```
%% TEST 1
1
 2
     clear all; close all; clc;
 3
    %% Import cam data
    load('cam1_1.mat');
 4
 5
     load('cam2_1.mat');
     load('cam3_1.mat');
 7
     %% Get rows/columns and dimensions
8
     [row1, col1, dim1_1, dim2_1] = size(vidFrames1_1);
9
     [row2, col2, dim1 2, dim2 2] = size(vidFrames2 1);
     [row3, col3, dim1_3, dim2_3] = size(vidFrames3_1);
10
11
     %% Store the video by frames
12
     for k = 1:dim2 1
         img1{k} = vidFrames1_1(:, :, :, k);
13
14
15
     for k = 1:dim2 2
16
         img2\{k\} = vidFrames2\ 1(:, :, :, k);
17
18
19
     for k = 1:dim2 3
20
         img3{k} = vidFrames3_1(:, :, :, k);
21
22
     %% Ideal Case
23
     x1 = zeros(1, dim2_1);
24
     y1 = zeros(1, dim2 1);
25
     boxX1 = [300, 350];
     boxY1 = [200, 250];
26
27
     for k = 1:dim2_1
28
         img = vidFrames1_1(:, :, 3, k);
29
         box = double(img(boxY1(1):boxY1(2), boxX1(1):boxX1(2)));
30
         [row, col] = find(box == max(max(box)));
         y1(k) = mean(row) + boxY1(1);
31
32
         x1(k) = mean(col) + boxX1(1);
33
         boxX1 = [round(x1(k) - 20), round(x1(k) + 20)];
34
         boxY1 = [round(y1(k) - 20), round(y1(k) + 20)];
35
     end
36
37
     x2 = zeros(1, dim2_2);
38
     y2 = zeros(1, dim2_2);
39
     boxX2 = [250, 300];
     boxY2 = [250, 300];
40
41
     for k = 1:dim2 2
42
         img = vidFrames2_1(:, :, 3, k);
43
         box = double(img(boxY2(1):boxY2(2), boxX2(1):boxX2(2)));
44
         [row, col] = find(box == max(max(box)));
45
         y2(k) = mean(row) + boxY2(1);
46
         x2(k) = mean(col) + boxX2(1);
47
         boxX2 = [round(x2(k) - 20), round(x2(k) + 20)];
48
         boxY2 = [round(y2(k) - 20), round(y2(k) + 20)];
49
     end
50
51
     x3 = zeros(1, dim2_3);
52
     y3 = zeros(1, dim2_3);
53
     boxX3 = [310, 340];
54
     boxY3 = [265, 295];
55
     for k = 1:dim2_3
56
         img = vidFrames3_1(:, :, 3, k);
57
         box = double(img(boxY3(1):boxY3(2), boxX3(1):boxX3(2)));
58
         [row, col] = find(box == max(max(box)));
59
         y3(k) = mean(row) + boxY3(1);
         x3(k) = mean(col) + boxX3(1);
60
61
         boxX3 = [round(x3(k) - 15), round(x3(k) + 15)];
62
         boxY3 = [round(y3(k) - 15), round(y3(k) + 15)];
63
64
65
     % %% Video1
```

```
% figure(1);
 66
 67
      % for i = 1:length(img1)
 68
            imshow(img1{i});
 69
    %
            hold on;
 70
    %
            rectangle('position', [x1(i) - 10, y1(i) - 10, 20, 20], 'Linewidth', 2);
 71
     %
            hold off;
 72
     %
            pause(0.001);
 73
     % end
 74
     % %% Video2
 75
     % figure(2);
 76
     % for i = 1:length(img2)
 77
     %
            imshow(img2{i});
 78 %
            hold on;
 79
    %
            rectangle('position', [x2(i) - 10, y2(i) - 10, 20, 20], 'Linewidth', 2);
 80
    %
            hold off;
 81
     %
            pause(0.001)
 82
     % end
     % %% Video3
 83
 84
     % figure(3);
 85
     % for i = 1:length(img3)
 86
            imshow(img3{i});
 87
     %
            hold on;
 88
    %
            rectangle('position', [x3(i) - 15, y3(i) - 15, 30, 30], 'Linewidth', 2);
 89
            hold off;
 90
     %
            pause(0.001)
 91
     % end
 92
 93
     %% Force everything to be in the same size
 94
     x1; y1; % Reference
 95
     x2 = x2(11:dim2_1 + 10);
     y2 = y2(11:dim2_1 + 10);
 96
 97
     x3 = x3(1:dim2 1);
 98
     y3 = 480 - y3(1:dim2_1);
 99
     %% Plot
100
