

code Synch

```
-- OS Class: Project 2
--
-- Ted Timmons, tedt@pdx.edu / ted@perljam.net
```

----- Semaphore -----

behavior Semaphore

```
-- This class provides the following methods:
-- Up() ...also known as "V" or "Signal"...
--     Increment the semaphore count. Wake up a thread if
--     there are any waiting. This operation always executes
--     quickly and will not suspend the thread.
-- Down() ...also known as "P" or "Wait"...
--     Decrement the semaphore count. If the count would go
--     negative, wait for some other thread to do an Up()
--     first. Conceptually, the count will never go negative.
-- Init(initialCount)
--     Each semaphore must be initialized. Normally, you should
--     invoke this method, providing an 'initialCount' of zero.
--     If the semaphore is initialized with 0, then a Down()
--     operation before any Up() will wait for the first
--     Up(). If initialized with i, then it is as if i Up()
--     operations have been performed already.
--
-- NOTE: The user should never look at a semaphore's count since the value
-- retrieved may be out-of-date, due to other threads performing Up() or
-- Down() operations since the retrieval of the count.
```

----- Semaphore . Init -----

```
method Init (initialCount: int)
    if initialCount < 0
        FatalError ("Semaphore created with initialCount < 0")
    endIf
    count = initialCount
    waitingThreads = new List [Thread]
endMethod
```

----- Semaphore . Up -----

```
method Up ()
    var
        oldIntStat: int
        t: ptr to Thread
    oldIntStat = SetInterruptsTo (DISABLED)
    if count == 0x7fffffff
        FatalError ("Semaphore count overflowed during 'Up' operation")
    endIf
    count = count + 1
    if count <= 0
        t = waitingThreads.Remove ()
        t.status = READY
        readyList.AddToEnd (t)
    endIf
    oldIntStat = SetInterruptsTo (oldIntStat)
endMethod
```

----- Semaphore . Down -----

```
method Down ()
    var
```

```

        oldIntStat: int
        oldIntStat = SetInterruptsTo (DISABLED)
        if count == 0x80000000
            FatalError ("Semaphore count underflowed during 'Down' operation")
        endIf
        count = count - 1
        if count < 0
            waitingThreads.AddToEnd (currentThread)
            currentThread.Sleep ()
        endIf
        oldIntStat = SetInterruptsTo (oldIntStat)
    endMethod

```

```
endBehavior
```

----- Mutex -----

```
behavior Mutex
```

```

-- This class provides the following methods:
--   Lock()
--       Acquire the mutex if free, otherwise wait until the mutex is
--       free and then get it.
--   Unlock()
--       Release the mutex.  If other threads are waiting, then
--       wake up the oldest one and give it the lock.
--   Init()
--       Each mutex must be initialized.
--   IsHeldByCurrentThread()
--       Return TRUE iff the current (invoking) thread holds a lock
--       on the mutex.

```

```
----- Mutex . Init -----
```

```
-- Takes initial state of the mutex (LOCKED, UNLOCKED).
```

```
--   Init()
--       Each mutex must be initialized.
```

```
method Init ()
```

```

    if waitCount < 0
        FatalError ("Mutex created with waitCount < 0")
    endIf

    -- set up our variables:
    -- heldBy: the Thread that is holding the lock
    heldBy = null
    -- state: the lock itself
    state = UNLOCKED
    -- waitingThreads: FIFO queue of threads that are asleep, waiting for lock
    waitingThreads = new List [Thread]
    -- waitCount: the number of items on the list/queue.
    waitCount = 0

```

```
endMethod
```

```
----- Mutex . Lock -----
```

```

--   Lock()
--       Acquire the mutex if free, otherwise wait until the mutex is
--       free and then get it.

```

```
method Lock ()
```

```

    var oldIntStat: int
    -- var oldState: int

