Objects in data set:

|  |  |  |  |
| --- | --- | --- | --- |
| object 0: human1 | object 1: human2 | object 2: cup | object 3: milk |
| object 4: coffee | object 5: scoop | object 6: sugar | object 7: kettle |
| object 8: honig | object 9: bowl | object 10: tee bag | object 11: cereal |
| object 12: rug | object 13: glasses | object 14: pencil | object 15: notebook |
| object 16: newspaper | object 17: phone | object 18: flower | object 19: plants |
| object 20: container | object 21: shears | object 22: computer | object 23: ipad |
| object 24: place mat | object 25: bread | object 26: plate | object 27: knife |
| object 28: chopping block | object 29: apple | object 30: banana | object 31: peeler |
| ~~object 32: perfume~~ | object 33: mirror | ~~object 34: lipstick~~ | object 35: cumb |
| ~~object 36: hut~~ | ~~object 37: cloth~~ | object 38: bag | ~~object 39: keys~~ |
| object 40: toothbrush | object 41: toothpaste |  | |

Because of the noise of realsense camera, the planer object will be segmented as table plane, so those kind of objects are dropped out, remaining is:

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| --- | --- | --- | --- |
|  |  | object 2: cup | object 3: milk |
|  |  |  | object 7: kettle |
| object 8: honey | object 9: bowl |  | object 11: cereal |
|  |  |  |  |
|  |  | object 18: flower | object 19: plants |
| object 20: container |  |  |  |
|  | object 25: bread |  |  |
|  | object 29: apple | object 30: banana |  |
|  | object 33: mirror |  |  |
|  |  |  |  |
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