

# COMPRESSIVE SENSING WITH APPLICATIONS TO NEAR-FIELD TO FAR-FIELD ANTENNA PATTERN EXTRAPOLATION

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June 20, 2025

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# INTRODUCTION PROJECT OVERVIEW

- ▶ **Compressive Sensing (CS):** A signal processing technique for recovering sparse signals from undersampled measurements.
- ▶ **Problem Statement:** Near-field to Far-field Antenna Pattern Extrapolation.
- ▶ **Project Goal:** Apply compressive sensing methods to improve antenna measurement techniques through efficient data acquisition and accurate field reconstruction.
- ▶ **Supervisors:** Prof. Dirk Slock, Dr. Zilu Zhao, and Dr. Fangqing Xiao.

# SPARSE BAYESIAN LEARNING (SBL)

- ▶ **Core Idea:** Inducing sparsity in weight vectors through an evidence maximization over a parameterized Gaussian prior.
- ▶ **Observation Model:**  $\mathbf{t} = \Phi \mathbf{w} + \epsilon$ , where  $\epsilon \sim \mathcal{N}(0, \sigma^2 \mathbf{I})$ .
- ▶ **Prior:**  $p(\mathbf{w}; \gamma) = \prod_{i=1}^M (2\pi\gamma_i)^{-\frac{1}{2}} \exp(-\frac{w_i^2}{2\gamma_i})$ .
- ▶ Hyperparameters  $\gamma$  inferred via Type-II maximum likelihood.

# EM-BASED SBL AND ITS SCALABILITY

- ▶ **EM Algorithm:** Alternates between E-step (posterior computation) and M-step (hyperparameter update).
  - ▶ E-step:  $\Sigma_w = (\beta \Phi^\top \Phi + \text{diag}(\gamma^{-1}))^{-1}$ ,  $\mu_w = \beta \Sigma_w \Phi^\top \mathbf{t}$ .
  - ▶ M-step:  $\gamma_i = \mu_{w,i}^2 + (\Sigma_w)_{ii}$ .
- ▶ **Limitation:** High computational cost due to  $D \times D$  matrix inversion in each iteration.
- ▶ **Covariance-Free EM (CoFEM):**
  - ▶ Avoids explicit posterior covariance computation.
  - ▶ Estimates statistics using linear systems and Rademacher probe vectors.

# STEIN'S UNBIASED RISK ESTIMATE (SURE)

- ▶ **Stein's Lemma:** Relates expectation of a function of a Gaussian variable to its derivative.
- ▶ **SURE Principle:** Provides an unbiased estimator for the risk ( $\mathbb{E}\|\boldsymbol{\mu} - \hat{\boldsymbol{\mu}}\|_2^2$ ) without knowing the true mean  $\boldsymbol{\mu}$ .
- ▶ **Application:** Enables hyperparameter optimization by minimizing the SURE.

$$\hat{\lambda} = \arg \min_{\lambda \in \Lambda} \left( \|\mathbf{y} - \hat{\boldsymbol{\mu}}_{\lambda}\|_2^2 + 2\sigma^2 \sum_{i=1}^n \frac{\partial \hat{\mu}_{\lambda,i}}{\partial y_i}(\mathbf{y}) \right)$$

# SYNTHETIC DATA GENERATION

- ▶ Generated data using a standard compressive sensing model:  
 $\mathbf{t} = \Phi \mathbf{w} + \mathbf{e}.$
- ▶ Components:
  - ▶ Measurement vector  $\mathbf{t} \in \mathbb{R}^N$ .
  - ▶ Sensing matrix  $\Phi \in \mathbb{R}^{N \times D}$  (e.g., DFT matrix or Gaussian random matrix).
  - ▶ Sparse signal  $\mathbf{w} \in \mathbb{R}^D$  with user-defined sparsity  $\rho$ .
  - ▶ Additive Gaussian noise  $\mathbf{e} \sim \mathcal{N}(0, \sigma^2)$ .
- ▶ Setup allows control over  $N$ ,  $D$ ,  $\rho$ , and  $\sigma$  for reproducible evaluation.

# CHOICE OF ALGORITHM: SBL OVER AMP

- ▶ **Approximate Message Passing (AMP):** Powerful but relies heavily on i.i.d. sub-Gaussian measurement matrices.
- ▶ **Project Context:** Application to antenna pattern extrapolation involves structured, non-random measurement matrices (e.g., FFT bases).
- ▶ **Decision:** Chose EM-based SBL for its robustness and generality, making fewer assumptions about the measurement matrix.

