

## Hw1. Chapter 1

# 5, 6, 7, 8, 9, 10, 12, 13

• typo on #9  $106 = 10^6$

1.6

- @① first check for input flag FG-I
- ② if  $F_{GI} = 0$ , data is accepted by input register INPR.
- ③ upon arriving 8-bit data from teletype it is stored in input register INPR.
- ④ FG-I is periodically checked and if  $\overline{FG-I} = 1$



1.5 pg 38

37 bit CPU

16 bit bus

8 MyHz clock, 8 mil clocks a second

8 mil / 4 = 2 mil memory cycle

4 mil cycles a second

⑥ double bus width to match register size

1.6

1.7 DMA is doing actual I/O, because it is transferring data, because there is a process waiting for the I/O data.

1.8 • 9600 ips moden @ 1mil instructions per second

• we need to know bus width assume 32-bit.

$$\frac{9600}{32} = 300 \text{ cycles/s}$$

1.9 5% used for I/O transfers

$$5\% \cdot (10^6 \text{ instructions}) = 50,000 \text{ instructions per second ips}$$

1/0 25,000 words.

$$0.05 \cdot 10^6 * 5 = 250,000 \text{ memory cycles}$$

$$0.95 * 10^6 * 2 = 1,900,000 \text{ memory cycles}$$

total of 2,150,000 memory cycles

upper bound

1.10 consider the code

for ( $i=0$ ;  $i < 20$ ;  $i++$ )

for ( $j=0$ ;  $j < 10$ ;  $j++$ )

$a[i] = a[i] * j$  or  $a[i, j] = 0$

locality principle

Memory & programs tend to stay locaL

1.12  $T_c = 100 \text{ ns}$        $C_c = 0.01 \text{ cents/bit}$

$T_m = 1,200 \text{ ns}$        $C_m = 0.001 \text{ cents/bit}$

$$12 \text{ mil} \cdot 8(0.001) =$$

$$T = 110 \text{ ns} = Ht \text{ ratio } H \cdot 100 \text{ ns} + (1-H)(1200 \text{ ns} + 100 \text{ ns})$$

$$110 = 100H + 1300 - 1300H \quad | 1300 \text{ ns}$$

$$1200H = 1190$$

$$H = \frac{1190}{1200} = .991 \approx 99\%$$

1.13  $T_c = \text{time cash} = 20 \text{ ns}$        $H_c = .9$       cash

$T_m = \text{time memory} = 60 \text{ ns}$        $H_m = .6$       memory

$T_{disk} = 12 \text{ ms}$

$$T = .9(20 \text{ ns}) + .1(0.6(60) + (0.4)(12 \text{ ms} = 12,000,000 \text{ ns}))$$

$$= 18 + 4.8 + 480,000,000 \text{ ns}$$

= 480, 0.26. ns offsite access time,

1.11

8/29

Day 5 ✓

Continued from last Friday week 1

## Performance Goals of OS

- ① Provide high utilization of resources to keep costs down
- ② Should provide high availability of resources
- ③ Promote user productivity
  - Make sure user works well
- ④ Reliable
- ⑤ Provide protection for important resources.
- ⑥ Efficient
  - Operating system needs small footprint.
- ⑦ Predictable
  - Action should produce same result each time.
- ⑧ Easy to use
- ⑨ Provide system resources
  - User needs enough CPU / memory / access to I/O
  - Access & management of system resources
    - communication between programs
  - Provide device independence
    - plug & play
    - access to files
  - diagnostic facilities

Note: Core dump is the file of contents of RAM

# Types of operating systems

① Batch systems - Like a payroll application

- for Batch processing
- all data present before program is run
- no interaction while program runs
- No outputs until finished.

- Goal

- minimize turnaround time
- maximize throughput

- Current Example

- Virus Scan
- Updates

② time Sharing / interactive system

- Use time slicing to share CPU

- Goal

- minimize response time
- interaction is allowed while program is running.

③ transaction process system

- characterized by a rigid controlled dialog between user and app.

- Goal

- no incomplete transactions
- reliable response time

#### ④ hard time systems - Motor controls

- process events that occur in "real" world.
- not interactive
- built for one purpose
- Goal is to meet deadline.
- soft real time
- hard real time

#### ⑤ personal computer system

- generally one user

#### ⑥ hybrid systems

- like a blue ray player
  - allow access to Netflix
  - but also finds blue Ray / CD
- cash registers.

