# Current-Shunt Monitors, Voltage Output, Bidirectional, Zero-Drift, Low- or High-Side Current Sensing

The NCS199A1R, NCS199A2R, and NCS199A3R are voltage output, current shunt monitors (also called current sense amplifiers) which can measure voltage across shunts at common–mode voltages from –0.3 V to 26 V, independent of supply voltage. The low offset of the zero–drift architecture enables current sensing across the shunt with maximum voltage drop as low as 10 mV full–scale. These devices can operate from a single +2.2 V to +26 V power supply, drawing a maximum of 80  $\mu A$  of supply current, and are specified over the extended operating temperature range (–40°C to +125°C). Available in the SC70–6 package.

#### **Features**

• Wide Common Mode Input Range: -0.3 V to 26 V

Supply Voltage Range: 2.2 V to 26 V
Low Offset Voltage: ±150 μV max
Low Offset Drift: 0.5 μV/°C max

• Low Gain Error: 1.5% max

• Low Gain Error Drift: 10 ppm/°C

• Rail-to-Rail Output Capability

• Low Current Consumption: 40 μA typ, 80 μA max

#### **Typical Applications**

• Current Sensing (High-Side/Low-Side)

• Telecom

Power Management

• Battery Charging and Discharging



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SC70-6 SQ SUFFIX CASE 419B

#### MARKING DIAGRAM

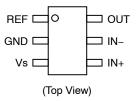


XXX = Specific Device Code M = Date Code

■ = Pb-Free Package

(Note: Microdot may be in either location)

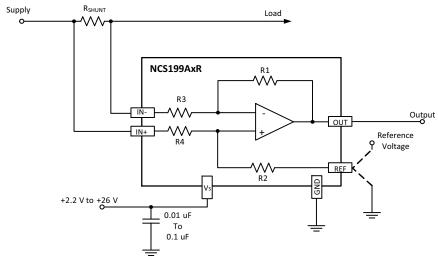
#### **PIN CONNECTIONS**



#### **ORDERING INFORMATION**

See detailed ordering, marking and shipping information on page 2 of this data sheet.

1



 $V_{OUT} = (I_{LOAD} \times R_{SHUNT})GAIN + V_{REF}$ 

#### **ORDERING INFORMATION**

Device	Gain	R3 and R4	R1 and R2	Marking	Package	Shipping <sup>†</sup>
NCS199A1RSQT2G	50	20 kΩ	1 ΜΩ	AZ3	SC70-6	3000 / Tape and Reel
NCS199A2RSQT2G	100	10 kΩ	1 ΜΩ	AZ4	SC70-6	3000 / Tape and Reel
NCS199A3RSQT2G	200	5 kΩ	1 ΜΩ	AZY	SC70-6	3000 / Tape and Reel

<sup>†</sup>For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

**Table 1. MAXIMUM RATINGS** 

F	Parameter	Symbol	Value	Unit
Supply Voltage (Note 1)		V <sub>S</sub>	+30	V
Analog Inputs Differential (V <sub>IN+</sub> )-(V <sub>IN-</sub> )		$V_{IN+,}V_{IN-}$	-30 to +30	V
	Common-Mode (Note 2)	]	(GND-0.3) to +30	
REF Input		$V_{REF}$	(GND-0.3) to (V <sub>s</sub> +0.3)	V
Output (Note 2)		V <sub>OUT</sub>	(GND-0.3) to (V <sub>s</sub> +0.3)	V
Input Current into Any Pin (Note 2)			5	mA
Maximum Junction Tempera	ature	T <sub>J(max)</sub>	+150	°C
Storage Temperature Range	)	T <sub>STG</sub>	-65 to +150	°C
ESD Capability, Human Body Model (Note 3)		НВМ	±2000	V
Charged Device Model (Note 3)		CDM	±2000	V
Latch-Up Current (Note 4)		I <sub>LU</sub>	100	mA

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

- Refer to ELECTRICAL CHĂRACTERISTICS, RECOMMENDED OPERATING RANGES and/or APPLICATION INFORMATION for safe operating parameters.
- 2. Input voltage at any pin may exceed the voltage shown if current at that pin is limited to 5 mA.
- 3. This device series incorporates ESD protection and is tested by the following methods: ESD Human Body Model tested per JEDEC standard JS-001-2017.
  - ESD Charged Device Model tested per JEDEC standard JS-002-2014.
- 4. Latch-up Current tested per JEDEC standard JESD78E.

#### **Table 2. RECOMMENDED OPERATING RANGES**

Parameter	Symbol	Min	Тур	Max	Unit
Common-Mode Input Voltage	V <sub>CM</sub>	-0.3	12	26	V
Supply Voltage	V <sub>S</sub>	2.2	5	26	V
Ambient Temperature	T <sub>A</sub>	-40		125	°C

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.

Table 3. THERMAL CHARACTERISTICS (Note 5)

	-			
Parameter		Symbol	Value	Unit
Thermal Resistance, Junction-to-Air (Note 6)	SC70-6	$R_{\theta JA}$	250	°C/W

<sup>5.</sup> Refer to ELECTRICAL CHARACTERISTICS, RECOMMENDED OPERATING RANGES and/or APPLICATION INFORMATION for safe operating parameters.

<sup>6.</sup> Values based on copper area of 645 mm<sup>2</sup> (or 1 in<sup>2</sup>) of 1 oz copper thickness and FR4 PCB substrate.

