### MICROWAVE ENGINEERING

# TRANSMISSION LINE THEORY (MODULE 2)











### Module Learning Outcomes

- Define the term Transmission Line.
- Derive the mathematical expression for propagation constant.
- Derive the mathematical expression for characteristic impedance, reflection coefficient, voltage standing wave ratio.
- Use Smith's Chart to solve transmission line problems.

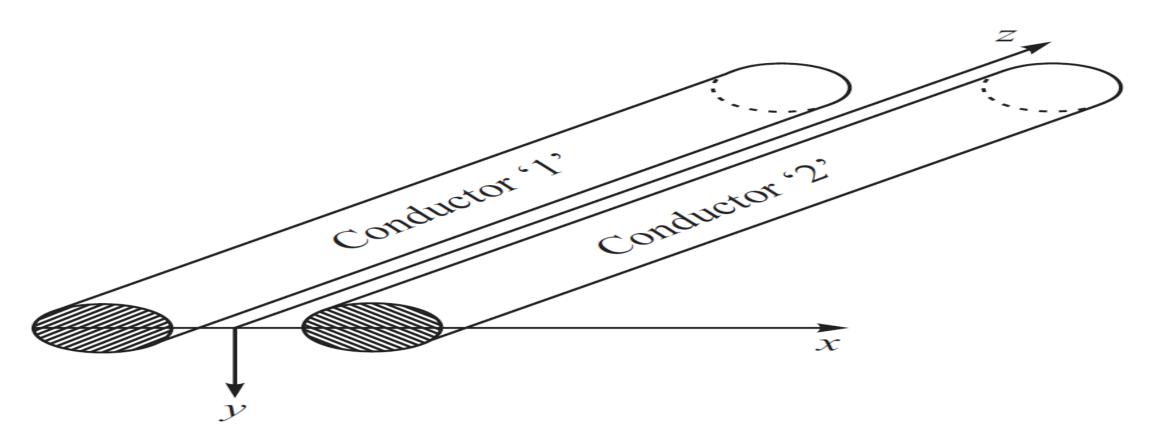
#### INTRODUCTION

- The term transmission line in electromagnetics is commonly reserved for those structures which are capable of guiding TEM waves.
- Transmission lines are a special class of the more general electromagnetic waveguide.
- TEM waves can only exist in structures which contain two or more separate conductors. For example, coaxial lines, parallel plates, and two-wire lines.

- At low frequencies, electromagnetic signal power can be easily transmitted from one point in a system to another without much loss using a conducting wire.
- But at higher frequencies, conducting wires dissipate electromagnetic signals as radiations (antenna).
- The radiation loss increases as the square of the frequency.



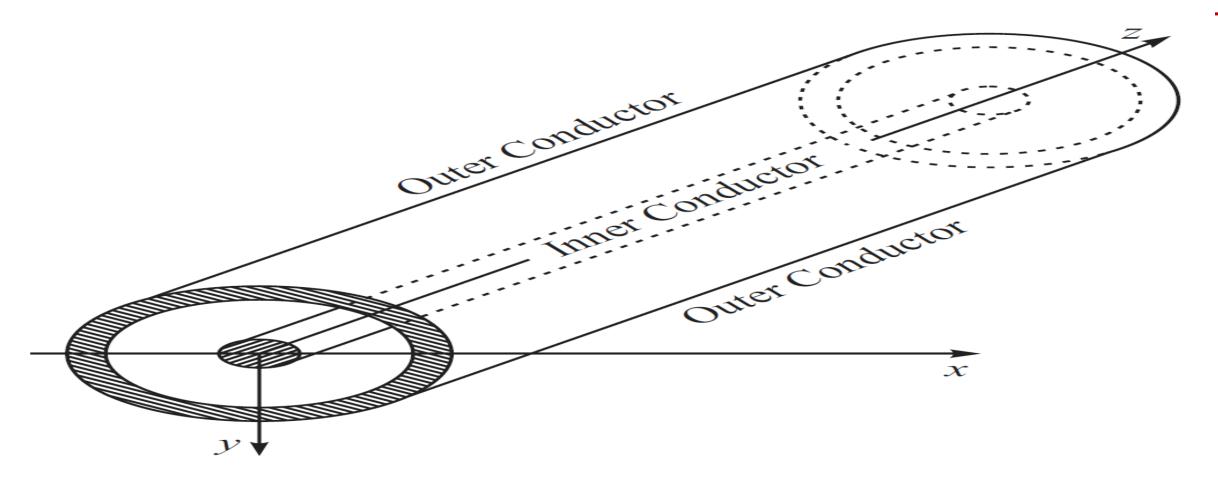
- The tendency of interconnecting wires to radiate may be curbed to some extent by making the return current flow through another wire placed very close and parallel to the interconnecting wire, thus forming the two-wire transmission line.
- This arrangement can be used satisfactorily only up to 300MHz.



