} - X_i| > \epsilon\right\}\right) \\ &\leq \sum_{i=1}^K P\left(|X_{n,i} - X_i| > \epsilon/\sqrt{K}\right) \rightarrow 0. \end{aligned}$$

while if $X_n \xrightarrow{p} X$, $P(|X_{n,i} - X_i| > \epsilon) \leq P(\|X_n - X\| > \epsilon) \rightarrow 0$. \square

Convergence in Distribution

- Weakest notion of convergence (implied by \xrightarrow{P}).
- Sequence of random variables X_n converges in distribution to X ($X_n \xrightarrow{d} X$) if

$$F_{X_n}(x) \rightarrow F_X(x)$$

for all x such that F_X is continuous at x .

- Why only at continuity points of F_X ?
 - For X continuous, F_X continuous everywhere, so no problem.
 - For X discrete, F_X is only right-continuous.
 - Take $X_n = \frac{1}{n}$. Clearly $X_n \rightarrow 0$, but $\forall n$,
 $F_{X_n}(0) = 0 \neq 1 = F_X(0)$.
 - Since $X_n \rightarrow X$ in ordinary sense, should expect $X_n \xrightarrow{d} X$.
 - 0 is the only point at which $F_{X_n} \rightarrow F_X$ fails, and is the only discontinuity point of F_X .

Convergence in Distribution

- In contrast to \xrightarrow{p} , $\xrightarrow{a.s.}$, $\xrightarrow{r-th}$, $\{X_n\}_{n \geq 1}$, X don't need to be defined on same probability space.
- Intuitively: \xrightarrow{d} merely requires distribution of X_n converges to distribution of X .
 - For this reason, if F_X is known (e.g. standard normal), it is common to see $X_n \xrightarrow{d} \mathcal{N}(0, 1)$.
- Equivalently, $X_n \xrightarrow{d} X$ iff either
 - 1 $E(g(X_n)) \rightarrow E(g(X)) \forall$ bounded continuous functions g .
 - 2 $E(g(X_n)) \rightarrow E(g(X)) \forall$ bounded lipschitz functions g .
- (g is Lipschitz if $\exists K$ such that $|g(x) - g(y)| \leq K|x - y|$).

Questions?

$X_n \xrightarrow{p} X$ implies $X_n \xrightarrow{d} X$

Proof.

Suppose $X_n \xrightarrow{p} X$. We will use equivalent condition 2. to show \xrightarrow{d} .
Let g be any bounded Lipschitz function:

$$|g(x) - g(y)| \leq K|x - y|; \quad |g(x)| \leq B.$$

We need to show

$$E(g(X_n)) \rightarrow E(g(X)).$$

First note that for any $\epsilon > 0$:

$$\begin{aligned} & |E(g(X_n) - g(X))| \\ & \leq E(|g(X_n) - g(X)|) \\ & = E(|g(X_n) - g(X)| \mathbf{1}_{|X_n - X| > \epsilon}) + E(|g(X_n) - g(X)| \mathbf{1}_{|X_n - X| \leq \epsilon}) \\ & \leq \underbrace{2BP(|X_n - X| > \epsilon)}_{(1)} + \underbrace{KE(|X_n - X| \mathbf{1}_{|X_n - X| \leq \epsilon})}_{(2)}. \end{aligned}$$

$$X_n \xrightarrow{p} X \text{ implies } X_n \xrightarrow{d} X$$

Proof.

Notice that

$$(1) = 2BP(|X_n - X| > \epsilon) \rightarrow 0$$

because $X_n \xrightarrow{p} X$. Also note that

$$(2) = KE(|X_n - X| \mathbf{1}_{|X_n - X| \leq \epsilon}) \leq K\epsilon.$$

In summary:

$$|E(g(X_n) - g(X))| \leq o(1) + K\epsilon,$$

where notation “ $o(1)$ ” means a sequence converging to 0. Since ϵ can be chosen arbitrarily small, result follows. □