     figure(4);
101
      subplot(2,1,1);
102
      plot(y1,'Linewidth', 3); hold on;
      plot(y2,'Linewidth', 3)
103
      plot(x3,'Linewidth', 3)
104
      title('Y Coordinates of Can in Ideal Case');
105
      xlabel('Timeframe');
106
107
      ylabel('Displacement');
108
      xlim([0 length(y1) + 50]);
109
      legend('cam1(y1)','cam2(y2)','cam3(y3)');
110
111
      subplot(2,1,2);
112
      plot(x1,'Linewidth', 3); hold on;
      plot(x2,'Linewidth', 3)
113
      plot(y3,'Linewidth', 3)
114
      title('X Coordinates of Can in Ideal Case');
115
      xlabel('Timeframe');
116
117
      ylabel('Displacement');
118
      xlim([0 length(y1) + 50]);
119
      legend('cam1(x1)','cam2(x2)','cam3(x3)');
120
121
      %% Normalize the Data
122
      figure(5)
123
      subplot(2,1,1);
      plot(y1 - mean(y1), 'Linewidth', 3); hold on;
124
      plot(y2 - mean(y2),'Linewidth', 3)
125
      plot(x3 - mean(x3), 'Linewidth', 3)
126
      title('Y Coordinates of Can in Ideal Case(Normalized)');
127
128
      xlabel('Time');
      ylabel('Displacement');
129
130
      xlim([0 length(y1) + 50]);
```

```
legend('cam1(y1)','cam2(y2)','cam3(y3)');
131
132
133
      subplot(2,1,2);
      plot(x1 - mean(x1), 'Linewidth', 3); hold on;
134
      plot(x2 - mean(x2), 'Linewidth', 3)
135
      plot(y3 - mean(y3),'Linewidth', 3)
136
137
      title('X Coordinates of Can in Ideal Case(Normalized)');
138
     xlabel('Time');
139
      ylabel('Displacement');
      legend('cam1(x1)','cam2(x2)','cam3(x3)');
140
141
      xlim([0 length(y1) + 50]);
142
     %% SVD
143
144
     X = [x1 - mean(x1); y1 - mean(y1); x2 - mean(x2); y2 - mean(y2); ...
145
          x3 - mean(x3); y3 - mean(y3)];
      [u, s, v] = svd(X, 'econ');
146
147
148
     %% Plot
149
     figure;
150
      plot(diag(s)/sum(diag(s)),'o', 'Linewidth', 2);
151
      title('Importance of Singular Values For All Directions in Ideal Case');
     xlabel('Singular values');
152
     ylabel('Energy');
153
154
     %%
                    155
     %-----
     %% TEST 2
156
     clc; clear all; close all;
157
158
     %% noisy case
159
     load('cam1 2.mat')
160
     load('cam2_2.mat')
      load('cam3_2.mat')
161
162
163
      [row1, col1, dim1_1, dim2_1] = size(vidFrames1_2);
164
      [row2, col2, dim1 2, dim2 2] = size(vidFrames2 2);
165
      [row3, col3, dim1_3, dim2_3] = size(vidFrames3_2);
166
     %%
167
      for k = 1:dim2 1
168
          img1{k} = vidFrames1_2(:, :, :, k);
169
      end
170
      for k = 1:dim2_2
171
          img2\{k\} = vidFrames2\ 2(:, :, :, k);
172
      end
173
174
      for k = 1:dim2 3
175
          img3\{k\} = vidFrames3_2(:, :, :, k);
176
      end
177
     %% case 2
178
     x1 = zeros(1, dim2_1);
179
     y1 = zeros(1, dim2_1);
     boxX = [300 \ 350];
180
181
     boxY = [300 \ 350];
     for i = 1:dim2_1
182
183
          img = vidFrames1 2(:,:,3,i);
184
          box = double(img(boxY(1):boxY(2), boxX(1):boxX(2)));
185
          [row, col] = find(box == max(max(box)));
186
          y1(i) = mean(row) + boxY(1);
          x1(i) = mean(col) + boxX(1);
187
188
          boxX = [round(x1(i) - 20), round(x1(i) + 20)];
189
          boxY = [round(y1(i) - 20), round(y1(i) + 20)];
190
     end
191
192
     x2 = zeros(1, dim2_2);
193
     y2 = zeros(1, dim2_2);
194
     boxX = [290 340];
     boxY = [330 380];
195
```

```
for i = 1:dim2 2
196
197
          img = vidFrames2_2(:,:,3,i);
198