Geometry of a two-conductor or two-wire transmission line

• At some frequencies higher than 300MHz, the radiation losses may be made negligible by employing a circular cylindrical conducting tube, placed coaxially with an inner conductor as the conductor for carrying the return currents. The resulting wave guiding structure, is called the Coaxial Line.

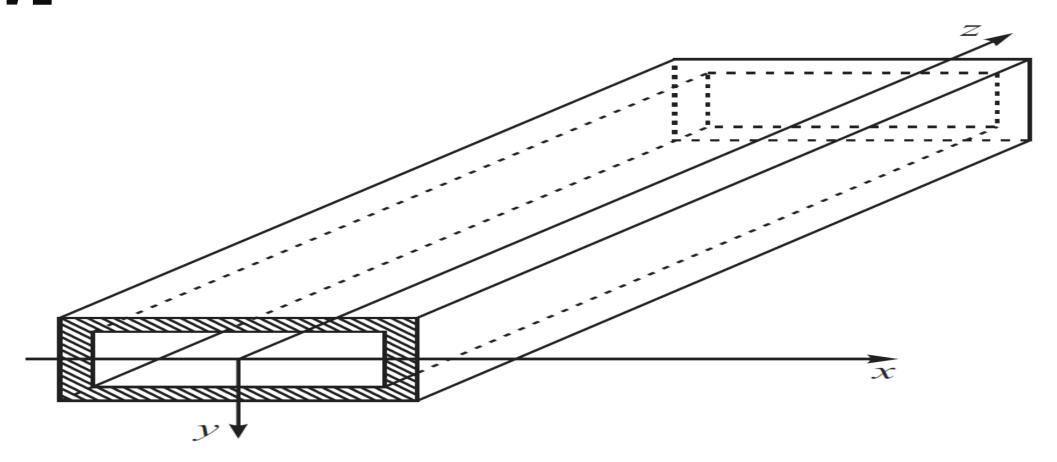




Geometry of a coaxial line

- The fields in the coaxial line remain confined to the annular region between the inner and the outer conductor and hence, no radiation takes place. The field configuration inside the coaxial line also corresponds to the TEM mode.
- The coaxial line is quite acceptable as a transmission structure up to 3000 MHz above which losses due to imperfections of the dielectric and conductor, become appreciable and cannot be neglected.

