

CDA 4203 Sec 001 Spring 2015
Computer System Design
Instructor: Dr. Srinivas Katkoori
Homework 2: PicoBlaze Microcontroller
Handed out on Monday, 26th January
DUE: 11:59:59PM, Monday, 2nd February

Note:

- 1) Recommended submission is by Canvas.
- 2) If you handwrite the answers, you may want to scan and upload to Canvas.
- 3) For all questions, that need assembly program, you should validate in pBlazeIDE and submit the code. You will get credit only if it works in pBlazeIDE.
- 4) Deliverables:
 - (a) Your answers to the problem in a PDF document
 - (b) Your PicoBlaze code validated in pBlaze IDE

Your Name:

Your U#:

1. (5 pts.) PicoBlaze Architecture

Answer the following questions about the PicoBlaze Architecture:

- a. List all storage units and what kind of data they can store (data, instructions, addresses)?
- b. What is the address range (in hex) for the instruction PROM?
- c. How many cycles does an instruction consume?
- d. What is the purpose of NOP instruction?
- e. List all instructions that *directly* manipulate the call/return stack.
- f. How many clock cycles does instruction decode take?
- g. What is the purpose of the interrupt input? How can we disable interrupts?
- h. What flags does the test instruction affect? Does it affect the register contents?
- i. When we execute a call instruction, does the PicoBlaze save the register file contents?
- j. What is the difference between ADD and ADDCY instructions? Explain why we need two variants of ADD instructions?

- 2. (5 pts.) PicoBlaze – Word Parity:** Write an assembly program to compute the parity of a given word. A word has an *even* parity if it has even number of 1's (e.g., 01101001). Otherwise, it has odd parity (e.g., 10101110). Assume that the word is presented on the IN_PORT (for only two clock cycles). The parity result must be presented on the OUT_PORT. The procedure must output 000hex if the word has even parity and 001hex if it has odd parity. Disable interrupt handling during the parity computation and re-enable when done. Simulate your program using pBlazeIDE simulator.

- 3. (15 pts.) Simple Loopback System¹:** Consider a simple “loopback” system as in Fig. 1. In such a setup, a PC can send a message which is returned (looped) back to PC by the processor. Such a loopback test is helpful to test if the processor is alive or not.

A PC (not shown) interfaces with PicoBlaze processor using an RS232 (serial) connection. Let us examine the case when the PC acts as a transmitter. In this case the data arrives serially on RS232_RX line. But we know that PicoBlaze accepts only byte-size data. So we need to convert the serial data into parallel (8-bit) data. In such a case, a UART (Universal Asynchronous Receiver Transmitter) block can help. UART_RX does the serial-to-parallel conversion i.e., the data arriving on RS232_RX line is buffered in a 16-byte buffer. Whenever new data is presented on rx_data output, UART_RX

¹Adapted from the assignment created by Eric Crabill at San Jose State University.

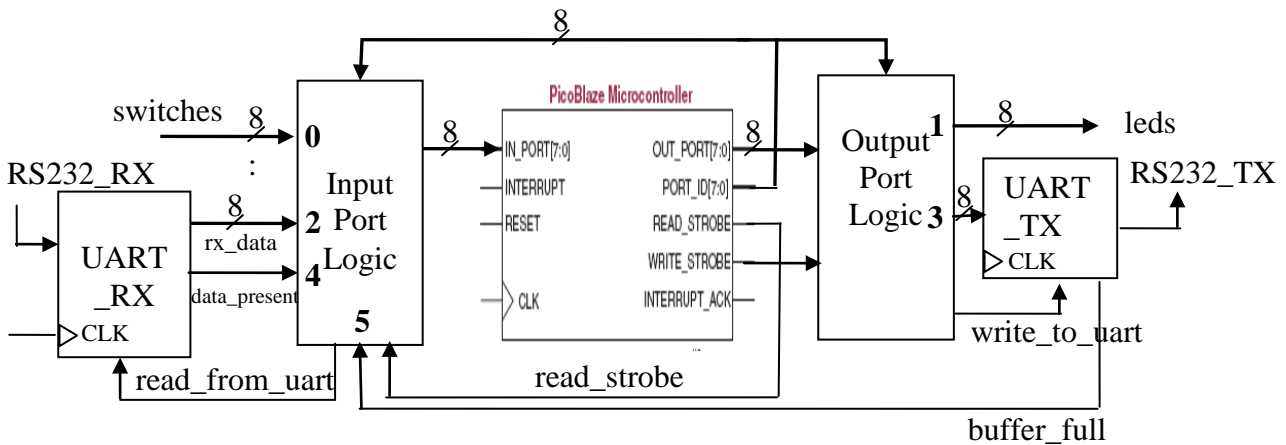


Figure 1: A simple loopback system

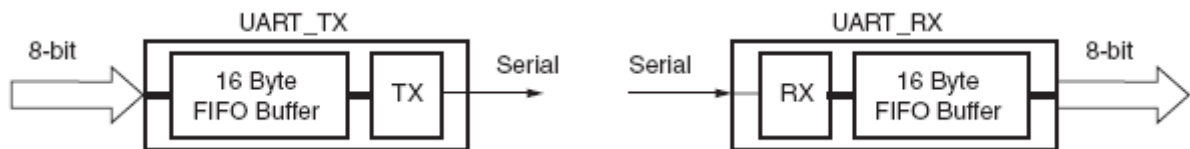


Figure 2 : UART Transmit and Receive Blocks - High Level View

Note that for the sake of clarity, we have not shown the clock and reset signal connections.

will assert `data_present` i.e., `data_present = '1'` in other words `data_present` validates `rx_data`. The “Input Port Logic” block consists of glue logic that connects `UART_RX` to the `IN_PORT`. After PicoBlaze reads the data, it can request the next data item by asserting `read_from_uart` signal.

Now, let us consider the case when PicoBlaze acts as a transmitter i.e., PC is the receiver. In this case, PicoBlaze puts out 8-bit data while PC is expecting serial data. Again, UART (`UART_TX` in Fig. 1) comes to our rescue! The output bus with `id=3` is connected to `UART_TX`. Output Port Logic block interfaces PicoBlaze with `leds` and `UART_TX`.

In this system, we can also manually provide 8-bit data via 8 switches (switches bus in Fig. 1). PicoBlaze can write 8-bit data to drive 8 leds (leds bus in Fig. 1).

Recall that PicoBlaze can accept up to 256 input ports each of which can be addressed by 8-bit `PORT_ID` bus. Similarly, it can drive up to 256 ports and the address of the port being driven appears on `PORT_ID` bus. In Fig. 1, for example, the `id` of the input port, switches, is 0. Similarly, the `rx_data` has `id` of 2. The port `ids` are shown in **bold** font in the Fig.1. The high-level views of UART in transmit and received modes are shown in Fig. 2.

Answer the following questions:

- (2 pts.) Explain under what condition(s) should the following signals be asserted?
 - `read_from_uart`
 - `write_to_uart`
- (4 pts.) `cold_start`: Write code to output a message “Welcome to Loopback!” to the serial port. You need to encode the message in ASCII format. For ASCII table see <http://www.asciitable.com>
Caution: UART_TX buffer size is only 16 bytes!!
- (4 pts.) `led_echo`: Write code to read switches and write it, inverted, to the LEDs.
- (5 pts.) `rs232_echo`: Write code to check if a byte has been received by `UART_RX`. If so, send it back to PC via `UART_TX`.