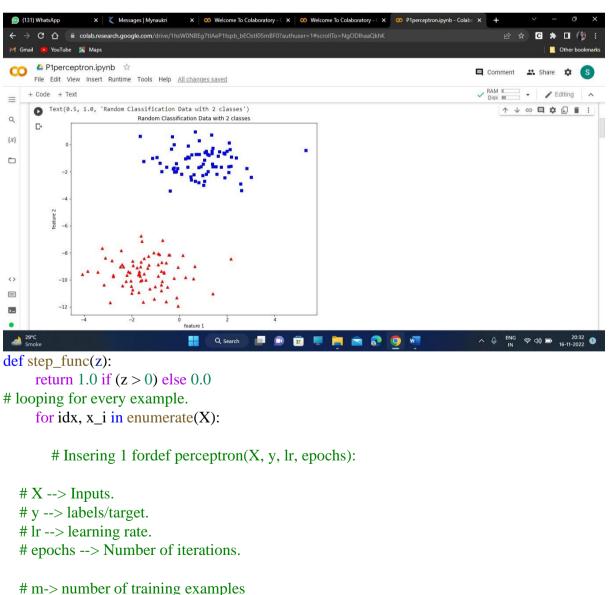
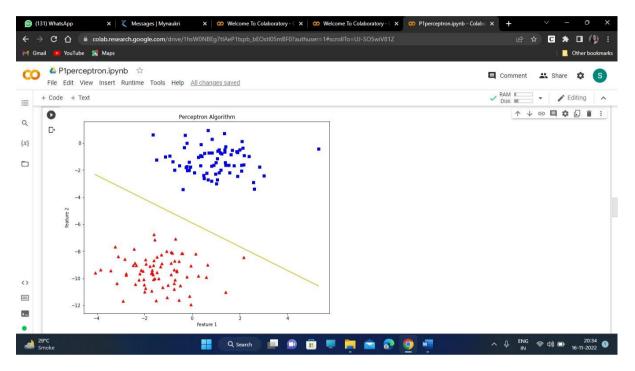


```
AIM: To implement Perceptron Algorithm
CODE:
from sklearn import datasets
import matplotlib.pyplot as plt
import numpy as np
X, y = datasets.make_blobs(n_samples=150,n_features=2,
                 centers=2,cluster_std=1.05,
                random_state=2)
X, y = datasets.make_blobs(n_samples=150,n_features=2,
                 centers=2,cluster_std=1.05,
                 random_state=2)
fig = plt.figure(figsize=(10,8))
plt.plot(X[:, 0][y == 0], X[:, 1][y == 0], 'r^{\prime})
plt.plot(X[:, 0][y == 1], X[:, 1][y == 1], bs')
plt.xlabel("feature 1")
plt.ylabel("feature 2")
plt.title('Random Classification Data with 2 classes')
```



