M2 ORO: Advanced Integer Programming Solution Final Exam – 2nd session

january 18, 2011

duration: 1h00.

documents: lecture notes are authorized. No book, no book copy.

grades: 3 problems of respectively 3+3+4 points each = 10 points.

Notations:

 $\mathbb{Z}, \mathbb{Z}_+, \mathbb{Z}_{+*}$ the sets of integer, non-negative integer, and positive integer numbers

 $\mathbb{R}, \mathbb{R}_+, \mathbb{R}_{+*}$ the sets of real, non-negative real, and positive real numbers

1 Model of graph

Problem 1 The Graph Bandwidth Problem.

Consider an undirected connected graph G=(V,E) with |V|=n vertices and |E|=m edges. A linear layout of G is a numbering of the vertices of G. In other words, it is an assignment $f:V\to\{1,2,\ldots,n\}$, such that different vertices $u,v\in V$ have different numbers $f(u)\neq f(v)$. The bandwidth of layout f, denoted by $\Phi_f(G)$, is the maximum difference between the numbers assigned to adjacent vertices, i.e. $\Phi_f(G)=\max\{|f(u)-f(v)|,(u,v)\in E\}$. The Graph Bandwidth Problem is to find the minimum bandwidth over all possible linear layouts of G. This value, denoted by $\Phi(G)$, is called the bandwidth of G.

Question 1 (3 points).

Q1.1. Model this problem as an Integer Linear Program.

Q1.2. Compute the optimal value of its continuous relaxation.

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1.

$$\begin{aligned} (\mathsf{GB}) \colon \min z \\ & \text{s.t. } z \geqslant \sum_{k=1}^n k(x_{\mathfrak{u}}^k - x_{\mathfrak{v}}^k) & \forall (\mathfrak{u}, \mathfrak{v}) \in \mathsf{E} \\ & z \geqslant \sum_{k=1}^n k(x_{\mathfrak{u}}^k - x_{\mathfrak{v}}^k) & \forall (\mathfrak{u}, \mathfrak{v}) \in \mathsf{E} \\ & \sum_{k=1}^n x_{\mathfrak{u}}^k = 1 & \forall \mathfrak{u} \in \mathsf{V}, \\ & \sum_{\mathfrak{u} \in \mathsf{V}} x_{\mathfrak{u}}^k = 1 & \forall k = 1, \dots, n, \\ & x_{\mathfrak{u}}^k \in \{0, 1\} & \forall \mathfrak{u} \in \mathsf{V}, k = 1, \dots, n \end{aligned}$$

where, in any solution, z is the bandwith of the layout f defined by $x_u^k = 1 \iff f(u) = k$, or alternatively by $f(u) = \sum_{k=1}^n k x_u^k$ for all $u \in V$.

2. The continuous relaxation of (GB) has an optimal value of 0. It is the cost of the optimal solution: $x_u^k = 1/n$ for all $u \in V$, k = 1, ..., n.

2 Model of logic

Problem 2 Suppose you are interested in choosing a set of investments among seven possible investments numbered from 1 to 7. The estimate profit of each investment i=1..7 is given by a positive integer $c_i \in \mathbb{Z}_{*+}$. You want to maximize your profit, knowing that:

- 1. you cannot invest in all of them
- 2. you must choose at least one of them
- 3. at most one of investments 1 and 3 can be chosen
- 4. investment 4 can be chosen only if investment 2 is also chosen
- 5. you must choose either both of investments 1 and 5, or neither
- 6. you must choose at least one of investments 1,2,3 or at least two of investments 2,4,5,6

Question 2 (3 points).

- **Q2.1.** Model this problem as a Binary Integer Linear Program, including all the individual constraints above.
- Q2.2. Simplify your model by fixing variables and removing redundant inequalities.

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1.

where $x_i = 1$ iff investment i is chosen, $y_1 = 1$ iff at least one of investments 1,2,3 is chosen, and $y_2 = 1$ iff at least two of investments 2,4,5,6 are chosen.