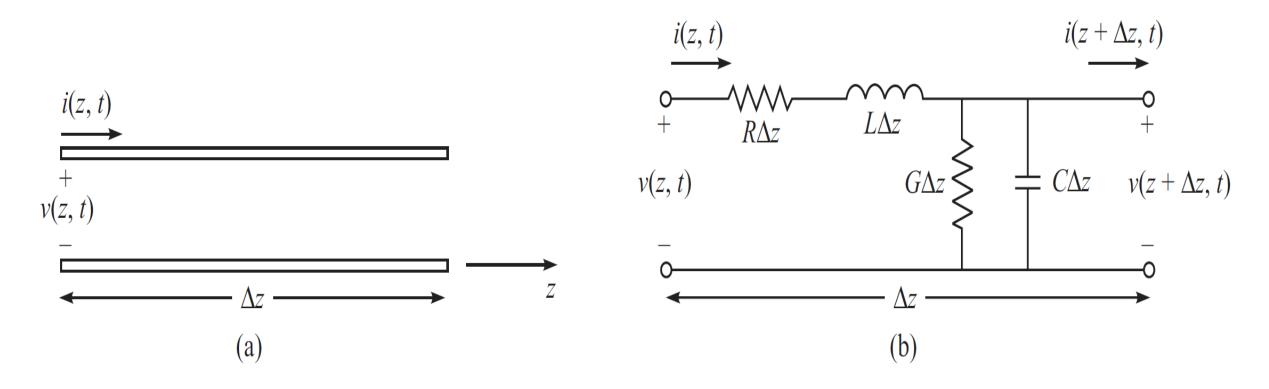
- These losses above 3000 MHz can be reduced considerably by dispensing with the centre conductor and using merely a hollow metal tube of circular or rectangular cross section. Such as system is called the Waveguide.
- In waveguides, the TEM mode cannot exist, instead, a longitudinal component of either the electric field or the magnetic field or both fields must exist.



Geometry of a rectangular, hollow waveguide

- The key difference between circuit theory and transmission line theory is electrical size.
- Circuit analysis assumes that the physical dimensions of a network are much smaller than the electrical wavelength; while transmission lines may be a considerable fraction of a wavelength, or many wavelengths, in size.

- Thus, a transmission line is a distributed-parameter network, where voltages and currents can vary in magnitude and phase over its length.
- Thus, a piece of line of infinitesimal length  $\Delta z$  can be modeled as a lumped-element circuit, where the resistance (R) in  $\Omega/m$ , inductance (L) in H/m, shunt conductance (G) in S/m, and the shunt capacitance (C) in F/m, are the per-unit length quantities.



Voltage and current definitions and equivalent circuit for an incremental length of transmission line: (a) Voltage and current definitions (b) Lumped-element equivalent circuit

- The series inductance L represents the total self-inductance of the two conductors, and the shunt capacitance C is due to the close proximity of the two conductance.
- The series resistance *R* represents the resistance due to the finite conductivity of the conductors.
- The shunt conductance G is due to dielectric loss in the material between the conductors.
- R and G represent loss.

Using Kirchhoff's voltage law on the outer loop only:

$$v(z,t) - R\Delta z i(z,t) - L\Delta z \frac{\partial i(z,t)}{\partial t} - v(z + \Delta z,t) = 0$$

la)

Using Kirchhoff's current law on the inner loop only:

$$i(z,t) - G\Delta z v(z + \Delta z, t) - C\Delta z \frac{\partial v(z + \Delta z, t)}{\partial t} - i(z + \Delta z, t) = 0$$

(lb)

Dividing (1a) and (1b) by  $\Delta z$  and taking the limit as  $\Delta z \to 0$ , gives the following differential equations:

$$\frac{\partial \mathbf{v}(z,t)}{\partial z} = -Ri(z,t) - L\frac{\partial \mathbf{i}(z,t)}{\partial t}$$

(2a)

$$\frac{\partial i(z,t)}{\partial z} = -Gv(z,t) - C\frac{\partial v(z,t)}{\partial t}$$

(2b)

Equations 2a and 2b are the time-domain form of the transmission line.

We rewrite equations 2a and 2b as cosine-based phasors as:

From complex numbers:

$$Xe^{j\theta} = X\cos(\theta) + Xj\sin(\theta)$$
$$Xe^{j\omega t} = X\cos(\omega t) + Xj\sin(\omega t)$$

This consists of the real (cosine-based)(Re) and the imaginary (sine-based)(Im) parts.

