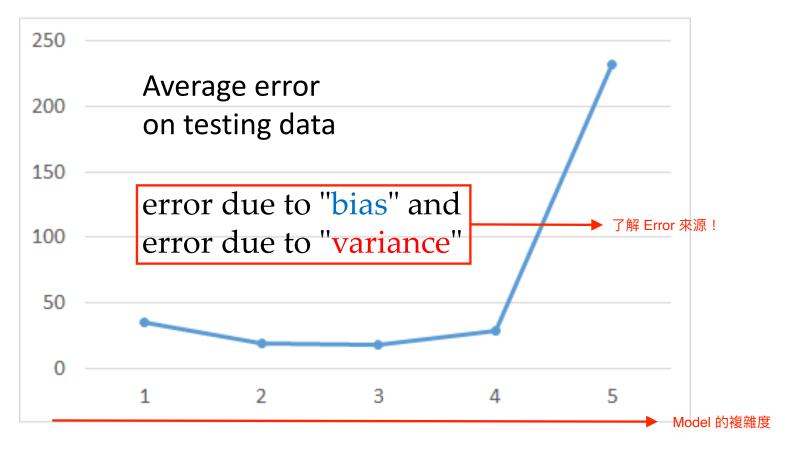
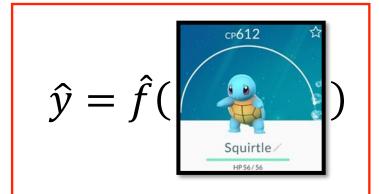
# Where does the error come from?

## Review



A more complex model does not always lead to better performance on *testing data*.

## Estimator

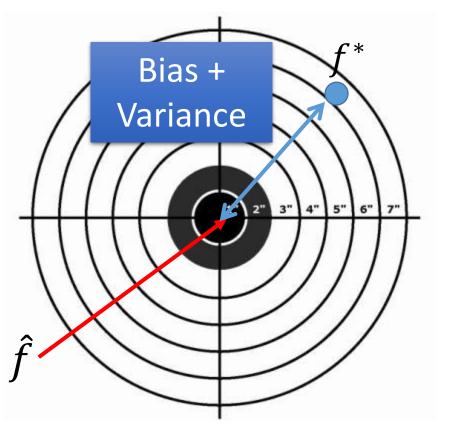


Only Niantic knows  $\hat{f}$ 

From training data, we find  $f^*$ 

 $f^*$  is an estimator of  $\hat{f}$ 

Machine 從 Function Set 中找到的 Best Function 與 真實 Function 的 距離 => Bias + Variance



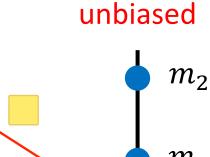
## Bias and Variance of Estimator

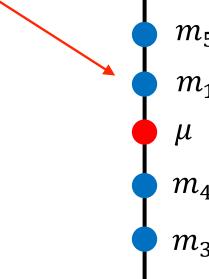
- Estimate the mean of a variable x

  - assume the mean of x is  $\mu$  assume the variance of x is  $\sigma^2$
- Estimator of mean  $\mu$ 
  - Sample N points:  $\{x^1, x^2, ..., x^N\}$

$$m = \frac{1}{N} \sum_{n} x^{n} \neq \mu$$

$$E[m] = E\left[\frac{1}{N}\sum_{n} x^{n}\right] = \frac{1}{N}\sum_{n} E[x^{n}] = \mu$$





