In [ ]: import numpy as np
 import matplotlib.pyplot as plt
 from scipy.optimize import minimize

## **Problem 1**

The given empirical risk function can be rewritten in its matrix form

$$egin{aligned} \hat{R}( heta) &= rac{1}{n} (\mathbf{X} heta - \mathbf{y})^2 \ &= rac{1}{n} (\mathbf{X} heta - \mathbf{y})^ op (\mathbf{X} heta - \mathbf{y}) \ &= rac{1}{n} ( heta^ op \mathbf{X}^ op \mathbf{X} heta - 2 \mathbf{y}^ op \mathbf{X} heta + \mathbf{y}^ op \mathbf{y}), \end{aligned}$$

we can compute the gradient of  $\hat{R}$  as follows

$$abla \hat{R}( heta) = rac{1}{n} (2 \mathbf{X}^ op \mathbf{X} heta - 2 \mathbf{y}^ op \mathbf{X}),$$

for the optimal heta, denoted as  $heta^*$ , the gradient should be 0, thus we have

$$2\mathbf{X}^{ op}\mathbf{X}\mathbf{ heta}^* = 2\mathbf{y}^{ op}\mathbf{X}.$$

For gradient descent, we have the following equation

$$egin{aligned} heta^{k+1} - heta^* &= heta^k - lpha 
abla \hat{R}( heta^k) - heta^* \ &= heta^k - rac{lpha}{n} (2\mathbf{X}^ op \mathbf{X} heta^k - 2\mathbf{y}^ op \mathbf{X}) - heta^*. \end{aligned}$$

According to eq. (1), we have:

$$egin{aligned} heta^{k+1} - heta^* &= heta^k - rac{lpha}{n} (2\mathbf{X}^ op \mathbf{X} heta^k - 2\mathbf{X}^ op \mathbf{X} heta^*) - heta^* \ &= \left(\mathbf{I} - rac{2lpha}{n} \mathbf{X}^ op \mathbf{X}
ight) \left( heta^k - heta^*
ight), \end{aligned}$$

so the following inequality holds:

$$\left\| heta^{k+1} - heta^* 
ight\|_2 \leq \left\| \mathbf{I} - rac{2lpha}{n} \mathbf{X}^ op \mathbf{X} 
ight\| \left\| heta^k - heta^* 
ight\|_2.$$

A good choice of  $\alpha$  should minimize the term  $\|\mathbf{I} - \frac{2\alpha}{n}\mathbf{X}^{\top}\mathbf{X}\|$ . We can justify that  $\mathbf{X}^{\top}\mathbf{X}$  is symmetric and positive definite, thus the eigenvalues and singluar values of the matrix are identical.

Now we perform singular value decomposition on  $\mathbf{X} \in \mathbb{R}^{n \times d}$ , the resulted sinlugar values are denoted by  $\mathbf{\Sigma} = [\sigma_1, \cdots, \sigma_d]$ , with which we have the singluar values of  $\mathbf{X}^{\top}\mathbf{X}$  can be intepreted as  $[\sigma_1^2, \cdots, \sigma_d^2]$ .

If we choose the optimal  $\alpha$ , the following equation holds

$$\left\|\mathbf{I} - rac{2lpha}{n}\mathbf{X}^{ op}\mathbf{X}
ight\| = \max\left(rac{2lpha}{n}\sigma_1^2 - 1, 1 - rac{2lpha}{n}\sigma_d^2
ight),$$

the right hand side is minimized by  $rac{2lpha}{n}=rac{2}{\sigma_1+\sigma_d}$  , which means, a good choice of lpha is given by

$$lpha^* = rac{n}{\sigma_1^2 + \sigma_d^2}.$$

## **Problem 2**

1

By definition, for a convex function, given  $\lambda \in (0,1)$  and 2 arbitrary points  $\mathbf{x}_1, \mathbf{x}_2 \in \mathbb{R}^n$ , the following inequality holds

$$\lambda f(\mathbf{x}_1) + (1-\lambda)f(\mathbf{x}_2) \ge f(\lambda \mathbf{x}_1 + (1-\lambda)\mathbf{x}_2).$$