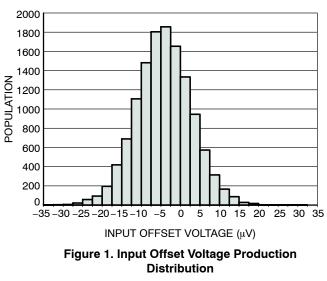
# Table 4. ELECTRICAL CHARACTERISTICS

At  $T_A = +25^{\circ}C$ ,  $V_{SENSE} = V_{IN+} - V_{IN-}$ ;  $V_S = +5$  V,  $V_{IN+} = 12$  V, and  $V_{REF} = V_S/2$ , unless otherwise noted. **Boldface** limits apply over the specified temperature range of  $T_A = -40^{\circ}C$  to  $125^{\circ}C$ , guaranteed by characterization and/or design.

NO   No   No   No   No   No   No   No	Symbol	Parameter		Test Conditions	Min	Тур	Max	Unit
CMRR   Common–Mode Rejection Ratio   V <sub>N, 1</sub> = 0 V to +26 V, V <sub>SENSE</sub> = 0 mV   T <sub>A</sub> = -40°C to 128°C   0.1   0.5   μV   V <sub>SENSE</sub> = 0 mV   100   120   0.5   μV   V <sub>SENSE</sub> = 0 mV   100   0.5   μΔ   V <sub>SENSE</sub> = 0 mV   100   0.5   0.5   V <sub>SENSE</sub> = 0 mV   100   0.5   0.5   V <sub>SENSE</sub> = 0 mV   100   0.5   0.5	INPUT					•		
Vos	V <sub>CM</sub>	Common-Mode Input Voltage Range			-0.3		26	V
Vos   Offset Voltage RTI (Note 7)	CMRR	Common-Mode Rejection Ratio		V <sub>SENSE</sub> = 0 mV	100	120		dB
PSRR   RTI vs Power Supply Ratic (Note 7)	Vos	Offset Voltage RTI (Note	7)			±5	±150	μV
No.   1	dV <sub>OS</sub> /dT	RTI vs Temperature (Note	∋ 7)	V <sub>SENSE</sub> = 0 mV T <sub>A</sub> = -40°C to +125°C		0.1	0.5	μV/°C
Input Offset Current	PSRR	RTI vs Power Supply Rat	io (Note 7)			±0.1	±10	μV/V
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	I <sub>IB</sub>	Input Bias Current		V <sub>SENSE</sub> = 0 mV		39	60	μΑ
Gain   NCS199A1R   NCS199A2R   NCS199A3R   NCS199A	I <sub>IO</sub>	Input Offset Current		V <sub>SENSE</sub> = 0 mV		±0.1		μΑ
NCS199A2R   NCS199A3R   100   200	OUTPUT							
NCS199A3R   NCS199A3R   200	G	Gain	NCS199A1R			50		V/V
			NCS199A2R	1		100	1	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			NCS199A3R			200	1	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	E <sub>G</sub>					±0.2	±1.5	%
$ \begin{array}{ c c c c c } \hline C_L & Maximum Capacitive Load & No sustained oscillation & 1 & nF \\ \hline \hline \textbf{VOLTAGE OUTPUT} \\ \hline \hline \textbf{VOH} & Swing to V_S Power Supply Rail & R_L = 10 k\Omega to GND \\ \hline \textbf{T}_A = -40^\circ C to + 125^\circ C & 0.075 & V_S - 0.2 & V \\ \hline \textbf{V}_{OL} & Swing to GND & R_L = 10 k\Omega to GND \\ \hline \textbf{T}_A = -40^\circ C to + 125^\circ C & 0.075 & V_{GND} & V_{GND} \\ \hline \textbf{FREQUENCY RESPONSE} \\ \hline \hline \textbf{BW} & Bandwidth (f_{-3dB}) & NCS199A1R & C_{LOAD} = 10 pF & 90 & kHz \\ \hline \textbf{NCS199A2R} & NCS199A3R & 0.000 & 0.000 & 0.000 \\ \hline \textbf{NCS199A3R} & 0.0000 & 0.0000 & 0.000 & 0.000 \\ \hline \textbf{NCS199A3R} & 0.00000 & 0.0000 & 0.0000 & 0.0000 \\ \hline \textbf{NOSS199A2R} & 0.00000 & 0.0000 & 0.0000 & 0.0000 \\ \hline \textbf{NOSS199A3R} & 0.0000000 & 0.00000 & 0.0000 & 0.0000 \\ \hline \textbf{NOSS2} & 0.0000000000000000000000000000000000$				$T_A = -40^{\circ}C$ to 125°C		3	10	ppm/°C
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$		Nonlinearity Error		$V_{SENSE} = -5 \text{ mV to } 5 \text{ mV}$		±0.01		%
$ \begin{array}{ c c c c c c } \hline V_{OH} & Swing to \ V_S \ Power \ Supply \ Rail & R_L = 10 \ k\Omega \ to \ GND \\ \hline T_A = -40^\circ C \ to + 125^\circ C & 0.075 & V_S - 0.2 & V \\ \hline V_{OL} & Swing to \ GND & R_L = 10 \ k\Omega \ to \ GND \\ \hline T_A = -40^\circ C \ to + 125^\circ C & V_{GND} \\ \hline T_A = -40^\circ C \ to + 125^\circ C & V_{GND} \\ \hline \hline FREQUENCY \ RESPONSE & & V_{GND} \\ \hline BW & Bandwidth \ (f_{-3dB}) & NCS199A1R & C_{LOAD} = 10 \ pF & 90 \\ \hline NCS199A2R & 0.05199A2R & 0.0000 & 0.0000 \\ \hline NCS199A3R & 0.00000 & 0.0000 & 0.0000 \\ \hline SR & Slew \ Rate & 1 & 1 & V/\mus \\ \hline \hline NOISE & & & & & & & & & & & & & & & & & & &$	C <sub>L</sub>	Maximum Capacitive Load		No sustained oscillation		1		nF
