

1 Recognising digits

```
#= This script answers the first question "One-step error probability" of Homework 1 =#

#= All the scrips are written in julia, since I didn't want to be bothered with the  =#
#=   slow programing languages such as python or matlab. I will do my best to make the  =#
#=   scripts understandable for someone with no experience with Julia. The performance  =#
#=   in this scrips are outstanding compared to the equivalent scripts that are written  =#
#=   with python or matlab, it only takes 5 seconds to execute this script on my laptop =#

using Distributions # used for random sampling

#= The main script computes the error probability for different values for P =#
function main()
    P = [12,24,48,70,100,120]
    trials = 1e5
    for pt in P
        P_error(pt, trials)
    end
end

#= This function computes the error probability for a given value for P patterns =#
#=   and a given value for trials =#
function P_error(P, trials)
    N = 120

    #= generate the patterns X =#
    X = generate_patterns(N, P)

    #= Compute the weights W =#
    zero_dig = false
    W = hebbs_rule(X, zero_dig)

    total_errors = 0
    for t in 1:trials
        # sample a random pixle from a random pattern
        i = sample(1:N)
        = sample(1:P)

        # perform a asynchronous update
        S_i = async_update(W, X[], i)

        # check wheter the pixle changed or not
        if S_i != X[][i]
            total_errors += 1
        end
    end

    # compute P_error and print it
    total_errors /= trials
    print(total_errors, ", ")
end

#= Generates a pattern of length N, where each element is = 1 with p=1/2 and -1 otherwise =#
function generate_pattern(N)
    sample([-1, 1], N)
end

#= Generates a list of P patterns and returns it =#
function generate_patterns(N, P)
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# = Initialize a empty list and append(push!) each pattern to it =#
X = []
for it in 1:P
    push!(X, generate_pattern(N))
end

return X
end

# = A function that computes the weights for a hopfield network using Hebb's rule =#
# = Inputs the patterns and a boolean that says wheter the diagonal should be zero or not =#
function hebbs_rule(X, zero_dig)
    P = length(X)
    N = length(X[1])
    W = zeros{Int, N, N}
    for it in 1:N
        for jt in 1:N
            for pt in 1:P
                W[it,jt] += X[pt][it] * X[pt][jt]
            end
        end
    end
    W /= N

    # if we want the diagonal to equal zero we need this extra loop
    if zero_dig
        for it in 1:N
            W[it,it] = 0
        end
    end

    return W
end

# = This function performs a asynchronous update on the pattern S at index i =#
# = using the weights W. Then returns the value, if the local field is equal =#
# = to 0, then it returns 1 =#
function async_update(W, S, i)
    N = length(S)

    # = Compute the localfield =#
    local_field = 0
    for j in 1:N
        local_field += W[i, j] * S[j]
    end

    # = Return the sign of the local field =#
    s_i = sign(local_field)
    if s_i == 0
        return 1
    else
        return s_i
    end
end

main()

(base) jona@marmor:~/NN$ cat recognizing_digits.jl
# = This script answers the second question "Recognising digits" in Homework 1 =#

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# In the main script we load the data, fit it to our model and later use the model to
# classify a pattern
function main()
    X, P = load_data()

    patterns = length(X)
    N = length(X[1])

    zero_dig = true
    W = hebbbs_rule(X, zero_dig)

    # Here we choose which pattern we want to try our model on
    S = copy(P[1])
    # Then we print it, just so that we can get a visual understanding of how the
    # model operates
    print_pattern(S)

    # This while-loop performs asynchronous updates until convergence
    while true
        S_t = update_pattern(W, S)
        # Again here we print the current pattern just for fun
        print_pattern(S_t)
        if S == S_t
            # Output the value when the model converges and outputs it to stdout
            println(reshape(S_t, (10,16)))
            break
        end
        S = S_t
    end
end

# This function takes as input the weight matrix and a pattern, then it returns a
# updated version of the pattern
function update_pattern(W, S)
    N = length(S)
    S_t = copy(S)
    for i in 1:N
        S_t[i] = async_update(W, S_t, i)
    end
    return S_t
end

# This function performs a asynchronous update on the pattern S at index i
# using the weights W. Then returns the value, if the local field is equal
# to 0, then it returns 1
function async_update(W, S, i)
    N = length(S)

    # Compute the localfield
    local_field = 0
    for j in 1:N
        local_field += W[i, j] * S[j]
    end

    # Return the sign of the local field
    s_i = sign(local_field)
    if s_i == 0
        return 1
    else
        return s_i
    end
end

