

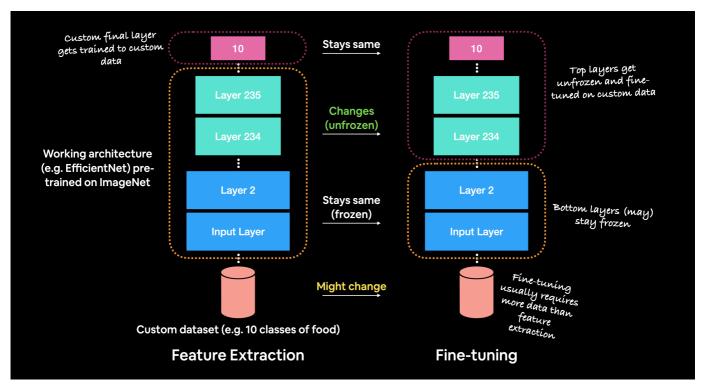
## Transfer Learning with TensorFlow Part 2: Fine-tuning

In the previous section, we saw how we could leverage feature extraction transfer learning to get far better results on our Food Vision project than building our own models (even with less data).

Now we're going to cover another type of transfer learning: fine-tuning.

In **fine-tuning transfer learning** the pre-trained model weights from another model are unfrozen and tweaked during to better suit your own data.

For feature extraction transfer learning, you may only train the top 1-3 layers of a pre-trained model with your own data, in fine-tuning transfer learning, you might train 1-3+ layers of a pre-trained model (where the '+' indicates that many or all of the layers could be trained).



Feature extraction transfer learning vs. fine-tuning transfer learning. The main difference between the two is that in fine-tuning, more layers of the pre-trained model get unfrozen and tuned on custom data. This fine-tuning usually takes more data than feature extraction to be effective.

## What we're going to cover

We're going to go through the follow with TensorFlow:

- Introduce fine-tuning, a type of transfer learning to modify a pre-trained model to be more suited to your data
- Using the Keras Functional API (a differnt way to build models in Keras)
- Using a smaller dataset to experiment faster (e.g. 1-10% of training samples of 10 classes of food)

- Data augmentation (how to make your training dataset more diverse without adding more data)
- Running a series of modelling experiments on our Food Vision data
  - Model 0: a transfer learning model using the Keras Functional API
  - Model 1: a feature extraction transfer learning model on 1% of the data with data augmentation
  - Model 2: a feature extraction transfer learning model on 10% of the data with data augmentation
  - Model 3: a fine-tuned transfer learning model on 10% of the data
  - Model 4: a fine-tuned transfer learning model on 100% of the data
- Introduce the ModelCheckpoint callback to save intermediate training results
- Compare model experiments results using TensorBoard

## How you can use this notebook

You can read through the descriptions and the code (it should all run, except for the cells which error on purpose), but there's a better option.

Write all of the code yourself.

Yes. I'm serious. Create a new notebook, and rewrite each line by yourself. Investigate it, see if you can break it, why does it break?

You don't have to write the text descriptions but writing the code yourself is a great way to get hands-on experience.

Don't worry if you make mistakes, we all do. The way to get better and make less mistakes is to write more code.

# Are we using a GPU? (if not & you're using Google Colab, go to Runtime -> Change Runtime !nvidia-smi

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## Creating helper functions

Throughout your machine learning experiments, you'll likely come across snippets of code you want to use over and over again.

For example, a plotting function which plots a model's history object (see plot\_loss\_curves() below).

You could recreate these functions over and over again.

from helper\_functions import plot\_loss\_curves

But as you might've guessed, rewritting the same functions becomes tedious.

One of the solutions is to store them in a helper script such as <a href="helper\_functions.py">helper\_functions.py</a>. And then import the necesary functionality when you need it.

