

ICCSwarm: Appendix

JONATHAN DILLER, Colorado School of Mines, USA

PETER HALL, Colorado School of Mines, USA

COREY SCHANKER, Colorado School of Mines, USA

KRISTEN UNG, Colorado School of Mines, USA

PHILIP BELOUS, Colorado School of Mines, USA

PETER RUSSELL, Colorado School of Mines, USA

QI HAN, Colorado School of Mines, USA

ACM Reference Format:

Jonathan Diller, Peter Hall, Corey Schanker, Kristen Ung, Philip Belous, Peter Russell, and Qi Han. 2022. *ICCSwarm: Appendix*. In *Eighth Workshop on Micro Aerial Vehicle Networks, Systems, and Applications (DroNet '22)*, July 1, 2022, Portland, OR, USA. ACM, New York, NY, USA, 4 pages. <https://doi.org/10.1145/3539493.3539579>

A FULL SIMULATION RESULTS

Table 1 shows the full simulation results on the full-scale orbits. These results show the volumes of data captured by six small data collecting satellites and returned to a single carrier satellite. Data was captured at a 20 second interval.

Table 1. Full Simulation Results

Sim. Duration (hr)	Data Collected (MB)	AODV		Single-Hop	
		Avg. Data Ret. (MB)	Std. Dev.	Avg. Data Ret. (MB)	Std Dev
24	38.87	30.88	2.68	13.43	5.16
27	43.73	39.01	0.47	12.54	5.70
30	48.59	45.69	1.05	12.77	8.69
33	53.45	50.30	0.97	8.93	3.27
36	58.31	47.78	3.41	20.95	6.73
39	63.17	55.80	0.50	20.42	6.13
42	68.03	58.60	4.56	21.01	3.88
45	72.89	65.39	4.75	17.64	3.69
48	77.75	61.50	4.85	13.69	6.62

Permission to make digital or hard copies of all or part of this work for personal or classroom use is granted without fee provided that copies are not made or distributed for profit or commercial advantage and that copies bear this notice and the full citation on the first page. Copyrights for components of this work owned by others than ACM must be honored. Abstracting with credit is permitted. To copy otherwise, or republish, to post on servers or to redistribute to lists, requires prior specific permission and/or a fee. Request permissions from permissions@acm.org.

© 2022 Association for Computing Machinery.

Manuscript submitted to ACM

B ORBIT TRANSFORMATION

To create replica orbits that can be flown by UAVs, we reduce the size of the orbits and transform them from the asteroid-centered frame of reference (as shown in Fig. 2 (a)) to the carrier-centered frame of reference, as seen in Fig. 2 (b).

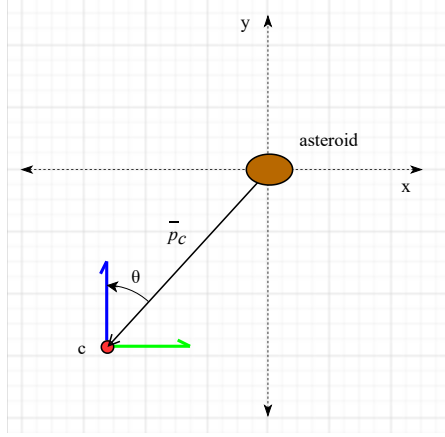


Fig. 1. Demonstration of how to find θ . The red dot is the carrier satellite and the brown object at the origin is the asteroid.

Each satellite's orbit is given as a set of x, y, z coordinates at discrete time steps. At any given time step, let \vec{p}_c be the coordinate vector for the carrier's position and \vec{p}_a and \vec{p}_s be the coordinate position vectors for the asteroid and some data collecting satellite, respectively. By definition, the asteroid sits at the origin with the carrier satellite orbiting the asteroid on the z -plane. Let θ be the angle from a unit vector at the carrier pointing in the y direction to the origin, where the asteroid sits. To transform the coordinates of the asteroid and the small satellite to the carrier's frame of reference, where the asteroid sits directly above the carrier along the y -axis, we first do a linear translation to move \vec{p}_c , \vec{p}_a and \vec{p}_s to the origin of the carrier's frame of reference then do a 3-dimensional rotation around the z -axis. Let \vec{t} be the translation to move the origin, which is defined as