 $m_6$ 

## Bias and Variance of Estimator

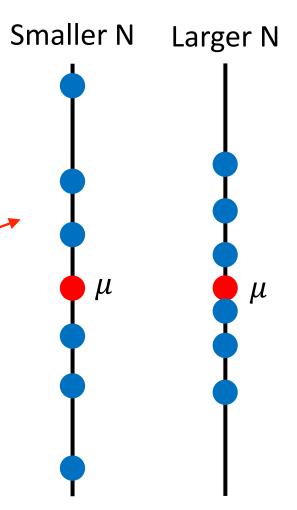
- Estimate the mean of a variable x
  - assume the mean of x is  $\mu$
  - assume the variance of x is  $\sigma^2$
- Estimator of mean  $\mu$ 
  - Sample N points:  $\{x^1, x^2, ..., x^N\}$

$$m = \frac{1}{N} \sum_{n} x^{n} \neq \mu$$

$$Var[m] = \frac{\sigma^2}{N}$$

Variance depends on the number of samples

#### unbiased



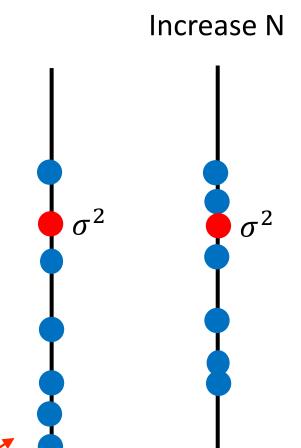
## Bias and Variance of Estimator

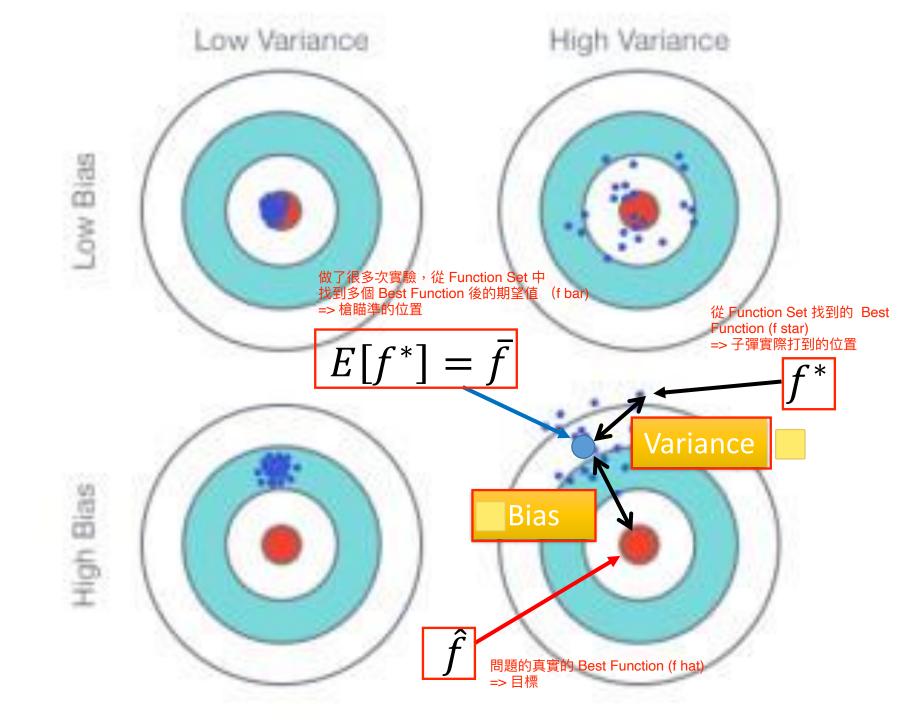
- Estimate the mean of a variable x
  - assume the mean of x is  $\mu$
  - assume the variance of x is  $\sigma^2$
- Estimator of variance  $\sigma^2$ 
  - Sample N points:  $\{x^1, x^2, ..., x^N\}$

$$m = \frac{1}{N} \sum_{n} x^{n}$$
  $s^{2} = \frac{1}{N} \sum_{n} (x^{n} - m)^{2}$ 