- 2. equality (5) can be removed by merging the two variable $x_1 = x_5$ and x_7 can be fixed to 1 in any optimal solution (since x_7 is unconstrained and $c_7 > 0$).
- 3. inequalities (1) and (2) can be removed: (1) is implied by (3), (2) is implied by (6). Note that (2) is also implied by the objective, because: this problem has feasible non-zero solutions, e.g. (1,0,0,0,1,0), with positive cost, then all optimal solutions are non-zero and satisfy (2).
- 4. to model constraint (6), one can relax the definitions of the y variables as: $y_1=1$ if at least one of investments 1,2,3 is chosen, and $y_2=1$ if at least two of investments 2,4,5,6 are chosen. As a consequence, we remove inequalities (6a) and (6c). Actually, (6e) enforces either y_1 or y_2 to be equal to 1, i.e. either $x_1+x_2+x_3\geqslant 1$ or $x_2+x_4+x_5+x_6\geqslant 2$.

5.

$$\begin{array}{lll} c_7 + \max{(c_1 + c_5)x_1 + c_2x_2 + c_3x_3 + c_4x_4 + c_6x_6} \\ & \text{s.t. } x_1 + x_3 \leqslant 1 & (3) \\ & x_4 \leqslant x_2 & (4) \\ & y_1 \leqslant x_1 + x_2 + x_3 & (6b) \\ & 2y_2 \leqslant x_1 + x_2 + x_4 + x_6 & (6d) \\ & y_1 + y_2 \geqslant 1 & (6e) \\ & x_i \in \{0,1\} & i = 1,2,3,4,6 \\ & y_i \in \{0,1\} & i = 1,2 \end{array}$$

3 Lagrangian Relaxation

Problem 3 Resource Constrained Shortest Path Problem (RCSPP).

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Let G(V,A) be a directed acyclic graph with a source $s \in V$ and a sink $t \in V$, and let R be a set of resources with limited capacities $C_{\tau} \in \mathbb{Z}_{+s}$, $\forall \tau \in R$. Each arc $\alpha \in A$ has a distance $d_{\alpha} \in \mathbb{Z}_{+}$, and traversing arc α consumes a given amount $c_{\alpha r} \in \mathbb{Z}_{+}$ of each resource $\tau \in R$. The RCSPP is to find a path from s to t of minimal distance and such that, for each resource $\tau \in R$, the total amount of resource τ consumed along the path does not exceed the capacity C_{τ} .

Question 3 (4 points).

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- **Q3.1.** Model this problem as a Binary Integer Linear Program using decision variables $x_\alpha=1$ if arc α belongs to the selected path, and $x_\alpha=0$ otherwise.
- **Q3.2.** Describe a lagrangian relaxation applied to this model by dualizing the resource constraints and exhibit the nature of the sub-problems and their complexity.
- Q3.3. Compare the optimum of the lagrangian dual with the optimum of the LP-relaxation.

$$(P) \ z = \min \sum_{\alpha \in A} d_{\alpha} x_{\alpha}$$

$$\sum_{\alpha \in \delta_{-}(i)} x_{\alpha} - \sum_{\alpha \in \delta_{+}(i)} x_{\alpha} = b_{i} \qquad \qquad i \in V$$

$$\sum_{\alpha \in A} c_{\alpha r} x_{\alpha} \leqslant C_{r} \qquad \qquad r \in R$$

$$x_{\alpha} \in \{0,1\} \qquad \qquad \alpha \in A$$

where $b_i=1$ if i=s, $b_i=-1$ if i=t, $b_i=0$ otherwise. Let dualize the resource constraints, then the lagrangian dual is $(D): max_{\lambda \in \mathbb{R}^R}(z_\lambda - \sum_{r \in \mathbb{R}} C_r \lambda_r)$ where:

$$\begin{split} (P_{\lambda}) \; z_{\lambda} &= \min \; \sum_{\alpha \in A} (d_{\alpha} + \sum_{r \in R} \lambda_{r} c_{\alpha r}) x_{\alpha} \\ &\qquad \qquad \sum_{\alpha \in \delta_{-}(\mathfrak{i})} x_{\alpha} - \sum_{\alpha \in \delta_{+}(\mathfrak{i})} x_{\alpha} = b_{\mathfrak{i}} \\ &\qquad \qquad \mathfrak{i} \in V \\ x_{\alpha} &\in \{0,1\} \end{split}$$

Such sub-problem is polynomially solvable as it is a shortest path problem from s to t on G using a distance value $d_{\alpha} + \sum_{r \in R} \lambda_r c_{\alpha r}$ on each arc $\alpha \in A$. Actually, model (P_{λ}) is ideal (its coefficient matrix is a flow matrix) hence the optimum of (D) is the optimum of the LP-relaxation.

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