

EE263 Homework 2
Fall 2025
due Thursday 10/9, at 11:59 PM

2.160. Some matrices from signal processing. We consider $x \in \mathbb{R}^n$ as a signal, with x_i the (scalar) value of the signal at (discrete) time period i , for $i = 1, \dots, n$. Below we describe several transformations of the signal x , that produce a new signal y (whose dimension varies). For each one, find a matrix A for which $y = Ax$.

- a) $2\times$ *up-conversion with linear interpolation*. We take $y \in \mathbb{R}^{2n-1}$. For i odd, $y_i = x_{(i+1)/2}$. For i even, $y_i = (x_{i/2} + x_{i/2+1})/2$. Roughly speaking, this operation doubles the sample rate, inserting new samples in between the original ones using linear interpolation.
- b) $2\times$ *down-sampling*. We assume here that n is even, and take $y \in \mathbb{R}^{n/2}$, with $y_i = x_{2i}$.
- c) $2\times$ *down-sampling with averaging*. We assume here that n is even, and take $y \in \mathbb{R}^{n/2}$, with $y_i = (x_{2i-1} + x_{2i})/2$.

3.250. Color perception. Human color perception is based on the responses of three different types of color light receptors, called *cones*. The three types of cones have different spectral-response characteristics, and are called L, M, and, S because they respond mainly to long, medium, and short wavelengths, respectively. In this problem we will divide the visible spectrum into 20 bands, and model the cones' responses as follows:

$$L_{\text{cone}} = \sum_{i=1}^{20} l_i p_i, \quad M_{\text{cone}} = \sum_{i=1}^{20} m_i p_i, \quad S_{\text{cone}} = \sum_{i=1}^{20} s_i p_i,$$

where p_i is the incident power in the i th wavelength band, and l_i , m_i and s_i are nonnegative constants that describe the spectral responses of the different cones. The perceived color is a complex function of the three cone responses, *i.e.*, the vector $(L_{\text{cone}}, M_{\text{cone}}, S_{\text{cone}})$, with different cone response vectors perceived as different colors. (Actual color perception is a bit more complicated than this, but the basic idea is right.)

- a) *Metamers*. When are two light spectra, p and \tilde{p} , visually indistinguishable? (Visually identical lights with different spectral power compositions are called *metamers*.)
- b) *Visual color matching*. In a color matching problem, an observer is shown a test light, and is asked to change the intensities of three primary lights until the sum of the primary lights looks like the test light. In other words, the observer is asked to find a spectrum of the form

$$p_{\text{match}} = a_1 u + a_2 v + a_3 w,$$

where u , v , w are the spectra of the primary lights, and a_i are the intensities to be found, that is visually indistinguishable from a given test light spectrum p_{test} . Can this always be done? Discuss briefly.

- c) *Visual matching with phosphors*. A computer monitor has three phosphors, R , G , and B . It is desired to adjust the phosphor intensities to create a color that looks like

a reference test light. Find weights that achieve the match or explain why no such weights exist. The data for this problem is in `color_perception_data.json`, which contains the vectors `wavelength`, `B_phosphor`, `G_phosphor`, `R_phosphor`, `L_coefficients`, `M_coefficients`, `S_coefficients`, and `test_light`.

- d) *Effects of illumination.* An object's surface can be characterized by its reflectance (*i.e.*, the fraction of light it reflects) for each band of wavelengths. If the object is illuminated with a light spectrum characterized by I_i , and the reflectance of the object is r_i (which is between 0 and 1), then the reflected light spectrum is given by $I_i r_i$, where $i = 1, \dots, 20$ denotes the wavelength band. Now consider two objects illuminated (at different times) by two different light sources, say an incandescent bulb and sunlight. Sally argues that if the two objects look identical when illuminated by a tungsten bulb, then they will look identical when illuminated by sunlight. Beth disagrees: she says that two objects can appear identical when illuminated by a tungsten bulb, but look different when lit by sunlight. Who is right? If Sally is right, explain why. If Beth is right give an example of two objects that appear identical under one light source and different under another. You can use the vectors `sunlight` and `tungsten` defined in the data file as the light sources.

Remark. Spectra, intensities, and reflectances are all nonnegative quantities, which the material of EE263 doesn't address. So just ignore this while doing this problem. These issues can be handled using the material of EE364a, however.