For example, you might write:

```
plot_loss_curves(history)

Let's see what this looks like.

# Get helper_functions.py script from course GitHub
!wget https://raw.githubusercontent.com/mrdbourke/tensorflow-deep-learning/main/extras/hel

# Import helper functions we're going to use
from helper_functions import create_tensorboard_callback, plot_loss_curves, unzip_data, wa

--2021-02-16 02:14:32-- https://raw.githubusercontent.com/mrdbourke/tensorflow-deep-
Resolving raw.githubusercontent.com (raw.githubusercontent.com)... 185.199.111.133, 1
Connecting to raw.githubusercontent.com (raw.githubusercontent.com)|185.199.111.133|
HTTP request sent, awaiting response... 200 0K
Length: 9373 (9.2K) [text/plain]
Saving to: 'helper_functions.py.1'
helper_functions.py 100%[===========]] 9.15K --.-KB/s in 0s
2021-02-16 02:14:32 (99.6 MB/s) - 'helper_functions.py.1' saved [9373/9373]
```

Wonderful, now we've got a bunch of helper functions we can use throughout the notebook without having to rewrite them from scratch each time.

Note: If you're running this notebook in Google Colab, when it times out Colab will delete the helper\_functions.py file. So to use the functions imported above, you'll have to rerun the cell.

## 10 Food Classes: Working with less data

We saw in the <u>previous notebook</u> that we could get great results with only 10% of the training data using transfer learning with TensorFlow Hub.

In this notebook, we're going to continue to work with smaller subsets of the data, except this time we'll have a look at how we can use the in-built pretrained models within the tf.keras.applications module as well as how to fine-tune them to our own custom dataset.

We'll also practice using a new but similar dataloader function to what we've used before, image dataset from directory() which is part of the tf.keras.preprocessing module.

Finally, we'll also be practicing using the <u>Keras Functional API</u> for building deep learning models. The Functional API is a more flexible way to create models than the tf.keras.Sequential API.

We'll explore each of these in more detail as we go.

Let's start by downloading some data.

The dataset we're downloading is the 10 food classes dataset (from Food 101) with 10% of the training images we used in the previous notebook.

Note: You can see how this dataset was created in the <u>image data</u> modification notebook.

```
There are 2 directories and 0 images in '10_food_classes_10_percent'.
There are 10 directories and 0 images in '10_food_classes_10_percent/train'.
There are 0 directories and 75 images in '10_food_classes_10_percent/train/ice_cream
There are 0 directories and 75 images in '10_food_classes_10_percent/train/ramen'.
There are 0 directories and 75 images in '10_food_classes_10_percent/train/chicken_wi
There are 0 directories and 75 images in '10 food classes 10 percent/train/pizza'.
There are 0 directories and 75 images in '10_food_classes_10_percent/train/steak'.
There are 0 directories and 75 images in '10_food_classes_10_percent/train/fried_rice
There are 0 directories and 75 images in '10_food_classes_10_percent/train/hamburger
There are 0 directories and 75 images in '10 food classes 10 percent/train/grilled sa
There are 0 directories and 75 images in '10_food_classes_10_percent/train/sushi'.
There are 0 directories and 75 images in '10_food_classes_10_percent/train/chicken_cu
There are 10 directories and 0 images in '10_food_classes_10_percent/test'.
There are 0 directories and 250 images in '10_food_classes_10_percent/test/ice_cream
There are 0 directories and 250 images in '10_food_classes_10_percent/test/ramen'.

There are 0 directories and 250 images in '10_food_classes_10_percent/test/chicken_wi
There are 0 directories and 250 images in '10 food classes 10 percent/test/pizza'.
There are 0 directories and 250 images in '10_food_classes_10_percent/test/steak'.
There are 0 directories and 250 images in '10_food_classes_10_percent/test/fried_rice
There are 0 directories and 250 images in '10_food_classes_10_percent/test/hamburger
There are 0 directories and 250 images in '10_food_classes_10_percent/test/grilled_sa
There are 0 directories and 250 images in '10 food classes 10 percent/test/sushi'.
There are 0 directories and 250 images in '10_food_classes_10_percent/test/chicken_cu
```

We can see that each of the training directories contain 75 images and each of the testing directories contain 250 images.

Let's define our training and test filepaths.

```
# Create training and test directories
train_dir = "10_food_classes_10_percent/train/"
test_dir = "10_food_classes_10_percent/test/"
```

Now we've got some image data, we need a way of loading it into a TensorFlow compatible format.

Previously, we've used the <u>ImageDataGenerator</u> class. And while this works well and is still very commonly used, this time we're going to use the <u>image</u> data from directory function.