          box = double(img(boxY(1):boxY(2), boxX(1):boxX(2)));
199
          [row, col] = find(box == max(max(box)));
200
          y2(i) = mean(row) + boxY(1);
          x2(i) = mean(col) + boxX(1);
201
202
          boxX = [round(x2(i) - 30), round(x2(i) + 30)];
203
          boxY = [round(y2(i) - 30), round(y2(i) + 30)];
204
      end
205
206
207
      x3 = zeros(1, dim2_3);
208
      y3 = zeros(1, dim2_3);
209
     boxX = [335 \ 365];
210
      boxY = [240 270];
     %[335, 240, 20, 20]
211
212
      count = 0;
      for i = 1:dim2_3
213
214
          count = count + 1;
215
          img = vidFrames3_2(:,:,3,i);
          box = double(img(boxY(1):boxY(2), boxX(1):boxX(2)));
216
217
          [row, col] = find(box == max(max(box)));
218
          y3(i) = mean(row) + boxY(1);
219
          x3(i) = mean(col) + boxX(1);
220
          boxX = [round(x3(i) - 30), round(x3(i) + 30)];
221
          boxY = [round(y3(i) - 30), round(y3(i) + 30)];
222
      end
      % %%
223
224
      % figure(1);
225
      % for i = 1:length(img1)
226
           imshow(img1{i});
227
           hold on;
228
           rectangle('position', [x1(i) - 20, y1(i) - 20, 40, 40], 'Linewidth', 2);
      %
           hold off;
229
230
     %
           pause(0.001)
231
     % end
232
     % %%
233
      % figure(2);
234
     % for i = 1:length(img2)
235
           imshow(img2{i});
236
     %
           hold on;
237
           rectangle('position', [x2(i) - 15, y2(i) - 15, 30, 30], 'Linewidth', 2);
     %
238
           hold off;
239
     %
           pause(0.001)
240
     % end
241
     % %%
242
     % figure(3);
     % for i = 1:length(img3)
243
244
           imshow(img3{i});
245
           hold on;
246
     %
           rectangle('position', [x3(i) - 15, y3(i) - 15, 30, 30], 'Linewidth', 2);
247
     %
           hold off;
248
           pause(0.001)
249
     % end
250
      %%
251
     x1; y1;
252
     x2 = x2(23:dim2_1 + 22);
253
     y2 = y2(23:dim2 1 + 22);
254
      x3 = x3(1:dim2_1);
255
      y3 = y3(1:dim2_1);
      %%
256
257
      figure(2)
258
      subplot(2,1,1);
259
      plot(y1 - mean(y1), 'Linewidth', 3); hold on;
      plot(y2 - mean(y2), 'Linewidth', 3)
260
```

```
plot(x3 - mean(x3), 'Linewidth', 3)
261
262
      title('Y Coordinates of Can in Noisy Case(Normalized)');
263
      xlabel('Time');
      ylabel('Displacement');
264
      xlim([0 length(y1) + 50]);
265
      legend('cam1(y1)','cam2(y2)','cam3(y3)');
266
267
268
      subplot(2,1,2);
      plot(x1 - mean(x1), 'Linewidth', 3); hold on;
269
      plot(x2 - mean(x2), 'Linewidth', 3)
270
      plot(y3 - mean(y3),'Linewidth', 3)
271
272
      title('X Coordinates of Can in Noisy Case(Normalized)');
273
      xlabel('Time');
274
      ylabel('Displacement');
275
      legend('cam1(x1)','cam2(x2)','cam3(x3)');
276
      xlim([0 length(y1) + 50]);
277
278
      X = [x1- mean(x1); y1- mean(y1); x2- mean(x2); y2- mean(y2); y3- mean(y3); x3- mean(x3);];
279
      [u, s, v] = svd(X, 'econ');
280
      %%
281
      figure(3)
      plot(diag(s)/sum(diag(s)), 'o','Linewidth', 2);
282
283
      title('Importance of Singular Values For All Directions in Noisy Case');
284
      xlabel('Singular values');
285
      ylabel('Energy');
      %%
286
      %----
287
288
      %% TEST 3
289
      clc; clear all; close all;
      %% horizontal displacement
290
      load('cam1_3.mat')
291
      load('cam2_3.mat')
292
293
      load('cam3 3.mat')
294
295