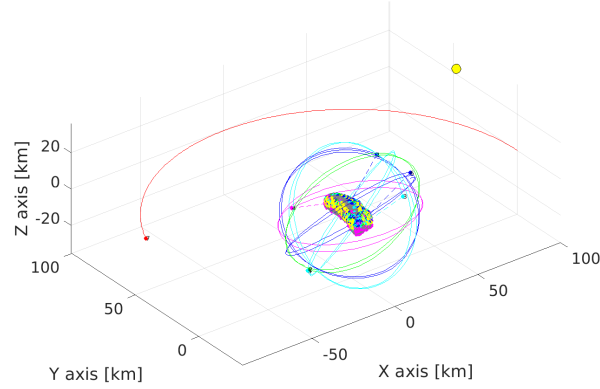
$$\vec{t} = \vec{p}_a - \vec{p}_c. \quad (1)$$

Let \mathbf{A} be the rotation matrix where

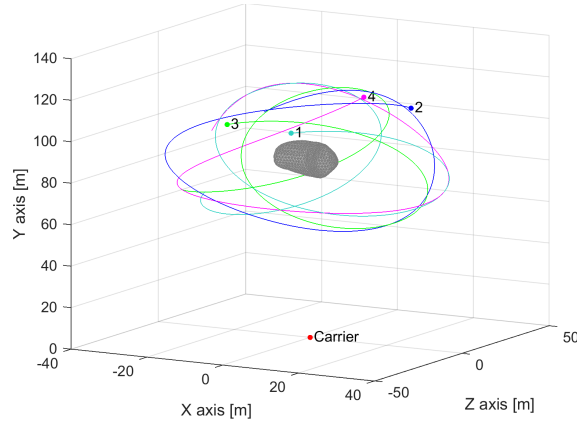
$$\mathbf{A} = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad (2)$$

To transform the asteroid's position to the carrier's frame of reference, we set the asteroid's position to

$$\vec{p}_a = \mathbf{A}(\vec{p}_a + \vec{t}) \quad (3)$$



(a) Output of orbit generator



(b) Transformed versions of the orbits.

Fig. 2. Example output from orbit generator. In (a), the larger, red orbit is the carrier satellite while the smaller, multi-colored orbits are the small satellites. Plot (b) shows the transformed versions of the orbits in (b), scaled down to a size that UAVs can travel.

We repeat this operation for the asteroid and every satellite's position at every time step in the orbit. To scale these transformed orbits down to a size that can be flown by UAVs on Earth, we found that a scaling factor of 7.9414×10^{-4} keeps the orbits below 121 m, the max allowable altitude for UAVs in the US.

C FIELD TEST RESULTS

Table 2 shows the results from both the testbed and simulation on the two orbit sets selected for field testing. Both the simulation and field-test were conducted using three small data collecting satellites and one carrier satellite. All data captured and returned is in *MB*. In the simulation, data was captured at a 20 second interval and on the physical testbed it was captured at a 50 millisecond interval. The simulations were on the original, full-size orbits while the testbed data was on the scaled-down orbits.

Table 2. Results on Field-Test Orbits

	Orbit 1						Orbit 2					
	AODV			Single-Hop			AODV			Single-Hop		
	Cap.	Ret.	% Ret.	Cap.	Ret.	% Ret.	Cap.	Ret.	% Ret.	Cap.	Ret.	% Ret.
Testbed	26.66	21.08	79.08	26.59	0.19	0.73	26.61	11.22	42.17	26.59	0	0
Sim. (116 dB)	29.16	21.44	73.55	29.16	3.56	12.21	29.16	13.38	45.88	29.16	4.67	16.03
Sim. (118 dB)	29.16	24.59	84.32	29.16	8.90	30.53	29.16	24.57	84.26	29.16	10.05	34.48