

DR. PILL

Automatic Pill Dispenser

MEET THE TEAM



Jonathan Cerniaz

- Power Supply& Regulation
- Circuit Design



Jehmel Espiritu

Development of Interface

Software



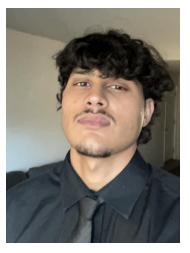
Jeremy Espiritu

Software
 Development
 of Interface



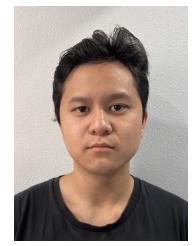
Joseph Guzman

- System prototyping and calibration
- 3D Design



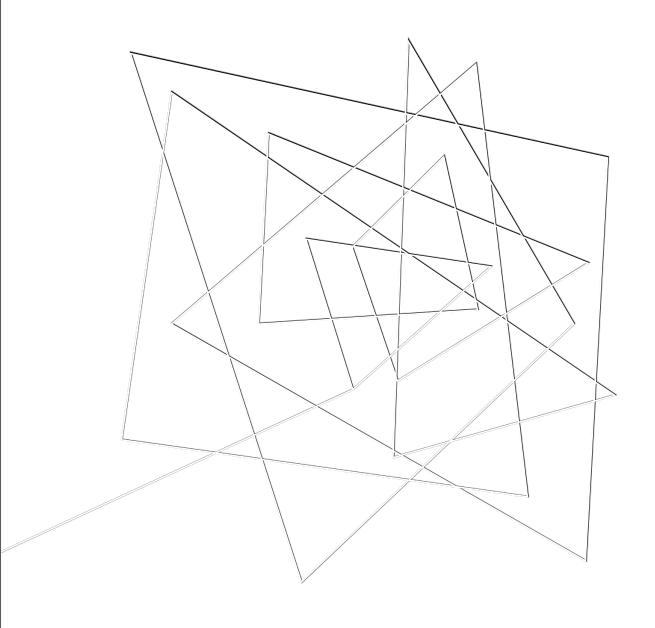
Afzal Hakim

 Log tracking and Security



Lee Roger Ordinario

- Pill Storage
 System and
 Organization
- Soldering

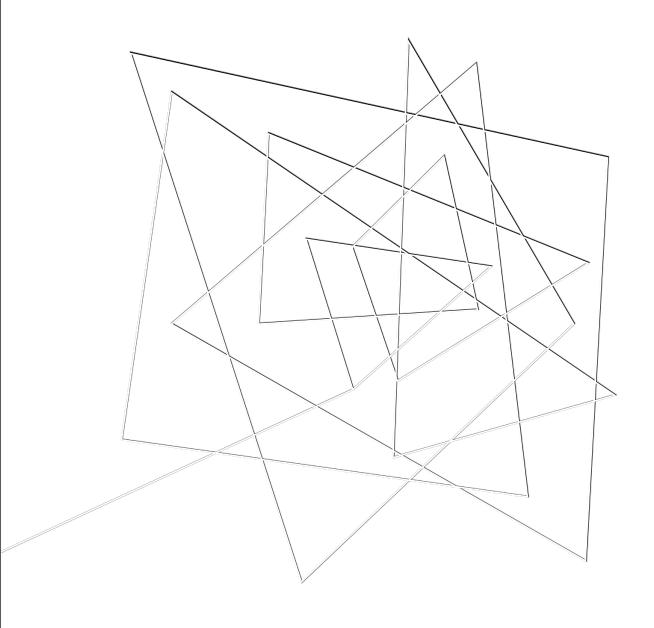


PROJECT OVERVIEW

"Our project consists of..."