$X_n \xrightarrow{d} X$ does not imply $X_n \xrightarrow{p} X$

- First note that $X_n \xrightarrow{d} X$ can occur even if random variables are not defined on the same probability space.
- For a more concrete example, let

$$X_n = Z = \begin{cases} 1 & \text{with probability } \frac{1}{2}; \\ -1 & \text{with probability } \frac{1}{2}; \end{cases}$$
$$X = -Z.$$

Then $X_n \xrightarrow{d} X$ since Z has the same distribution as $-Z$, but, for ϵ small,

$$P(|X_n - X| > \epsilon) = P(2|Z| > \epsilon) = 1$$

for all n , so $X_n \not\xrightarrow{p} X$.

Exception! $X_n \xrightarrow{d} c$ implies $X_n \xrightarrow{p} c$

- If $X_n \xrightarrow{d} c$ for some constant c , then $X_n \xrightarrow{p} c$:

Proof.

Suppose $X_n \xrightarrow{d} c$. This means

$$F_{X_n}(x) \rightarrow \begin{cases} 0 & x < c; \\ 1 & x > c. \end{cases}$$

Need to show $\forall \epsilon > 0$:

$$P(|X_n - c| > \epsilon) \rightarrow 0.$$

Rewrite

$$\begin{aligned} P(|X_n - c| > \epsilon) &= P(\{X_n - c > \epsilon\} \cup \{X_n - c < -\epsilon\}) \\ &= P(X_n > c + \epsilon) + P(X_n < c - \epsilon) \\ &= 1 - F_{X_n}(c + \epsilon) + F_{X_n}(c - \epsilon) - P(X_n = c - \epsilon) \\ &\leq 1 - F_{X_n}(c + \epsilon) + F_{X_n}(c - \epsilon) \rightarrow 1 - 1 + 0 = 0. \end{aligned}$$

\xrightarrow{d} for random vectors

- Let $\{X_n\}_{n \geq 1}, X$ be $(K \times 1)$ random vectors with distribution functions $\{F_{X_n}\}_{n \geq 1}, F_X$.
- X_n converges in distribution to X if

$$F_{X_n}(x) \rightarrow F_X(x)$$

for all x such that F_X is continuous at x .

- Show in Problem Set that $X_n \xrightarrow{d} X$ implies $X_{n,i} \xrightarrow{d} X_i$ for $i = 1, \dots, K$.

\xrightarrow{d} for random vectors

- Earlier we saw that for random vectors $X_n \xrightarrow{\text{a.s.} / p / r\text{-th}} X$, iff the components $X_{n,i} \xrightarrow{\text{a.s.} / p / r\text{-th}} X_i$.
- NOT true for \xrightarrow{d} : e.g. Suppose for all n :

$$\begin{pmatrix} X_n \\ Y_n \end{pmatrix} = \begin{pmatrix} X \\ Y \end{pmatrix} \sim \mathcal{N} \left(\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 & \rho \\ \rho & 1 \end{pmatrix} \right).$$

Now let

$$\begin{pmatrix} Z \\ W \end{pmatrix} \sim \mathcal{N} \left(\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right).$$

Clearly $X_n \xrightarrow{d} Z$ and $Y_n \xrightarrow{d} W$ (since X, Y, Z, W all have marginal distribution $\mathcal{N}(0, 1)$) but

$$\begin{pmatrix} X_n \\ Y_n \end{pmatrix} \xrightarrow{d} \begin{pmatrix} X \\ Y \end{pmatrix} \neq \begin{pmatrix} Z \\ W \end{pmatrix}.$$

\xrightarrow{d} for random vectors

- Takeaway: We can't simply define \xrightarrow{d} for vectors by applying the definition for random variables to each component, because the marginal distributions do not contain all the information of the joint distribution.
- Exception: Suppose random vectors $X_n \xrightarrow{d} X$ and $Y_n \xrightarrow{p} c$ for some constant vector c . Then:

$$\begin{pmatrix} X_n \\ Y_n \end{pmatrix} \xrightarrow{d} \begin{pmatrix} X \\ c \end{pmatrix}.$$

- We will use this fact later to find the asymptotic distribution of OLS/IV estimators.