      [row1, col1, dim1_1, dim2_1] = size(vidFrames1_3);
296
      [row2, col2, dim1_2, dim2_2] = size(vidFrames2_3);
297
      [row3, col3, dim1_3, dim2_3] = size(vidFrames3_3);
298
      %%
299
      for k = 1:dim2 1
300
          img1{k} = vidFrames1_3(:, :, :, k);
301
      end
302
      for k = 1:dim2_2
303
          img2\{k\} = vidFrames2\ 3(:, :, :, k);
304
      end
305
306
      for k = 1:dim2 3
307
          img3{k} = vidFrames3_3(:, :, :, k);
308
      end
309
      %% case 2
310
      x1 = zeros(1, dim2_1);
      y1 = zeros(1, dim2_1);
311
     boxX = [310 \ 330];
312
313
      boxY = [280 \ 300];
314
      for i = 1:dim2_1
315
          img = vidFrames1_3(:,:,3,i);
316
          box = double(img(boxY(1):boxY(2), boxX(1):boxX(2)));
317
          [row, col] = find(box == max(max(box)));
318
          y1(i) = mean(row) + boxY(1);
319
          x1(i) = mean(col) + boxX(1);
          boxX = [round(x1(i) - 10), round(x1(i) + 10)];
320
          boxY = [round(y1(i) - 10), round(y1(i) + 10)];
321
322
      end
323
324
      x2 = zeros(1, dim2_2);
325
      y2 = zeros(1, dim2_2);
```

```
326
      boxX = [230 \ 260];
327
      boxY = [280 310];
328
      for i = 1:dim2_2
329
          img = vidFrames2_3(:,:,3,i);
          box = double(img(boxY(1):boxY(2), boxX(1):boxX(2)));
330
331
          [row, col] = find(box == max(max(box)));
332
          y2(i) = mean(row) + boxY(1);
333
          x2(i) = mean(col) + boxX(1);
334
          boxX = [round(x2(i) - 10), round(x2(i) + 10)];
          boxY = [round(y2(i) - 10), round(y2(i) + 10)];
335
336
      end
337
338
339
      x3 = zeros(1, dim2 3);
340
      y3 = zeros(1, dim2_3);
341
      boxX = [345 \ 375];
342
      boxY = [220 \ 250];
343
     count = 0;
344
     for i = 1:dim2_3
345
          count = count + 1;
346
          img = vidFrames3_3(:,:,3,i);
          box = double(img(boxY(1):boxY(2), boxX(1):boxX(2)));
347
348
          [row, col] = find(box == max(max(box)));
349
          y3(i) = mean(row) + boxY(1);
350
          x3(i) = mean(col) + boxX(1);
          boxX = [round(x3(i) - 20), round(x3(i) + 20)];
351
          boxY = [round(y3(i) - 20), round(y3(i) + 20)];
352
353
      end
354
     % %%
355
      % figure(1);
     % for i = 1:length(img1)
356
357
     %
           imshow(img1{i});
358
     %
           hold on;
359
           rectangle('position', [x1(i) - 10, y1(i) - 10, 20, 20], 'Linewidth', 2);
360
      %
           hold off;
361
      %
           pause(0.001)
362
      % end
363
     %%
364
      % figure(2);
365
      % for i = 1:length(img2)
366
     %
           imshow(img2{i});
     %
367
           hold on;
368
           rectangle('position', [x2(i) - 10, y2(i) - 10, 20, 20], 'Linewidth', 2);
369
           hold off;
370
      %
           pause(0.001)
371
      % end
372
     %%
373
      % figure(3);
      % for i = 1:length(img3)
374
375
           imshow(img3{i});
376
     %
           hold on;
377
           rectangle('position', [x3(i) - 10, y3(i) - 10, 20, 20], 'Linewidth', 2);
     %
378
      %
           hold off;
379
      %
           pause(0.001)
380
      % end
381
      %%
382
     x1 = x1(8:177 + 7);
383
     y1 = y1(8:177 + 7);
384
     x2 = x2(36:177+35);
      y2 = y2(36:177+35);
385
      x3 = x3(1:177);
386
387
      y3 = 480 - y3(1:177);
388
      %%
389
      figure(2)
390
      subplot(2,1,1);
```

```
plot(y1 - mean(y1), 'Linewidth', 3); hold on;
391
      plot(y2 - mean(y2),'Linewidth', 3)
