

Algorithm PQ-Sort(S, C)
Input sequence S, comparator C
for the elements of S
Output sequence S sorted in
P ← priority queue with
comparator C
while ¬S.isEmpty()
 e ← S.removeFirst()
 P.insert(e, 0)
while ¬P.isEmpty()
 e ← P.removeMin().key()
 S.insertLast(e)

Algorithm SelectionSort(A);
Input sequence A
Output sorted sequence A
for i = 1 **to** n - 1
 posmin ← i
 for j = (i + 1) **to** n
 if a[j] < a[posmin]
 posmin ← j
 if posmin != i
 tmp ← a[i]
 a[i] ← a[posmin]
 a[posmin] ← tmp

Algorithm InsertionSort(A)
Input sequence A
Output sorted sequence A
for i ← 1 **to** length[A]
 do value ← A[i]
 j ← i-1
 while j >= 0 **and** A[j] > value
 do A[j + 1] ← A[j]
 j ← j-1
 A[j+1] ← value

Algorithm mergeSort(S, C)
Input sequence S with n
elements, comparator C
Output sequence S sorted
according to C
if S.size() > 1
 (S1, S2) ← partition(S, n/2)
 mergeSort(S1, C)
 mergeSort(S2, C)
 S ← merge(S1, S2)

Algorithm merge(A, B)
Input sequences A and B with
n/2 elements each
Output sorted sequence of A ∪ B
S ← empty sequence
while ¬A.isEmpty() ∧ ¬B.isEmpty()
 if A.first().element() < B.first().element()
 S.insertLast(A.remove(A.first()))
 else
 S.insertLast(B.remove(B.first()))
while ¬A.isEmpty()
 S.insertLast(A.remove(A.first()))
while ¬B.isEmpty()
 S.insertLast(B.remove(B.first()))
return S

Algorithm inPlaceQuickSort(S, l, r)
Input sequence S, ranks l and r
Output sequence S with the elements of rank
between l and r rearranged in increasing order.
if l ≥ r
 return
i ← a random integer between l and r
x ← S.elemAtRank(i)
(h, k) ← inPlacePartition(x)
inPlaceQuickSort(S, l, h - 1)
inPlaceQuickSort(S, k + 1, r)

Algorithm quickSelect(A, l, r, k)
Input sequence A, left index l, right index r,
Output
if l = r
 return A[l]
Select pivotIndex between l and r
pivotIndex ← partition(A, l, r, pivotIndex)
if (k = pivotIndex)
 return A[k]
else if (k < pivotIndex)
 quickSelect(A, l, pivotIndex-1, k)
else
 quickSelect(A, pivotIndex +1, r, k)

Algorithm heapsort(A, n)
Input sequence A and size n
Output sorted A
for i ← n/2 -1 **to** 0
 heapify(A, n, i)
for i ← n -1 **to** 0
 swap(A, i, 0)
 heapify(A, i, 0)

Algorithm DFS(G, v)
Input grafo G vertice iniziale v di G (con grafo
inizialmente settato ad UNEXPLORED)
Output etichettatura degli spigoli di G
nella componente connessa di v
come tree-edge e back-edge
setLabel(v, VISITED)
for all e ∈ G.incidentEdges(v)
 if getLabel(e) = UNEXPLORED
 w ← opposite(v, e)
 if getLabel(w) = UNEXPLORED
 setLabel(e, DISCOVERY)
 DFS(G, w)
 else
 setLabel(e, BACK)

Algorithm pathDFS(G, v, z)
Input grafo G vertice iniziale v di G e vertice di
arrivo z (con grafo inizialmente settato ad
UNEXPLORED)
Output percorso tra v e z
setLabel(v, VISITED)
S.push(v)
if (v = z)
 return S.elements()
for all e ∈ G.incidentEdges(v)
 if getLabel(e) = UNEXPLORED
 w ← opposite(v, e)
 if getLabel(w) = UNEXPLORED
 setLabel(e, DISCOVERY)
 S.push(e)
 pathDFS(G, w, z)
 S.pop(e)
 else
 setLabel(e, BACK)
S.pop(e)