Cramér-Wold Device

- Although convergence of marginals doesn't imply joint convergence, we can express \xrightarrow{d} for vectors in terms of \xrightarrow{d} for linear combinations of elements:

Theorem

(Cramér–Wold) Let $\{X_n\}_{n \geq 1}, X$ be $(K \times 1)$ random vectors.

Then:

$$X_n \xrightarrow{d} X \iff t'X_n \xrightarrow{d} t'X \text{ for all } t \in \mathbb{R}^k.$$

Continuous Mapping Theorem

- Let $g : \mathbb{R}^k \rightarrow \mathbb{R}^n$ be a function that is continuous on a set $S \subset \mathbb{R}^k$ with $P(X \in S) = 1$. Then the following hold:

$$X_n \xrightarrow{a.s.} X \implies g(X_n) \xrightarrow{a.s.} g(X);$$

$$X_n \xrightarrow{p} X \implies g(X_n) \xrightarrow{p} g(X);$$

$$X_n \xrightarrow{d} X \implies g(X_n) \xrightarrow{d} g(X).$$

- The theorem doesn't hold for $\xrightarrow{r\text{-th}}$: Take

$$X_n = \begin{cases} n & \text{with probability } \frac{1}{n^2}; \\ 0 & \text{with probability } 1 - \frac{1}{n^2}. \end{cases}$$

Letting $g(x) = x^2$, we see $E(|X_n - 0|) = \frac{1}{n} \rightarrow 0$ but, for all n :

$$E(|g(X_n) - g(0)|) = E(|X_n^2 - 0|) = 1.$$

Continuous Mapping theorem

- It is important that $P(X \in S) = 1$. To see this, suppose

$$\begin{pmatrix} X_n \\ Y_n \end{pmatrix} \xrightarrow{d} \begin{pmatrix} X \\ c \end{pmatrix}.$$

- Consider the continuous function $g : \mathbb{R}^2 \rightarrow \mathbb{R}$ given by $g(x, y) = \frac{x}{y}$. g is continuous except at points $(x, 0) \in \mathbb{R}^2$.
Set

$$S = \mathbb{R}^2 \setminus \{(x, 0) : x \in \mathbb{R}\}.$$

If $c \neq 0$, then $P((X, c) \in S) = 1$, and the CMT gives

$$g(X_n, Y_n) = \frac{X_n}{Y_n} \xrightarrow{d} \frac{X}{c} = g(X, c).$$

If $c = 0$, then $P((X, c) \in S) = 0$. This would lead to the nonsensical result

$$\frac{X_n}{Y_n} \xrightarrow{d} \frac{X}{0}.$$

Proofs

- $\xrightarrow{a.s.}$: $X_n \xrightarrow{a.s.} X$ means $P(\omega : X_n(\omega) \rightarrow X(\omega)) = 1$. Since $P(\omega : g \text{ is continuous at } X(\omega)) = 1$, it follows that

$$P(\omega : X_n(\omega) \rightarrow X(\omega) \text{ and } g \text{ is continuous at } X(\omega)) = 1.$$

It follows from ordinary analysis that

$$P(\omega : g(X_n(\omega)) \rightarrow g(X(\omega))) = 1.$$

Proofs

- \xrightarrow{P} : Want to show that $P(|g(X_n) - g(X)| > \epsilon) \rightarrow 0$ for any $\epsilon > 0$, and we know that $P(|X_n - X| > \delta) \rightarrow 0$ for any $\delta > 0$.
- Given $\epsilon > 0$, define for each $\delta > 0$:

$$B_\delta = \{x \in \mathbb{R}^k | \exists y \in \mathbb{R}^k : |x - y| \leq \delta \text{ and } |g(x) - g(y)| > \epsilon\}.$$

- These are points where $|X - X_n|$ small *doesn't* imply $|g(X_n) - g(X)|$ is small.