- Pill Dispensing
- Touchscreen Display
- Authenticators and Cloud Database





OUR 3 DEMOS

- 1. Dispense Mechanism & Storage
 - 2. Displaying User Interface
 - 3. Authentication & Security

Final: Dr. Pill The Automatic Pill Dispenser



TODAY'S DEMO

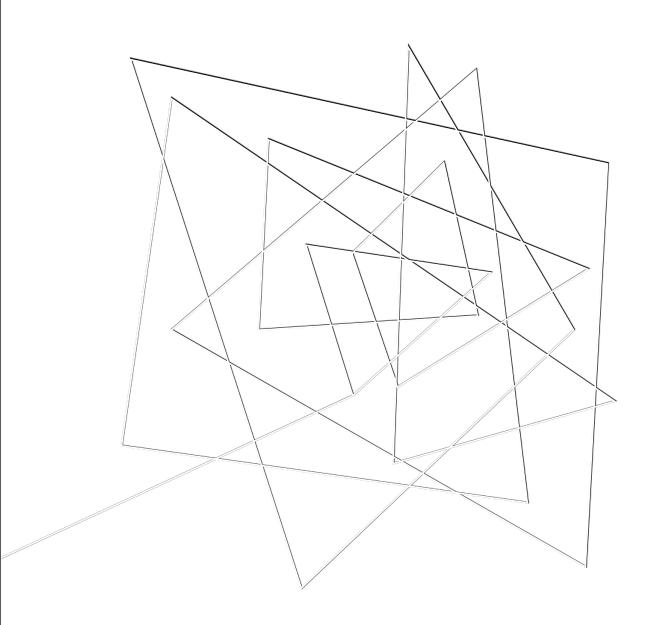
Dispense Mechanism and Storage

Requirements: Drop system, storage compartments with funnel, 2 different pills minimum, correct amount of pills dropped

Constraints: Power Consumption, Motor Accuracy, Pill Dispensing Accuracy

Success: Correct pills and amount dispensed, motor efficiently moves, storage dispenses pills smoothly





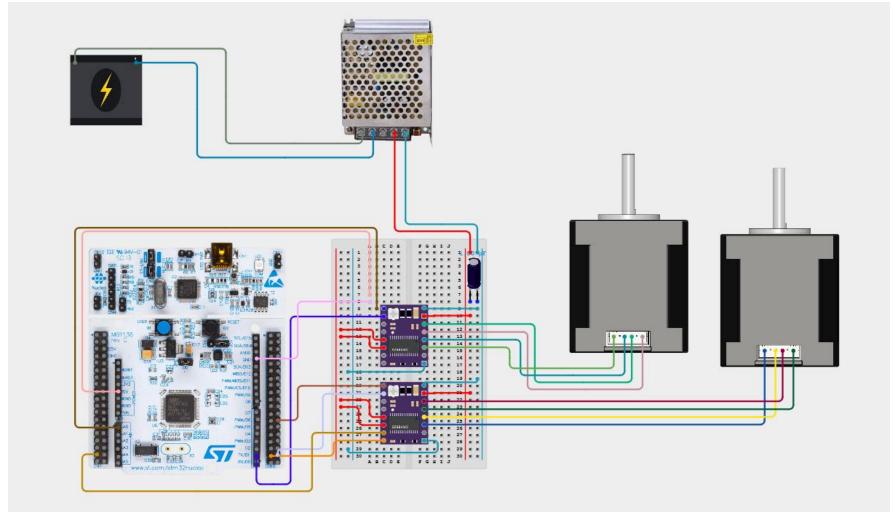
DEMO TIME

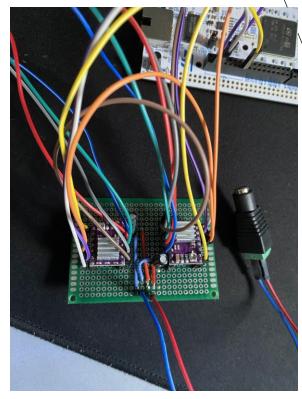
```
/* Variables for position control */
uint8_t current_position = 0;
uint8_t target_position = 0;
uint8_t direction = 0;
uint8_t rxData;
uint8_t pill_count = 0;
char user_type_prompt[] = "Choose user or staff by clicking 1 or 2: ";
char user_id_prompt[] = "Please enter your user ID: ";
char invalid_id_msg[] = "Invalid user profile. Please re-enter your user ID.\r\n";
char welcome_msg[] = "Welcome, ";
char position_prompt[] = ", what pill would you like to request? Pill 1, Pill 2, Pill 3 or Pill 4?: ";
char count_prompt[] = "Enter number of pills (1-9): ";
char newline[] = "\r\n";
```