392
393
      plot(x3 - mean(x3), 'Linewidth', 3)
394
      title('Y Coordinates of Can in Horizontal Displacement Case(Normalized)');
      xlabel('Time');
395
      ylabel('Displacement');
396
397
      xlim([0 length(y1) + 50]);
398
      legend('cam1(y1)','cam2(y2)','cam3(y3)');
399
400
      subplot(2,1,2);
401
      plot(x1 - mean(x1), 'Linewidth', 3); hold on;
      plot(x2 - mean(x2),'Linewidth', 3)
402
403
      plot(y3 - mean(y3),'Linewidth', 3)
404
      title('X Coordinates of Can in Horizontal Displacement Case(Normalized)');
405
      xlabel('Time');
406
      ylabel('Displacement');
      legend('cam1(x1)','cam2(x2)','cam3(x3)');
407
408
      xlim([0 length(y1) + 50]);
409
      X = [x1- mean(x1); y1- mean(y1); x2- mean(x2); y2- mean(y2); y3- mean(y3); x3- mean(x3);];
410
      [u, s, v] = svd(X, 'econ');
411
412
413
      figure(3)
414
      plot(diag(s)/sum(diag(s)), 'o','Linewidth', 2);
415
      title('Importance of Singular Values For All Directions in Noisy Case');
      xlabel('Singular values');
416
      ylabel('Energy');
417
418
419
      %-----
420
      %% TEST 4
      clc; clear all; close all;
421
422
      %% horizontal displacement and rotation
423
      load('cam1 4.mat')
424
      load('cam2 4.mat')
425
      load('cam3_4.mat')
426
      %%
427
      [row1, col1, dim1_1, dim2_1] = size(vidFrames1_4);
428
      [row2, col2, dim1_2, dim2_2] = size(vidFrames2_4);
429
      [row3, col3, dim1_3, dim2_3] = size(vidFrames3_4);
430
431
      for k = 1:dim2 1
432
          img1{k} = vidFrames1_4(:, :, :, k);
433
      end
434
      for k = 1:dim2 2
435
          img2\{k\} = vidFrames2_4(:, :, :, k);
436
437
438
      for k = 1:dim2 3
          img3{k} = vidFrames3_4(:, :, :, k);
439
440
      end
441
      boxX = [430 \ 460];
442
443
      boxY = [260 \ 290];
      for i = 20:70
444
445
          img = vidFrames1_4(:,:,3,i);
446
          box = double(img(boxY(1):boxY(2), boxX(1):boxX(2)));
447
          if (max(max(box)) == max(max(img)))
448
              [row, col] = find(box == max(max(box)));
449
              y1(i) = mean(row) + boxY(1);
450
              x1(i) = mean(col) + boxX(1);
451
              boxX = [round(x1(i) - 15), round(x1(i) + 15)];
452
              boxY = [round(y1(i) - 15), round(y1(i) + 15)];
453
          end
454
      end
455
```

```
boxX = [340 \ 370];
456
457
      boxY = [320 \ 350];
458
      for i = 150:200
459
          img = vidFrames1_4(:,:,3,i);
460
          box = double(img(boxY(1):boxY(2), boxX(1):boxX(2)));
          if (max(max(box)) == max(max(img)))
461
462
              [row, col] = find(box == max(max(box)));
463
              y1(i) = mean(row) + boxY(1);
464
              x1(i) = mean(col) + boxX(1);
465
              boxX = [round(x1(i) - 15), round(x1(i) + 15)];
              boxY = [round(y1(i) - 15), round(y1(i) + 15)];
466
467
          end
468
      end
469
      x1 = x1(y1>0);
470
      y1 = y1(y1>0);
471
472
473
      boxX = [255 285];
474
      boxY = [180 \ 210];
475
      for i = 152:200
476
          img = vidFrames2_4(:,:,3,i);
477
          box = double(img(boxY(1):boxY(2), boxX(1):boxX(2)));
478
          if (max(max(box)) == max(max(img)))
479
              [row, col] = find(box == max(max(box)));
480
              y2(i) = mean(row) + boxY(1);
              x2(i) = mean(col) + boxX(1);
481
482
              boxX = [round(x2(i) - 15), round(x2(i) + 15)];
483
              boxY = [round(y2(i) - 15), round(y2(i) + 15)];
