

Cubical Abstract Machine

Jon Sterling and Kuen-Bang Hou (Favonia)

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M, A	$::= a \mid \text{coe}_{x.A}^{r \rightsquigarrow r'}(M) \mid \dots$	(terms)
K	$::= \text{coe}_{\square}^{r \rightsquigarrow r'}(M) \mid \dots$	(continuations)
C	$::= M \triangleleft \mathcal{E}$	(closures)
\mathcal{E}	$::= (\emptyset, \gamma, \psi)$	(environments)
\emptyset	$::= \frac{x \hookrightarrow \vec{x}; \vec{a}.M \triangleleft \mathcal{E}}{\quad}$	(meta env.)
γ	$::= \frac{a \hookrightarrow C}{\quad}$	(object env.)
ψ	$::= \frac{x \hookrightarrow r}{\quad}$	(dimension env.)
f	$::= (K, \mathcal{E}, \Psi)$	(frames)
π	$::= \cdot \mid f :: \pi$	(stacks)
\mathcal{C}	$::= \langle M \triangleleft \mathcal{E} \parallel \pi \rangle$	(states)

Stack frames and machine states A stack frame (K, \mathcal{E}, Ψ) represents a continuation whose whole binds Ψ dimensions. For a stack π , let $\vec{\Psi}$ be the aggregation of all the dimension bindings Ψ mentioned in π ; then the extension of a stack $(K, \mathcal{E}, \Phi) :: \pi$ is wellformed when \mathcal{E} is an environment for $\mathbf{FD}(K) \setminus \vec{\Psi}$; moreover, K is allowed to mention the dimensions in $\vec{\Psi}$.

A machine state $\langle M \triangleleft \mathcal{E} \parallel \pi \rangle$, where $\vec{\Psi}$ is the aggregation of dimension bindings in π , is wellformed when \mathcal{E} is an environment for $\mathbf{FD}(M) \setminus \vec{\Psi}$; moreover, M is allowed to mention the dimensions in $\vec{\Psi}$.

Selected transition rules We define a transition judgment $\mathcal{C} \succ_{\mu} \mathcal{C}'$ with μ ranging over the following possible modes:

1. \boxtimes , denoting a cubically stable transition
2. \bullet , denoting a non-cubically stable transition

Moreover, if $\mathcal{C} \succ_{\boxtimes} \mathcal{C}'$ then $\mathcal{C} \succ_{\bullet} \mathcal{C}'$.

$$\langle a \triangleleft (\gamma, \psi) \parallel \pi \rangle \succ_{\boxtimes} \langle \gamma(a) \triangleleft (\gamma, \psi) \parallel \pi \rangle \quad (1)$$

$$\langle M(N) \triangleleft \mathcal{E} \parallel \pi \rangle \succ_{\boxtimes} \langle M \triangleleft \mathcal{E} \parallel (\square(N), \mathcal{E}, [] :: \pi) \rangle \quad (2)$$

$$\langle \lambda a. M \triangleleft \mathcal{E} \parallel (\square(N), \mathcal{E}', [] :: \pi) \rangle \succ_{\boxtimes} \langle M \triangleleft [\mathcal{E}, a \hookrightarrow N \triangleleft \mathcal{E}] \parallel \pi \rangle \quad (3)$$

$$\langle \text{fst}(M) \triangleleft \mathcal{E} \parallel \pi \rangle \succ_{\boxtimes} \langle M \triangleleft \mathcal{E} \parallel (\text{fst}(\square), \mathcal{E}, [] :: \pi) \rangle \quad (4)$$

$$\langle \text{snd}(M) \triangleleft \mathcal{E} \parallel \pi \rangle \succ_{\boxtimes} \langle M \triangleleft \mathcal{E} \parallel (\text{snd}(\square), \mathcal{E}, [] :: \pi) \rangle \quad (5)$$

$$\langle \langle M, N \rangle \triangleleft \mathcal{E} \parallel (\text{fst}(\square), \mathcal{E}', [] :: \pi) \rangle \succ_{\boxtimes} \langle M \triangleleft \mathcal{E} \parallel \pi \rangle \quad (6)$$