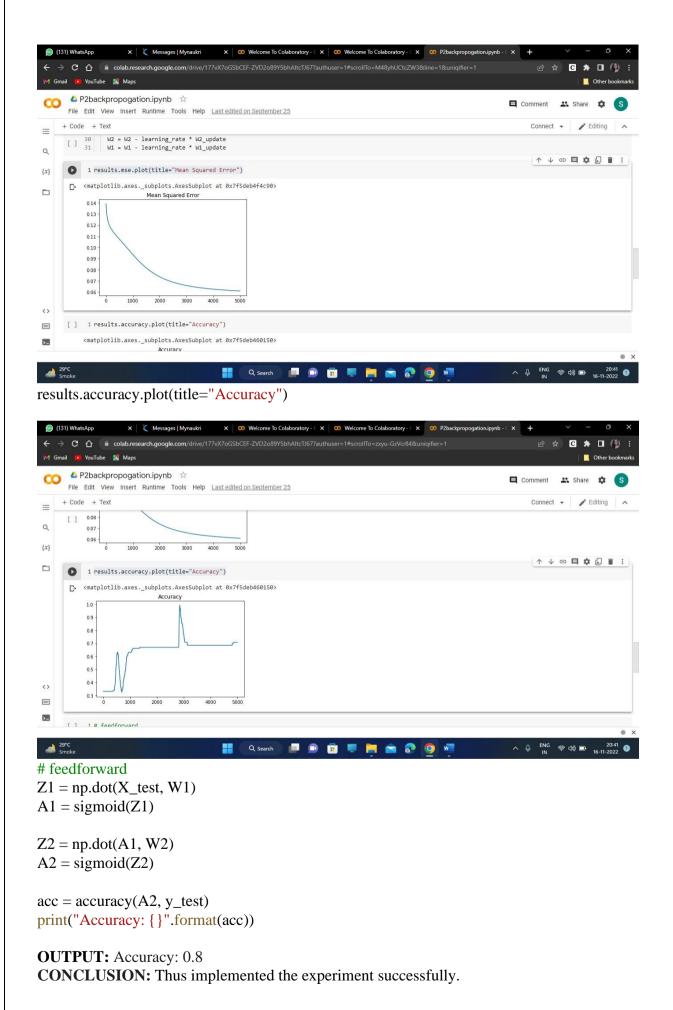
```
# n-> number of features
  m, n = X.shape
  # Initializing parapeters(theta) to zeros.
  \# +1 in n+1 for the bias term.
  theta = np.zeros((n+1,1))
  # Empty list to store how many examples were
  # misclassified at every iteration.
  n_miss_list = []
  # Training.
  for epoch in range(epochs):
     # variable to store #misclassified.
n \text{ miss} = 0
     bias, X0 = 1.
       x_i = np.insert(x_i, 0, 1).reshape(-1,1)
       # Calculating prediction/hypothesis.
       y_hat = step_func(np.dot(x_i.T, theta))
       # Updating if the example is misclassified.
       if (np.squeeze(y_hat) - y[idx]) != 0:
          theta += lr*((y[idx] - y_hat)*x_i)
          # Incrementing by 1.
          n_miss += 1
     # Appending number of misclassified examples
     # at every iteration.
     n_miss_list.append(n_miss)
  return theta, n_miss_list
def plot_decision_boundary(X, theta):
  # X --> Inputs
  # theta --> parameters
  # The Line is y=mx+c
  \# So, Equate mx+c = theta0.X0 + theta1.X1 + theta2.X2
  # Solving we find m and c
  x1 = [min(X[:,0]), max(X[:,0])]
  m = -theta[1]/theta[2]
  c = -theta[0]/theta[2]
  x2 = m*x1 + c
  # Plotting
  fig = plt.figure(figsize=(10,8))
```

```
\begin{array}{l} plt.plot(X[:,0][y==0],\,X[:,1][y==0],\,"r^{\wedge}")\\ plt.plot(X[:,0][y==1],\,X[:,1][y==1],\,"bs")\\ plt.xlabel("feature 1")\\ plt.ylabel("feature 2")\\ plt.title('Perceptron Algorithm')\\ plt.plot(x1,\,x2,\,'y-')\\ theta,\,miss\_l = perceptron(X,\,y,\,0.5,\,100)\\ plot\_decision\_boundary(X,\,theta) \end{array}
```



```
AIM: To implement Back Propagation Algorithm
CODE:
# Import Libraries
import numpy as np
import pandas as pd
from sklearn.datasets import load_iris
from sklearn.model_selection import train_test_split
import matplotlib.pyplot as plt
# Load dataset
data = load iris()
# Get features and target
X=data.data
y=data.target
# Get dummy variable
y = pd.get\_dummies(y).values
y[:3]
Output: array([[1, 0, 0], [1, 0, 0], [1, 0, 0]], dtype=uint8)
#Split data into train and test data
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=20, random_state=4)
# Initialize variables
learning rate = 0.1
iterations = 5000
N = y_{train.size}
# number of input features
input\_size = 4
# number of hidden layers neurons
hidden_size = 2
# number of neurons at the output layer
output size = 3
results = pd.DataFrame(columns=["mse", "accuracy"])
# Initialize weights
np.random.seed(10)
# initializing weight for the hidden layer
W1 = np.random.normal(scale=0.5, size=(input_size, hidden_size))
# initializing weight for the output layer
W2 = np.random.normal(scale=0.5, size=(hidden_size, output_size))
def sigmoid(x):
  return 1/(1 + np.exp(-x))
def mean_squared_error(y_pred, y_true):
```

```
return ((y_pred - y_true)**2).sum() / (2*y_pred.size)
def accuracy(y_pred, y_true):
  acc = y pred.argmax(axis=1) == y true.argmax(axis=1)
  return acc.mean()
for itr in range(iterations):
  # feedforward propagation
  # on hidden layer
  Z1 = np.dot(X_train, W1)
  A1 = sigmoid(Z1)
  # on output layer
  Z2 = np.dot(A1, W2)
  A2 = sigmoid(Z2)
