Robust Regression with Particle Swarm Optimisation and Differential Evolution

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Abstract

A brief tutorial on using Differential Evolution and Particle Swarm Optimisation to estimate a regression model.

1 Introduction

We provide a code example for a robust regression problem. The purpose of this vignette is to provide the code in a convenient way; for more details, please see Gilli et al. [2011]. (The vignette builds on the script comparisonLMS.R.)

2 Data and settings

We start by attaching the package.

```
> require("NMOF")
> require("MASS")
> set.seed(11223344)
```

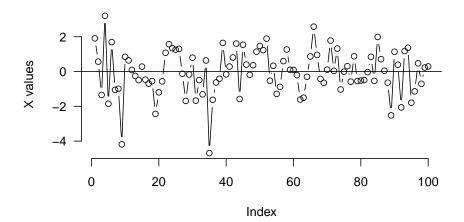
We will use the function lqs from the MASS package [Venables and Ripley, 2002]. We will use an artificial data set with n observations and p regressors, created with the function createData.

We start by creating some artifial data. We collect X and y in the list data. We also add the scalar h which gives the order statistic of the squared residuals to be minimised. Note that we put as .vector(y) into data so that the vector gets 'recycled' in the objective function.

```
> n <- 100L
> p <- 10L
> constant <- TRUE
> sigma <- 3
> oFrac <- 0.1
> h <- 75L
> aux <- createData(n, p, constant, sigma, oFrac)
> X <- aux$X
> y <- aux$y
> data <- list(y = as.vector(y), X = X, h = h)</pre>
```

The outliers are visible.

```
> par(bty = "n", las = 1)
> plot(X[, 2L], type = "b", ylab = "X values")
> abline(h = 0)
```



Two example objective functions, Least Trimmed Squares (LTS) and Least Quantile of Squares (LQS). Note that they are almost identical.

Both functions are vectorised. They work with a single solution (param would be a vector) or a whole population (param would be a matrix; each column would be one solution).

3 Using DE and PSO

We run DE and PSO. We compare the result with lqs.

```
> popsize <- 100L
> generations <- 500L
> ps <- list(min = rep(-10, p), max = rep(10, p), c1 = 0.5, c2 = 1.1,
+ iner = 0.9, initV = 1, nP = popsize, nG = generations, maxV = 5,
+ loopOF = FALSE, printBar = FALSE, printDetail = FALSE)
> de <- list(min = rep(-10, p), max = rep(10, p), nP = popsize,
+ nG = generations, F = 0.7, CR = 0.9, loopOF = FALSE, printBar = FALSE,
+ printDetail = FALSE)
> system.time(solPS <- PSopt(OF = OF, algo = ps, data = data))</pre>
```

```
user system elapsed
   1.89
           0.00
                 1.89
> system.time(solDE <- DEopt(OF = OF, algo = de, data = data))
   user system elapsed
   1.90
           0.00
                    1.91
> if (require(MASS, quietly = TRUE)) {
      system.time(test1 <- lqs(y \sim X[, -1L], adjust = TRUE, nsamp = 100000L,
          method = "lqs", quantile = h))
      res1 <- sort((y - X %*% as.matrix(coef(test1)))^2)[h]
+ } else res1 <- NA
> (res2 <- sort((y - X %*% as.matrix(solPS$xbest))^2)[h])</pre>
[1] 0.2633539
> (res3 <- sort((y - X %*% as.matrix(solDE$xbest))^2)[h])</pre>
[1] 0.2798945
> cat("lqs: ", res1, "\n", "PSopt: ", res2, "\n", "DEopt: ",
      res3, "\n", sep = "")
lqs:
       0.3807335
PSopt: 0.2633539
DEopt: 0.2798945
   To demonstrate the advantage of a vectorised objective function, we can compare it with looping over
the solutions. We first set loopOF to TRUE, so we actually loop over the solutions. (We also reduce the
number of objective function evaluations.)
> popsize <- 20L
> generations <- 150L
> de$nP <- popsize
> de$nG <- generations
> ps$nP <- popsize
> ps$nG <- generations
> de$loopOF <- TRUE
> ps$loopOF <- TRUE
> (t1ps <- system.time(solPS <- PSopt(OF = OF, algo = ps, data = data)))
   user system elapsed
   0.41
           0.00
> (t1de <- system.time(solDE <- DEopt(OF = OF, algo = de, data = data)))
   user system elapsed
   0.39
           0.00
                    0.39
To evaluate the objective function in one step, we loopOF to FALSE.
> de$loopOF <- FALSE
> ps$loopOF <- FALSE
> (t2ps <- system.time(solPS <- PSopt(OF = OF, algo = ps, data = data)))
   user system elapsed
   0.12
           0.00
                    0.12
> (t2de <- system.time(solDE <- DEopt(OF = OF, algo = de, data = data)))
   user system elapsed
```

0.14

0.00

0.14

Speedup:

- > t1ps[[3L]]/t2ps[[3L]]
- [1] 3.416667
- > t1de[[3L]]/t2de[[3L]]
- [1] 2.785714

References

Manfred Gilli, Dietmar Maringer, and Enrico Schumann. *Numerical Methods and Optimization in Finance*. Elsevier, 2011.

William N. Venables and Brian D. Ripley. *Modern Applied Statistics with S.* Springer, 4th edition, 2002. URL http://www.stats.ox.ac.uk/pub/MASS4.