```

```

-- critical section, disable interrupts.
oldIntStat = SetInterruptsTo (DISABLED)

-- if an "if" is used here instead of "while", that will potentially cause
-- the code to wake up while the lock is held elsewhere. The "while" makes
-- sure that we loop until the lock is actually available, not simply until
-- we wake up.
while state == LOCKED
    -- print (" sleeping on lock, we don't have it (")
    -- print (currentThread.name)
    -- print (").\n")
    waitingThreads.AddToEnd (currentThread)
    waitCount = waitCount + 1
    currentThread.Sleep ()
endWhile

-- We are guaranteed to have state=UNLOCKED at this point.
-- mutex is free, so we'll acquire it.
-- print (" getting the lock for ")
-- print (currentThread.name)
-- print ("\n")

-- sanity-check/assert that we aren't locking an already-held lock
if heldBy != null
    -- print ("holding a held lock. state: ")
    -- if (state == LOCKED)
    --     print ("locked")
    -- endif
    -- print ("\n")
    FatalError ("about to hold a held lock, eep!")
endif

-- actually lock the state and indicate who it is held by
state = LOCKED
heldBy = currentThread

-- success!
oldIntStat = SetInterruptsTo (oldIntStat)
endMethod

----- Mutex . Unlock -----

method Unlock ()
    var
        oldIntStat: int
        nextThread: ptr to Thread

    oldIntStat = SetInterruptsTo (DISABLED)

    if state == UNLOCKED
        FatalError ("asked for lock to be released, but nothing was locked!")
    endif

    -- Make sure we are releasing a lock that we hold, not someone else.
    if heldBy != currentThread
        -- print ("heldby: ")
        -- print (heldBy.name)
        -- print (" .. currentThread: ")
        -- print (currentThread.name)
        -- print ("\n")
        FatalError ("thread was not locked by currentThread.")
    endif

```

```
-- print (" unlocking for ")
-- print (currentThread.name)
-- print ("\n")
-- Actually release the lock, now that we've verified everything.
state = UNLOCKED
heldBy = null
```

```
-- pull our next thread from the (lock) waiting list.
-- Don't start it, but mark it ready.
if waitCount > 0
    waitCount = waitCount - 1
    nextThread = waitingThreads.Remove()
    nextThread.status = READY
    readyList.AddToEnd (nextThread)
endIf
```

```
oldIntStat = SetInterruptsTo (oldIntStat)
```

```
endMethod
```

```
----- Mutex . IsHeldByCurrentThread -----
```

```
method IsHeldByCurrentThread () returns bool
```

```
-- is it locked? Are we holding it? Great!
if (state == LOCKED && heldBy == currentThread)
    return true
endIf
```

```
-- Not held, or at least not held by us.
return false
endMethod
```

```
endBehavior
```

```
----- Condition -----
```

```
behavior Condition
```

```
-- This class is used to implement monitors. Each monitor will have a
-- mutex lock and one or more condition variables. The lock ensures that
-- only one process at a time may execute code in the monitor. Within the
-- monitor code, a thread can execute Wait() and Signal() operations
-- on the condition variables to make sure certain condions are met.
--
```

```
-- The condition variables here implement "Mesa-style" semantics, which
-- means that in the time between a Signal() operation and the awakening
-- and execution of the corrsponding waiting thread, other threads may
-- have snuck in and run. The waiting thread should always re-check the
-- data to ensure that the condition which was signalled is still true.
--
```

```
-- This class provides the following methods:
```

```
-- Wait(mutex)
```

```
-- This method assumes the mutex has already been locked.
-- It unlocks it, and goes to sleep waiting for a signal on
-- this condition. When the signal is received, this method
-- re-awakens, re-locks the mutex, and returns.
```

```
-- Signal(mutex)
```

```
-- If there are any threads waiting on this condition, this
-- method will wake up the oldest and schedule it to run.
-- However, since this thread holds the mutex and never unlocks
-- it, the newly awakened thread will be forced to wait before
-- it can re-acquire the mutex and resume execution.
```

```

-- Broadcast(mutex)
--     This method is like Signal() except that it wakes up all
--     threads waiting on this condition, not just the next one.
-- Init()
--     Each condition must be initialized.

----- Condition . Init -----

method Init ()
    waitingThreads = new List [Thread]
endMethod

----- Condition . Wait -----

method Wait (mutex: ptr to Mutex)
    var
        oldIntStat: int
    if ! mutex.IsHeldByCurrentThread ()
        FatalError ("Attempt to wait on condition when mutex is not held")
    endIf
    oldIntStat = SetInterruptsTo (DISABLED)
    mutex.Unlock ()
    waitingThreads.AddToEnd (currentThread)
    currentThread.Sleep ()
    mutex.Lock ()
    oldIntStat = SetInterruptsTo (oldIntStat)
endMethod

----- Condition . Signal -----

method Signal (mutex: ptr to Mutex)
    var
        oldIntStat: int
        t: ptr to Thread
    if ! mutex.IsHeldByCurrentThread ()
        FatalError ("Attempt to signal a condition when mutex is not held")
    endIf
    oldIntStat = SetInterruptsTo (DISABLED)
    t = waitingThreads.Remove ()
    if t
        t.status = READY
        readyList.AddToEnd (t)
    endIf
    oldIntStat = SetInterruptsTo (oldIntStat)
endMethod

----- Condition . Broadcast -----

method Broadcast (mutex: ptr to Mutex)
    var
        oldIntStat: int
        t: ptr to Thread
    if ! mutex.IsHeldByCurrentThread ()
        FatalError ("Attempt to broadcast a condition when lock is not held")
    endIf
    oldIntStat = SetInterruptsTo (DISABLED)
    while true
        t = waitingThreads.Remove ()
        if t == null
            break
        endIf
        t.status = READY
        readyList.AddToEnd (t)
    end

