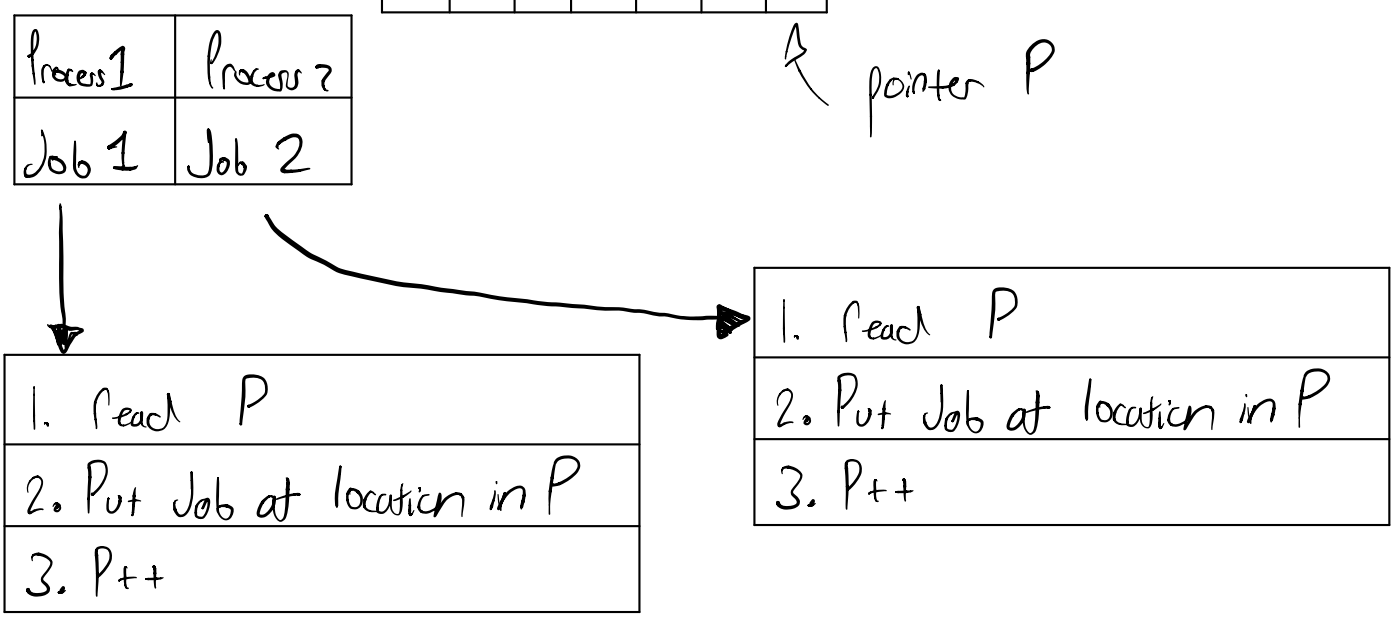
9/17/18 Day 11

PT

- Events
  - listen for programs
    - if (today == "off") {
    - if program poc.exe is "seen" close operation
    }

Mutual exclusion - Chapter 5

Suppose we have a print spooler (queue for print)



Note if a timeout occurs after reading P an error occurs where one will write over the other this happens when resources are shared

Critical section the area where we do not want to edit memory. Programs won't have infinite loops in critical sections.

How do we avoid this?

Process 1	Process 2

while true
{
while (turn == 0);
{ < Critical code >
turn = 1;
}
}
	while true
	{
	while (turn == 1);
	{ < Critical code >
	turn = 0;
	}
	}

// is this mutually exclusive.?

we cannot assume that both processes are taking the same time, so we do have mutual exclusion but we have to take turns through strict alternation.

Process 1	Process 2
while flag[1] do ; flag[0] = true ⟨critical section⟩ flag[1] = false ⋮	while flag[0] do ; flag[1] = true ⟨critical section⟩ flag[1] = false ⋮

// here both processes could grab the flag at the same time if they finish at the same time

Process 1	Process 2
1. flag[0] = true while flag[1] do ⟨critical section⟩ flag[0] = false ⋮	flag[1] = true while flag[1] do ⟨critical section⟩ flag[1] = false ⋮

// this is live lock

if after line 1 a timeout occurs we can deadlock

- Race condition - when things happen they may or may not work.
  hard to recreate.

9/19/18 Day 12

$$\int \frac{1}{e^{x^2}} = e^u \qquad u = -x^2 \qquad du = -2x\,dx \qquad \frac{du}{-2x} = dx$$

$$\frac{e^u}{-2x} = \left[\frac{e^{-x^2}}{-2x}\right]$$

$$\lim \frac{e^{-x^2}}{-2x} = \frac{1}{-2xe^{x^2}}$$

$$\frac{1}{e^{-x^2}} \cdot \frac{1}{-2x}$$

Can't apply l'hospital's

Grading criteria paper

- unified
- to the point
- Logical
- Correct in grammar
- appropiate to audience

Deadlock

- For the next test we need to be ready to read pseudo code determine if code is mutually exclusive, bound or livelock

```
# define TRUE
```

Process 0

```
while true
{ flag[0] = true
  while (flag[1])
  { if (turn=1)
    { flag[0]=false
      while (turn==1);
      flag[0]=true
    }
  }
  <critical Sect>
  turn = 1
  flag[0] = false
    :
}
```

Process 1

```
while true
{ flag[1] = true
  while (flag[0])
  { if (turn=0)
    { flag[1]=false
      while (turn==0);
      flag[1]=true
    }
  }
  <critical Sect>
  turn = 0
  flag[1] = false
    :
}
```

// this method works

// Dekker's Algorithm

Next paper
- three methods in distributed environments
- processes need to communicate to be able to control access to resources
  - Ex: token ring

P0

```
flag[0] = true
turn = 1
while(flag[1] && turn == 1) // busy wait only when both
<C.S.>                      // true can we proceed
flag[0] = false
```

⋮

Peterson's Algorithm

TODO: he is going to rearrange or cut this on the test.

HW 1 - Software solutions

#7, chapter 5 pg. 249

- works for any number of processes

- Hardware Solutions
  - disable interrupts
    - Not a good idea
  - Special instructions - Machine instruction
    - instructions cannot be interrupted

Example

Test and set instruction pseudo Code

```
boolean testset (int i)
{ if (i==0)
  { i=1
    return true;
  }
  else
    { return false; }
}
  :
int bolt;
while true
{ while (!testset(bolt)); // busy wait Lock
  Critical section
  bolt = 0;
}
```

Exchange instruction - Intel

Pseudo code

```
Void exchange (int register, int memory)
{ int temp
  tem = memory;
  memory = register;
  register = temp;
}
```

// Hw how would this work on a lock

HW