484
          end
485
      end
486
487
      boxX = [248 \ 278];
488
      boxY = [198 228];
489
      for i = 235:274
490
          img = vidFrames2_4(:,:,3,i);
491
          box = double(img(boxY(1):boxY(2), boxX(1):boxX(2)));
492
          if (max(max(box)) == max(max(img)))
493
              [row, col] = find(box == max(max(box)));
494
              y2(i) = mean(row) + boxY(1);
              x2(i) = mean(col) + boxX(1);
495
496
              boxX = [round(x2(i) - 15), round(x2(i) + 15)];
              boxY = [round(y2(i) - 15), round(y2(i) + 15)];
497
498
          else
499
              y2(i) = y2(i-1);
500
              x2(i) = x2(i-1);
501
              boxX = [round(x2(i) - 50), round(x2(i) + 50)];
502
              boxY = [round(y2(i) - 50), round(y2(i) + 50)];
503
          end
504
      end
505
      x2 = x2(y2>0);
506
      y2 = y2(y2>0);
507
508
      boxX = [310 \ 340];
509
      boxY = [210 240];
510
      for i = 50:100
511
          img = vidFrames3_4(:,:,2,i);
          box = double(img(boxY(1):boxY(2), boxX(1):boxX(2)));
512
513
          [row, col] = find(box == max(max(box)));
514
          y3(i) = mean(row) + boxY(1);
515
          x3(i) = mean(col) + boxX(1);
516
          boxX = [round(x3(i) - 15), round(x3(i) + 15)];
517
          boxY = [round(y3(i) - 15), round(y3(i) + 15)];
518
      end
519
      boxX = [365 \ 395];
      boxY = [220 \ 250];
520
```

```
521
     for i = 120:170
          img = vidFrames3_4(:,:,2,i);
522
523
          box = double(img(boxY(1):boxY(2), boxX(1):boxX(2)));
          [row, col] = find(box == max(max(box)));
524
525
          y3(i) = mean(row) + boxY(1);
          x3(i) = mean(col) + boxX(1);
526
527
          boxX = [round(x3(i) - 15), round(x3(i) + 15)];
528
          boxY = [round(y3(i) - 15), round(y3(i) + 15)];
529
     end
     y3 = x3(x3>0);
530
531
     x3 = x3(x3>0);
532
     y3 = [y3(10:40) y3(63:end)];
533
     x3 = [x3(10:40) x3(63:end)];
534
     %%
535
     x1 = x1(5:length(x3));
536
     y1 = y1(5:length(x3));
537
     x2 = x2(1:length(x3) - 4);
     y2 = y2(1:length(x3) - 4);
538
539
     x3 = x3(5:length(x3));
540
     y3 = 480 - y3(1:length(x3));
     %%
541
542
     figure(2)
543
     subplot(2,1,1);
      plot(y1 - mean(y1), 'Linewidth', 3); hold on;
544
     plot(y2 - mean(y2), 'Linewidth', 3)
545
      plot(x3 - mean(x3), 'Linewidth', 3)
546
547
     title('Y Coordinates of Can in Horizontal Displacement and Rotation Case(Normalized)');
548
     xlabel('Time');
549
     ylabel('Displacement');
550
     xlim([0 length(y1) + 10]);
     legend('cam1(y1)','cam2(y2)','cam3(y3)');
551
552
553
     subplot(2,1,2);
      plot(x1 - mean(x1), 'Linewidth', 3); hold on;
554
      plot(x2 - mean(x2), 'Linewidth', 3)
555
      plot(y3 - mean(y3),'Linewidth', 3)
556
557
     title('X Coordinates of Can in Horizontal Displacement and Rotation Case(Normalized)');
558
     xlabel('Time');
559
     ylabel('Displacement');
     legend('cam1(x1)','cam2(x2)','cam3(x3)');
560
561
     xlim([0 length(y1) + 10]);
     %% SVD
562
563
     X = [x1- mean(x1); y1- mean(y1); x2- mean(x2); y2- mean(y2); y3- mean(y3); x3- mean(x3);];
564
     [u, s, v] = svd(X, 'econ');
565
     %%
566
     figure(3)
567
      plot(diag(s)/sum(diag(s)), 'o', 'Linewidth', 2);
     title('Importance of Singular Values For All Directions in Noisy Case');
568
569
     xlabel('Singular values');
     ylabel('Energy');
570
```