```

end

#= A function that computes the weights for a hopfield network using Hebb's rule =#
#= Inputs the patterns and a boolean that says wheter the diagonal should be zero or not =#

```
function hebbs_rule(X, zero_dig)
    P = length(X)
    N = length(X[1])
    W = zeros(Int, N, N)
    for it in 1:N
        for jt in 1:N
            for pt in 1:P
                W[it,jt] += X[pt][it] * X[pt][jt]
            end
        end
    end
    W /= N

    # if we want the diagonal to equal zero we need this extra loop
    if zero_dig
        for it in 1:N
            W[it,it] = 0
        end
    end

    return W
end
```

#= To make the script a bit more fun and also esier to troubleshoot this function where =#
#= created. It is just a very simple visualization of the patterns =#

```
function print_pattern(X, m=16, n=10)
    for it in 1:length(X)
        if X[it] == 1
            print('X')
        else
            print(' ')
        end
        if it % 10 == 0
            print('\n')
        end
    end
    print('\n')
end
```

#= Here are the data that I got from OpenTA =#

```
function load_data()
    # 0
    x1=[ [-1, -1, -1, -1, -1, -1, -1, -1, -1, -1], [-1, -1, -1, 1, 1, 1, 1, -1, -1, -1], [-1, -1, 1, 1, 1, 1, 1, 1, 1, 1],
    # 1
    x2=[ [-1, -1, -1, 1, 1, 1, 1, -1, -1, -1], [-1, -1, -1, 1, 1, 1, 1, -1, -1, -1], [-1, -1, -1, 1, 1, 1, 1, 1, 1, -1],
    # 2
    x3=[ [ 1, 1, 1, 1, 1, 1, 1, 1, -1, -1], [ 1, 1, 1, 1, 1, 1, 1, 1, -1, -1], [-1, -1, -1, -1, -1, 1, 1, 1, 1, -1],
    # 3
    x4=[ [-1, -1, 1, 1, 1, 1, 1, 1, -1, -1], [-1, -1, 1, 1, 1, 1, 1, 1, 1, -1], [-1, -1, -1, -1, -1, -1, 1, 1, 1, 1],
    # 4
    x5=[ [-1, 1, 1, -1, -1, -1, -1, 1, 1, -1], [-1, 1, 1, -1, -1, -1, -1, 1, 1, -1], [-1, 1, 1, -1, -1, -1, -1, 1, 1, -1],

    # combined
    xs=[x1, x2, x3, x4, x5]
    X = transform_data(xs)
```

```

# distorted 3
p1 = [[1, 1, -1, -1, -1, -1, -1, -1, 1, 1], [1, 1, -1, -1, -1, -1, -1, -1, -1, 1], [-1, -1, -1, -1, -1, -1, -1, -1, -1, 1]
# distorted 4
p2 = [[1, -1, -1, 1, 1, 1, 1, -1, -1, 1], [-1, 1, 1, -1, -1, -1, -1, 1, 1, -1], [-1, 1, 1, -1, -1, -1, -1, -1, 1, 1]
# distorted 1
p3 = [[-1, -1, -1, 1, 1, 1, 1, -1, -1, -1], [-1, -1, -1, 1, 1, 1, 1, -1, -1, -1], [-1, -1, -1, 1, 1, 1, 1, -1, -1, -1]

# combinind
ps = [p1, p2, p3]
P = transform_data(ps)

return X, P
end

# I ran in to a problem with the way the patterns where stored, so this helper =#
# function was necessary to make use of the functions created previously. =#
# It basically turns a matrix in to a long vector. =#
function transform_data(ts, m=16)
    T = []
    for t in ts
        tmp = []
        for it in 1:m
            tmp = vcat(tmp, t[it])
        end
        push!(T, tmp)
    end
    return T
end

main()

```