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	VOLTAGE	OUTPUT						
$ \begin{array}{ c c c c c } \hline FREQUENCY \ RESPONSE \\ \hline FREQUENCY \ RESPONSE \\ \hline BW & Bandwidth \ (f_{-3dB}) & NCS199A1R & C_{LOAD} = 10 \ pF & 90 & kHz \\ \hline NCS199A2R & 60 & 40 & 40 \\ \hline NCS199A3R & 1 & 1 & V/\mus \\ \hline NOISE \\ \hline e_n & Voltage \ Noise \ Density & f = 1 \ kHz & 45 & nV/\lambda \ T_A = -40^{\circ}C \ to +125^{\circ}C & 2.2 & 26 & V \\ \hline I_Q & Quiescent \ Current & V_{SENSE} = 0 \ mV & 40 & 80 & \mu A \\ \hline \end{array} $	V <sub>OH</sub>	Swing to V <sub>S</sub> Power Supp	ly Rail	$R_L$ = 10 kΩ to GND $T_A$ = -40°C to +125°C		V <sub>S</sub> – 0.075	V <sub>S</sub> - 0.2	V
BW       Bandwidth (f <sub>-3dB</sub> )       NCS199A1R       CLOAD = 10 pF       90       kHz         NCS199A2R       NCS199A3R       40       40         SR       Slew Rate       1       V/μs         NOISE         en       Voltage Noise Density $f = 1 \text{ kHz}$ 45       nV/ $\sqrt{\text{Hz}}$ POWER SUPPLY         V <sub>S</sub> Operating Voltage Range $T_A = -40^{\circ}\text{C to} + 125^{\circ}\text{C}$ 2.2       26       V         I <sub>Q</sub> Quiescent Current       V <sub>SENSE</sub> = 0 mV       40       80       μA	V <sub>OL</sub>	Swing to GND		$R_L$ = 10 kΩ to GND $T_A$ = -40°C to +125°C		V <sub>GND</sub> +0.005		V
NCS199A2R   NCS199A3R   60   40   40   W   W   W   W   W   W   W   W   W	FREQUEN	ICY RESPONSE					1	
NCS199A3R   A0   A0   A0   SR   Slew Rate   1   V/μs   NOISE	BW	Bandwidth (f <sub>-3dB</sub> )	NCS199A1R	C <sub>LOAD</sub> = 10 pF		90		kHz
SR Slew Rate 1 V/ $\mu$ s  NOISE  e <sub>n</sub> Voltage Noise Density f = 1 kHz 45 nV/ $\overline{Hz}$ POWER SUPPLY  V <sub>S</sub> Operating Voltage Range T <sub>A</sub> = -40°C to +125°C 2.2 26 V  I <sub>Q</sub> Quiescent Current V <sub>SENSE</sub> = 0 mV 40 80 $\mu$ A			NCS199A2R	1		60	1	
NOISEenVoltage Noise Density $f = 1 \text{ kHz}$ 45 $nV/\sqrt{\text{Hz}}$ POWER SUPPLY $V_S$ Operating Voltage Range $T_A = -40^{\circ}\text{C to} + 125^{\circ}\text{C}$ 2.226V $I_Q$ Quiescent Current $V_{SENSE} = 0 \text{ mV}$ 4080 $\mu A$			NCS199A3R	1		40	1	
e <sub>n</sub> Voltage Noise Density $f = 1 \text{ kHz}$ 45 $\text{nV}/\sqrt{\text{Hz}}$ POWER SUPPLY  V <sub>S</sub> Operating Voltage Range $T_A = -40^{\circ}\text{C to} + 125^{\circ}\text{C}$ 2.2 26 V  I <sub>Q</sub> Quiescent Current $V_{SENSE} = 0 \text{ mV}$ 40 80 $\mu A$	SR	Slew Rate				1		V/μs
POWER SUPPLY $V_S$ Operating Voltage Range $T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$ 2.2     26     V $I_Q$ Quiescent Current $V_{SENSE} = 0 \text{ mV}$ 40     80 $\mu A$	NOISE					-	-	
$V_S$ Operating Voltage Range $T_A = -40^{\circ}\text{C}$ to $+125^{\circ}\text{C}$ 2.2 26 V $I_Q$ Quiescent Current $V_{SENSE} = 0 \text{ mV}$ 40 80 μA	e <sub>n</sub>	Voltage Noise Density		f = 1 kHz		45		nV/√ <del>Hz</del>
I <sub>Q</sub> Quiescent Current V <sub>SENSE</sub> = 0 mV 40 80 μA	POWER SUPPLY							
	Vs	Operating Voltage Range		$T_A = -40^{\circ}C \text{ to } +125^{\circ}C$	2.2		26	V
Quiescent Current Over Temperature $T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$ 100 $\mu\text{A}$	IQ	Quiescent Current		V <sub>SENSE</sub> = 0 mV		40	80	μΑ
		Quiescent Current Over	Temperature	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$	+125°C		100	μΑ

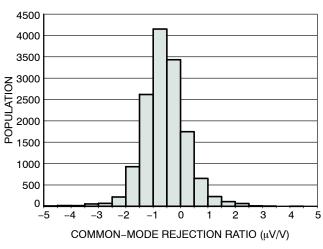
<sup>7.</sup> RTI = referenced-to-input

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.



