

Report on Visualization Project

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1 Introduction

2 Algorithm

2.1 Optimization

In the code (BSGD.m), we solve the following optimization problem:

$$\operatorname{argmin}_{U,V,a,b} \frac{\lambda}{2} (\|U\|^2 + \|V\|^2 + \|a\|^2 + \|b\|^2) + \sum_{(i,j) \in S} (Q_{i,j})^2$$

where $Q_{i,j} = (u_i^T v_j + a_i + b_j + \mu - Y_{i,j})$. Then,

$$\frac{\partial J}{\partial U_l} = \lambda U_l + \sum_{(i,j) \in S} 2Q_{i,j} 1_{i=l} V_j$$

We call the first term in the gradient as “norm term”, and the second term “error term”.

U_l is updated iteratively through gradient method:

$$U_l^{n+1} = U_l^n - \eta \frac{\partial J}{\partial U_l}$$

In BSGD, for each iteration, we randomly loop through all the data and update U_l with “error term” only in the loop, then after the loop, correct U_l with “norm term”. We can do V_k , a_l and b_k similarly.

2.2 Visualization

3 Implementation

3.1 Find U & V

To solve the optimization problem with Bias-SGD, we simply divide the data by 5 fold, use 4 folds as training data and 1 fold as test data to find the optimal

damping parameter λ and number of iteration. The step size η is chosen as $1e-2$ and is decreased by 10% for each iteration. From the results shown below (Fig. 1), we choose $\lambda = 25$. For $\lambda = 25$, the out-of-sample error is still decreasing at the 100th iteration (Fig. 1), however, the improvement is minimal. Therefore, we choose the number of iteration as 100.

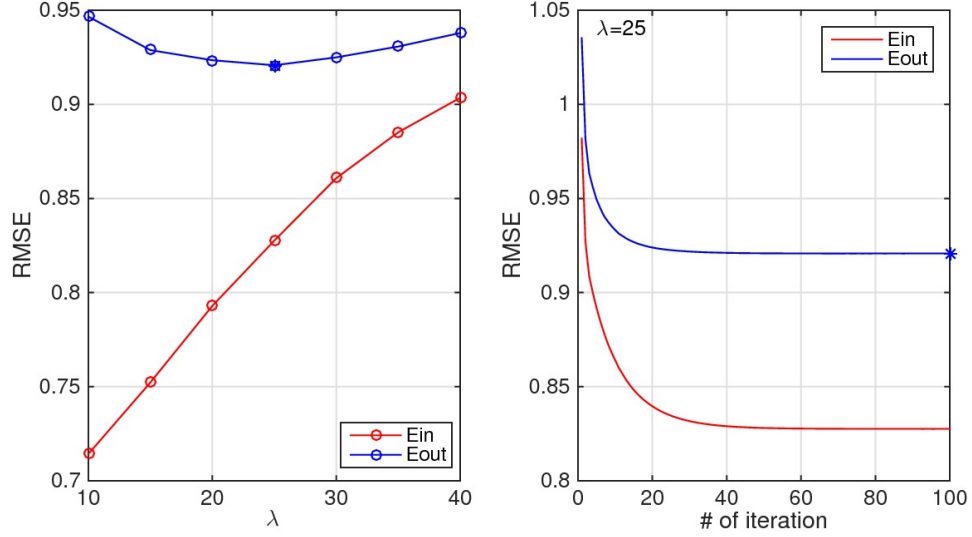


Figure 1: RMS error (RMSE) vs. Parameter. Left: For different λ , we plot the minimum RMSE in 100 iterations. We see that $\lambda = 25$ is the optimum choice. Right: For $\lambda = 25$, we plot the RMSEs in 100 iterations. We see that RMSE decays slowly after about 15 iterations. We simply choose the number of iteration as 100 for final run.

3.2 Projection