Algorithm cycleDFS(G, v)
setLabel(v, VISITED)
S.push(v)
for all e ∈ G.incidentEdges(v)
 if getLabel(e) = UNEXPLORED
 w ← opposite(v, e)
 S.push(e)
 if getLabel(w) = UNEXPLORED
 setLabel(e, DISCOVERY)
 cycleDFS(G, w)
 S.pop(e)
 else
 T ← new empty stack
 repeat
 o ← S.pop()
 T.push(o)
 until o = w
 return T.elements()
S.pop(v)

D-DFS(Digraph G, Vertex v)**Input** graph G and source vertex v**Output** labeled graph (of v)

(N.B. getDiscoveryLabel = getDiscLabel)

setDiscoveryLabel(v, getNextDLLabel());

for all e in outgoingEdges(v) **if**(getLabel(e) == UNEXPLORED)

w = opposite(e, v)

if(getDiscoveryLabel(w) == UNEXPLORED)

setLabel(e, DISCOVERY)

D-DFS(G, w)

else if(getLeavingLabel(w) == 0)

setLabel(e, BACK)

else if (getDiscLabel(v) < getDiscLabel(w))

setLabel(e, FORWARD)

else

setLabel(e, CROSS)

setLeavingLabel(v, getNextLLLabel())

Algorithm FloydWarshall(G)**Input** digrafo G**Output** la chiusura transitiva G^* di G $i \leftarrow 1$ **for all** v \in G.vertices()

denota v come v i

 $i \leftarrow i + 1$ $G_0 \leftarrow G$ **for** k $\leftarrow 1$ to n do $G_k \leftarrow G_{k-1}$ **for** i $\leftarrow 1$ to n (i \neq k) do **for** j $\leftarrow 1$ to n (j \neq i, k) do **if** G_{k-1} .areAdjacent(v_i, v_k) \wedge G_{k-1} .areAdjacent(v_k, v_j) **if** $\neg G_k$.areAdjacent(v_i, v_j) G_k .insertDirectedEdge(v_i, v_j, k) return G_n **Algorithm topologicalDFS(G, v)****Input** grafo G e vertice iniziale v di G

(supponendo archi e nodi inizializzati a UNEXPLORED)

Output etichettatura dei vertici di G

nella componente connessa di v

setLabel(v, VISITED)

for all e \in G.incidentEdges(v) **if** getLabel(e) = UNEXPLORED

w = opposite(v, e)

if getLabel(w) = UNEXPLORED

setLabel(e, DISCOVERY)

topologicalDFS(G, w)

else

{ e è uno spigolo forward o cross }

etichetta v con il numero n

 $n \leftarrow n - 1$ // side effect!**Algorithm BFS(G, s)****Input** graph G, vortex s**Output** grafo delle etichettature partendo dal vertice s $L_0 \leftarrow$ new empty sequence L_0 .insertLast(s)

setLabel(s, VISITED)

 $i \leftarrow 0$ **while** $\neg L_i$.isEmpty() $L_{i+1} \leftarrow$ new empty sequence **for all** v $\in L_i$.elements() **for all** e \in G.incidentEdges(v) **if** getLabel(e) = UNEXPLORED

w = opposite(v, e)

if getLabel(w) = UNEXPLORED

setLabel(e, DISCOVERY)

setLabel(w, VISITED)

 L_{i+1} .insertLast(w) **else**

setLabel(e, CROSS)

 $i \leftarrow i + 1$ **Method TopologicalSort(G)** $H \leftarrow G$

// copia temporanea di G

 $n \leftarrow$ G.numVertices()**while** H è non vuoto **do**

trova un pozzo v // esiste sempre?