It works much the same way as ImageDataGenerator's flow\_from\_directory method meaning your images need to be in the following file format:

```
# Example of file structure

10_food_classes_10_percent <- top level folder

L___train <- training images

| L___pizza
| | 1008104.jpg
| | 1638227.jpg
| | ...
| L___steak
```

```
| | 1000205.jpg
| 1647351.jpg
| ...
| test <- testing images
| pizza
| | 1001116.jpg
| 1507019.jpg
| | ...
| steak
| 100274.jpg
| 1653815.jpg
```

One of the main benefits of using

#### tf.keras.prepreprocessing.image dataset from directory() rather than

ImageDataGenerator is that it creates a <u>tf.data.Dataset</u> object rather than a generator. The main advantage of this is the tf.data.Dataset API is much more efficient (faster) than the ImageDataGenerator API which is paramount for larger datasets.

Let's see it in action.

Wonderful! Looks like our dataloaders have found the correct number of images for each dataset.

For now, the main parameters we're concerned about in the <code>image\_dataset\_from\_directory()</code> funtion are:

- directory the filepath of the target directory we're loading images in from.
- image\_size the target size of the images we're going to load in (height, width).
- batch\_size the batch size of the images we're going to load in. For example if the batch\_size is 32 (the default), batches of 32 images and labels at a time will be passed to the model.

There are more we could play around with if we needed to <u>in the tf.keras.preprocessing</u> documentation.

If we check the training data datatype we should see it as a BatchDataset with shapes relating to our data.

```
# Check the training data datatype
train_data_10_percent

<BatchDataset shapes: ((None, 224, 224, 3), (None, 10)), types: (tf.float32, tf.float</pre>
```

In the above output:

- (None, 224, 224, 3) refers to the tensor shape of our images where None is the batch size, 224 is the height (and width) and 3 is the color channels (red, green, blue).
- (None, 10) refers to the tensor shape of the labels where None is the batch size and 10 is the number of possible labels (the 10 different food classes).
- Both image tensors and labels are of the datatype tf.float32.

The batch\_size is None due to it only being used during model training. You can think of None as a placeholder waiting to be filled with the batch\_size parameter from image\_dataset\_from\_directory().

Another benefit of using the tf.data.Dataset API are the assosciated methods which come with it.

For example, if we want to find the name of the classes we were working with, we could use the class\_names attribute.

```
# Check out the class names of our dataset
train_data_10_percent.class_names

['chicken_curry',
    'chicken_wings',
    'fried_rice',
    'grilled_salmon',
    'hamburger',
    'ice_cream',
    'pizza',
    'ramen',
    'steak',
    'sushi']
```

Or if we wanted to see an example batch of data, we could use the take() method.

```
# See an example batch of data
for images, labels in train_data_10_percent.take(1):
    print(images, labels)
```

```
tf.Tensor(
[[[1.00000000e+00 0.0000000e+00 3.10000000e+01]
   [1.00000000e+00 0.00000000e+00 3.10000000e+01]
   [1.00000000e+00 0.0000000e+00 3.10000000e+01]
   [1.00000000e+00 0.00000000e+00 3.10000000e+01]
   [1.00000000e+00 0.00000000e+00 3.10000000e+01]
   [1.00000000e+00 0.00000000e+00 3.10000000e+01]]
  [[1.00000000e+00 0.0000000e+00 3.10000000e+01]
   [1.00000000e+00 0.00000000e+00 3.10000000e+01]]
  [[1.00000000e+00 0.0000000e+00 3.10000000e+01]
   [1.00000000e+00 0.00000000e+00 3.10000000e+01]]
  [[1.07500107e+02 9.49286346e+01 8.90816803e+01]
   [1.15714394e+02 1.01285782e+02 9.41582489e+01]
   [1.17974548e+02 1.04188812e+02 9.51888123e+01]
   [1.18617378e+02 2.90000000e+01 2.76939182e+01]
   [1.19000000e+02 2.90000000e+01 2.80000000e+01]
   [1.20076530e+02 3.00765305e+01 2.98622665e+01]]
  [[1.07045891e+02 9.20458908e+01 8.70458908e+01]
   [1.15852043e+02 1.00852043e+02 9.38520432e+01]
   [1.15841820e+02 1.02056099e+02 9.32703857e+01]
   [1.17943863e+02 2.99438648e+01 2.87296009e+01]
   [1.17923454e+02 2.79234543e+01 2.79234543e+01]
   [1.17857117e+02 2.78571167e+01 2.78571167e+01]]
  [[1.00785606e+02 8.57856064e+01 8.07856064e+01]
   [1.13999931e+02 9.89999313e+01 9.28061218e+01]
   [1.11999931e+02 9.74284973e+01 9.06427841e+01]
   [1.16857086e+02 2.88570862e+01 2.76428223e+01]
   [1.14571381e+02 2.65713806e+01 2.55713806e+01]
   [1.14642822e+02 2.46428223e+01 2.66428223e+01]]]
 [[[9.76530609e+01 7.90663223e+01 6.50663223e+01]
   [1.04392860e+02 8.82500000e+01 7.33214264e+01]
   [1.09520409e+02 9.69591827e+01 8.36683655e+01]
   [2.44423492e+02 2.37423492e+02 2.19423492e+02]
   [2.46760208e+02 2.39760208e+02 2.21760208e+02]
   [1 400000000.00 1 440000000.00 1 120000000.001]
```

