BECAUSE computers cannot actually resolve all real numbers, we are justified in approximating any real (and computer-compatible) number as:

$$X = (-1)^m \left(\frac{a}{b}\right)$$
 $Y = (-1)^m \left(\frac{a}{b}\right)$
 $A = (-1)^m \left(\frac{a}{b}\right)$

Except in the (trivial) case where x or y=0, any floating-point number can be resolved as a ratio of positive integers and a (-1), when needed. For example:

Using exponent rules, the real number exponent operation can be decomposed as follows:

S=
$$[(-0)^n 6]$$

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$$S = [($$

Beginning with the first of three major terms, the four permutations of m and n are:

In the trivial case that m=0 (i.e. X is positive), the entire first term works out to 1, and the result S is guaranteed to be real. If X is negative, however, there are some conditions that result in nonreal answers.

If c is even, then the -1 is flipped positive and the first term works out to 1. However, if c is odd, then the first term becomes:

In order to resolve the dth-root of -1, we first represent -1 as a complex number using de Moivre's theorem:

In polar form, a complex number is described by:

$$z = r(\cos x + i\sin x)$$

 $-1 + i0 = 1(\cos x + i\sin x)$ $(r = 1, x = \pi)$
 $-1 = 1(-1) + i0)$
 $-1 = -1$

An extension of de Moivre's theorem states that:

$$r^{1/n} \left[\cos(\frac{x+2\pi k}{n}) + i\sin(\frac{x+2\pi k}{n}) \right]$$

Complexnumbers have n nth roots, and 04k≤n-1 are used to compute each one. For our purposes, we are justified in taking the first convenient one, k=0. Using this and returning to the definitions of our particular problem:

$$T_{1d} = (-1)^{1/d} = (1)^{1/d} [\cos(\frac{\pi}{d}) + i\sin(\frac{\pi}{d})]$$

 $T_{1} = (-1)^{1/d} = \cos(\frac{\pi}{d}) + i\sin(\frac{\pi}{d})$

Cosine and sine both have very well-defined Taylor series expansions, which means T_1 can be computed easily.

To compute the second and third terms, it is useful to recognize the fact that they can be treated similarly, both being positive integers. If n = 0: $(a')^{5d}$

If
$$n = 0$$
: $(a')^{4}/(b)^{4}$

If $n = 1$: $(a')^{4}/(b)^{4}$

Therefore, there is always going to be a 1/ term to deal with. However, using the power of a quotient rule:

$$\left(-\frac{1}{a}-\right)^{C}_{d} = -\frac{1}{c}_{a}$$

Thus, both T_2 and T_3 can both be calculated the same way, and if one of them is a 1/ term, then it can be reckoned with as a final step.

The full decomposition is (ignoring a -1 exponent, as it has been shown to be a trivial step):

Ittis important to note that, because of the constraints put on a, b, c, and d (that is, that they are integers > 0), the use of the natural logarithm is legal under its particular domain.

To finally resolve T_2 (and T_3 , by extension), first the natural log must be calculated. To do so, we use Halley's method, which is an augmented form of Newton's method:

$$y_{n+1} = y_n + 2\left(\frac{x - e^{y_n}}{x + e^{y_n}}\right)$$

This will converge rather quickly, with high precision. Obviously, a method for the natural exponent is also needed, and there is a convenient power series expansion that will also converge very quickly:

What the preceding groundwork ultimately accomplishes is decomposing the real number exponent, in any possible computer-understandable form, into a set of smaller computations that are easily programmed into a computer. Every computation needed relies only on:

- Addition, subtraction, multiplication, division
- Whole number, positive exponents (repeated multiplication)
- Direct case checking (i.e. m=0, $T_1=1$)
- "infinite" series (that break on convergence)

Of course, it remains to be seen whether the efficiency of these methods are within acceptable bounds.

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