

# **IBEX Framework**

Technical Documentation

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Technical documentation for the IBEX Framework.

## API REFERENCE

### 1.1 TensorCreator

**class** IBEX\_Module.TensorCreator.**TensorCreator** (*config: str*)

Bases: object

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Class responsible for constructing structured PyTorch tensors from raw IBEX measurement data files.

The class traverses the IBEX raw data directory tree, loads event-level data for individual energy channels, applies basic preprocessing steps (including optional hexadecimal value translation), and combines the data into channel-specific tensors saved in `.pt` format.

Tensor creation can be performed either for continuous orbital ranges or for datasets split around the perigee change of the IBEX spacecraft.

**init\_channel\_tensors** (*perigee\_change: bool = False*) → None

Initialize multithreaded tensor creation for all energy channels.

The method spawns a separate worker thread for each energy channel and generates channel-specific tensors according to the configured instruction file and directory boundaries.

#### Parameters

**perigee\_change** (*bool, optional*) – If True, tensor creation is performed across subfolders spanning the perigee change of the IBEX spacecraft. If False, data are processed within a continuous directory range.

#### Raises

**ValueError** – If an unsupported instruction file is specified.

#### Return type

None

### 1.2 TensorAnalyzer

**class** IBEX\_Module.TensorAnalyzer.**ChannelAnalyzer** (*config: str = 'MainConfig.yml'*)

Bases: object

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Class responsible for preprocessing IBEX ENA data based on high-quality acquisition time intervals specified in instruction files (HiCullGoodTimes.txt and LoGoodTimes.txt).

The class provides three main data preprocessing modes:

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1. Extraction of raw ENA events satisfying quality criteria and saving them as PyTorch tensors.
2. Calculation of good data sums (total number of ENA detections per valid time interval).
3. Aggregation of ENA detection features by computing physically meaningful statistical descriptors (means, circular means, and standard deviations).

The preprocessing is performed independently for each IBEX-Hi and IBEX-Lo energy channel.

## Notes

Some methods of this class are marked as deprecated and preserved only as legacy artefacts from earlier versions of the analysis pipeline. They are not used in the current implementation but remain available for reference and reproducibility of previous results.

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**analyze** (*method: str, file\_path\_prefix: str, file\_path\_suffix: str*) → None

Deprecated since version 1.1: Deprecated end-to-end analysis routine from an earlier version of the ChannelAnalyzer class. This method is retained for archival and reference purposes only and is not used in the current data processing pipeline.

Perform correlation analysis between all energy channels and generate correlation matrices and heatmaps.

### Parameters

- **method** (*str*) – Correlation method identifier ('pearson', 'weighted\_pearson', 'spearman', or 'MI').
- **file\_path\_prefix** (*str*) – Prefix of input file paths.
- **file\_path\_suffix** (*str*) – Suffix of input file paths.

### Return type

None

**init\_analyzer\_tensors** (*hi\_name: str = 'hi\_hex\_channel', lo\_name: str = 'lo\_hex\_channel', option: str = 'save\_good\_data\_sums'*) → None

Initialize multithreaded preprocessing of all IBEX energy channels.

Depending on the selected option, the method performs one of the supported preprocessing procedures independently for each channel using a thread pool.

### Parameters

- **hi\_name** (*str, optional*) – Filename prefix for IBEX-Hi channel tensor files.
- **lo\_name** (*str, optional*) – Filename prefix for IBEX-Lo channel tensor files.
- **option** (*str, optional*) – Type of preprocessing to perform. Supported values are:
  - "save\_raw\_good\_data" — extract and save raw filtered ENA events.
  - "save\_good\_data\_sums" — compute and save ENA detection sums.
  - "aggregate\_all\_physical\_features" — aggregate ENA features for global analysis.

**Raises**

**Exception** – If an unsupported option value is provided.

**load\_data** (*file\_path: str*) → ndarray

Deprecated since version 1.1: Deprecated I/O helper method retained from a previous version of the class. File loading is no longer handled by this component.

Load numerical data from a text file.

**Parameters**

**file\_path** (*str*) – Path to the input file.

**Returns**

Loaded data array, or an empty array in case of an error.

**Return type**

np.ndarray

**mutual\_information** (*x: ndarray, y: ndarray*) → float

Deprecated since version 1.1: Deprecated legacy method retained for reference purposes. Mutual information analysis is no longer part of the current processing workflow.

Estimate mutual information between two one-dimensional arrays.

**Parameters**

- **x** (*np.ndarray*) – First input array.
- **y** (*np.ndarray*) – Second input array.

**Returns**

Estimated mutual information value.

**Return type**

float

**pearson\_correlation** (*x: ndarray, y: ndarray*) → float

Deprecated since version 1.1: This method is deprecated and preserved only as a legacy implementation from a previous version of the ChannelAnalyzer class. It is no longer used in the current analysis pipeline.

Compute the Pearson correlation coefficient between two one-dimensional arrays.

**Parameters**

- **x** (*np.ndarray*) – First input array.
- **y** (*np.ndarray*) – Second input array.