Notice how the image arrays come out as tensors of pixel values where as the labels come out as one-hot encodings (e.g. [0. 0. 0. 0. 1. 0. 0. 0. 0. ] for hamburger).

Model 0: Building a transfer learning model using the Keras Functional API Alright, our data is tensor-ified, let's build a model.

To do so we're going to be using the <u>tf.keras.applications</u> module as it contains a series of already trained (on ImageNet) computer vision models as well as the Keras Functional API to construct our model.

We're going to go through the following steps:

- 1. Instantiate a pre-trained base model object by choosing a target model such as <u>EfficientNetB0</u> from tf.keras.applications, setting the include\_top parameter to False (we do this because we're going to create our own top, which are the output layers for the model).
- 2. Set the base model's trainable attribute to False to freeze all of the weights in the pretrained model.
- 3. Define an input layer for our model, for example, what shape of data should our model expect?
- 4. [Optional] Normalize the inputs to our model if it requires. Some computer vision models such as ResNetV250 require their inputs to be between 0 & 1.
  - Note: As of writing, the EfficientNet models in the tf.keras.applications module do not require images to be normalized (pixel values between 0 and 1) on input, where as many of the other models do. I posted an issue to the TensorFlow GitHub about this and they confirmed this.
- 5. Pass the inputs to the base model.
- 6. Pool the outputs of the base model into a shape compatible with the output activation layer (turn base model output tensors into same shape as label tensors). This can be done using <a href="mailto:tf.keras.layers.GlobalAveragePooling2D()">tf.keras.layers.GlobalMaxPooling2D()</a> though the former is more common in practice.
- 7. Create an output activation layer using tf.keras.layers.Dense() with the appropriate activation function and number of neurons.
- 8. Combine the inputs and outputs layer into a model using tf.keras.Model().
- 9. Compile the model using the appropriate loss function and choose of optimizer.
- 10. Fit the model for desired number of epochs and with necessary callbacks (in our case, we'll start off with the TensorBoard callback).

Woah... that sounds like a lot. Before we get ahead of ourselves, let's see it in practice.

```
nase_monet - riveras.abbitcartons.rilitatenarena(incinae_cob-Laise)
# 2. Freeze the base model (so the pre-learned patterns remain)
base_model.trainable = False
# 3. Create inputs into the base model
inputs = tf.keras.layers.Input(shape=(224, 224, 3), name="input_layer")
# 4. If using ResNet50V2, add this to speed up convergence, remove for EfficientNet
\# x = tf.keras.layers.experimental.preprocessing.Rescaling(1./255)(inputs)
# 5. Pass the inputs to the base_model (note: using tf.keras.applications, EfficientNet in
x = base_model(inputs)
# Check data shape after passing it to base_model
print(f"Shape after base_model: {x.shape}")
# 6. Average pool the outputs of the base model (aggregate all the most important informat
x = tf.keras.layers.GlobalAveragePooling2D(name="global_average_pooling_layer")(x)
print(f"After GlobalAveragePooling2D(): {x.shape}")
# 7. Create the output activation layer
outputs = tf.keras.layers.Dense(10, activation="softmax", name="output_layer")(x)
# 8. Combine the inputs with the outputs into a model
model 0 = tf.keras.Model(inputs, outputs)
# 9. Compile the model
model_0.compile(loss='categorical_crossentropy',
           optimizer=tf.keras.optimizers.Adam(),
           metrics=["accuracy"])
# 10. Fit the model (we use less steps for validation so it's faster)
history_10_percent = model_0.fit(train_data_10_percent,
                            epochs=5,
                            steps_per_epoch=len(train_data_10_percent),
                            validation_data=test_data_10_percent,
                            # Go through less of the validation data so epochs are fa
                            validation_steps=int(0.25 * len(test_data_10_percent)),
                            # Track our model's training logs for visualization later
                            callbacks=[create_tensorboard_callback("transfer_learning")
    Shape after base model: (None, 7, 7, 1280)
    After GlobalAveragePooling2D(): (None, 1280)
    Saving TensorBoard log files to: transfer_learning/10_percent_feature_extract/2021021
    Epoch 1/5
    24/24 [=============== ] - 14s 313ms/step - loss: 2.1271 - accuracy: 0
    Epoch 2/5
    Epoch 3/5
    Epoch 4/5
    Epoch 5/5
```

