

Week 1: 11 Nov - 13 Nov

Started this week learning about how to use MPI in Athena++. Followed the [3D blast wave tutorial](#) and managed to get it working on Thunderbird with HDF5. Jono also recommended learning a text editor, so I spent an hour learning the basics of Vim. **Note:** HDF5 is better to use than .vtk with parallel computing as it allows all the processors being used to write the data in one file compared to a file for each processor that need to be joined (less hassle).

Jono then gave me an Athena++ hydrodynamic turbulence input script to play around with, and some MATLAB scripts that analyse the energy spectrum of the fluid in question. At the moment, we model the fluid in a cube. There are two different modes that we're wanting to focus on: decaying turbulence (disturb the fluid initially then leave it to its own devices) and continuously driven turbulence. Ran the Athena++ code with 3 different grid sizes for both modes; see screenshots below.

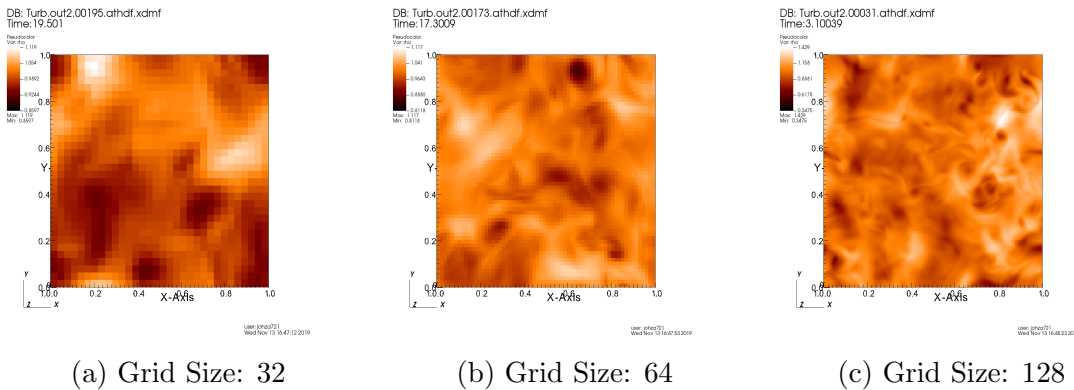


Figure 1: Face-on view of the 3D forced turbulence simulations with different grid sizes; density plotted

These were just the simulations with none of the parameters changed in the input script. Using the MATLAB scripts I also obtained the energy spectrum of the fluid; was very rough due to the low resolution. Wanted to try start a 256^3 grid size simulation before I left on Wednesday but didn't have enough time to set up; will try again later. Thursday and Friday of this week were spent at the [Otago Software Carpentry Workshop](#).

Next Week: Play around with parameters. Want to run the larger grid size simulations to obtain a better energy spectrum that fits the $k^{-5/3}$ law, will add screenshots of spectrum then. Plot the total energy over time for both modes; should observe fluctuations in the energy for forced turbulence.

Week 2: 18 Nov - 22 Nov

This week I ran bigger simulations for both decay and forced turbulence from last week in order to be able to plot the energy spectrum and time evolution. The grid size ranged from 32 to 256, and runs over 30 seconds. All simulations left the parameters in `athinput.turb` unchanged.

Calculated the turnover time $\tau \sim L/u_l$ of eddies on the scale of the box to get an idea of the timescales involved in the energy cascade. This is important in the decaying case as all the input energy dissipates within a few turnover times, so this allowed me to get an approximate time range to average the energy spectrum over. For the decay simulations I used $L = 1$ and $u_L = \sqrt{u_x^2 + u_y^2 + u_z^2}$ taken at the start of the simulation; for the continuous simulations the average turnover time in the saturated state was used. The data was gotten from the `Turb.hst` file.

Continuous Forcing: For the continuously forced case, the 256 grid size gave the best result. This is expected as it is able to simulate smaller scale eddies compared to lower resolution simulations, allowing more of the energy cascade to be observed. We see that the energy spectrum does follow the $k^{-5/3}$ law (shown in Fig. 2a) for a given range of wavevectors.

The energy evolution (Fig. 2b) shows an increase in kinetic energy until it levels out after a few turnover times. This leveling out is due to the energy dissipation rate matching the energy input rate from the forcing. There is still some variation around the mean value, which arises from fluctuations due to turbulence.