$$\langle \langle M, N \rangle \triangleleft \mathcal{E} \parallel (\text{snd}(\square), \mathcal{E}', [] :: \pi) \rangle \succ_{\boxtimes} \langle N \triangleleft \mathcal{E} \parallel \pi \rangle \quad (7)$$

$$\langle \text{loop}_r \triangleleft (\gamma, \psi) \parallel \pi \rangle \succ_{\boxtimes} \langle \text{base} \triangleleft (\gamma, \psi) \parallel \pi \rangle \textbf{ when } r\psi = \epsilon \quad (8)$$

$$(9)$$

$$\langle \text{coe}_{x.A}^{r \rightsquigarrow r'}(M) \triangleleft \mathcal{E} \parallel \pi \rangle \succ_{\square} \langle A \triangleleft \mathcal{E} \parallel (\text{coe}_{\square}^{r \rightsquigarrow r'}(M), \mathcal{E}', [x]) :: \pi \rangle \quad (10)$$

$$\langle \text{bool} \triangleleft \mathcal{E} \parallel (\text{coe}_{\square}^{r \rightsquigarrow r'}(M), \mathcal{E}', [x]) :: \pi \rangle \succ_{\square} \langle M \triangleleft \mathcal{E}' \parallel \pi \rangle \quad (11)$$

The rules for coercions are more difficult, but using second-order substitutions we can account for them without needing to force closures.

$$\begin{aligned} & \langle (a : A) \rightarrow B \triangleleft \mathcal{E} \parallel (\text{coe}_{\square}^{r \rightsquigarrow r'}(M), \mathcal{E}', [x]) :: \pi \rangle \succ_{\square} \langle \lambda a. \text{coe}_{x.\mathbb{X}[x;a]}^{r \rightsquigarrow r'}(M(\text{coe}_{x.\mathbb{Y}[x]}^{r' \rightsquigarrow r}(a))) \triangleleft \mathcal{E}'' \parallel \pi \rangle \\ & \textbf{where } \mathcal{E}'' = [\mathcal{E}', \mathbb{X} \hookrightarrow x; a.B \triangleleft [\mathcal{E}, a \hookrightarrow \text{coe}_{x.\mathbb{Z}[x]}^{r' \rightsquigarrow x}(a) \triangleleft [\mathcal{E}', \mathbb{Z} \hookrightarrow x.A \triangleleft \mathcal{E}]], \mathbb{Y} \hookrightarrow x.A \triangleleft \mathcal{E}] \end{aligned}$$

$$\begin{aligned} & \langle (a : A) \times B \triangleleft \mathcal{E} \parallel (\text{coe}_{\square}^{r \rightsquigarrow r'}(M), \mathcal{E}', [x]) :: \pi \rangle \succ_{\square} \langle \langle \text{coe}_{x.\mathbb{X}[x]}^{r \rightsquigarrow r'}(\text{fst}(M)), \text{coe}_{x.\mathbb{Y}[x]}^{r \rightsquigarrow r'}(\text{snd}(M)) \rangle \triangleleft \mathcal{E}'' \parallel \pi \rangle \\ & \textbf{where } \mathcal{E}'' = [\mathcal{E}', \mathbb{X} \hookrightarrow x.A \triangleleft \mathcal{E}, \mathbb{Y} \hookrightarrow x.B \triangleleft [\mathcal{E}, a \hookrightarrow \text{coe}_{y.\mathbb{X}[y]}^{r \rightsquigarrow x}(\text{snd}(M)) \triangleleft [\mathcal{E}, \mathbb{X} \hookrightarrow x.A \triangleleft \mathcal{E}]]] \end{aligned}$$

Unloading the machine We can unload the machine at any time; this is useful if we are computing an open term and hit a variable.

$$\frac{}{\langle M \triangleleft \mathcal{E} \parallel \cdot \rangle \Longrightarrow M[\mathcal{E}]} \qquad \frac{\langle K[\Psi.M[\mathcal{E}]] \triangleleft \mathcal{E}' \parallel \pi \rangle \Longrightarrow N}{\langle M \triangleleft \mathcal{E} \parallel (K[\square], \mathcal{E}', \Psi) :: \pi \rangle \Longrightarrow N}$$