#### Biased estimator

$$E[s^2] = \frac{N-1}{N}\sigma^2 \neq \sigma^2$$

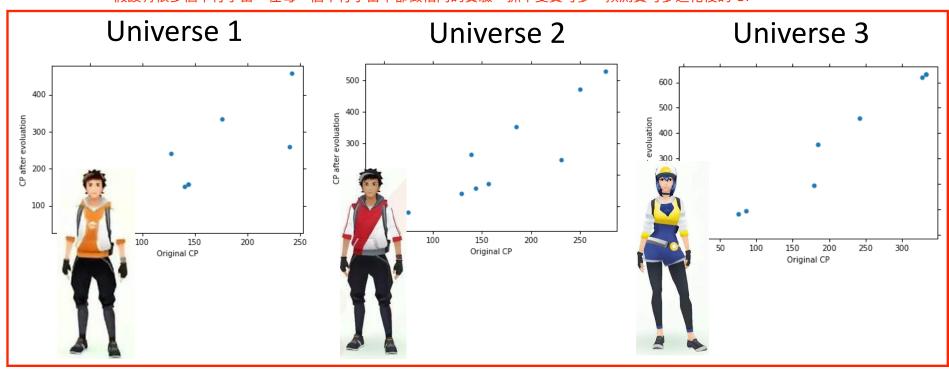




## Parallel Universes

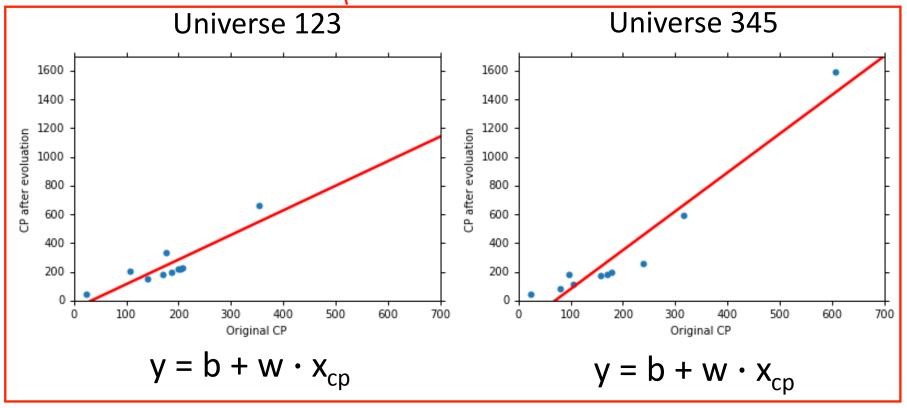
• In all the universes, we are collecting (catching) 10 Pokémons as training data to find  $f^{\,*}$ 

假設有很多個平行宇宙,在每一個平行宇宙中都做相同的實驗:抓十隻寶可夢,預測寶可夢進化後的 CP

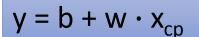


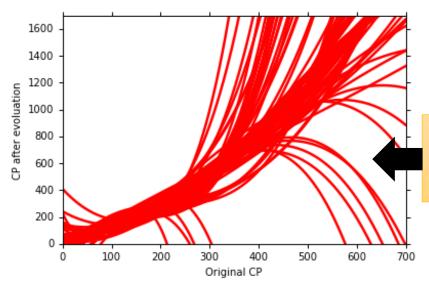
## Parallel Universes

• In different universes, we use the same model, but obtain different  $f^*$ 在不同的平行宇宙中,都使用相同的 Model (Function Set) 與相同的 Loss function,因為抓到的十隻寶可夢 (Training Data) 都不同,所以從 Function Set 中找到的 Best Function 也會不同!