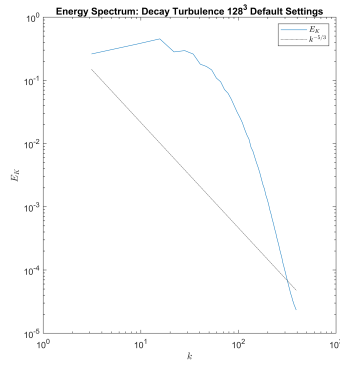


Figure 2: Plots showing the energy spectrum and time evolution of the 256 grid size continuous forcing simulation

Decay: The energy spectrum (Fig 3a), averaged over the first two turnover cycles, is not

as well defined as the continuous case. I think this is because the energy depends on time instead of being approximately constant. The energy evolution (Fig. 3b) shows that the total kinetic energy decreases over time due to dissipation from viscosity.

For the spectrum evolution (Figure 3c) I took snapshots of the spectrum at 3 second intervals, with a snapshot at 0.1 seconds to observe the energy input (the curve sharply peaked at $k \sim 10$). We see that the energy cascades down through the length scales directly after input (at 6 seconds), and then decreases as it is dissipated as heat at the micro scale (shown by the “sinking” of the spectrum). This is expected as we saw that the total energy in Fig. 3b is decreasing.



(a) Averaged Spectrum



(b) Energy Evolution



(c) Spectrum Evolution

Figure 3: Plots showing the energy spectrum and time evolution of the 128 grid size decay simulation

The magnetic and thermal energy had no relevance to these simulations; it's just part of the MATLAB script that I forgot to remove.

I learnt that it's good to run the simulations at different resolutions starting with the lowest as it allows you to get a rough idea of what is going to happen without the expense of computing time. It also helps as you can compare with the model to see whether the configuration used is worth investigating. The higher resolutions could differ as turbulence depends strongly on all length scales in the inertial subrange, which are included in the bigger simulations, but it still helps to see what could happen.

Week 3: 25 Nov - 29 Nov

Ran the linear wave problem in Athena to observe Alfvén waves. The pressure and density of the plasma should be constant as these waves travel, which was observed in the simulation (Fig. 4). Alfvén waves have the following dispersion relationship:

$$\omega = k_{\parallel} v_A$$

where k_{\parallel} is the component of the wavevector parallel to the magnetic field and $v_A = B_0 / \sqrt{4\pi\rho}$ is the Alfvén velocity at which the waves move, where B_0 and ρ are the magnetic field strength and fluid density.

The linear wave problem has the default settings (I'm not sure about units): $\rho = 1$, $\mathbf{B}_0 = (1, \sqrt{2}, 0.5) \Rightarrow B_0 = \sqrt{13}/2$. This gives a value for the Alfvén velocity of $v_A \approx 0.5086$. The next thing to do is to see whether the wave gives us this value through the dispersion relationship above.



Figure 4: Plots of different properties of the fluid as a linear wave passes through

I wrote a small Python script to calculate and compare the simulation and theoretical Alfvén velocities. The angular frequency was calculated by measuring the (simulated) time it took for a peak of the wave to travel through the box, as it has periodic boundary conditions, and dividing this by 2π . The magnitude of the wavevector was gotten by dividing 2π by the wavelength. All quantities were eyeballed as only a quick check was needed. The result is seen in Fig. 5, showing the dispersion relationship holds in the simulation.

```
print("Alfven speed:", v_A) Alfven speed: 0.5085536181410275
print("Calculated speed:", v_pred) Calculated speed: 0.5045045045045046
print("Ratio:", v_pred / v_A) Ratio: 0.9920379808695018
```

Figure 5: Output of the Python script I wrote

Questions:

- Is \mathbf{k} automatically parallel to \mathbf{B} when the `ang_3_vert` variable is set to `True`?

No, it just rotates the axes such that \mathbf{k} is along the y-axis. Can make it parallel to \mathbf{B} through code.

- Why are the density and pressure constant for an Alfvén wave?

Because the Alfvén wave is a **shear wave** i.e. no compression at all. This means $\nabla \cdot \mathbf{u} = 0 \implies D\rho/Dt = 0$ i.e. the density is constant in time and thus so is the pressure.

- Why is a rectangle used instead of a square for the region of interest?

Just to make the numbers work out right; there is no real reason for it in this case.