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Homework 11

Problem 1

For a single step of convolution on an arbitary data point in an arbitrary channel, we have $k \times k$ many multiplications and $k \cdot (k-1)$ many additions, which means within a single channel, there are in total $(k^2 + k(k-1)) \cdot w \cdot h$ many calculations, and we have c channels, which gives us $(k^2 + k(k-1)) \cdot w \cdot h \cdot c$ many calculations. In $\mathcal O$ notation, the computational cost should be $\mathcal O(k^2 whc)$.

Problem 2

1

Load data set

Files already downloaded and verified Files already downloaded and verified

• Filter the data set

```
In []: class_names = ['cat', 'dog', 'ship']
    class_indices = {'cat': 0, 'dog': 1, 'ship': 2}

def filter_classes(dataset, classes):
        class_to_idx = {dataset.classes[i]: i for i in range(len(dataset.clasfiltered_indices = []
        labels = []
        for i, (_, label) in enumerate(dataset):
            if dataset.classes[label] in classes:
```

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• Remap the labels

```
In []:
    class remappedDataset(Dataset):
        def __init__(self, subset, labels):
            self.subset = subset
            self.labels = labels

    def __getitem__(self, idx):
            image, _ = self.subset[idx]
            return image, self.labels[idx]

    def __len__(self):
        return len(self.subset)

train_dataset = remappedDataset(trainset_filtered, train_labels)
test_dataset = remappedDataset(testset_filtered, test_labels)

trainloader = DataLoader(train_dataset, batch_size=4, shuffle=True, num_w
testloader = DataLoader(test_dataset, batch_size=4, shuffle=False, num_wo
```

Implement the CNN

```
In [ ]: class CNN(nn.Module):
          def __init__(self):
            super(). init ()
            self.conv1 = nn.Conv2d(3, 6, 5)
            self.conv2 = nn.Conv2d(6, 16, 5)
            self.pooling = nn.MaxPool2d(2, 2)
            self.linear1 = nn.Linear(5*5*16, 120)
            self.linear2 = nn.Linear(120, 84)
            self.linear3 = nn.Linear(84, 3)
          def forward(self, x):
            x = self.pooling(F.relu(self.conv1(x)))
            x = self.pooling(F.relu(self.conv2(x)))
            x = x.view(-1, 16 * 5 * 5)
            x = F.relu(self.linear1(x))
            x = F.relu(self.linear2(x))
            x = self.linear3(x)
            return x
        cnn = CNN()
```

• Define optimizer and loss function

```
In [ ]: loss_function = nn.CrossEntropyLoss()
    optimizer = optim.SGD(cnn.parameters(), lr=0.001, momentum=0.9)
```

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Train and Evaluate

```
In [ ]: def train_and_evaluate(cnn, trainloader, testloader, optimizer,
                                loss function, epochs=10):
          best accuracy = 0
          best model state = None
          for epoch in range(epochs):
            cnn.train()
            running loss = 0.0
            for i, data in enumerate(trainloader, 0):
              inputs, labels = data
              # print("label: %s", labels)
              optimizer.zero grad()
              outputs = cnn(inputs)
              loss = loss function(outputs, labels)
              loss.backward()
              optimizer.step()
              running loss += loss.item()
            # Evaluate on test data
            cnn.eval()
            correct = 0
            total = 0
            with torch.no grad():
              for data in testloader:
                images, labels = data
                outputs = cnn(images)
                , predicted = torch.max(outputs.data, 1)
                total += labels.size(0)
                correct += (predicted == labels).sum().item()
            test accuracy = 100 * correct / total
            print(f'Epoch {epoch + 1}, Loss: {running_loss / len(trainloader)},
                  Test Accuracy: {test accuracy}%')
            # Save the best model
            if test_accuracy > best_accuracy:
              best accuracy = test accuracy
              best model state = cnn.state dict()
          print('Training Finished')
          return best_model_state
        # Train the cnnwork and save the best model
        best model state = train and evaluate(cnn, trainloader, testloader,
                                               optimizer, loss_function)
        # Save the best model
        torch.save(best_model_state, './best_model.pth')
```

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• We can observe that the convolutional neural network performs better than the simple fully connected neural network.

2

• Shuffle the dataset

```
In [ ]: class shuffledDataset(Dataset):
            def init (self, original dataset):
                self.dataset = original dataset
                self.permutation = torch.randperm(3 * 32 * 32)
            def getitem (self, index):
                image, label = self.dataset[index]
                # Convert image to 1D tensor and apply the same permutation to al
                image 1d = image.view(-1)
                shuffled image 1d = image 1d[self.permutation]
                # Convert back to original shape
                shuffled image = shuffled image 1d.view(3, 32, 32)
                return shuffled image, label
            def len (self):
                return len(self.dataset)
        # Create shuffled datasets
        trainset shuffled = shuffledDataset(trainset filtered)
        testset_shuffled = shuffledDataset(testset_filtered)
        trainset shuffled remapped = remappedDataset(trainset shuffled, train lab
        testset shuffled remapped = remappedDataset(testset shuffled, test labels
        # DataLoader
        trainloader shuffled = DataLoader(trainset shuffled remapped, batch size=
                                          shuffle=True, num workers=2)
        testloader_shuffled = DataLoader(testset_shuffled_remapped, batch size=4,
                                         shuffle=False, num workers=2)
```

· Train with shuffled data

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loss function)

• Evaluation

We found that the performance is lot worse, because by shuffling the pixels, we distorted the shape of original object

3

• Implement fully connected layer

```
In []:
    class FCNN(nn.Module):
        def __init__(self):
            super(FCNN, self).__init__()
            # Hidden layer with d=3*32*32 and 512 neurons
            self.layer1 = nn.Linear(3 * 32 * 32, 512)
            # Output layer maps number of neurons to the output dimension
            self.layer2 = nn.Linear(512, len(class_names))

    def forward(self, x):
            x = x.view(-1, 3 * 32 * 32)
            x = F.relu(self.layer1(x))
            x = self.layer2(x)
            return x

fcnn = FCNN()
```

• Train on shuffled set

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• Evaluation

From test accuracies we noticed that the classifier is accturally randomly labeling the input, which means it cannot work properly, the reason is the same as mentioned in subtask 2