

Beeldverwerken assignment 2

Harm Manders, Jonas van Oenen 10670947

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Theory Questions

1 Convolution

Everything outside of the signal f is considered 0

1. $f * g = \{4 \underline{3} 1\}$

2. $f * g = \{0 \ 0 \ 0 \ 1 \ \underline{3} \ 4 \ 4 \ 3\}$

3. $f * g = \{0 \ 0 \ 0 \ 0 \ \underline{1} \ 0 \ 0 \ 0\}$

4. ...

5. ...

6. $\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

7. $\begin{bmatrix} 0 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

8. $\begin{bmatrix} 0 & 0 & 1 \\ \bar{0} & 0 & 0 \end{bmatrix}$

9. Not possible

10. $\frac{1}{9} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$

11. Not possible

12. Not possible

13. $\frac{1}{6} [1 \ 1 \ 1 \ 1 \ 1]$

14.
$$\begin{bmatrix} 0.0113 & 0.0149 & 0.0176 & 0.0186 & 0.0176 & 0.0149 & 0.0113 \\ 0.0149 & 0.0197 & 0.0233 & 0.0246 & 0.0233 & 0.0197 & 0.0149 \\ 0.0176 & 0.0233 & 0.0275 & 0.0290 & 0.0275 & 0.0233 & 0.0176 \\ 0.0186 & 0.0246 & 0.0290 & 0.0307 & 0.0290 & 0.0246 & 0.0186 \\ 0.0176 & 0.0233 & 0.0275 & 0.0290 & 0.0275 & 0.0233 & 0.0176 \\ 0.0149 & 0.0197 & 0.0233 & 0.0246 & 0.0233 & 0.0197 & 0.0149 \\ 0.0113 & 0.0149 & 0.0176 & 0.0186 & 0.0176 & 0.0149 & 0.0113 \end{bmatrix}$$
15. Unsharp masking is simply blurring an image and then subtracting that blurred image from the original. A kernel for a blur could be something like shown above or a gaussian. (An example of unsharp masking is provided in the matlab code)
16. $g = 1/2\{1 \ 0 \ -1\}$
17. ...
18. Not possible, since this would require more than one convolution kernel.
19. Not possible, a convolution kernel cannot specify differences between point.
20. The applied filters are shown in the matlab file.
- 21.
22. $f(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{\|x\|^2}{2\sigma^2}}$
- 23.
- 24.
- 25.
- 26.
- 27.

2 Implementation of Gaussian derivatives

This part was entirely made in matlab.

3 The Canny Edge Detector

1. $f(x, y) = A \sin(Vx) + B \cos(Wy)$
 $f'_x(x, y) = AV \cos(Vx)$
 $f'_y(x, y) = -BW \sin(Wy)$
 $f''_{xx}(x, y) = -AV \sin(Vx)$
 $f''_{yy}(x, y) = -BW \cos(Wy)$
 $f'_{xy}(x, y) = 0$