

CS 452 Review 4

Scheduling Algorithms

First Come First Served

Shortest Time First

Round Robin

Priority Scheduling

| Process | Arrival Time | Execute Time |
|---------|--------------|--------------|
| A | 0 | 3 |
| B | 0 | 6 |
| C | 0 | 4 |
| D | 0 | 2 |

Assignment 2

Implement a Dice Device Driver

The driver will support the read() system call

Reading a byte will return a number 1-5

```
read(dice_fd, buffer, 1) // This will read 1 byte with a value 1-5 into the buffer
```

```
read(dice_fd, buffer, 5) // This will read 5 bytes with values 1-5 into the buffer
```

```
read(dice_fd, buffer, 0) // This will do nothing
```



Printk

Printk is a linux function, not a C function, so you can use it for debugging.

```
printk(log_level, "string to print")
```

```
printk(KERN_ALERT, "you can use string interpolation with printk\n")
```

```
printk(KERN_ALERT, "Hello w%drld\n", 0)
```

Initializing a Device Driver

```
#include <linux/init.h>
```

```
#include <linux/module.h>
```

```
static int __init
```

```
your_driver_init(void){
```

```
    return 0;
```

```
}
```

```
module_init(your_driver_init);
```

Uninitializing a Device Driver

```
#include <linux/init.h>
```

```
#include <linux/module.h>
```

```
static int __exit
```

```
your_driver_exit(void){
```

```
    return 0;
```

```
}
```

```
module_init(your_driver_exit);
```

Enabling system calls for your driver

```
static const struct file_operations your_driver_fops = {  
    .owner    = THIS_MODULE,  
    .read     = your_drivers_read_function;  
}  
  
static struct miscdevice your_dev_config = {  
    MISC_DYNAMIC_MINOR,    //Dynamically assign driver number  
    "Your Device Driver's Name" //name your device creating /dev/dev_name  
    &your_driver_fops      //Struct above  
}
```

Registering Device operations

```
#include <linux/init.h>
```

```
#include <linux/module.h>
```

```
#include <linux/miscdevice.h>
```

```
static int __init
```

```
your_driver_init(void){
```

```
    return misc_register(&your_dev_config);
```

```
}
```

```
module_init(your_driver_init);
```


Deregister Device

```
#include <linux/init.h>
```

```
#include <linux/module.h>
```

```
static int __exit
```

```
your_driver_exit(void){
```

```
    return misc_deregister(&your_dev_config);
```

```
}
```

```
module_init(your_driver_exit);
```

Implementing read system call

```
static size_t your_drivers_read_function  
(struct file* fd, char* buf, size_t amount_to_read, loff_t* offset_into_file) {  
    int num_of_bytes_read = 0;  
    return num_of_bytes_read;  
}
```

```
static const struct file_operations your_driver_fops = {  
    .owner    = THIS_MODULE,  
    .read     = your_drivers_read_function;  
}
```