```

```
        endWhile  
        oldIntStat = SetInterruptsTo (oldIntStat)  
    endMethod
```

```
endBehavior
```

```
endCode
```

header Synch

uses Thread

```
class Semaphore
  superclass Object
  fields
    count: int
    waitingThreads: List [Thread]
  methods
    Init (initialCount: int)
    Down ()
    Up ()
endClass
```

```
enum UNLOCKED, LOCKED -- Mutex status
class Mutex
  superclass Object
  fields
    state: int
    heldBy: ptr to Thread
    waitingThreads: List [Thread]
    waitCount: int
  methods
    Init ()
    Lock ()
    Unlock ()
    IsHeldByCurrentThread () returns bool
endClass
```

```
class Condition
  superclass Object
  fields
    waitingThreads: List [Thread]
  methods
    Init ()
    Wait (mutex: ptr to Mutex)
    Signal (mutex: ptr to Mutex)
    Broadcast (mutex: ptr to Mutex)
endClass
```

endHeader

```
Script started on Sun 18 Oct 2009 07:16:54 PM PDT
$ make && blitz -g os
kpl Main -unsafe
asm Main.s
lddd System.o List.o Thread.o Switch.o Synch.o Main.o Runtime.o -o os
Beginning execution...
===== KPL PROGRAM STARTING =====
Example Thread-based Programs...
Initializing Thread Scheduler...
```

-- You should see 70 lines, each consecutively numbered. --

```
LockTester-A = 1
LockTester-A = 2
LockTester-A = 3
LockTester-A = 4
LockTester-A = 5
LockTester-A = 6
LockTester-F = 7
LockTester-F = 8
LockTester-F = 9
LockTester-F = 10
LockTester-F = 11
LockTester-A = 12
LockTester-A = 13
LockTester-A = 14
LockTester-A = 15
LockTester-C = 16
LockTester-C = 17
LockTester-C = 18
LockTester-C = 19
LockTester-D = 20
LockTester-D = 21
LockTester-E = 22
LockTester-F = 23
LockTester-F = 24
LockTester-F = 25
LockTester-F = 26
LockTester-F = 27
LockTester-G = 28
LockTester-G = 29
LockTester-G = 30
LockTester-G = 31
LockTester-G = 32
LockTester-G = 33
LockTester-G = 34
LockTester-G = 35
LockTester-E = 36
LockTester-C = 37
LockTester-C = 38
LockTester-C = 39
LockTester-C = 40
LockTester-C = 41
LockTester-C = 42
LockTester-E = 43
LockTester-B = 44
LockTester-E = 45
LockTester-G = 46
LockTester-G = 47
LockTester-E = 48
LockTester-D = 49
LockTester-D = 50
LockTester-E = 51
```



```
LockTester-B = 52
LockTester-E = 53
LockTester-D = 54
LockTester-D = 55
LockTester-E = 56
LockTester-B = 57
LockTester-E = 58
LockTester-D = 59
LockTester-D = 60
LockTester-E = 61
LockTester-B = 62
LockTester-D = 63
LockTester-B = 64
LockTester-D = 65
LockTester-B = 66
LockTester-B = 67
LockTester-B = 68
LockTester-B = 69
LockTester-B = 70
```

```
***** A 'wait' instruction was executed and no more interrupts are scheduled... halting +
emulation! *****
```

Done! The next instruction to execute will be:

```
000EC8: 09000000      ret
Number of Disk Reads    = 0
Number of Disk Writes   = 0
Instructions Executed    = 353623
Time Spent Sleeping     = 0
    Total Elapsed Time  = 353623
$ exit
```

Script done on Sun 18 Oct 2009 07:17:07 PM PDT