Nice! After a minute or so of training our model performs incredibly well on both the training (87%+ accuracy) and test sets (~83% accuracy).

This is incredible. All thanks to the power of transfer learning.

It's important to note the kind of transfer learning we used here is called feature extraction transfer learning, similar to what we did with the TensorFlow Hub models.

In other words, we passed our custom data to an already pre-trained model (EfficientNetB0), asked it "what patterns do you see?" and then put our own output layer on top to make sure the outputs were tailored to our desired number of classes.

We also used the Keras Functional API to build our model rather than the Sequential API. For now, the benefits of this main not seem clear but when you start to build more sophisticated models, you'll probably want to use the Functional API. So it's important to have exposure to this way of building models.

Resource: To see the benefits and use cases of the Functional API versus the Sequential API, check out the <u>TensorFlow Functional API documentation</u>.

Let's inspect the layers in our model, we'll start with the base.

```
# Check layers in our base model
for layer_number, layer in enumerate(base_model.layers):
  print(layer number, layer.name)
     0 input_1
     1 rescaling
     2 normalization
     3 stem_conv_pad
     4 stem_conv
     5 stem_bn
     6 stem activation
     7 block1a dwconv
     8 block1a_bn
     9 block1a activation
     10 block1a_se_squeeze
     11 block1a_se_reshape
     12 block1a se reduce
     13 block1a_se_expand
     14 block1a_se_excite
     15 block1a_project_conv
     16 block1a_project_bn
     17 block2a_expand_conv
     18 block2a expand bn
     19 block2a_expand_activation
     20 block2a dwconv pad
     21 block2a_dwconv
     22 block2a_bn
     23 block2a_activation
     24 block2a se squeeze
     25 block2a_se_reshape
```

26 block2a\_se\_reduce 27 block2a\_se\_expand

```
28 block2a_se_excite
```

- 29 block2a\_project\_conv
- 30 block2a\_project\_bn
- 31 block2b\_expand\_conv
- 32 block2b\_expand\_bn
- 33 block2b\_expand\_activation
- 34 block2b\_dwconv
- 35 block2b\_bn
- 36 block2b activation
- 37 block2b\_se\_squeeze
- 38 block2b\_se\_reshape
- 39 block2b\_se\_reduce
- 40 block2b\_se\_expand
- 41 block2b\_se\_excite
- 42 block2b\_project\_conv
- 43 block2b\_project\_bn
- 44 block2b\_drop
- 45 block2b add
- 46 block3a\_expand\_conv
- 47 block3a\_expand\_bn
- 48 block3a\_expand\_activation
- 49 block3a\_dwconv\_pad
- 50 block3a\_dwconv
- 51 block3a bn
- 52 block3a\_activation
- 53 block3a\_se\_squeeze
- 54 block3a se reshape
- 55 block3a\_se\_reduce
- 56 block3a\_se\_expand
- 57 block3a\_se\_excite
- 58 block3a project conv

Wow, that's a lot of layers... to handcode all of those would've taken a fairly long time to do, yet we can still take advatange of them thanks to the power of transfer learning.