 etichetta v \leftarrow n $n \leftarrow n - 1$

rimuovi v da H // anche gli spigoli incidenti

Algorithm DijkstraDistances(G, s) $Q \leftarrow$ new heap-based priority queue**for all** v \in G.vertices() **if** v = s

setDistance(v, 0)

else setDistance(v, ∞) $l \leftarrow$ Q.insert(getDistance(v), v)

setLocator(v, l)

while $\neg Q$.isEmpty() u \leftarrow Q.removeMin() **for all** e \in G.incidentEdges(u)

{ relax edge e }

 z \leftarrow G.opposite(u, e) r \leftarrow getDistance(u) + weight(e) **if** r < getDistance(z)

setDistance(z, r)

Q.replaceKey(getLocator(z), r)

Algorithm DijkstraShortestPathsTree(G, s) $Q \leftarrow$ new heap-based priority queue**for all** v \in G.vertices() setParent(v, 0) **if** v = s

setDistance(v, 0)

else setDistance(v, ∞) $l \leftarrow$ Q.insert(getDistance(v), v)

setLocator(v, l)

while $\neg Q$.isEmpty() u \leftarrow Q.removeMin() **for all** e \in G.incidentEdges(u)

{ relax edge e }

 z \leftarrow G.opposite(u, e) r \leftarrow getDistance(u) + weight(e) **if** r < getDistance(z)

setDistance(z, r)

setParent(z, e)

Q.replaceKey(getLocator(z), r)

Algorithm PrimJarnikMST(G) $Q \leftarrow$ new heap-based priority queues \leftarrow a vertex of G**for all** v \in G.vertices() **if** v = s

setDistance(v, 0)

else setDistance(v, ∞) setParent(v, \emptyset) $l \leftarrow$ Q.insert(getDistance(v), v)

setLocator(v, l)

while $\neg Q$.isEmpty() u \leftarrow Q.removeMin() **for all** e \in G.incidentEdges(u) z \leftarrow G.opposite(u, e) r \leftarrow weight(e) **if** r < getDistance(z)

setDistance(z, r)

setParent(z, e)

Q.replaceKey(getLocator(z), r)

Algorithm Kruskal(G)A = \emptyset **foreach** v \in G.vertices

make-set(v)

foreach (u, v) ordered by weight of (u, v) **if** FIND-SET(u) \neq FIND-SET(v): A = A \cup {(u, v)}

UNION(u, v)

return A

Algorithm BoruvkaMST(G)

```

T ← V {subgraph containing just the vertices of G,
no edges}
while T has fewer than n-1 edges do
    for each connected component C in T do
        Let edge e be the smallest-weight edge
        from C to another component in T.
        if e is not already in T then
            Add edge e to T
return T

```

Algorithm countingSort(A,n)**Input** sequenza A con size n**Output** sequenza A ordinata senza confronto

```

max ← 0
min ← 0
for i ← 1 to n
    if(a[i] > a[max])
        max ← i
    else if(a[i] < min) min ← i
B ← empty sequence
for i ← 1 to n
    B[A[i] - min]++
h ← 0
for i ← 0 to max - min
    while(B[i]--)
        A[h++] ← i + min

```

BUCKET-SORT(array A, int n)

```

for(i = 1; i <= n; i++)
    insert A[i] nella lista B[floor(n*A[i])]
for(i = 0; i <= n-1; i++)
    sort B[i]
concatenate B[0] ... B[n-1]

```

RADIX-SORT(array A, int d)

```

for i=1 to d
    do use a stable sort to sort array A on digit i
// es. Java semplificato
static void rs(int[] a, int start, int endp1, int
mask) {
    if((endp1 - start <= 1) || (mask == 0))
        return;
    int j = start, k = endp1;
    while(j < k) {
        while((j < k) && ((a[j] & mask) == 0x0))
            j++;
        while((j < k) && ((a[k-1] & mask) != 0x0))
            k--;
        if(j < k) swap(a, j, k-1);
    }
    rs(a, start, j, mask >>> 1);
    rs(a, j, endp1, mask >>> 1);
}

```