3.260. Halfspace. Suppose $a, b \in \mathbb{R}^n$ are two given points. Show that the set of points in \mathbb{R}^n that are closer to a than b is a halfspace, *i.e.*:

$$\{x \mid \|x - a\| \leq \|x - b\|\} = \{x \mid c^T x \leq d\}$$

for appropriate $c \in \mathbb{R}^n$ and $d \in \mathbb{R}$. Give c and d explicitly, and draw a picture showing a , b , c , and the halfspace.

3.300. Orthogonal complement of a subspace. If \mathcal{V} is a subspace of \mathbb{R}^n we define \mathcal{V}^\perp as the set of vectors orthogonal to every element in \mathcal{V} , *i.e.*,

$$\mathcal{V}^\perp = \{x \mid \langle x, y \rangle = 0, \forall y \in \mathcal{V}\}.$$

- Verify that \mathcal{V}^\perp is a subspace of \mathbb{R}^n .
- Suppose \mathcal{V} is described as the span of some vectors v_1, v_2, \dots, v_r . Express \mathcal{V} and \mathcal{V}^\perp in terms of the matrix $V = \begin{bmatrix} v_1 & v_2 & \cdots & v_r \end{bmatrix} \in \mathbb{R}^{n \times r}$ using common terms (range, nullspace, transpose, etc.)
- Show that every $x \in \mathbb{R}^n$ can be expressed uniquely as $x = v + v^\perp$ where $v \in \mathcal{V}$, $v^\perp \in \mathcal{V}^\perp$. *Hint:* let v be the projection of x on \mathcal{V} .
- Show that $\dim \mathcal{V}^\perp + \dim \mathcal{V} = n$.
- Show that $\mathcal{V} \subseteq \mathcal{U}$ implies $\mathcal{U}^\perp \subseteq \mathcal{V}^\perp$.

3.450. Minimum distance and maximum correlation decoding. We consider a simple communication system, in which a sender transmits one of N possible signals to a receiver, which receives a version of the signal sent that is corrupted by noise. Based on the corrupted received signal, the receiver has to estimate or guess which of the N signals was sent. We will represent the signals by vectors in \mathbb{R}^n . We will denote the possible signals as $a_1, \dots, a_N \in \mathbb{R}^n$. These signals, which collectively are called the *signal constellation*, are known to both the transmitter and receiver. When the signal a_k is sent, the received signal is $a_{\text{recd}} = a_k + v$, where $v \in \mathbb{R}^n$ is (channel or transmission) noise. In a communications course, the noise v is described by a statistical model, but here we'll just assume that it is 'small' (and in any case, it does not matter for the problem). The receiver must make a guess or estimate as to which of the signals was sent, based on the received signal a_{recd} . There are many ways to do this, but in this problem we explore two methods.

- *Minimum distance decoding.* Choose as the estimate of the decoded signal the one in the constellation that is closest to what is received, *i.e.*, choose a_k that minimizes $\|a_{\text{recd}} - a_i\|$. For example, if we have $N = 3$ and

$$\|a_{\text{recd}} - a_1\| = 2.2, \quad \|a_{\text{recd}} - a_2\| = 0.3, \quad \|a_{\text{recd}} - a_3\| = 1.1,$$

then the minimum distance decoder would guess that the signal a_2 was sent.

- *Maximum correlation decoding.* Choose as the estimate of the decoded signal the one in the constellation that has the largest inner product with the received signal, *i.e.*, choose a_k that maximizes $a_{\text{recd}}^T a_i$. For example, if we have $N = 3$ and

$$a_{\text{recd}}^T a_1 = -1.1, \quad a_{\text{recd}}^T a_2 = 0.2, \quad a_{\text{recd}}^T a_3 = 1.0,$$

then the maximum correlation decoder would guess that the signal a_3 was sent.

For both methods, let's not worry about breaking ties. You can just assume that ties never occur; one of the signals is always closest to, or has maximum inner product with, the received signal. Give some general conditions on the constellation (*i.e.*, the set of vectors a_1, \dots, a_N) under which these two decoding methods are the same. By 'same' we mean this: for any received signal a_{recd} , the decoded signal for the two methods is the same. Give the simplest condition you can. You must show how the decoding schemes always give the same answer, when your conditions hold. Also, give a specific counterexample, for which your conditions don't hold, and the methods differ. (We are *not* asking you to show that when your conditions don't hold, the two decoding schemes differ for some received signal.) You might want to check simple cases like $n = 1$ (scalar signals), $N = 2$ (only two messages in the constellation), or draw some pictures. But then again, you might not.