  # Calculating error
  mse = mean_squared_error(A2, y_train)
  acc = accuracy(A2, y_train)
  results=results.append({"mse":mse, "accuracy":acc},ignore_index=True)
  # backpropagation
  E1 = A2 - y_train
  dW1 = E1 * A2 * (1 - A2)
  E2 = np.dot(dW1, W2.T)
  dW2 = E2 * A1 * (1 - A1)
  # weight updates
  W2 update = np.dot(A1.T, dW1) / N
  W1\_update = np.dot(X\_train.T, dW2) / N
  W2 = W2 - learning_rate * W2_update
  W1 = W1 - learning_rate * W1_update
results.mse.plot(title="Mean Squared Error")
```



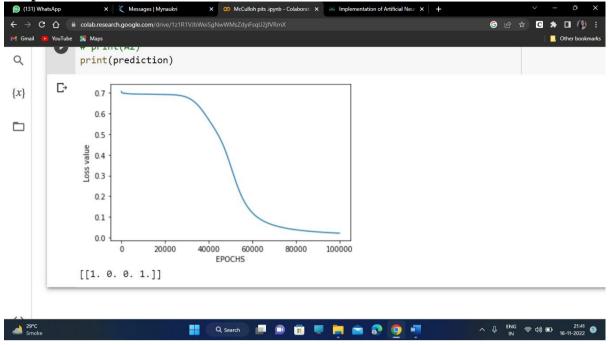
```
AIM: To implement Hebb's Rule in C++
CODE:
#include<iostream>
using namespace std;
int main()
  int m,n;
  cout<<"enter no.of features and no.of training datasets: \n";
  cin>> m>>n;
  int wt1[m], wt2[m];
  int input[n][m];
  cout<<"enter the input matrix row wise "<<endl;
  for(int i=0;i<n;i++)
     for(int j=0;j< m;j++)
       cin>>input[i][j];
  int target1[n], target2[n];
  cout<<" Enter the target in binary : "<<endl;</pre>
  for(int i=0;i<n;i++)
     cin>>target1[i];
 cout<<"Enter the target in bipolar: "<<endl;
  for(int i=0;i<n;i++)
     cin>>target2[i];
  for(int i=0;i<m;i++)
     wt1[i]=0; //step 1: initialise all wts to 0
     wt2[i]=0;
  for(int j=0;j< n;j++)
     cout<<"#########j="<<j<<endl;
     for(int i=0; i< m; i++)
       wt1[i]+= (input[j][i]*target1[j]);
       cout<<"weight1 at i="<<i<" is "<<wt1[i]<<endl;
       wt2[i] += (input[j][i]*target2[j]);
       cout<<"wt2 at i="<<i<" is "<<wt2[i]<<endl;
     }
  cout<<"********OUTPUT*********\nafter 1 epoch: binary weights: "<<endl;
for (int i = 0; i < m; ++i)
```

```
/* code */
    cout<<wt1[i]<<" ";
  cout<<"\nafter 1 epoch: bipolar weights: "<<endl;</pre>
  for (int i = 0; i < m; ++i)
    /* code */
    cout << wt2[i] << " ";
  return 0;
Output:
enter no.of features and no.of training datasets:
enter the input matrix row wise
-1 -1 1
-111
11-1
111
Enter the target in binary:
0
0
Enter the target in bipolar:
-1
-1
-1
########j=0
weight1 at i=0 is 0
wt2 at i=0 is 1
weight1 at i=1 is 0
wt2 at i=1 is 1
weight1 at i=2 is 0
wt2 at i=2 is -1
########j=1
weight1 at i=0 is 0
wt2 at i=0 is 2
weight1 at i=1 is 0
wt2 at i=1 is 0
weight 1 at i=2 is 0
wt2 at i=2 is -2
#######j=2
weight1 at i=0 is 0
wt2 at i=0 is 1
weight1 at i=1 is 0
wt2 at i=1 is -1
weight 1 at i=2 is 0
wt2 at i=2 is -1
########j=3
```

```
AIM: To implement McCulloh Pits model for XOR gate
CODE:
# import Python Libraries
import numpy as np
from matplotlib import pyplot as plt
# Sigmoid Function
def sigmoid(z):
  return 1/(1 + np.exp(-z))
# Initialization of the neural network parameters
# Initialized all the weights in the range of between 0 and 1
# Bias values are initialized to 0
def initializeParameters(inputFeatures, neuronsInHiddenLayers, outputFeatures):
  W1 = np.random.randn(neuronsInHiddenLayers, inputFeatures)
  W2 = np.random.randn(outputFeatures, neuronsInHiddenLayers)
  b1 = np.zeros((neuronsInHiddenLayers, 1))
  b2 = np.zeros((outputFeatures, 1))
  parameters = {"W1" : W1, "b1": b1,
           "W2" : W2, "b2": b2}
  return parameters
# Forward Propagation
def forwardPropagation(X, Y, parameters):
  m = X.shape[1]