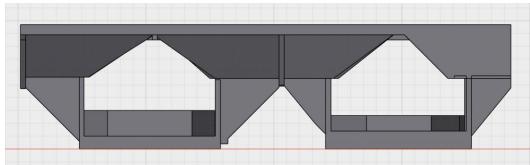
```
if (current position == 0)
                                                                          else if (target position == 2){
                                                                              direction = 1;
    if (target_position == 1){
                                                                              HAL GPIO WritePin(DIR GPIO Port, DIR Pin, direction);
        direction = 0;
                                                                              HAL_GPIO_WritePin(GPIOB, LD1_Pin, GPIO_PIN_RESET);
        HAL_GPIO_WritePin(DIR_GPIO_Port, DIR_Pin, direction);
                                                                              HAL_GPIO_WritePin(GPIOB, LD3_Pin, GPIO_PIN_SET);
        HAL_GPIO_WritePin(GPIOB, LD1_Pin, GPIO_PIN_SET);
                                                                              HAL GPIO WritePin(Enable GPIO Port, Enable Pin, GPIO PIN RESET);
        HAL_GPIO_WritePin(GPIOB, LD3_Pin, GPIO_PIN_RESET);
                                                                              HAL_TIM_PWM_Start(&htim2, TIM_CHANNEL_1);
        HAL GPIO WritePin(Enable GPIO Port, Enable Pin, GPIO PIN RESET);
                                                                              HAL_Delay(1000);
        HAL_TIM_PWM_Start(&htim2, TIM_CHANNEL_1);
                                                                              direction = 0;
        HAL Delay(1000);
                                                                              HAL_GPIO_WritePin(DIR_GPIO_Port, DIR_Pin, direction);
        direction = 1;
                                                                              HAL_GPIO_WritePin(GPIOB, LD1_Pin, GPIO_PIN_SET);
        HAL_GPIO_WritePin(DIR_GPIO_Port, DIR_Pin, direction);
                                                                              HAL GPIO WritePin(GPIOB, LD3 Pin, GPIO PIN RESET);
        HAL_GPIO WritePin(GPIOB, LD1_Pin, GPIO_PIN_RESET);
                                                                              HAL Delay(1000);
        HAL_GPIO_WritePin(GPIOB, LD3_Pin, GPIO_PIN_SET);
                                                                              HAL_TIM_PWM_Stop(&htim2, TIM_CHANNEL_1);
        HAL_Delay(1000);
                                                                              HAL_GPIO_WritePin(Enable_GPIO_Port, Enable_Pin, GPIO_PIN_SET);
        HAL TIM PWM Stop(&htim2, TIM CHANNEL 1);
        HAL_GPIO_WritePin(Enable_GPIO_Port, Enable_Pin, GPIO_PIN_SET);
```