**Returns**

Pearson correlation coefficient.

**Return type**

float

**spearman\_correlation** (*x, y*) → float

Deprecated since version 1.1: Legacy method retained for backward compatibility with older analysis scripts. Not used in the current version of the pipeline.

Compute the Spearman rank correlation coefficient.

#### Parameters

- **x** (*np.ndarray*) – First input array.
- **y** (*np.ndarray*) – Second input array.

#### Returns

Spearman rank correlation coefficient.

#### Return type

float

**weighted\_pearson\_correlation** (*x: ndarray, y: ndarray, time\_durations\_x: ndarray, time\_durations\_y: ndarray*) → float

Deprecated since version 1.1: Deprecated weighted correlation method retained as a historical artefact from an earlier analysis approach. It is not used in the current workflow.

Compute a weighted Pearson correlation coefficient using time durations as weights.

#### Parameters

- **x** (*np.ndarray*) – First input array.
- **y** (*np.ndarray*) – Second input array.
- **time\_durations\_x** (*np.ndarray*) – Weights associated with the first array.
- **time\_durations\_y** (*np.ndarray*) – Weights associated with the second array.

#### Returns

Weighted Pearson correlation coefficient.

#### Return type

float

## 1.3 FileMerger

**class** IBEX\_Module.FileMerger.**FileMerger** (*config: str*)

Bases: object

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Class responsible for merging preprocessed IBEX data files into unified, channel-specific output files.

The class operates on data batches generated in earlier stages of the analysis pipeline and combines them into single merged datasets. This approach enables processing large data volumes while limiting system resource usage, in particular RAM memory consumption.

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**merge\_files** (*channel\_num: int = 15*) → dict | None

Merge preprocessed IBEX data files into channel-specific merged datasets.

For each energy channel, the method loads partial data files defined in the configuration, concatenates them vertically, and saves the merged result to the output directory.

**Parameters**

**channel\_num** (*int*, *optional*) – Upper bound of channel indices to process. Channels are iterated from 1 to `channel_num - 1`. Default is 15 (corresponding to 14 channels).

**Returns**

Dictionary containing `return_code` and `error_message` in case of an error. Returns `None` if all channels are merged successfully.

**Return type**

dict or None

**write\_log** (*return\_code: int*, *error\_message: str*) → None

Log an error message and return code to the execution terminal.

**Parameters**

- **return\_code** (*int*) – Numeric code describing the error type.
- **error\_message** (*str*) – Description of the encountered error.

**Return type**

None

**write\_message** (*message: str*) → None

Log a status or informational message to the execution terminal.

**Parameters**

**message** (*str*) – Informational message to be logged.

**Return type**

None

## 1.4 IBEX\_NN

**class** `IBEX_Module.IBEX_NN.RateAutoencoder` (*input\_dim: int = 14*, *latent\_dim: int = 4*)

Bases: `Module`

Autoencoder model for ENA detection rate vectors.

The model compresses 14-dimensional per-channel ENA rate vectors into a low-dimensional latent representation and reconstructs the original rates from it.

**forward** (*x: Tensor*) → tuple[`Tensor`, `Tensor`]

Forward pass through the autoencoder.

**Parameters**

**x** (*torch.Tensor*) – Input tensor of shape (batch\_size, input\_dim).

**Returns**

- **x\_hat** (*torch.Tensor*) – Reconstructed input tensor.
- **z** (*torch.Tensor*) – Latent representation.

`IBEX_Module.IBEX_NN.aggregate_events_to_bins` (*event\_data*: *dict[int, Tensor]*, *time\_bin*: *float = 600.0*) → *tuple[ndarray, ndarray]*

Aggregate raw ENA events into fixed-duration time bins.

For each time interval, the function computes:

- ENA detection rates for all 14 energy channels,
- auxiliary physical and geometrical conditions derived from a reference channel.

Time bins with missing data in any channel are discarded.

#### Parameters

- **event\_data** (*dict[int, torch.Tensor]*) – Dictionary mapping channel indices to event-level tensors.
- **time\_bin** (*float, optional*) – Width of the time bin in seconds. Default is 600 s.

#### Returns

- **rates** (*np.ndarray*) – Array of shape (N\_bins, 14) containing ENA detection rates for all energy channels.
- **conditions** (*np.ndarray*) – Array of shape (N\_bins, N\_conditions) containing aggregated physical and geometrical features per time bin.

`IBEX_Module.IBEX_NN.init_dataset_preparation_pipeline` (*base\_dir*: *str*, *out\_dir*: *str*, *regimes*: *list[str] = ['BeforePerigeeChange', 'AfterPerigeeChange']*) → *None*

Execute the full dataset preparation pipeline for multiple mission regimes.

For each regime, the function loads raw event data, aggregates it into time bins, and saves the resulting datasets to disk.

#### Parameters

- **base\_dir** (*str*) – Base directory containing regime-specific input data.
- **out\_dir** (*str*) – Output directory for aggregated datasets.
- **regimes** (*list of str, optional*) – List of regime identifiers to process.