How about a summary of the base model?

base\_model.summary()

Model: "efficientnetb0"

Layer (type)	Output Shape		Param #	Connected to
<pre>input_1 (InputLayer)</pre>	[(None, None	, None,	0	============
rescaling (Rescaling)	(None, None,	None, 3	0	input_1[0][0]
normalization (Normalization)	(None, None,	None, 3	7	rescaling[0][0]
stem_conv_pad (ZeroPadding2D)	(None, None,	None, 3	0	normalization[0][
stem_conv (Conv2D)	(None, None,	None, 3	864	stem_conv_pad[0][
stem_bn (BatchNormalization)	(None, None,	None, 3	128	stem_conv[0][0]
stem_activation (Activation)	(None, None,	None, 3	0	stem_bn[0][0]
block1a_dwconv (DepthwiseConv2D	(None, None,	None, 3	288	stem_activation[0

block1a_bn (BatchNormalization)	(None,	None,	None,	3	128	block1a_dwconv[0]
block1a_activation (Activation)	(None,	None,	None,	3	0	block1a_bn[0][0]
block1a_se_squeeze (GlobalAvera	(None,	32)			0	block1a_activatio
block1a_se_reshape (Reshape)	(None,	1, 1,	32)		0	block1a_se_squeez
block1a_se_reduce (Conv2D)	(None,	1, 1,	8)		264	block1a_se_reshap
block1a_se_expand (Conv2D)	(None,	1, 1,	32)		288	block1a_se_reduce
block1a_se_excite (Multiply)	(None,	None,	None,	3	0	block1a_activatio block1a_se_expand
block1a_project_conv (Conv2D)	(None,	None,	None,	1	512	block1a_se_excite
block1a_project_bn (BatchNormal	(None,	None,	None,	1	64	block1a_project_c
block2a_expand_conv (Conv2D)	(None,	None,	None,	9	1536	block1a_project_b
block2a_expand_bn (BatchNormali	(None,	None,	None,	9	384	block2a_expand_co
block2a_expand_activation (Acti	(None,	None,	None,	9	0	block2a_expand_bn
block2a_dwconv_pad (ZeroPadding	(None,	None,	None,	9	0	block2a_expand_ac
block2a_dwconv (DepthwiseConv2D	(None,	None,	None,	9	864	block2a_dwconv_pac
block2a_bn (BatchNormalization)	(None,	None,	None,	9	384	block2a_dwconv[0]
block2a_activation (Activation)	(None,	None,	None,	9	0	block2a_bn[0][0]
block2a_se_squeeze (GlobalAvera	(None,	96)			0	block2a_activatio
block2a_se_reshape (Reshape)	(None,	1, 1,	96)		0	block2a_se_squeeze
block2a se reduce (Conv2D)	(None.	1. 1.	4)		388	block2a se resham

You can see how each of the different layers have a certain number of parameters each. Since we are using a pre-trained model, you can think of all of these parameters are patterns the base model has learned on another dataset. And because we set <code>base\_model.trainable = False</code>, these patterns remain as they are during training (they're frozen and don't get updated).

Alright that was the base model, let's see the summary of our overall model.

# Check summary of model constructed with Functional API
model\_0.summary()

Model: "model"

Layer (type)	Output Shape	Param #
		=======
<pre>input_layer (InputLayer)</pre>	[(None, 224, 224, 3)]	0
efficientnetb0 (Functional)	(None, None, None, 1280)	4049571

output_layer ([	Dense)	(None, 10)	12810

Total params: 4,062,381 Trainable params: 12,810

Non-trainable params: 4,049,571

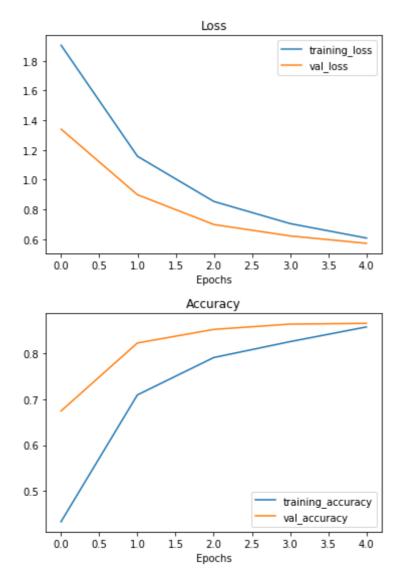
Our overall model has five layers but really, one of those layers (efficientnetb0) has 236 layers.