  W1 = parameters["W1"]
  W2 = parameters["W2"]
  b1 = parameters["b1"]
  b2 = parameters["b2"]
  Z1 = np.dot(W1, X) + b1
  A1 = sigmoid(Z1)
  Z2 = np.dot(W2, A1) + b2
  A2 = sigmoid(Z2)
  cache = (Z1, A1, W1, b1, Z2, A2, W2, b2)
  logprobs = np.multiply(np.log(A2), Y) + np.multiply(np.log(1 - A2), (1 - Y))
  cost = -np.sum(logprobs) / m
  return cost, cache, A2
# Backward Propagation
def backwardPropagation(X, Y, cache):
  m = X.shape[1]
  (Z1, A1, W1, b1, Z2, A2, W2, b2) = cache
  dZ2 = A2 - Y
  dW2 = np.dot(dZ2, A1.T) / m
  db2 = np.sum(dZ2, axis = 1, keepdims = True)
```

```
dA1 = np.dot(W2.T, dZ2)
  dZ1 = np.multiply(dA1, A1 * (1- A1))
  dW1 = np.dot(dZ1, X.T) / m
  db1 = np.sum(dZ1, axis = 1, keepdims = True) / m
  gradients = {"dZ2": dZ2, "dW2": dW2, "db2": db2,
          "dZ1": dZ1, "dW1": dW1, "db1": db1}
  return gradients
# Updating the weights based on the negative gradients
def updateParameters(parameters, gradients, learningRate):
  parameters["W1"] = parameters["W1"] - learningRate * gradients["dW1"]
  parameters["W2"] = parameters["W2"] - learningRate * gradients["dW2"]
  parameters["b1"] = parameters["b1"] - learningRate * gradients["db1"]
  parameters["b2"] = parameters["b2"] - learningRate * gradients["db2"]
  return parameters
# Model to learn the XOR truth table
X = \text{np.array}([[0, 0, 1, 1], [0, 1, 0, 1]]) \# XOR \text{ input}
Y = np.array([[0, 1, 1, 0]]) # XOR output
# Define model parameters
neuronsInHiddenLayers = 2 \# number of hidden layer neurons (2)
inputFeatures = X.shape[0] # number of input features (2)
outputFeatures = Y.shape[0] # number of output features (1)
parameters = initializeParameters(inputFeatures, neuronsInHiddenLayers, outputFeatures)
epoch = 100000
learningRate = 0.01
losses = np.zeros((epoch, 1))
for i in range(epoch):
  losses[i, 0], cache, A2 = forwardPropagation(X, Y, parameters)
  gradients = backwardPropagation(X, Y, cache)
  parameters = updateParameters(parameters, gradients, learningRate)
# Evaluating the performance
plt.figure()
plt.plot(losses)
plt.xlabel("EPOCHS")
plt.ylabel("Loss value")
plt.show()
# Testing
X = \text{np.array}([[1, 1, 0, 0], [0, 1, 0, 1]]) \# XOR \text{ input}
cost, A2 = forwardPropagation(X, Y, parameters)
prediction = (A2 > 0.5) * 1.0
# print(A2)
print(prediction)
```

Output:



```
AIM: To implement Maxnet
CODE:
def winner(mylist):
  a=[]
  for i in range(0,len(mylist)):
    if mylist[i]>0:
       a.append(i)
  return a
m=0
delta=0
vin=[0]
epoch=0
f=open("maxnet input.txt")
linenumber=0
while True:
       line=f.readline()
       line=line.rstrip('\n')
       if len(line)==0:
         break
       linenumber+=1
       word=line.split('=')
       if linenumber==1:
         m=int(word[1])
         yin=yin*m
       if linenumber==3:
         x=word[1].split(',')
         for i in range(x. len ()):
            yin[i]=float(x[i])
       if linenumber==2:
         delta=float(word[1])
f.close();
while True:
  epoch+=1
  yout=[]
  for i in range(0,m):
     if yin[i] >= 0:
       yout.append(yin[i])
     else:
       yout.append(0)
  if len(winner(yout))==1:
     print('winner unit is : ',winner(yout)[0]+1)
