## Reciprocal basis

Let  $\{e_i\} \subset V$  be a basis and  $\cdot : V \times V \to \mathbb{R}$  a bilinear form.

A reciprocal basis  $\{\overline{e}_i\} \subset V$  with respect to  $\{e_i\}$  and  $\cdot$  satisfies  $e_i \cdot \overline{e}_i = \delta_{ij}$ .

The basis  $\{e_i\}$  need not be orthogonal.

## Solving for the reciprocal basis

There exists some matrix A such that  $u \cdot v = u^T A v$ .

Using matrix notation,  $E=(e_1 \cdots e_n)$  is an  $n \times n$  matrix.

Define:

$$G = E^T A E \iff G_{ij} = e_i^T A e_j = e_i \cdot e_j$$

We want to find  $\overline{E} = (\overline{e}_1 \cdots \overline{e}_n)$  so that:

$$I = E^T A \overline{E} \iff \delta_{ij} = e_i^T A \overline{e}_j = e_i \cdot \overline{e}_j$$

Solve this as  $\overline{E} = \left(E^TA\right)^{-1}I = \left(E^TAEE^{-1}\right)^{-1} = \left(GE^{-1}\right)^{-1} = EG^{-1} \Leftrightarrow \overline{e}_i = e_iG^{-1}.$ 

$$\overline{E} = EG^{-1} \Longleftrightarrow \overline{e}_k = e_k \big[ e_i \cdot e_j \big]_{ij}^{-1}$$

See [reciprocal-basis-test] for Julia example.