#### Return type

*None*

`IBEX_Module.IBEX_NN.load_autoencoder_data` (*path*: *str | Path*) → *tuple[ndarray, StandardScaler]*

Load and preprocess aggregated rate data for autoencoder training.

The preprocessing includes logarithmic transformation and per-channel standardization.

#### Parameters

- **path** (*str or pathlib.Path*) – Path to the directory containing *rates.npy*.

#### Returns

- **X** (*np.ndarray*) – Preprocessed rate matrix.



- **scaler** (*StandardScaler*) – Fitted scaler used for standardization.

`IBEX_Module.IBEX_NN.load_event_data(base_dir: str | Path) → dict[int, Tensor]`

Load raw IBEX event-level data for all energy channels.

The function loads preprocessed PyTorch tensors corresponding to individual IBEX-Hi (channels 1–6) and IBEX-Lo (channels 7–14) energy channels.

#### Parameters

**base\_dir** (*str or pathlib.Path*) – Base directory containing Hi\_data and Lo\_data subdirectories.

#### Returns

Dictionary mapping global channel indices (1–14) to event tensors of shape (N\_events, K\_features).

#### Return type

dict[int, torch.Tensor]

#### Raises

**FileNotFoundError** – If any required channel file is missing.

`IBEX_Module.IBEX_NN.make_data loaders(X: ndarray, batch_size: int = 256, val_frac: float = 0.2) → tuple[DataLoader, DataLoader]`

Create training and validation DataLoaders from a NumPy array.

#### Parameters

- **X** (*np.ndarray*) – Input data matrix.
- **batch\_size** (*int, optional*) – Batch size.
- **val\_frac** (*float, optional*) – Fraction of data reserved for validation.

#### Returns

- **train\_loader** (*DataLoader*) – DataLoader for training.
- **val\_loader** (*DataLoader*) – DataLoader for validation.

`IBEX_Module.IBEX_NN.per_channel_mse(model: Module, X: ndarray, device: str = 'cpu') → ndarray`

Compute per-channel reconstruction mean squared error.

#### Parameters

- **model** (*torch.nn.Module*) – Trained autoencoder model.
- **X** (*np.ndarray*) – Input data matrix.
- **device** (*str, optional*) – Computation device.

#### Returns

Array of per-channel MSE values.

#### Return type

np.ndarray

`IBEX_Module.IBEX_NN.plot_per_channel_mse(mse: ndarray, title: str) → None`

Plot per-channel reconstruction error.

#### Parameters

- **mse** (*np.ndarray*) – Per-channel MSE values.
- **title** (*str*) – Plot title.

**Return type**

None

`IBEX_Module.IBEX_NN.plot_training_history` (*history: dict[str, list[float]], title: str*) → None

Plot training and validation loss curves.

**Parameters**

- **history** (*dict*) – Dictionary containing loss histories.
- **title** (*str*) – Plot title.

**Return type**

None

`IBEX_Module.IBEX_NN.reconstruction_mse` (*model: Module, X: ndarray, device: str = 'cpu'*) → float

Compute global reconstruction mean squared error.

**Parameters**

- **model** (*torch.nn.Module*) – Trained autoencoder model.
- **x** (*np.ndarray*) – Input data matrix.
- **device** (*str, optional*) – Computation device.

**Returns**

Global reconstruction MSE.

**Return type**

float

`IBEX_Module.IBEX_NN.save_aggregated_dataset` (*output\_dir: str | Path, rates: ndarray, conditions: ndarray, time\_bin: float*) → None

Save aggregated rate and condition datasets to disk.

The function stores NumPy arrays along with a JSON metadata file describing the aggregation parameters.

**Parameters**

- **output\_dir** (*str or pathlib.Path*) – Output directory for the aggregated dataset.
- **rates** (*np.ndarray*) – Array containing per-channel ENA detection rates.
- **conditions** (*np.ndarray*) – Array containing aggregated physical and geometrical features.
- **time\_bin** (*float*) – Time bin width used during aggregation (in seconds).

**Return type**

None

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IBEX_Module.IBEX_NN.train_autoencoder(model: Module, train_loader: DataLoader,  
                                         val_loader: DataLoader | None = None, n_epochs:  
                                         int = 200, lr: float = 0.001, device: str = 'cpu',  
                                         verbose: bool = True) → dict[str, list[float]]
```

Train an autoencoder model using mean squared error loss.

#### Parameters

- **model** (*torch.nn.Module*) – Autoencoder model to be trained.
- **train\_loader** (*DataLoader*) – DataLoader providing training samples.
- **val\_loader** (*DataLoader, optional*) – DataLoader providing validation samples.
- **n\_epochs** (*int, optional*) – Number of training epochs.
- **lr** (*float, optional*) – Learning rate.
- **device** (*str, optional*) – Device identifier ('cpu' or 'cuda').
- **verbose** (*bool, optional*) – If True, training progress is printed.

#### Returns

Dictionary containing training and validation loss histories.

#### Return type

dict