Taking only the real (cosine-based part) becomes:

$$Re(Xe^{j\omega t}) = Re(X\cos(\omega t))$$

Taking only the imaginary (sine-based part) becomes:

$$Im(Xe^{j\omega t}) = Im(Xjsin(\omega t))$$

For the most part, we would use only the cosine-based, real part of the TEM waves.

$$v(z,t) = Re[V(z)e^{j\omega t}]$$

$$\frac{\partial v(z,t)}{\partial t} = \frac{\partial Re[V(z)e^{j\omega t}]}{\partial t}$$

$$= Re[V(z)\frac{\partial e^{j\omega t}}{\partial t}]$$

$$= Re[j\omega V(z)e^{j\omega t}]$$

$$j\omega V(z) - is the phasor of \frac{\partial v(z,t)}{\partial t}$$

$$i(z,t) = Re[I(z)e^{j\omega t}]$$

$$\frac{\partial i(z,t)}{\partial t} = \frac{\partial Re[I(z)e^{j\omega t}]}{\partial t}$$

$$= Re[I(z)\frac{\partial e^{j\omega t}}{\partial t}]$$

$$= Re[j\omega I(z)e^{j\omega t}]$$

$$j\omega I(z) - is the phasor of \frac{\partial i(z,t)}{\partial t}$$

Similarly,

$$\frac{\partial v(z,t)}{\partial z} = \frac{\partial Re[V(z)e^{j\omega t}]}{\partial z}$$
$$= Re\left[\frac{\partial V(z)}{\partial z}e^{j\omega t}\right]$$

$$\frac{\partial i(z,t)}{\partial z} = \frac{\partial Re[I(z)e^{j\omega t}]}{\partial z}$$
$$= Re\left[\frac{\partial I(z)}{\partial z}e^{j\omega t}\right]$$

Therefore, the transmission-line equations in cosine-based phasor form become:

$$\frac{\partial \mathbf{v}(z,t)}{\partial z} = -Ri(z,t) - L\frac{\partial \mathbf{i}(z,t)}{\partial t} \tag{2a}$$

Recall that in phasor form,  $\frac{\partial u}{\partial z} = \frac{\partial V(z)}{\partial z}$ ; i(z,t) = I(z); and  $\frac{\partial i(z,t)}{\partial t} = i\omega I(z)$ 

Therefore equation 2a becomes:

$$\frac{\partial \mathbf{v}(z)}{\partial z} = -RI(z) - j\omega LI(z)$$

(3a)

### 

$$\frac{\partial i(z,t)}{\partial z} = -Gv(z,t) - C\frac{\partial v(z,t)}{\partial t}$$
 (2b)

Recall that in phasor form,  $\frac{\partial i(z,t)}{\partial z} = \frac{\partial I(z)}{\partial z}$ ; v(z,t) = V(z); and  $\frac{\partial v(z,t)}{\partial t} = j\omega V(z)$ 

Therefore equation 2b becomes:

$$\frac{\partial I(z)}{\partial z} = -GV(z) - j\omega CV(z)$$

(3b)

Bringing 3a and 3b together forms the transmission line equations in phasor form:

$$\frac{\partial \mathbf{v}(z)}{\partial z} = -RI(z) - j\omega LI(z)$$

(3a)

$$\frac{\partial I(z)}{\partial z} = -GV(z) - j\omega CV(z)$$

(3b)

- The solution of the equations (3a and 3b) is the sinusoidal excited steady-state voltage and current phasor along the transmission line.
- These two first-order coupled equations (3a and 3b) can be combined to give two second-order uncoupled wave equations. Steps:
- 1. Differentiate both sides of equation 3a.
- 2. Substitute equation 3b into the differentiated equation 3a.

1. 
$$\frac{\partial^2 \mathbf{v}(z)}{\partial z^2} = -(R + j\omega L) \frac{dI(z)}{dz}$$

2. 
$$\frac{\partial^2 \mathbf{v}(z)}{\partial z^2} = -(R + j\omega L)[-GV(z) - j\omega CV(z)]$$

Taking like-terms of equation 4a we have:

$$\frac{\partial^2 \mathbf{v}(z)}{\partial z^2} = -(R + j\omega L)[-(G + j\omega C)V(z)]$$
$$\frac{\partial^2 \mathbf{v}(z)}{\partial z^2} = (R + j\omega L)(G + j\omega C)V(z)$$

(5a)

(4a)