100 80 INPUT OFFSET VOLTAGE (µV) 60 40 20 0 -20 -40 -60 -80 -100 -10 0 25 85 125 -50-40 150 TEMPERATURE (°C)

Figure 2. Input Offset Voltage vs. Temperature



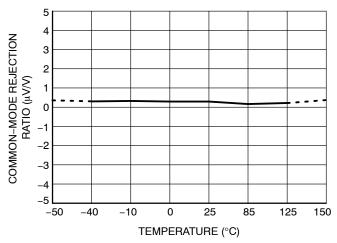
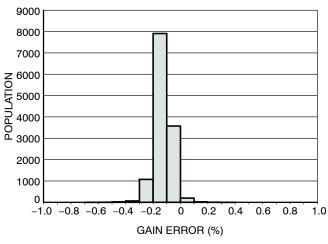


Figure 3. Common-Mode Rejection Production Distribution

Figure 4. Common-Mode Rejection Ratio vs. Temperature



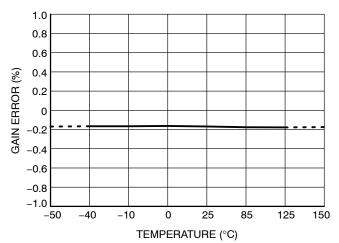


Figure 5. Gain Error Production Distribution

Figure 6. Gain Error vs. Temperature

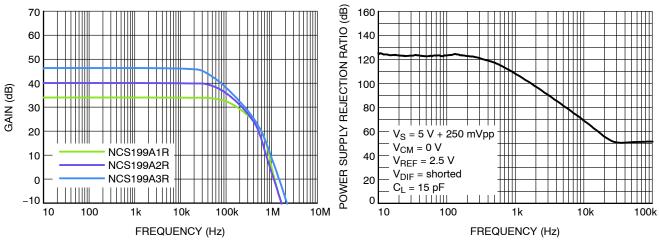


Figure 7. Gain vs. Frequency

Figure 8. Power Supply Rejection Ratio vs.
Frequency

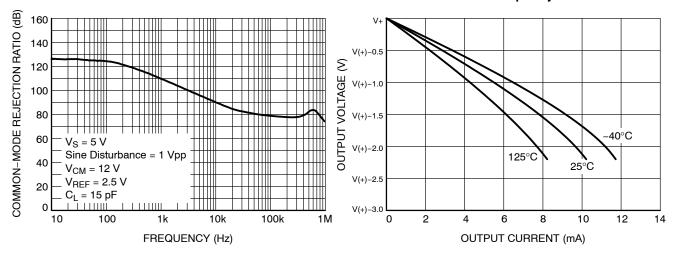


Figure 9. Common-Mode Rejection Ratio vs. Frequency

Figure 10. Positive Output Voltage Swing vs. Output Current,  $V_S = 2.2 \text{ V}$ 

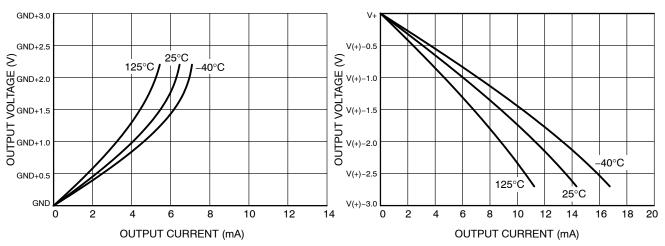


Figure 11. Negative Output Voltage Swing vs. Output Current,  $V_S = 2.2 \text{ V}$ 

Figure 12. Positive Output Voltage Swing vs. Output Current,  $V_S = 2.7 \text{ V}$ 

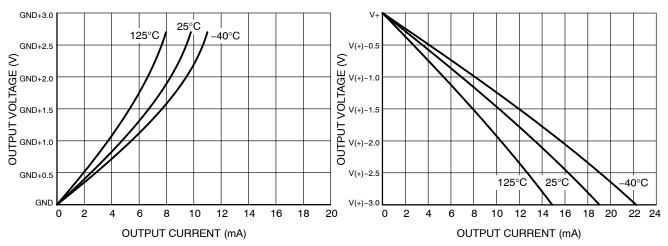


Figure 13. Negative Output Voltage Swing vs. Output Current,  $V_S = 2.7 \text{ V}$ 

Figure 14. Positive Output Voltage Swing vs. Output Current,  $V_S = 5 \text{ V}$ 