    break
  for i in range(0,m):
     yin[i]=yout[i]-(sum(yout)-yout[i])*delta
  if epoch==100:
    break
OUTPUT: winner unit is: 4
CONCLUSION: Thus implemented the experiment successfully.
```

```
AIM: To implement BAM using python
CODE:
# Import Python Libraries
import numpy as np
# Take two sets of patterns:
# Set A: Input Pattern
x1 = \text{np.array}([1, 1, 1, 1, 1, 1]).\text{reshape}(6, 1)
x2 = np.array([-1, -1, -1, -1, -1, -1]).reshape(6, 1)
x3 = np.array([1, 1, -1, -1, 1, 1]).reshape(6, 1)
x4 = np.array([-1, -1, 1, 1, -1, -1]).reshape(6, 1)
# Set B: Target Pattern
y1 = np.array([1, 1, 1]).reshape(3, 1)
y2 = np.array([-1, -1, -1]).reshape(3, 1)
y3 = np.array([1, -1, 1]).reshape(3, 1)
y4 = np.array([-1, 1, -1]).reshape(3, 1)
print("Set A: Input Pattern, Set B: Target Pattern")
print("\nThe input for pattern 1 is")
print(x1)
print("\nThe target for pattern 1 is")
print(y1)
print("\nThe input for pattern 2 is")
print(x2)
print("\nThe target for pattern 2 is")
print(y2)
print("\nThe input for pattern 3 is")
print(x3)
print("\nThe target for pattern 3 is")
print(y3)
print("\nThe input for pattern 4 is")
print(x4)
print("\nThe target for pattern 4 is")
print(y4)
print("\n_____")
# Calculate weight Matrix: W
inputSet = np.concatenate((x1, x2, x3, x4), axis = 1)
targetSet = np.concatenate((y1.T, y2.T, y3.T, y4.T), axis = 0)
print("\nWeight matrix:")
weight = np.dot(inputSet, targetSet)
print(weight)
print("\n_____")
```

```
# Testing Phase
# Test for Input Patterns: Set A
print("\nTesting for input patterns: Set A")
def testInputs(x, weight):
 # Multiply the input pattern with the weight matrix
 # (weight.T X x)
 y = np.dot(weight.T, x)
 y[y < 0] = -1
 y[y >= 0] = 1
 return np.array(y)
print("\nOutput of input pattern 1")
print(testInputs(x1, weight))
print("\nOutput of input pattern 2")
print(testInputs(x2, weight))
print("\nOutput of input pattern 3")
print(testInputs(x3, weight))
print("\nOutput of input pattern 4")
print(testInputs(x4, weight))
# Test for Target Patterns: Set B
print("\nTesting for target patterns: Set B")
def testTargets(y, weight):
 # Multiply the target pattern with the weight matrix
 # (weight X y)
 x = np.dot(weight, y)
 x[x \le 0] = -1
 x[x > 0] = 1
 return np.array(x)
print("\nOutput of target pattern 1")
print(testTargets(y1, weight))
print("\nOutput of target pattern 2")
print(testTargets(y2, weight))
print("\nOutput of target pattern 3")
print(testTargets(y3, weight))
print("\nOutput of target pattern 4")
print(testTargets(y4, weight))
Output:
Weight matrix:
[[4 0 4]
[404]
[040]
[040]
[404]
[4 \ 0 \ 4]]
```

Testing for input patterns: Set A
Output of input pattern 1 [[1] [1] [1]
Output of input pattern 2 [[-1] [-1] [-1]
Output of input pattern 3 [[1] [-1] [1]]
Output of input pattern 4 [[-1] [1] [-1]]
Testing for target patterns: Set B
Output of target pattern 1 [[1] [1] [1] [1] [1] [1] [1] [1]
Output of target pattern 2 [[-1] [-1] [-1] [-1] [-1] [-1]
Output of target pattern 3 [[1] [1] [-1] [-1] [1] [1]
Output of target pattern 4 [[-1] [-1]

[1] [1] [-1] [-1]]
CONCLUSION: Thus implemented the experiment successfully.