Proofs

- Note if $X \notin B^\delta$ then $|g(X) - g(y)| \leq \epsilon$ for all y such that $|X - y| \leq \delta$.
- If $X \notin B^\delta$, $|g(X) - g(X_n)| \leq \epsilon$ when $|X - X_n| \leq \delta$. So:

$$\begin{aligned} P(|g(X) - g(X_n)| > \epsilon) &\leq P(|X - X_n| > \delta) \\ &\quad + P(\{|X - X_n| \leq \delta\} \cap \{X \in B^\delta\}) \\ &\leq P(|X - X_n| > \delta) + P(X \in B^\delta) \\ &= P(|X - X_n| > \delta) + P(X \in B^\delta \cap S), \end{aligned}$$

since

$$\begin{aligned} P(X \in B^\delta \cap S) &= P(X \in B^\delta) + P(X \in S) - P(X \in B^\delta \cup S) \\ &= P(X \in B^\delta) + 1 - 1 = P(X \in B^\delta). \end{aligned}$$

Proofs

- $P(|X - X_n| > \delta)$ can be made arbitrarily small for any $\delta > 0$.
- Since $B^\delta \cap S$ only contains continuity points of g , $B^\delta \cap S \downarrow \emptyset$ as $\delta \downarrow 0$ because for any $x \in S$, $x \notin B^\delta$ for δ small enough.
- Let $\delta_n \downarrow 0$. We have

$$\lim_{\delta \rightarrow 0} P(X \in B^\delta \cap S) = \lim_{n \rightarrow \infty} P(X \in B^{\delta_n} \cap S) = P(X \in \emptyset) = 0.$$

- The proof for \xrightarrow{d} is omitted.

Questions?

Example: Slutsky's Theorem

Theorem

Suppose $X_n \xrightarrow{d} X$ and $Y_n \xrightarrow{p} c$ for some constant c . Then:

$$X_n + Y_n \xrightarrow{d} X + c;$$

$$X_n Y_n \xrightarrow{d} Xc;$$

$$X_n/Y_n \xrightarrow{d} X/c \text{ provided } c \neq 0.$$

Proof.

We stated that $X_n \xrightarrow{d} X$ and $Y_n \xrightarrow{p} c$ implies

$$\begin{pmatrix} X_n \\ Y_n \end{pmatrix} \xrightarrow{d} \begin{pmatrix} X \\ c \end{pmatrix}.$$

The result follows by noting that $x + y$, xy and x/y are all continuous functions of (x, y) , provided $y \neq 0$ in the last case. \square

Example: Slutsky's Theorem

- It is important that Y_n converges in probability to a constant! If instead, for all n

$$Y_n = (-1)^n X_n \sim \mathcal{N}(0, 1),$$

then $X_n + Y_n = 0$ for odd n , and $X_n + Y_n \sim \mathcal{N}(0, 4)$ for even n . Thus,

$$F_{X_n + Y_n}(x)$$

does not converge for any $x \in \mathbb{R}$. This means $X_n + Y_n$ cannot converge in distribution.

Example: Sample Correlation

- Suppose $\{(X_i, Y_i)\}_{i \geq 1}$ is a sequence of (2×1) iid random vectors with $E(X_i^2) < \infty$, $E(Y_i^2) < \infty$.
- The sample correlation between X, Y is given by

$$\begin{aligned}\hat{\rho}_{XY} &= \frac{\sum_{i=1}^n (X_i - \bar{X})(Y_i - \bar{Y})}{\sqrt{\sum_{i=1}^n (X_i - \bar{X})^2} \sqrt{\sum_{i=1}^n (Y_i - \bar{Y})^2}} \\ &= \frac{\frac{1}{n} \sum_{i=1}^n X_i Y_i - \bar{X} \bar{Y}}{\sqrt{\frac{1}{n} \sum_{i=1}^n X_i^2 - \bar{X}^2} \sqrt{\frac{1}{n} \sum_{i=1}^n Y_i^2 - \bar{Y}^2}},\end{aligned}$$

where $\bar{X} := \frac{1}{n} \sum_{i=1}^n X_i$ and $\bar{Y} = \frac{1}{n} \sum_{i=1}^n Y_i$ are the sample means.