### $f^*$ in 100 Universes

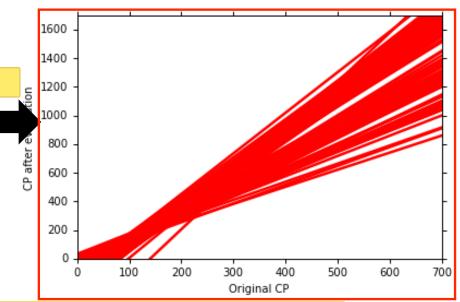




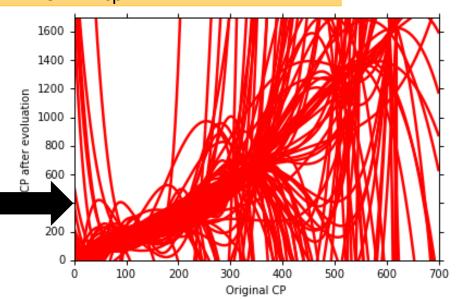
$$y = b + w_{1} \cdot x_{cp} + w_{2} \cdot (x_{cp})^{2}$$

$$+ w_{3} \cdot (x_{cp})^{3} + w_{4} \cdot (x_{cp})^{4}$$

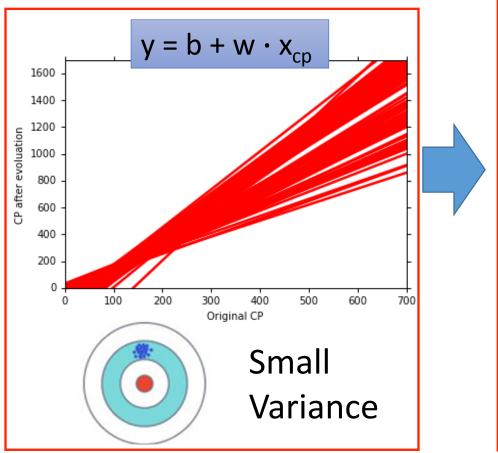
$$+ w_{5} \cdot (x_{cp})^{5}$$

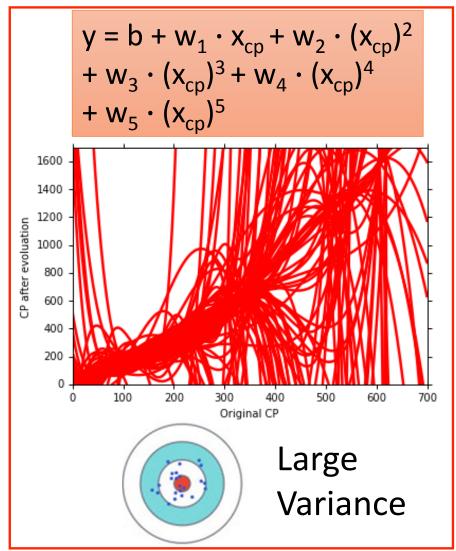


$$y = b + w_1 \cdot x_{cp} + w_2 \cdot (x_{cp})^2 + w_3 \cdot (x_{cp})^3$$



## Variance





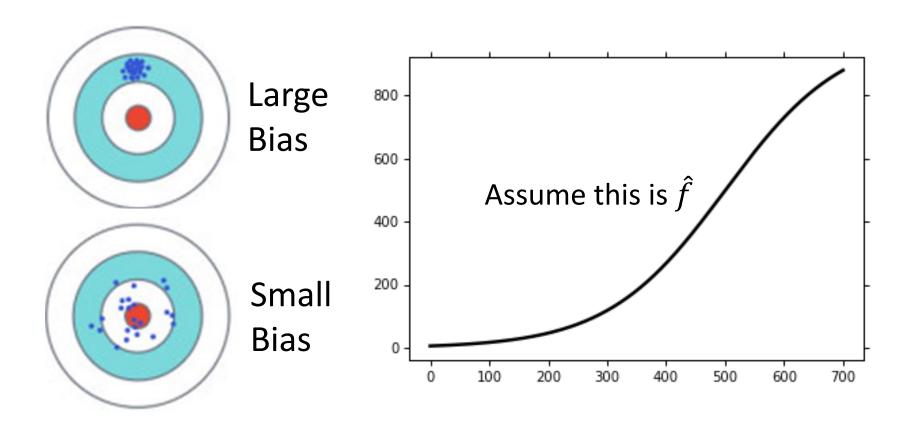
Simpler model is less influenced by the sampled data

