

Jonathan Ouyang

+1 669-400-6891 | jonsouyang@gmail.com | linkedin.com/in/jon-ouyang | github.com/JonOuyang

EDUCATION

University of California, Los Angeles (UCLA)
B.S. in Computer Science

Los Angeles, CA
Expected Graduation: Jun 2027

ACHIEVEMENTS

- Grand Prize Winner, 2024 Google Gemini API Developer Competition** | [Demo Video](#) Nov 2024
- Outperformed 4,500+ submissions from 45,000 developers across 119 countries, and recognized by Google executives
 - Engineered an autonomous computer agent that executes complex tasks by integrating LLM and VLM-based reasoning with real-time visual feedback for closed-loop control of applications and web environments

RESEARCH

- Stanford University, Intelligent and Interactive Autonomous Systems Group** Jan 2025 — Present
Visiting Researcher (advised by [Prof. Dorsa Sadigh](#), Stanford & Google DeepMind)
- Collaborating with Toyota Research Institute (TRI) to develop shared autonomy algorithms using zone of proximal development (ZPD), and supporting validation through CARLA Python simulation with user studies
 - Built a two-phase NMPC expert agent for parallel parking in CARLA, achieving 96% success by blending expert and user control, refined through iterative user study feedback and trajectory analysis using NumPy/Pandas

- UCLA, Robot Intelligence Lab** Sep 2024 — Present
Undergraduate Researcher (advised by [Prof. Yuchen Cui](#))
- Adapted the Action Chunking Transformer (ACT) to a custom ALOHA setup on lab hardware, achieving 90% success on bimanual manipulation by reengineering core PyTorch code for hardware compatibility and precision control
 - Fused Meta Aria glasses gaze data with LLMs for real-time intent prediction by building gaze streaming and VLM infrastructure, boosting task speed by 250%, reducing teleoperation, and enhancing robotic control in shared tasks

- San Jose State University, AI/DL FPGA/DSP Lab** Feb 2023 — Feb 2025
Graduate Research Advisor (advised by [Prof. Chang Choo](#))
- Led a 3-person team to build TensorFlow-based swimmer action recognition using CMU OpenPose and YOLOv7, improving accuracy and real-time performance by 30% via novel data augmentation; presented at IEEE SSIAI 2024
 - Co-authored a master's thesis benchmarking NVIDIA GeForce GPUs, Jetson Nano, and AMD Kria across 20+ deep learning models, demonstrating NVIDIA GPUs achieve 5% higher accuracy on average

WORK EXPERIENCE

- Amazon** Jun 2025 – Sep 2025
Software Engineer Intern
- Engineered a production-ready catalog compiler in Java to generate partner-specific outputs for Apple, Google, and Samsung, processing 7M+ titles/day and reducing manual reporting and validation for the Amazon Studios team
 - Automated metadata transformation and schema checks on AWS S3/Athena for Prime Video, removing manual QA

- Sighthound, Inc.** Jun 2024 – Sep 2024
Computer Vision Intern
- Built an internal Python tool using Hugging Face and Google VLMs (PaliGemma, OWL) to automate object detection and classification, accelerating data labeling by 50% across the annotation pipeline
 - Fixed cross-platform bugs in Python, shell scripts, and Docker for stable deployment of the redactor annotation tool

PUBLICATIONS

- T. Tay, X. Yan*, **J. Ouyang***, W. Jiang, D. Wu, J. Cao, Y. Cui, “Gaze Assisted Manipulation for Modular Autonomy (GAMMA),” Robotics: Science and Systems (RSS), 2025
- J. Ouyang**, D. Trinh and C. C. Choo, "[Optimization of Swim Pose Estimation and Recognition with Data Augmentation](#)," 2024 IEEE Southwest Symposium on Image Analysis and Interpretation (SSIAI), Santa Fe, NM, USA, 2024, pp. 101-104.