For the given function, we have

$$\lambda f(\mathbf{x}_1) + (1 - \lambda)f(\mathbf{x}_2) = \lambda \|\mathbf{x}_1 - \mathbf{b}\|_2 + (1 - \lambda)\|\mathbf{x}_2 - \mathbf{b}\|_2,$$
  
 $f(\lambda \mathbf{x}_1 + (1 - \lambda)\mathbf{x}_2) = \|\lambda \mathbf{x}_1 + (1 - \lambda)\mathbf{x}_2 - \mathbf{b}\|_2.$ 

The second equation can be rewritten as

$$f(\lambda \mathbf{x}_1 + (1 - \lambda)\mathbf{x}_2) = \|\lambda \mathbf{x}_1 + (1 - \lambda)\mathbf{x}_2 - \lambda \mathbf{b} - (1 - \lambda)\mathbf{b}\|_2$$
  
=  $\|\lambda(\mathbf{x}_1 - b) + (1 - \lambda)(\mathbf{x}_2 - b)\|_2$ ,

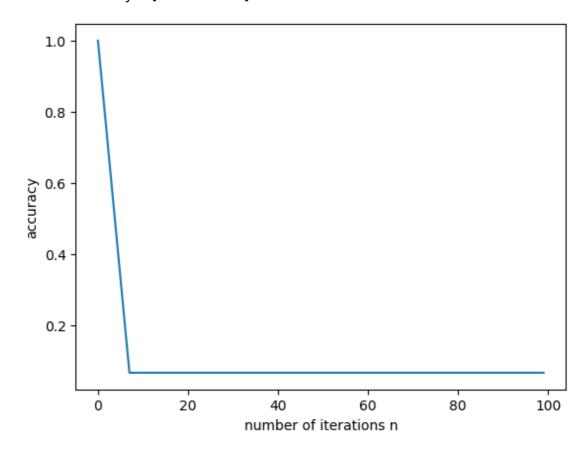
according to triangle inequality, we have

$$f(\lambda \mathbf{x}_1 + (1 - \lambda)\mathbf{x}_2) \le \|\lambda(\mathbf{x}_1 - b)\| + \|(1 - \lambda)(\mathbf{x}_2 - b)\|_2$$
  
=  $\lambda \|(\mathbf{x}_1 - b)\| + (1 - \lambda)\|(\mathbf{x}_2 - b)\|_2$   
=  $\lambda f(\mathbf{x}_1) + (1 - \lambda)f(\mathbf{x}_2)$ .

Therefore the given function is convex.

```
In [ ]: # Define the gradient of the function
        def gradient(x):
          b = np.array([4.5, 6])
          return (x - b) / np.linalg.norm(x - b, ord=2)
        # Beginning from subtask 5, we have a new gradient
        def gradient 2(x):
          b = np.array([4.5, 6])
          return 2 * (x - b)
        # Define the accuracy calculation
        def accuracy(x, x star):
          return np.linalg.norm(x star - x, ord=2) / np.linalg.norm(x sta
        r, ord=2)
        # Define the generation of x k+1
        def new_x_gen(x, alpha):
          return x - alpha * gradient(x)
        # Define the generation of x k+1 for subtask 5 and later
        def new_x_gen_2(x, alpha):
          return x - alpha * gradient_2(x)
        # Define the function
        b = np.array([4.5, 6])
        f 1 = lambda x : np.linalg.norm(x - b, ord=2)
        # Find the minimizer using scipy
        initial_guess = np.array([0, 0])
        opt result = minimize(f 1, initial guess, method='BFGS')
        x star = opt result.x
        print("optimal x:", x star)
        # Define the number of loops
        n = np.linspace(0, 99, 100)
        # Define the x array
        x 2 = np.array([[0, 0]])
        accu_2 = np.zeros([n.shape[0], 1])
        for i in range(0, n.shape[0]):
          nwe x 2 = new x gen(x 2[i, :], 1)
          x_2 = np.append(x_2, [nwe_x_2], axis=0)
          accu 2[i] = accuracy(x 2[i, :], x star)
          if accu_2[i, :] <= 0.01:
            print(i)
            break
        print("final accuracy:", min(accu 2))
        plt.plot(n, accu 2)
        plt.xlabel("number of iterations n")
        plt.ylabel("accuracy")
        plt.show()
```

optimal x: [4.5 6.] final accuracy: [0.06666667]



