UART Example

1. Write the UART module and the application

a. UART.h

```
#ifndef _UART_H_
#define _UART_H_

//UART APIS
void Uart_Send_String(unsigned char *P_tx_string);
#endif
```

b. UART.c

```
#include "uart.h"
#define UARTODR *((volatile unsigned int* const)((unsigned int*) 0x101f1000))

void Uart_Send_String(unsigned char *P_tx_string){

    while (*P_tx_string != '\0')
    {

        UARTODR = (unsigned int)(*P_tx_string);
        P_tx_string++;
    }
}
```

c. App.c

```
#include "uart.h"

//to check content " arm-none-eabi-objdump.exe -h app.o"
unsigned char string_buffer[100] = "Learn-in-depth:<John Magdy William> ~ 23/7/2022";
unsigned char const ro_data[50] = "read only data /'rodata/' ";
unsigned char unint_data[50];

void main(void){
    Uart_Send_String(string_buffer);
}
```

2. Compile the files using GNU ARM-Crosstoolchain "arm-none-eabi-gcc.exe" that we downloaded (after adding it to the path variables)

```
arm-none-eabi-gcc.exe -c -I . -mcpu=arm926ej-s app.c -o app.o
```

arm-none-eabi-gcc.exe -c -I . -mcpu=arm926ej-s Uart.c -o Uart.o

```
-c Compile and assemble, but do not link arm926ej-S is the board that we will use
```

3. Navigate the .obj files (relocatable images)

```
$ arm-none-eabi-objdump.exe --help
Usage: D:\courses\new_diploma\Diploma online\En\beddedC\labs\unit3-lesson2\ARM\bir
ion(s)> <file(s)>
 Display information from object <file(s)>.
 At least one of the following switches must be given:
  -a, --archive-headers
-f, --file-headers
                                     Display archive header information
Display the contents of the overall file header
   -p, --private-headers
                                      Display object format specific file header contents
  -P, --private=OPT,OPT... Display object format specific contents
-h, --[section-]headers
-x, --all-headers
-d, --disassemble
Display assembler contents of executable section.
                                      Display the contents of all headers
Display assembler contents of executable sections
  -D, --disassemble-all
-S, --source
-s, --full-contents
                                      Display assembler contents of all sections
                                      Intermix source code with disassembly
Display the full contents of all sections requested
                                     Display debug information in object file
Display debug information using ctags style
Display (in raw form) any STABS info in the file
   -g, --debugging
   -e, --debugging-tags
   -G. --stabs
  -W[]LiaprmfFsoRtUuTgAckK] or
   --dwarf[=rawline,=decodedline,=info,=abbrev,=pubnames,=aranges,=macro,=frames,
```

```
arm-none-eabi-objdump.exe -D app.o > app.s
```

arm-none-eabi-objdump.exe -h uart.o

4. Startup code

a. Write Startup.s

```
.global reset
reset:
    ldr sp, = stack_top
    bl main
stop: b stop
```

b. Compile

```
arm-none-eabi-as.exe -mcpu=arm926ej-s startup.s -o startup.o
```

c. Analyze it

```
arm-none-eabi-objdump.exe -h startup.o
```

5. Linker Script

```
ENTRY(reset)
MEMORY{
    Mem(rwx): ORIGIN = 0X00000000, LENGTH = 64M
SECTIONS{
    . = 0x10000;
    .startup . :
        startup.o(.text)
    }> Mem
    .text:
        *(.text) *(.rodata)
    }> Mem
    .data :
        *(.data)
    }> Mem
    .bss:
        *(.bss) *(COMMON)
    . = . + 0x1000; /*stack memory is 4 kb*/
    stack_top = .;
}
```

6. Link all the objects together

arm-none-eabi-ld.exe -T linker_script.ld startup.o app.o uart.o -o learn-in-depth-john.elf -Map=Map_file.map

arm-none-eabi-objdump.exe learn-in-depth-john.elf -h

7. Run the program in the QEMU Simulator

qemu-system-arm -M versatilepb -m 128M -nographic -kernel learn-in-depth-john.elf

```
johnm@John MINGW64 /d/University/Courses/Embedded Diplo
ma/Embedded_Systems_Diploma/Unit_3/Lesson 2 - UART Exam
ple (master)
$ qemu-system-arm -M versatilepb -m 128M -nographic -k
ernel learn-in-depth-john.elf
Learn-in-depth:<John Magdy William> ~ 23/7/2022
```

8. Creating the Makefile

```
#copyright : John
#name of compiler
CC=arm-none-eabi-
#repeated flags in the build
CFLAGS= -g -mcpu=arm926ej-s
LIBS=
INCS= -I .
SRC = $(wildcard *.c)
OBJ = \$(SRC:.c=.o)
As = $(wildcard *.s)
AsOBJ = \$(As:.s=.o)
Project_name=Learn-in-depth-john
all: $(Project_name).bin
    @echo "Build is done"
%.o: %.c
    $(CC)gcc.exe -c $(INCS) $(CFLAGS) $< -o $@
%.o: %.s
    $(CC)as.exe -c $(INCS) $(CFLAGS) $< -o $@
$(Project_name).elf: $(OBJ) $(AsOBJ)
    $(CC)ld.exe -T linker_script.ld $(LIBS) $(OBJ) $(AsOBJ) -o $@
$(Project_name).bin: $(Project_name).elf
    $(CC)objcopy.exe -0 binary $< $@</pre>
clean_all:
    rm *.o *.elf *.bin
clean:
    rm *.elf *.bin
```