Consider the extreme case f(x) = c

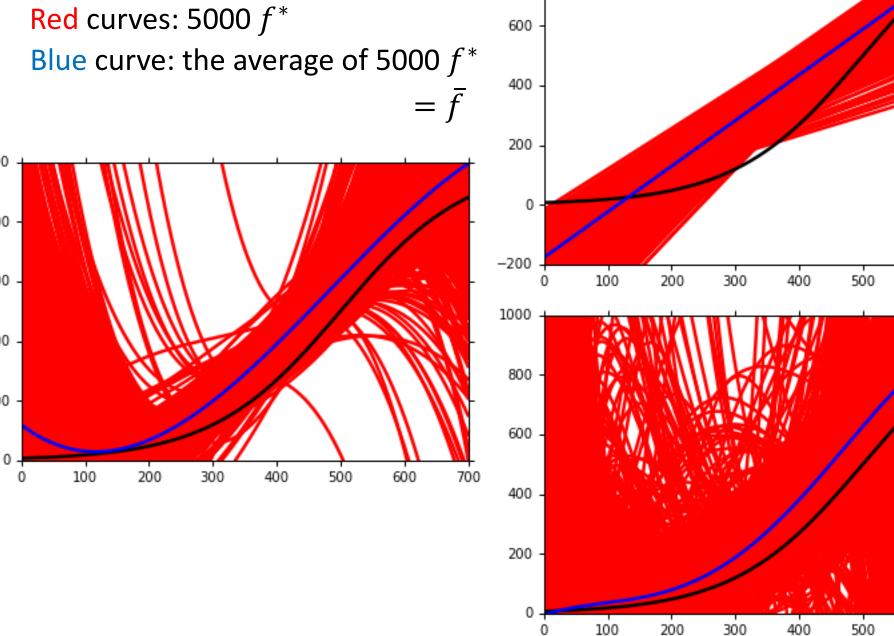
## Bias

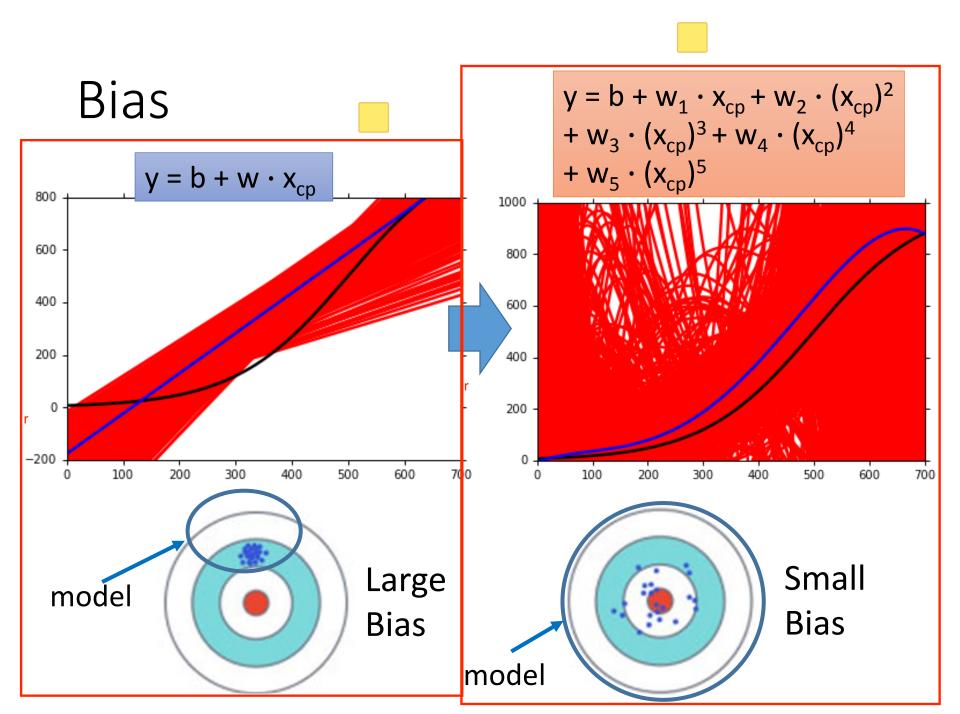
$$E[f^*] = \bar{f}$$

• Bias: If we average all the  $f^*$ , is it close to  $\hat{f}$ 