From the plot we can see that after few iterations, the accuracy stops decaying, which means the newly generated  $\mathbf{x}^{k+1}$  starts to oscillate around the optimal  $\mathbf{x}^*$ 

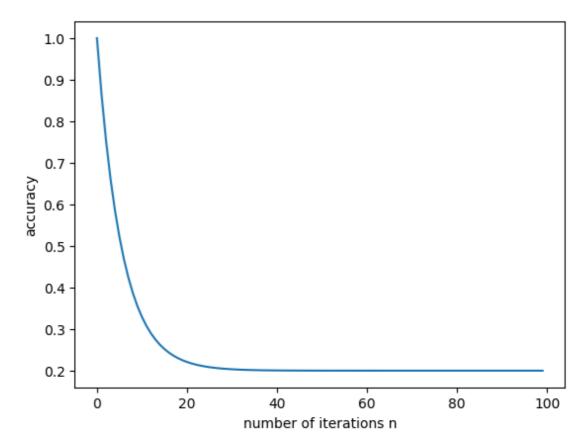
```
In []: # Define the x array
x_3 = np.array([[0, 0]])
accu_3 = np.zeros([n.shape[0], 1])

for i in range(0, n.shape[0]):
    nwe_x_3 = new_x_gen(x_3[i, :], (5/6)**i)
    x_3 = np.append(x_3, [nwe_x_3], axis=0)
    accu_3[i] = accuracy(x_3[i, :], x_star)
    if accu_3[i, :] <= 0.01:
        break

print("final accuracy:", min(accu_3))

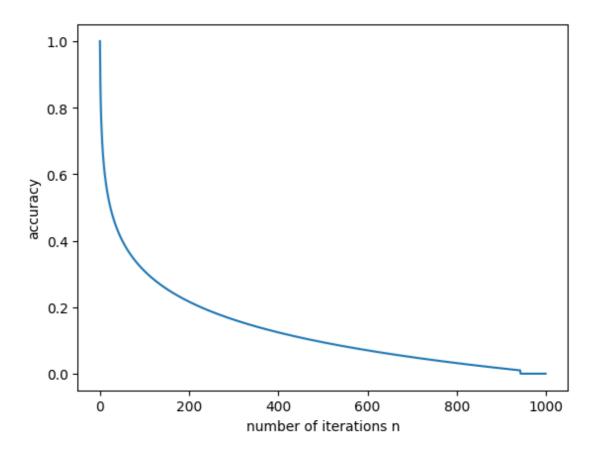
plt.plot(n, accu_3)
    plt.xlabel("number of iterations n")
    plt.ylabel("accuracy")
    plt.show()</pre>
```

final accuracy: [0.20000001]



The same happens here,  $\mathbf{x}^{k+1}$  oscillates around the optimal  $\mathbf{x}^*$  and never converge to the optimal