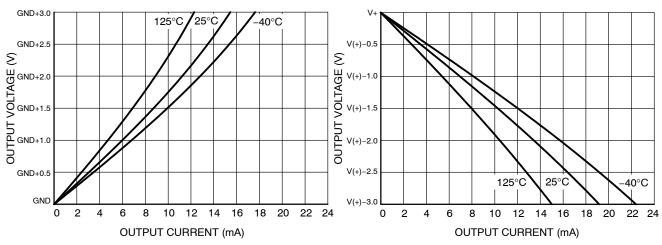


Figure 15. Negative Output Voltage Swing vs. Output Current,  $V_S = 5 \text{ V}$ 

Figure 16. Positive Output Voltage Swing vs. Output Current,  $V_S = 26 \text{ V}$ 

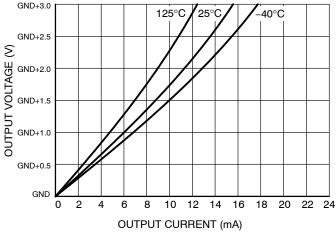


Figure 17. Negative Output Voltage Swing vs. Output Current,  $V_S = 26 \text{ V}$ 

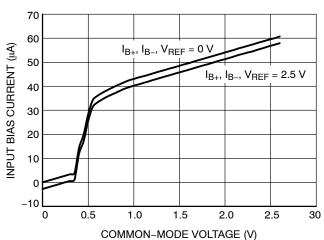
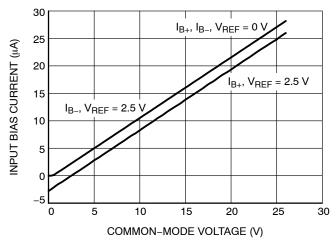


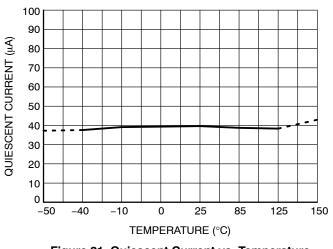
Figure 18. Input Bias Current vs. Common–Mode Voltage with  $V_S = 5 \ V$ 



40 INPUT BIAS CURRENT (µA) 35 30 25 20 15 10 5 0 -10 0 25 85 125 -40 150 TEMPERATURE (°C)

Figure 19. Input Bias Current vs. Common–Mode Voltage with  $V_S = 0 \text{ V (Shutdown)}$ 

Figure 20. Input Bias Current vs. Temperature



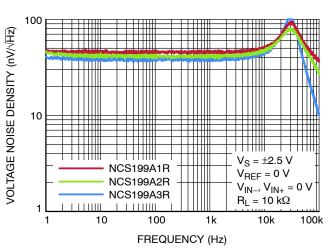


Figure 21. Quiescent Current vs. Temperature

Figure 22. Voltage Noise Density vs. Frequency

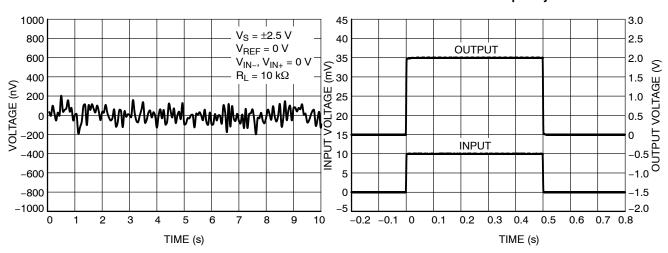


Figure 23. 0.1 Hz to 10 Hz Voltage Noise (Referred to Input)

Figure 24. Step Response (10 mVpp Input Step)

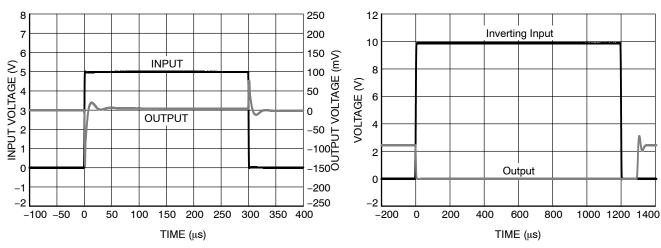


Figure 25. Common-Mode Voltage Transient Response

Figure 26. Inverting Differential Input Overload

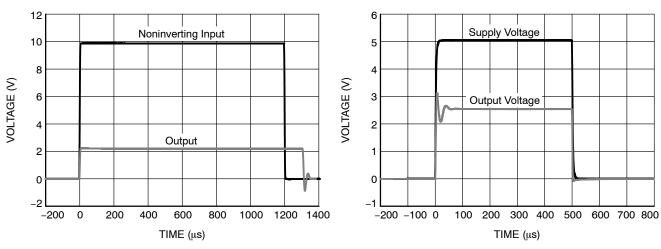


Figure 27. Noninverting Differential Input Overload

Figure 28. Start-Up Response

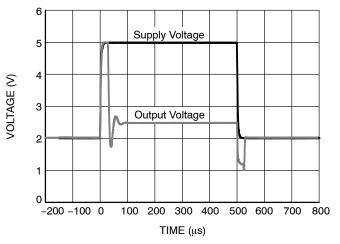


Figure 29. Brownout Recovery

#### **Basic Connections**

#### **Current Sensing Techniques**

The NCS199AxR current-sense amplifiers can be configured for both low-side and high-side current sensing. Low-side sensing appears to have the advantage of being straightforward, inexpensive, and can be implemented with a simple op amp circuit. However, the NCS199AxR series of devices provides the full differential input necessary to get accurate shunt connections, while also providing a built-in gain network with precision difficult to obtain with external resistors. While at times the application requires low-side sensing, only high-side sensing can detect a short from the positive supply line to ground. Furthermore, high-side sensing avoids adding resistance to the ground path of the load being measured. The sections below focus primarily on high-side current sensing.