By comparison of both sides of equation 5a we have:

$$\frac{\partial^2 \mathbf{v}(z)}{\partial z^2} = (R + j\omega L)(G + j\omega C)V(z)$$

$$\frac{\partial^2 \mathbf{v}(z)}{\partial z^2} = \gamma^2 V(z)$$

$$(R + j\omega L)(G + j\omega C) = \frac{\partial^2}{\partial z^2} = \gamma^2$$

Where  $\gamma$  is the propagation constant which is equivalent to:

$$\gamma = \sqrt{(R + j\omega L)(G + j\omega C)}$$
 (7)

(6a)

Similarly,

$$\frac{\partial^2 I(z)}{\partial z^2} = \gamma^2 I(z) \tag{6b}$$

Combining equations 6a and 6b gives:

$$\frac{\partial^2 \mathbf{v}(z)}{\partial z^2} = \gamma^2 V(z) \tag{6a}$$

$$\frac{\partial^2 \mathbf{v}(z)}{\partial z^2} = \gamma^2 V(z) \tag{6a}$$

$$\frac{\partial^2 I(z)}{\partial z^2} = \gamma^2 I(z) \tag{6b}$$

The solution to equations 6a and 6b are:

$$V(z) = V_o^+ e^{-\gamma z} + V_o^- e^{+\gamma z}$$
 (8a)

$$I(z) = I_o^+ e^{-\gamma z} + I_o^- e^{+\gamma z}$$
 (8b)

 $V_o^+ e^{-\gamma z}$ : traveling wave propagating in the +z direction

 $V_o^- e^{+\gamma z}$  : traveling wave propagating in the –z direction

$$e^{-\gamma z} = e^{-(\alpha+j\beta)z} = e^{-\alpha z}e^{-j\beta z}$$

Where  $\alpha$  is the attenuation constant in neper/m and  $\beta$  is the phase constant in radians/m.

- Characteristic Impedance is the ratio of the forward travelling voltage to the forward travelling current wave at any point on the transmission line.
- Characteristic impedance is also the input impedance of an infinite line.
- The characteristic impedance is also called the input impedance of an infinite line.

It can be shown that:

$$\frac{V_o^+}{I_o^+} = z_o = Characteristic Impedance$$

$$\frac{V_o^-}{I_o^-} = -z_o$$

$$Z_o = \sqrt{\frac{R + j\omega L}{G + j\omega C}}$$

Important fundamental equations to recall:

1. To convert the phasor representation of the voltage back to its time domain representation:

$$v(z,t)$$

$$= |V_o^+| \cos(\omega t - \beta z + \emptyset^+) e^{-\alpha z}$$

$$+ |V_o^-| \cos(\omega t + \beta z + \emptyset^-) e^{\alpha z}$$

Important fundamental equations to recall:

1. The wavelength  $(\lambda)$ :

$$\lambda = \frac{2\pi}{\beta}$$

 $\beta$  – the phase constant.

2. The phase velocity  $(V_p)$ :  $V_p = \frac{\omega}{\beta} = \lambda f$ 

#### The Lossless Line

• In practical cases, however, the loss of the line is very small and so can be neglected, resulting in a simpler equation.

Set  $R = G = \alpha = 0$  and the propagation constant becomes:

$$\gamma = \alpha + j\beta = j\omega\sqrt{LC}$$
$$\beta = \omega\sqrt{LC}$$

$$Z_o = \sqrt{\frac{L}{C}}$$

### Transmission on Lines of Finite Length

- In practice, infinite long lines do not exist, but finite lines can be made to behave like infinitely long lines if they are terminated with the characteristic impedance of the line.
- A transmission line which is terminated by its own characteristic impedance,  $Z_o$ , is said to be matched or properly terminated (this prevents reflections).

### Transmission on Lines of Finite Length

• A line which is terminated in any impedance other than  $Z_o$  is said to be unmatched or improperly terminated.