```
AIM: Find the ratios using fuzzy logic
CODE:
!pip install fuzzywuzzy
!pip install python-Levenshtein
from fuzzywuzzy import fuzz
from fuzzywuzzy import process
s1 = "I love fuzzysforfuzzys"
s2 = "I am loving fuzzysforfuzzys"
print ("FuzzyWuzzy Ratio:", fuzz.ratio(s1, s2))
print ("FuzzyWuzzy PartialRatio: ", fuzz.partial ratio(s1, s2))
print ("FuzzyWuzzy TokenSortRatio: ", fuzz.token_sort_ratio(s1, s2))
print ("FuzzyWuzzy TokenSetRatio: ", fuzz.token_set_ratio(s1, s2))
print ("FuzzyWuzzy WRatio: ", fuzz.WRatio(s1, s2),\\n\n')
# for process library,
query = 'fuzzys for fuzzys'
choices = ['fuzzy for fuzzy', 'fuzzy fuzzy', 'g. for fuzzys']
print ("List of ratios: ")
print (process.extract(query, choices), '\n')
print ("Best among the above list: ",process.extractOne(query, choices))
OUTPUT:
FuzzyWuzzy Ratio: 86
FuzzyWuzzy PartialRatio: 86
FuzzyWuzzy TokenSortRatio: 86
FuzzyWuzzy TokenSetRatio: 87
FuzzyWuzzy WRatio: 86
List of ratios:
[('g. for fuzzys', 95), ('fuzzy for fuzzy', 94), ('fuzzy fuzzy', 86)]
Best among the above list: ('g. for fuzzys', 95)
```

```
AIM: Fuzzy logic for tipping
CODE:
!pip install scikit-fuzzy
import numpy as np
import skfuzzy as fuzz
from skfuzzy import control as ctrl
# New Antecedent/Consequent objects hold universe variables and membership
# functions
quality = ctrl.Antecedent(np.arange(0, 11, 1), 'quality')
service = ctrl.Antecedent(np.arange(0, 11, 1), 'service')
tip = ctrl.Consequent(np.arange(0, 26, 1), 'tip')
quality.automf(3)
service.automf(3)
tip['low'] = fuzz.trimf(tip.universe, [0, 0, 13])
tip['medium'] = fuzz.trimf(tip.universe, [0, 13, 25])
tip['high'] = fuzz.trimf(tip.universe, [13, 25, 25])
quality['average'].view()
service.view()
tip.view()
rule1 = ctrl.Rule(quality['poor'] | service['poor'], tip['low'])
rule2 = ctrl.Rule(service['average'], tip['medium'])
rule3 = ctrl.Rule(service['good'] | quality['good'], tip['high'])
rule1.view()
tipping_ctrl = ctrl.ControlSystem([rule1, rule2, rule3])
tipping = ctrl.ControlSystemSimulation(tipping_ctrl)
tipping.input['quality'] = 6.5
tipping.input['service'] = 9.8
tipping.compute()
print (tipping.output['tip'])
tip.view(sim=tipping)
OUTPUT:
```

19.847607361963192