#### **Unidirectional Operation**

In unidirectional current sensing, the current always flows in the same direction. Common applications for unidirectional operation include power supplies and load current monitoring. Figure 30 shows the NCS199AxR circuit implementation for unidirectional operation using high-side current sensing.

Basic connections for unidirectional operation include connecting the load power supply, connecting a current shunt to the differential inputs of the NCS199AxR, grounding the REF pin, and providing a power supply for the NCS199AxR. The NCS199AxR can be connected to the same power supply that it is monitoring current from, or it can be connected to a separate power supply. If it is necessary to detect short circuit current on the load power supply, which may cause the load power supply to sag to near zero volts, a separate power supply must be used on the NCS199AxR. When using multiple supplies, there are no restrictions on power supply sequencing.

When no current is flowing though the  $R_{SHUNT}$ , and the REF pin is connected to ground, the NCS199AxR output is expected to be within 50 mV of ground. When current is flowing through  $R_{SHUNT}$ , the output will swing positive, up to within 200 mV of the applied supply voltage,  $V_S$ .

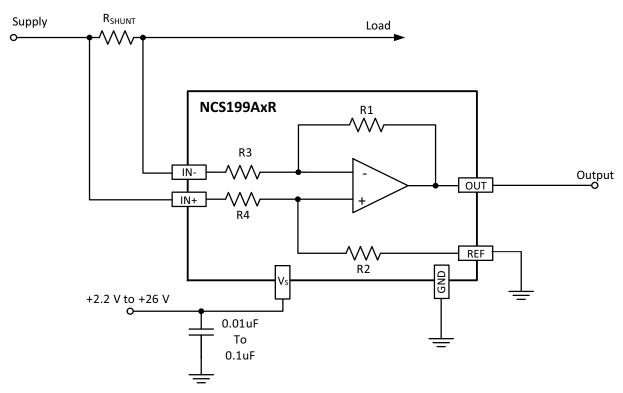


Figure 30. Basic Unidirectional Connection

#### **Bidirectional Operation**

In bidirectional current sensing, the current measurements are taken when current is flowing in both directions. For example, in fuel gauging, the current is measured when the battery is being charged or discharged. Bidirectional operation requires the output to swing both positive and negative around a bias voltage applied to the REF pin. The voltage applied to the REF pin depends on the

application. However, most often it is biased to either half of the supply voltage or to half the value of the measurement system reference. Figure 31 shows bidirectional operation with three different circuit choices that can be connected to the REF pin to provide a voltage reference to the NCS199AxR.

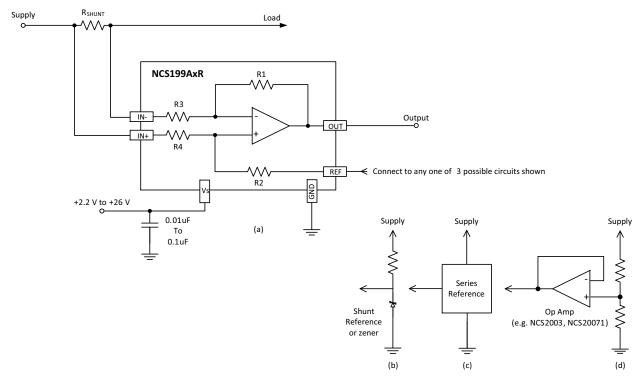


Figure 31. Bidirectional Current Sensing with Three Example Voltage Reference Circuits

The REF pin must always be connected to a low impedance circuit, such as in the Figure 31(b), (c), and (d). The REF pin can be connected directly to any voltage supply or voltage reference (shunt or series). However, if a resistor divider network is used to provide the reference voltage, a unity gain buffer circuit must be used, as shown in Figure 31(d).

In bidirectional applications, any voltage that exceeds  $V_S+0.3~V$  applied to the REF pin will forward bias an ESD diode between the REF pin and the  $V_S$  pin. Note that this exceeds the Absolute Maximum Ratings for the device.

### **Input and Output Filtering**

Filtering at the input or output may be required for several different reasons. In this section we will discuss the main considerations with regards to these filter circuits.

In some applications, the current being measured may be inherently noisy. In the case of a noisy signal, filtering after the output of the current sense amplifier is often simpler, especially where the amplifier output is fed into high impedance circuitry. The amplifier output node provides the greatest freedom when selecting components for the filter and is very straightforward to implement, although it may require subsequent buffering.

Other applications may require filtering at the input of the current sense amplifier. Figure 32 shows the recommended schematic for input filtering.