#### Reflection Coefficient

- Reflections occur due to imperfect termination of transmission lines.
- Reflection coefficient is the ratio of the reflected power to the incident power.

$$\Gamma = \frac{Reflected\ Power}{Incident\ Power}$$

• The reflection coefficient varies between (0 (perfect match) and 1 (perfect mismatch))

#### Voltage Reflection Coefficient

 Voltage reflection coefficient is a measure of the degree of mismatch between the source and load impedances that causes the reflection of incident waves:

$$\Gamma_v = rac{V_{reflected}}{V_{incident}}$$
 $\Gamma_I = rac{I_{reflected}}{I_{incident}}$ 

#### Voltage Reflection Coefficient

$$\Gamma_{v} = \frac{Z_{L} - Z_{o}}{Z_{L} + Z_{o}}$$

$$-\Gamma_{v} = \frac{i_{r}}{i_{i}} = \frac{-v_{r}/z_{o}}{v_{i}/z_{o}}$$

#### Return Loss

• Incident power  $(P_{inc})$  and reflected power  $(P_{ref})$  can be related using the magnitude of the voltage reflection coefficient  $(\Gamma)$ . Since  $\Gamma = \frac{V_{ref}}{V_{inc}}$ , it follows that:

$$\frac{P_{ref}}{P_{inc}} = \frac{v_{ref}^2/R_{load}}{v_{inc}^2/R_{load}} = \Gamma^2$$

The return loss gives the amount of power reflected from a load and is calculated as:

Return Loss (dB) =  $-10\log\Gamma^2 = -20\log\Gamma$ 

#### Mismatched Loss

• The amount of power transmitted to the load  $(P_L)$  is determined from:

$$P_L = P_{inc} - P_{ref} = P_{inc}(1 - \Gamma^2)$$

The fraction of the incident power not reaching the load because of mismatches and reflections is:

$$\frac{P_{load}}{P_{incident}} = \frac{P_L}{P_{inc}} = 1 - \Gamma^2$$

Hence, the mismatch loss (or reflection loss) is calculated as:

$$\mathbf{ML} (\mathbf{dB}) = -10\log(1 - \Gamma^2)$$

#### Transmission Coefficient

• The transmission coefficient  $(\tau_v)$  if defined as the ratio of the load voltage  $(v_l)$  to the incident voltage  $(v_i)$ .

$$\tau_v = \frac{v_l}{v_i} = 1 + \Gamma_v = \frac{2z}{z+1}$$

### Voltage Standing Wave Ratio (VSWR)

• It is an indication of the degree of mismatch in a termination. It is the ratio of the maximum voltage to the minimum voltage.

$$VSWR = \frac{v_{max}}{v_{min}} = \frac{1 + \Gamma_v}{1 - \Gamma_v}$$

• The input impedance for lossy media:

$$Z_{in} = Z_o \left[ \frac{Z_L + jZ_o tanh\gamma l}{Z_o + jZ_L tanh\gamma l} \right]$$

• The input impedance for lossless media:

$$Z_{in} = Z_o \left[ \frac{Z_L + jZ_o tan\beta l}{Z_o + jZ_L tan\beta l} \right]$$

The voltage reflection coefficient (at the load):

$$\Gamma_L = \frac{V_o^- e^{\gamma l}}{V_o^+ e^{-\gamma l}}$$

$$\Gamma_L = \frac{Z_L - Z_o}{Z_L + Z_o}$$

 The voltage reflection coefficient at any point on the line is the ratio of the reflected voltage wave to that of the incident wave:

$$\Gamma(z) = \frac{V_o^- e^{\gamma z}}{V_o^+ e^{-\gamma z}} = \frac{V_o^-}{V_o^+} e^{2\gamma z}$$

Where z = l - l'

$$\Gamma(z) = \frac{V_o^- e^{\gamma z}}{V_o^+ e^{-\gamma z}} = \frac{V_o^-}{V_o^+} e^{2\gamma l} e^{-2\gamma l'} = \Gamma_L e^{-2\gamma l'}$$