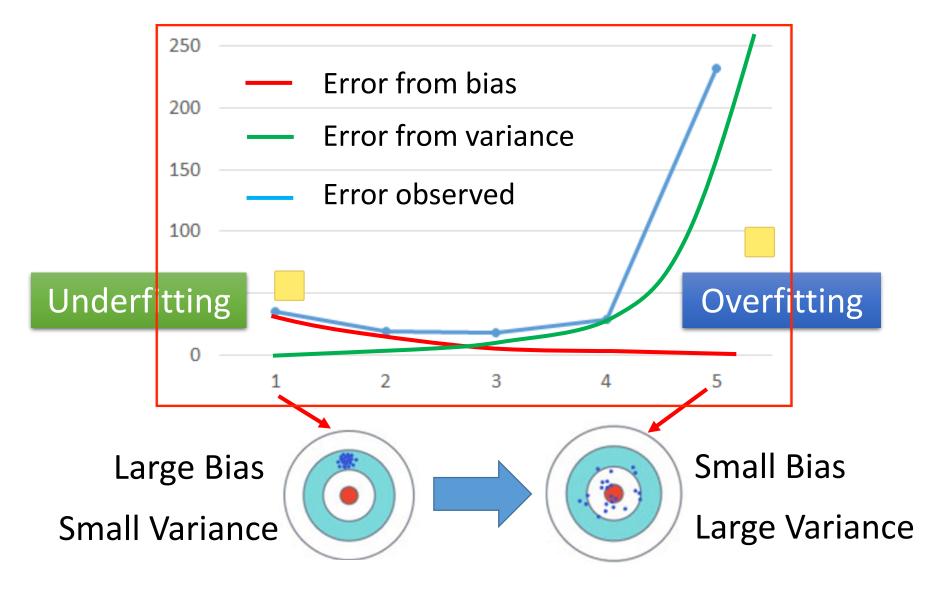


Black curve: the true function  $\hat{f}$ 





## Bias v.s. Variance

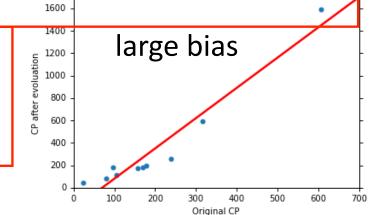


# What to do with large bias?

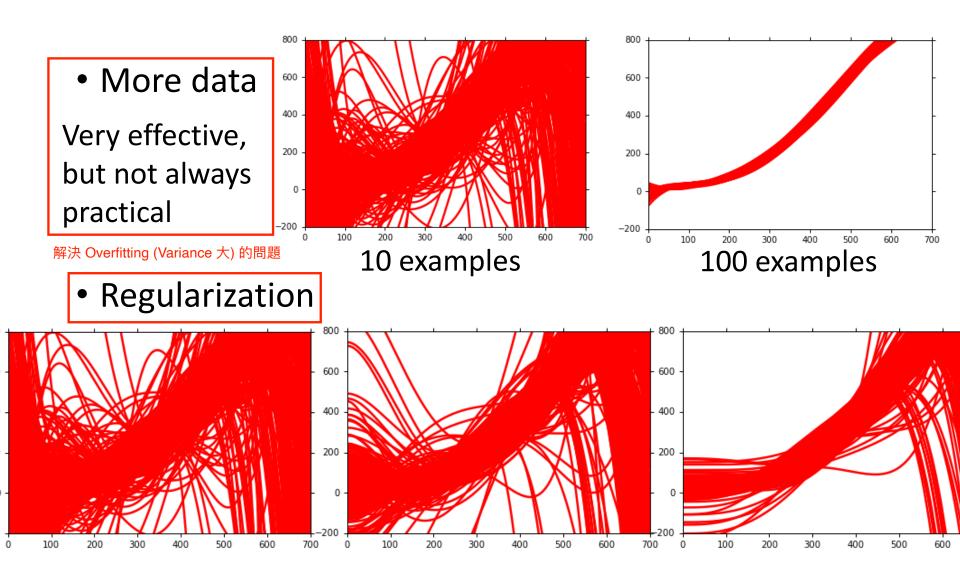
#### • Diagnosis:

- If your model cannot even fit the training examples, then you have large bias Underfitting
- If you can fit the training data, but large error on testing data, then you probably have large variance

  Overfitting
- For bias, redesign your model:
  - Add more features as input
  - A more complex model

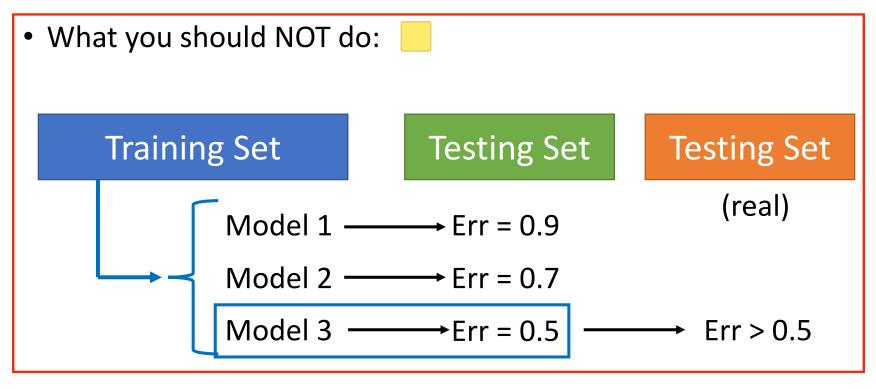


# What to do with large variance?

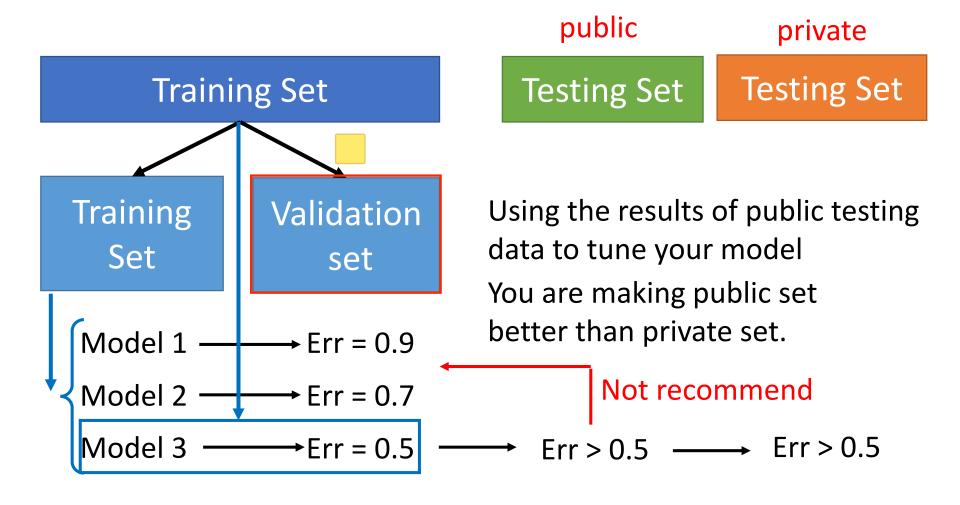


## Model Selection

- There is usually a trade-off between bias and variance.
- Select a model that balances two kinds of error to minimize total error



## Cross Validation



## N-fold Cross Validation