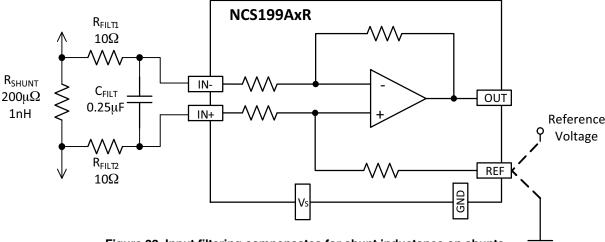


Figure 32. Input filtering compensates for shunt inductance on shunts less than 1 m $\Omega$ , as well as high frequency noise in any application

Input filtering is complicated by the fact that the added resistance of the filter resistors and the associated resistance mismatch between them can adversely affect gain, CMRR, and  $V_{OS}$ . The effect on  $V_{OS}$  is partly due to input bias currents as well. As a result, the value of the input resistors should be limited to  $10\,\Omega$  or less. Ideally, select the capacitor to exactly match the time constant of the shunt resistor and its inductance; alternatively, select the capacitor to provide a pole below that point. As an example, a filtering frequency of 100~kHz would require an 82~nF capacitor. The capacitor can have a low voltage rating, but should have good high frequency characteristics.

Make the input filter time constant equal to or larger than the shunt and its inductance time constant:

$$\frac{L_{\text{SHUNT}}}{R_{\text{SHUNT}}} \geq 2 \cdot R_{\text{FILT}} \cdot C_{\text{FILT}}$$

This simplifies to determine the value of  $C_{FILT}$  based on using 10  $\Omega$  resistors for each  $R_{FILT}$ :

$$C_{FILT} \ge \frac{L_{SHUNT}}{20R_{SHUNT}}$$

If the main purpose is to filter high frequency noise, the capacitor should be increased to a value that provides the desired filtering.

As the shunt resistors decrease in value, shunt inductance can significantly affect frequency response. At values below  $1 \text{ m}\Omega$ , the shunt inductance causes a zero in the transfer function that often results in corner frequencies in the low 100's of kHz. This inductance increases the amplitude of

high frequency spike transient events on the current sensing line that can overload the front end of any shunt current sensing IC. This problem must be solved by filtering at the input of the amplifier. Note that all current sensing IC's are vulnerable to this problem, regardless of manufacturer claims. Filtering is required at the input of the device to resolve this problem, even if the spike frequencies are above the rated bandwidth of the device.

#### Advantages When Used for Low-Side Current Sensing

The NCS199AxR series offer many advantages for low-side current sensing. The true differential input is ideal for connection to either Kelvin Sensing shunts or conventional shunts. Additionally, the true differential input rejects the common-mode noise often present even in low-side current sensing. The NCS199AxR also provides a reference pin to set the output offset from an external reference. Providing all of these features in a tiny package makes the NCS199AxR very competitive when compared to discrete op amp solutions.

#### **Designing for Input Transients Exceeding 30 Volts**

For applications that have transient common–mode voltages greater than 30 volts, external input resistors of  $10~\Omega$  provide a convenient location to add either Zener diodes or transient voltage suppression diodes (also known as TVS diodes). There are two possible configurations: one using a single TVS diode with diodes across the amplifier inputs as shown in Figure 33, and the second configuration using two TVS diodes as shown in Figure 34.

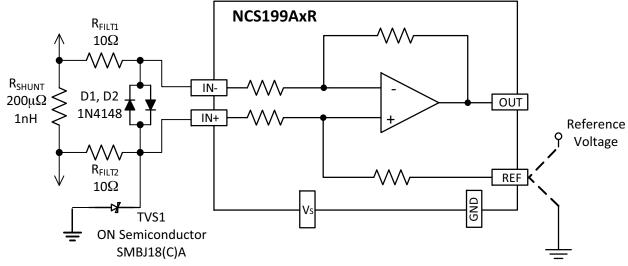


Figure 33. Single TVS transient common-mode protection

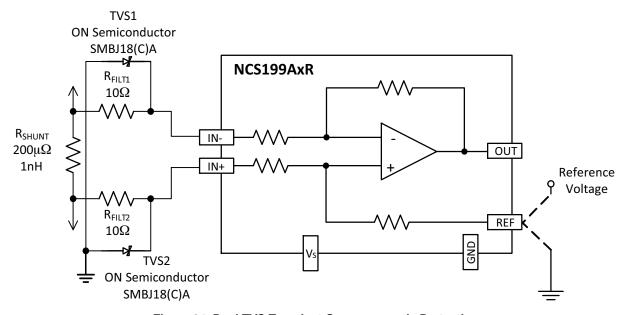


Figure 34. Dual TVS Transient Common-mode Protection

Use Zener diodes or unidirectional TVS diodes with clamping voltage ratings up to a maximum of 30 volts. Select TVS diodes with the lowest voltage rating possible for use in the system. There is a wide range between standoff voltage and maximum clamping voltage in TVS diodes. Most diodes rated at a standoff voltage of 18 V have a maximum clamping voltage of 29.2 V. Refer to the TVS data sheet and the parameters of your power supply to make the selection. In general, higher power TVS diodes demonstrate a sharper clamping knee; providing a tighter relationship between rated breakdown and maximum clamping voltage.

#### **Selecting the Shunt Resistor**

The desired accuracy of the current measurement determines the precision, shunt size, and the resistor value. The larger the resistor value, the more accurate the measurement possible, but a large resistor value also results in greater current loss.

For the most accurate measurements, use four terminal current sense resistors, as shown in Figure 35. It provides two terminals for the current path in the application circuit, and a second pair for the voltage detection path of the sense amplifier. This technique is also known as *Kelvin Sensing*. This insures that the voltage measured by the sense amplifier is the actual voltage across the resistor and does not include the small resistance of a combined connection. When using non–Kelvin shunts, follow manufacturer recommendations on how to lay out the sensing traces closely.