 The current reflection coefficient at any point on the line is the negative of the voltage reflection coefficient at that point:

$$\frac{I_o^- e^{\gamma l}}{I_o^+ e^{-\gamma l}} = -\Gamma_L$$

• The standing wave ratio (S):

$$s = \frac{V_{max}}{V_{min}} = \frac{I_{max}}{I_{min}} = \frac{1 + |\Gamma_L|}{1 - |\Gamma_L|}$$

$$|\Gamma_L| = \frac{S-1}{S+1}$$

• The standing wave ratio (S):

$$|Z_{in}|_{max} = \frac{V_{max}}{I_{min}} = sZ_o$$

$$|Z_{in}|_{min} = \frac{V_{min}}{I_{max}} = \frac{Z_o}{s}$$

• A transmission line is used in transferring power from the source to the load. The average input power at a distance l from the load is given by:

$$P_{ave} = \frac{|V_o^+|^2}{2Z_o} (1 - |\Gamma|^2) = P_i - P_r = P_t$$

The factor  $\frac{1}{2}$  is needed because we are dealing with the peak values instead of rms values.

• For a shorted line  $(Z_L = 0)$ :

The input impedance:

$$Z_{in} = Z_o \left[ \frac{Z_L + jZ_o tan\beta l}{Z_o + jZ_L tan\beta l} \right]$$

becomes,

$$Z_{sc} = Z_{in} \mid_{Z_L=0} = jZ_o tan\beta l$$
  
 $\Gamma_L = -1, s = \infty$ 

• For open-circuited line  $(Z_L = \infty)$ :

The input impedance:

$$Z_{in} = Z_o \left[ \frac{Z_L + jZ_o tan\beta l}{Z_o + jZ_L tan\beta l} \right]$$

becomes,

$$Z_{oc} = \lim_{Z_L \to \infty} Z_{in} = \frac{Z_o}{jtan\beta l} = -jZ_o cot\beta l$$
$$\Gamma_L = 1, s = \infty$$

#### Note that:

$$Z_{sc}Z_{oc}=Z_o^2$$

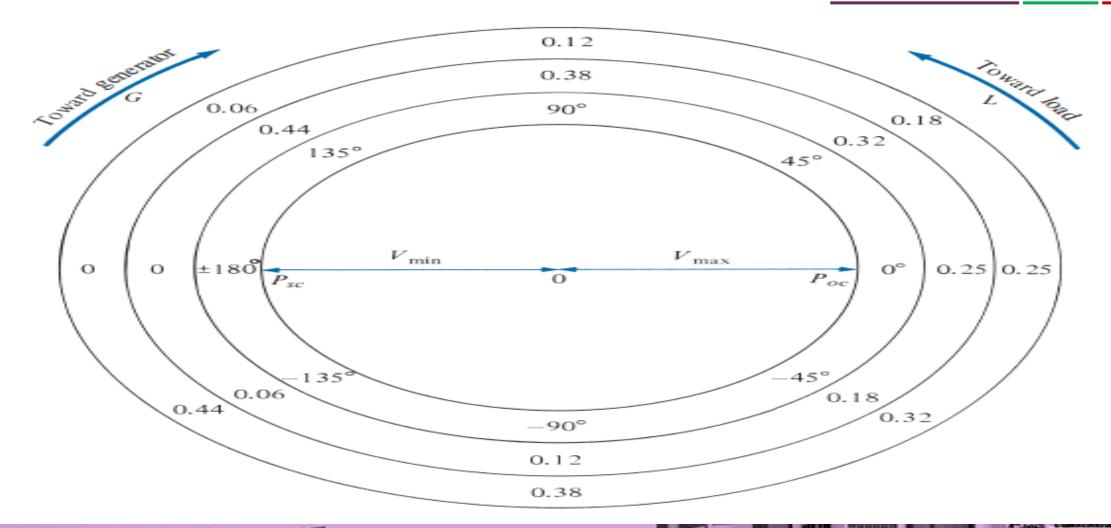
• For matched line  $(Z_L = Z_o)$ :

The input impedance:

$$Z_{in} = Z_o$$

$$\Gamma_L = 0$$
,  $s = 1$ 

#### THE SMITH CHART



#### THE SMITH CHART

• The Smith's chart can be used to get the location of  $V_{max}$ ,  $V_{min}$ ,  $\Gamma$ , and s provided we are given  $Z_o$ ,  $Z_L$ ,  $\lambda$ , and the length of the line.

• We are going to use a compass, and a plain straightedge.