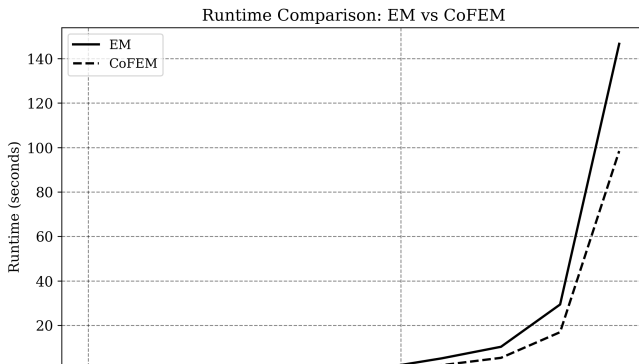


# FAST MARGINAL LIKELIHOOD ALGORITHM (TIPPING'S ALGORITHM)

- ▶ Efficient basis selection and pruning strategy for SBL.
- ▶ Optimizes hyperparameters via Type II Maximum Likelihood.
- ▶ **Iterative Process:**
  1. Initialize hyperparameters and noise variance.
  2. Compute posterior statistics.
  3. Update hyperparameters by adding, deleting, or re-estimating basis functions to maximize marginal likelihood.
  4. Iterate until convergence, guided by SURE for MSE minimization.
- ▶ Handles both real and complex-valued inputs.

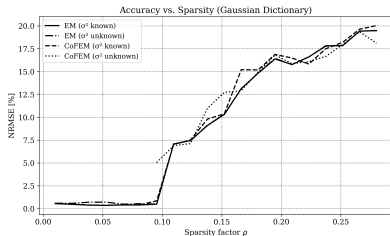
# EM vs. CoFEM RUNTIME COMPARISON

- ▶ CoFEM significantly reduces runtime compared to standard EM, especially with increasing dimensionality.
- ▶ For  $N=500$ , CoFEM achieved 98.4 seconds vs. EM's 146.6 seconds.

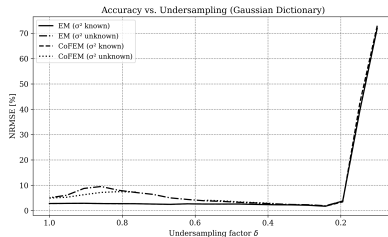


# ACCURACY COMPARISON: GAUSSIAN MATRICES

- ▶ EM and CoFEM exhibited nearly identical reconstruction accuracy in Gaussian measurement systems.
- ▶ CoFEM with unknown noise variance performed on par with variants assuming known noise level.



(A) NRMSE vs. sparsity level  $\rho$ .



(B) NRMSE vs. undersampling factor  $\delta$ .

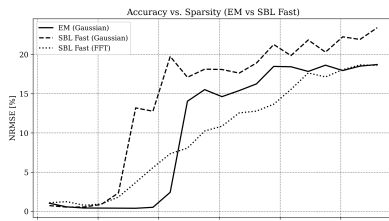
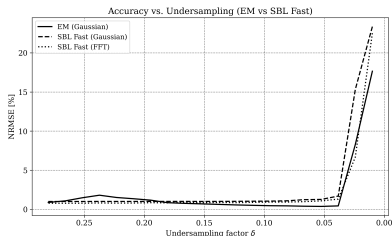
**FIGURE:** Reconstruction accuracy for EM and CoFEM algorithms with

# CHALLENGES WITH FOURIER MATRICES (EM/CoFEM)

- ▶ EM algorithm showed unstable behavior and sensitivity to initialization for complex-valued (FFT-based) dictionaries.
- ▶ Efforts to adapt EM for this case were discontinued due to unreliability.

# SBL-SURE (TIPPING'S FML) PERFORMANCE

- ▶ Demonstrated robust performance across both Gaussian and complex-valued systems.
- ▶ Accuracy in Gaussian systems closely matched EM's, with EM showing marginal improvements.
- ▶ **Key Finding:** In complex-valued systems (Fourier matrices), Tipping's method outperformed its own Gaussian results, suggesting better adaptation to structured dictionaries.





# FUTURE WORK

- ▶ Reformulate EM algorithm to reduce computational complexity for high-dimensional problems (e.g., using Woodbury identity).
- ▶ Explore further optimization of algorithms for specific antenna models.
- ▶ Validate findings with real-world antenna measurement data.
- ▶ Extend the framework to other types of electromagnetic problems.

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