Ctobs- brong entropy Ophnizer = Sgd Loss = ME Lorning lote of H This cole lacks severs line of cule that I want recall correctly this case creates a function colled Everteon-distance, which copyets it important variotles from the provided data. These are Iraport-Iohhut, Pickup-Johhhut, draport-luzahib, and pulsare largetime The tunctur Sulfraits the Mirelated values from controller while also applying an exponent of 2 too each outcore. It then all s his outcome and equares the final output. This gives by a distance variotic that we can now use to product the targets & value of fare an aunt. We then begin to create the deep learning model structure this is done by adding two trides layer models and an outcome proved. I think Standard Gradient descent will provide the best results with this dator. We will we this as our ephoneer hinchism. Import panas ospl Import robots from heras pd.cow. It (NYC _toxi _ fors. LSV) drap of isnull volves def ever distance (lat1, long 1, lat2, long 2): (etum (((lot1-lot2)**2 + (long 1-long 2** 2) ** 5) If [distance] = euc_distance (df [pickup_atitude], df [pickup_lungitude] X _ Jaha = dt [distance] Alrepost = longitude] df Pickup of two Y-data = dt[Farc_ament'] -> Splitdran and fest data all mults dense layer 16 ('(EL4') all models. Jonselay or 1 ('Sigmon') optimiza = Sgd Loss = 11con Square Learning lake -1 HI This code is the some except we added additional features to the X data We also Increased the nodes in the holder layer