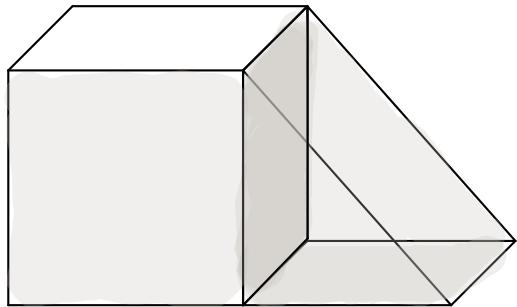
### Typical Components

- ① User Interface
- ② Process Management
- ③ CPU Scheduling
- ④ Memory Management

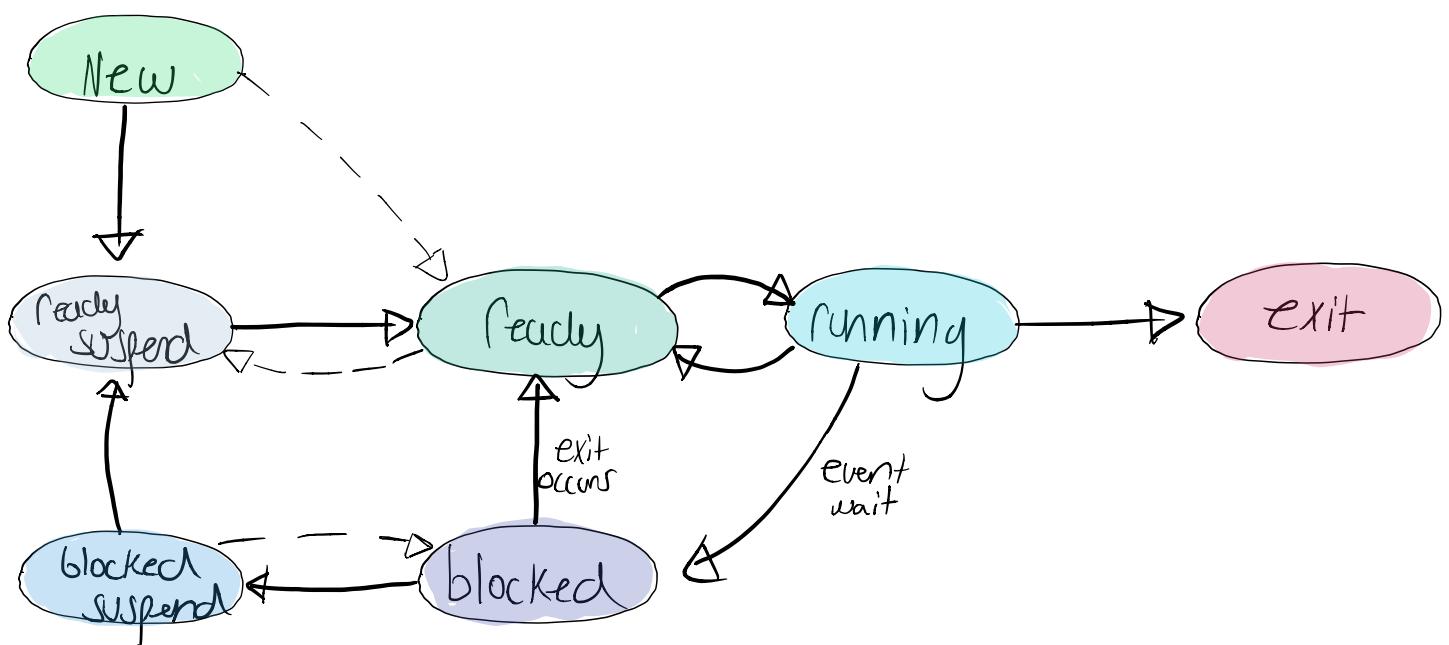
- ⑤ Secondary Storage Management
- ⑥ File Management
- ⑦ Interrupt error Management
- ⑧ Security features / Monitoring
- ⑨ Accounting - tracking information about system.
- ⑩ System Management tools

## Process Management

- Process - running program that use resources.
- State of process
  - Running
  - Ready
  - Blocked - generally waiting on I/O
  - New - loading program
  - Exit - clean up memory.



## • Process States



## • Suspend States

1. Swapping
2. OS reasons
  - process suspected of causing a problem
3. Timer - periodic processor
4. User request
5. Parent request

Process description - OS central Data Structures

- o Memory table - allocation of main memory
  - secondary storage
  - protection attributes.

o I/O tables - Manage I/O devices

o file tables - Manage files

- o PCB
  - Process control block
  - Principle data structure used by OS to manage process.

PCB contains:

- o Process name
- o Process number
- o Process state
- o Process context - CPU state
  - Used to register contents when it is not running
- o Memory use
- o Resource use
- o Process priority
  - used for scheduling
- o Relationships

- child / parent, communicating accounting information

When we create a process

- ① assign a unique process ID
  - for parent process  $ID = 1$
- ② Allocate space for process
  - process image
  - Memory allocation
- ③ PCB initialized
- ④ Linkages set
  - put in queue
- ⑤ All other data structures initialized

Process Switching

- Save context of process
- update PCB
- Move PCB to appropriate queue
- Select another process to execute.
- Update PCB of selected process
- Update Memory Management and anything else that

VS

Context Switching

- Interrupt handler returns control to same process

needs updated.

- Restore context