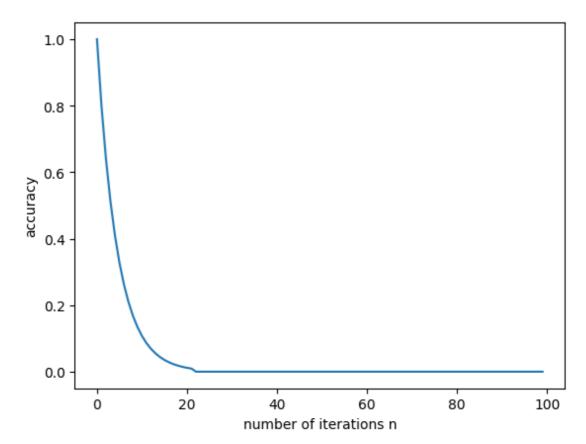
number of iterations = 942



We see that after 942 iterations the required accuracy is satisfied.

```
In []: f = 1 ambda x : (np.linalg.norm(x - b, ord=2)) ** 2
        # Find the minimizer using scipy
        initial_guess = np.array([0, 0])
        opt_result_2 = minimize(f_2, initial_guess, method='BFGS')
        x star 2 = opt result 2.x
        print("optimal solution:", x star 2)
        # Define the number of loops
        n = np.linspace(0, 99, 100)
        # Define the x array
        x 5 = np.array([[0, 0]])
        accu_5 = np.zeros([n.shape[0], 1])
        for i in range(0, n.shape[0]):
          nwe_x_5 = new_x_gen_2(x_5[i, :], 0.1)
          x_5 = np.append(x_5, [nwe_x_5], axis=0)
          accu_5[i] = accuracy(x_5[i, :], x_star_2)
          if accu 5[i, :] <= 0.01:
            print("number of iterations =", i)
            break
        plt.plot(n, accu 5)
        plt.xlabel("number of iterations n")
        plt.ylabel("accuracy")
        plt.show()
```

optimal solution: [4.4999963 6.00000296] number of iterations = 21



6

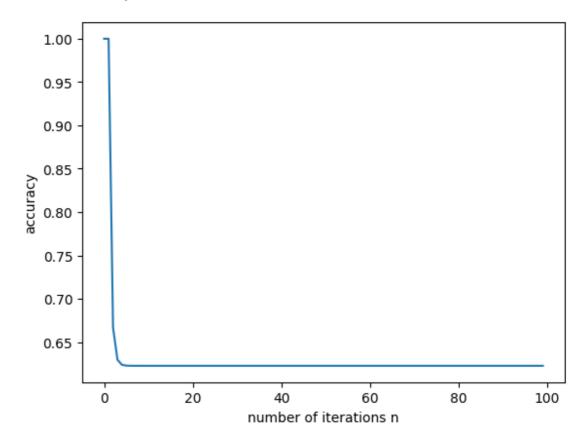
```
In [ ]: x_6 = np.array([[0, 0]])
    accu_6 = np.zeros([n.shape[0], 1])

for i in range(0, n.shape[0]):
    nwe_x_6 = new_x_gen_2(x_6[i, :], (1/6)**i)
    x_6 = np.append(x_6, [nwe_x_6], axis=0)
    accu_6[i] = accuracy(x_6[i, :], x_star_2)
    if accu_6[i, :] <= 0.01:
        print("number of iterations =", i)
        break

print("final accuracy:", min(accu_6))

plt.plot(n, accu_6)
    plt.xlabel("number of iterations n")
    plt.ylabel("accuracy")
    plt.show()</pre>
```

final accuracy: [0.62264482]



As shown, with this choice of stepsize, gradient descent will never converge to optimal

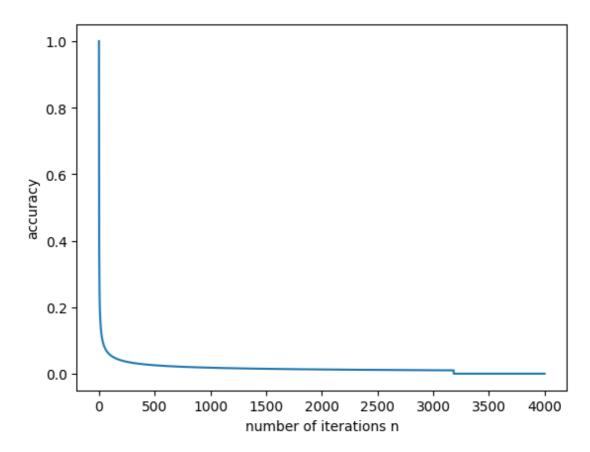
```
In []: n = np.linspace(0, 3999, 4000)

x_7 = np.array([[0, 0]])
accu_7 = np.zeros([n.shape[0], 1])

for i in range(0, n.shape[0]):
    nwe_x_7 = new_x_gen_2(x_7[i, :], (1/(4*(i+1))))
    x_7 = np.append(x_7, [nwe_x_7], axis=0)
    accu_7[i] = accuracy(x_7[i, :], x_star_2)
    if accu_7[i, :] <= 0.01:
        print("number of iterations =", i)
        break

plt.plot(n, accu_7)
    plt.xlabel("number of iterations n")
    plt.ylabel("accuracy")
    plt.show()</pre>
```

number of iterations = 3183



After 3183 iterations, the required accuracy will be achieved