Figure 35. Surface Mount Kelvin Shunt

# **Current Output Configuration**

In applications where the readout boards are remotely located, the voltage output of the NCS199AxR can be converted to a precision current output. The precision output current measurements are read more accurately as it overcomes the errors due to ground drops between the boards.

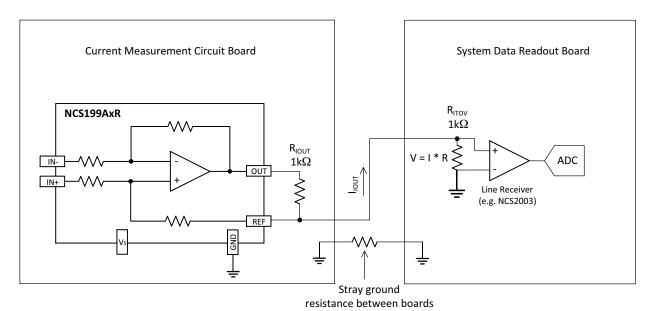


Figure 36. Remote Current Sensing

As shown in Figure 36, the R<sub>IOUT</sub> resistor is added between the OUT pin and the REF pin to convert the voltage output to a current output which is taken from the REF pin to the readout board. This circuit is intended to function with low potentials between the boards due to ground drops or noise. The current output is simply the relationship of the normal output voltage of the NCS199AxR:

$$I_{OUT} = \frac{V_{OUT}}{R_{IOUT}}$$

A resistor value of 1 k $\Omega$  for R<sub>IOUT</sub> is always a convenient value as it provides 1 mA/V scaling.

On the readout board, for simplicity,  $R_{\rm ITOV}$  can be equal to  $R_{\rm IOUT}$  to provide identical voltage drops across both. It is important to take into consideration that  $R_{\rm ITOV}$  and  $R_{\rm IOUT}$  add additional voltage drops in the current measurement path. The current source can provide enough compliance to

overcome most ground voltage drop, stray voltages, and noise. However, accuracy will degrade if noise or ground drops exceed 1 V.

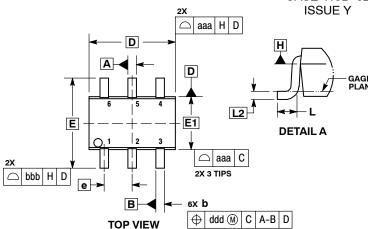
#### Shutting Down the NCS199AxR

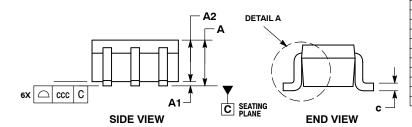
While the NCS199AxR does not provide a shutdown pin, a simple MOSFET, power switch, or logic gate can be used to switch off the power to the NCS199AxR and eliminate the quiescent current. Note that the shunt input pins will always have a current flow via the input and feedback resistors (total resistance of each leg always equals slightly higher than 1 M $\Omega$ ). Also note that when powered, the shunt input pins will exhibit the specified and well–matched typical bias current of 39  $\mu$ A. The shunt input pins support the rated common mode voltage even when the NCS199AxR does not have power applied.

#### PACKAGE DIMENSIONS

#### SC-88/SC70-6/SOT-363

CASE 419B-02



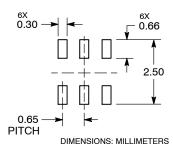


#### NOTES

- DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.
- CONTROLLING DIMENSION: MILLIMETERS.
  DIMENSIONS D AND E1 DO NOT INCLUDE MOLD FLASH,
- PROTRUSIONS, OR GATE BURRS. MOLD FLASH, PROTRUSIONS, OR GATE BURRS SHALL NOT EXCEED 0.20 PER END.
- DIMENSIONS D AND E1 AT THE OUTERMOST EXTREMES OF THE PLASTIC BODY AND DATUM H.
- DATUMS A AND B ARE DETERMINED AT DATUM H.
  DIMENSIONS 6 AND 6 APPLY TO THE FLAT SECTION OF THE
  LEAD BETWEEN 0.08 AND 0.15 FROM THE TIP.
- DIMENSION & DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.08 TOTAL IN EXCESS OF DIMENSION b AT MAXIMUM MATERIAL CONDI-TION. THE DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OF THE FOOT.

	MILLIMETERS			INCHES			
DIM	MIN	NOM	MAX	MIN	NOM	MAX	
Α			1.10			0.043	
A1	0.00		0.10	0.000		0.004	
A2	0.70	0.90	1.00	0.027	0.035	0.039	
b	0.15	0.20	0.25	0.006	0.008	0.010	
С	0.08	0.15	0.22	0.003	0.006	0.009	
D	1.80	2.00	2.20	0.070	0.078	0.086	
Е	2.00	2.10	2.20	0.078	0.082	0.086	
E1	1.15	1.25	1.35	0.045	0.049	0.053	
е	0.65 BSC			0.	.026 BS	С	
L	0.26	0.36	0.46	0.010	0.014	0.018	
L2	0.15 BSC			0.006 BSC			
aaa	0.15			0.006			
bbb	0.30			0.012			
ccc	0.10			0.004			
ddd		0.10		0.004			

#### RECOMMENDED **SOLDERING FOOTPRINT\***



\*For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

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