Example: Sample Correlation

- We have already seen that $\bar{X} \xrightarrow{p} E(X)$ and $\bar{Y} \xrightarrow{p} E(Y)$.
- Next, note that since the vectors (X_i, Y_i) are iid, the product $X_i Y_i$ is an iid sequence of random variables.
- By the weak law of large numbers,

$$\frac{1}{n} \sum_{i=1}^n X_i Y_i \xrightarrow{p} E(XY);$$

$$\frac{1}{n} \sum_{i=1}^n X_i^2 \xrightarrow{p} E(X^2);$$

$$\frac{1}{n} \sum_{i=1}^n Y_i^2 \xrightarrow{p} E(Y^2).$$

Example: Sample Correlation

- It follows that

$$\left(\bar{X}, \bar{Y}, \frac{1}{n} \sum_{i=1}^n X_i Y_i, \frac{1}{n} \sum_{i=1}^n X_i^2, \frac{1}{n} \sum_{i=1}^n Y_i^2 \right) \\ \xrightarrow{P} (E(X), E(Y), E(XY), E(X^2), E(Y^2)).$$

- Now let

$$g(x, y, s, t, w) = \frac{s - xy}{\sqrt{t - x^2} \sqrt{w - y^2}}.$$

- g is continuous at all points except where $t = x^2$ and $w = y^2$.
Provided neither X nor Y are constant random variables (if they were the sample variances would also be 0!) we get

$$E(X^2) > E(X)^2; \quad E(Y^2) > E(Y)^2,$$

so g is continuous at

$$(E(X), E(Y), E(XY), E(X^2), E(Y^2)).$$

Example: Sample Correlation

- It follows by the continuous mapping theorem that:

$$\begin{aligned} & \frac{\frac{1}{n} \sum_{i=1}^n X_i Y_i - \bar{X} \bar{Y}}{\sqrt{\frac{1}{n} \sum_{i=1}^n X_i^2 - \bar{X}^2} \sqrt{\frac{1}{n} \sum_{i=1}^n Y_i^2 - \bar{Y}^2}} \\ & \xrightarrow{p} \frac{E(XY) - E(X)E(Y)}{\sqrt{E(X^2) - E(X)^2} \sqrt{E(Y^2) - E(Y)^2}} \\ & = \frac{\text{Cov}(X, Y)}{\sqrt{\text{Var}(X) \text{Var}(Y)}}, \end{aligned}$$

which is the population correlation coefficient.

Example

- A form of the following result will appear several times when we analyse OLS/IV estimators.
- Let $A_n \in \mathbb{R}^{P \times K}$ be a sequence of matrices converging in probability to a constant matrix A .
 - This is just the same as vector convergence: Stack the columns on top of each other!
- Let B_n be a sequence of $(K \times 1)$ random vectors such that

$$B_n \xrightarrow{d} \mathcal{N}(\mu, \Sigma).$$

Then:

$$A_n B_n \xrightarrow{d} A \mathcal{N}(\mu, \Sigma) \sim \mathcal{N}(A\mu, A\Sigma A').$$

Example

Proof.

Since the vector consisting of the columns of A_n , denoted $\text{vec}(A_n)$ converges in probability to $\text{vec}(A)$, a constant vector, we obtain

$$\begin{pmatrix} B_n \\ \text{vec}(A_n) \end{pmatrix} \xrightarrow{d} \begin{pmatrix} \mathcal{N}(\mu, \Sigma) \\ \text{vec}(A) \end{pmatrix}.$$

By the continuous mapping theorem,

$$A_n B_n \xrightarrow{d} A \mathcal{N}(\mu, \Sigma).$$

Since $E(AX) = AE(X)$, and we showed in problem set 1 that $\text{Var}(AX) = A\text{Var}(X)A'$, we conclude that

$$A \mathcal{N}(\mu, \Sigma) \sim \mathcal{N}(A\mu, A\Sigma A')$$

because linear transformations of multivariate normals are also (multivariate) normal. □

Summary of implications

Questions?