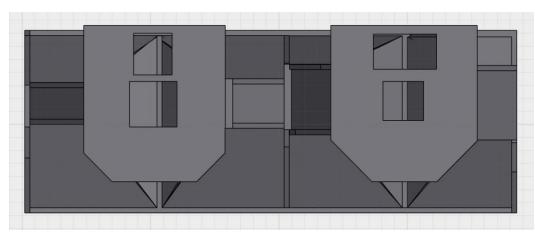






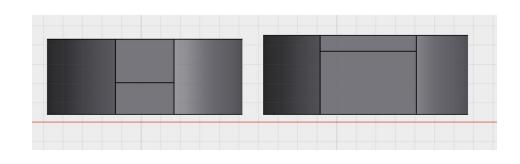


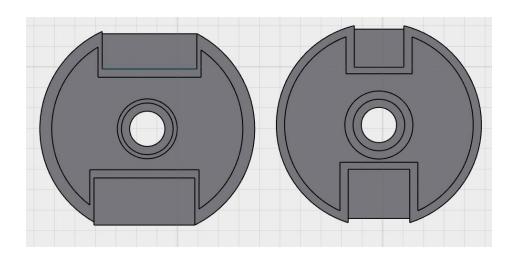


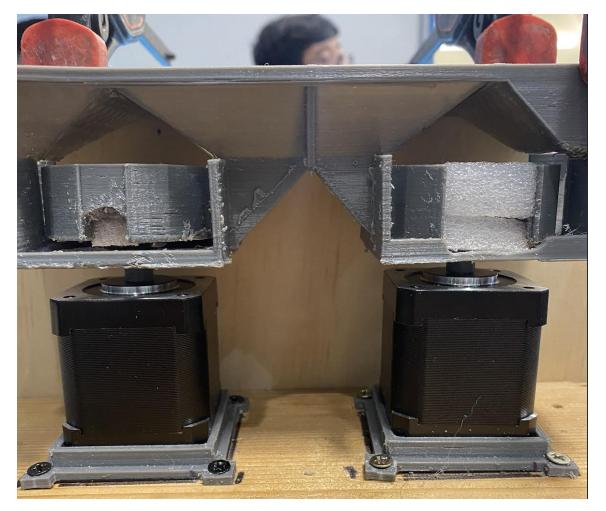








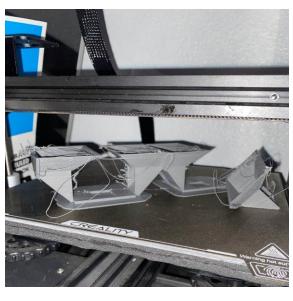






CHALLENGES

Printing time



Pocket refill



Printing Dimensions





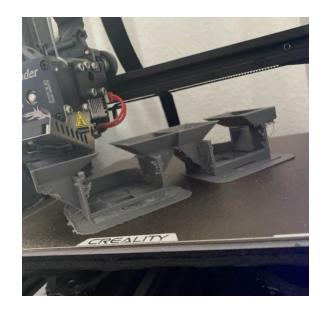
OVERCOMING CHALLENGES

Printing Time

- Redesign pocket and storage to lower material and time required without compromising the stability of the design. Simplifying the design, making it easier to recreate/expand on for later demos.

Pocket refill

- So we don't have to reprint too many times, we decided to have the funnel and pocket be open to customize based on the pill we will test. Pockets will be replaceable depending on the pill.







NEXT DEMO

DISPLAYING USER INTERFACE

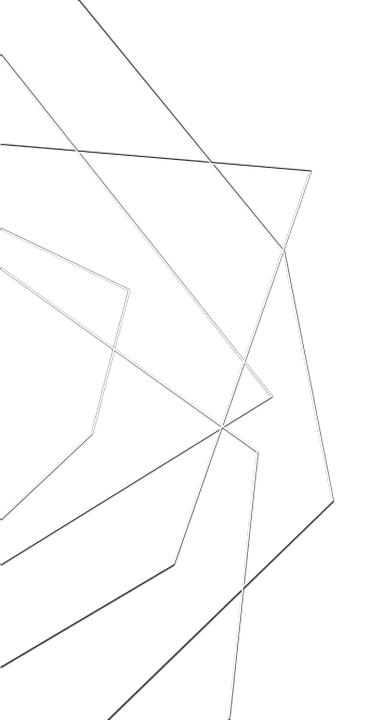
Requirements: Touchscreen LCD Display, Raspberry Pi 5

Success: Responds accurately and consistently, Terminal displays correctly on the LCD









THANK YOU