You can see how the output shape started out as (None, 224, 224, 3) for the input layer (the shape of our images) but was transformed to be (None, 10) by the output layer (the shape of our labels), where None is the placeholder for the batch size.

Notice too, the only trainable parameters in the model are those in the output layer.

How do our model's training curves look?

# Check out our model's training curves
plot\_loss\_curves(history\_10\_percent)



## Getting a feature vector from a trained model

Question: What happens with the

tf.keras.layers.GlobalAveragePooling2D() layer? I haven't seen it before.

The <u>tf.keras.layers.GlobalAveragePooling2D()</u> layer transforms a 4D tensor into a 2D tensor by averaging the values across the inner-axes.

```
The provious contained is a bit of a mouthful as late ass an example
# Define input tensor shape (same number of dimensions as the output of efficientnetb0)
input\_shape = (1, 4, 4, 3)
# Create a random tensor
tf.random.set seed(42)
input_tensor = tf.random.normal(input_shape)
print(f"Random input tensor:\n {input_tensor}\n")
# Pass the random tensor through a global average pooling 2D layer
global_average_pooled_tensor = tf.keras.layers.GlobalAveragePooling2D()(input_tensor)
print(f"2D global average pooled random tensor:\n {global_average_pooled_tensor}\n")
# Check the shapes of the different tensors
print(f"Shape of input tensor: {input_tensor.shape}")
print(f"Shape of 2D global averaged pooled input tensor: {global_average_pooled_tensor.sha
    Random input tensor:
     [-1.4075519 -2.3880599 -1.0392479]
       [-0.5573232  0.539707  1.6994323 ]
       [ 0.28893656 -1.5066116 -0.2645474 ]]
      [[-0.59722406 -1.9171132 -0.62044144]
       [ 0.8504023 -0.40604794 -3.0258412 ]
       [-0.7616443 -1.891714 -0.9384712]]
      [[ 0.77852213 -0.47338897 0.97772694]
       [ 0.24694404  0.20573747 -0.5256233 ]
       [ 0.32410017  0.02545409  -0.10638497]
       [-0.5931857 -1.6617213 0.33567193]
       [ 0.10815629  0.2347968  -0.56668764]
       [-0.35819843 0.88698614 0.52744764]]]]
    2D global average pooled random tensor:
     [[-0.09368646 -0.45840448 -0.2885598 ]]
    Shape of input tensor: (1, 4, 4, 3)
    Shape of 2D global averaged pooled input tensor: (1, 3)
```

You can see the tf.keras.layers.GlobalAveragePooling2D() layer condensed the input tensor from shape (1, 4, 4, 3) to (1, 3). It did so by averaging the input\_tensor across the middle two axes.

We can replicate this operation using the tf.reduce\_mean() operation and specifying the appropriate axes.

```
# This is the same as GlobalAveragePooling2D()
tf.reduce_mean(input_tensor, axis=[1, 2]) # average across the middle axes

<tf.Tensor: shape=(1, 3), dtype=float32, numpy=array([[-0.09368646, -0.45840448, -0.2</pre>
```

Doing this not only makes the output of the base model compatible with the input shape requirement of our output layer (tf.keras.layers.Dense()), it also condenses the information found by the base model into a lower dimension **feature vector**.

Note: One of the reasons feature extraction transfer learning is named how it is is because what often happens is a pretrained model outputs a **feature vector** (a long tensor of numbers, in our case, this is the output of the <a href="mailto:tf.keras.layers.GlobalAveragePooling2D(">tf.keras.layers.GlobalAveragePooling2D(")</a> layer) which can then be used to extract patterns out of.

\* Practice: Do the same as the above cell but for tf.keras.layers.GlobalMaxPool2D().

## Running a series of transfer learning experiments

We've seen the incredible results of transfer learning on 10% of the training data, what about 1% of the training data?

What kind of results do you think we can get using 100x less data than the original CNN models we built ourselves?

Why don't we answer that question while running the following modelling experiments:

- 1. model\_1: Use feature extraction transfer learning on 1% of the training data with data augmentation.
- 2. model\_2: Use feature extraction transfer learning on 10% of the training data with data augmentation.
- 3. model\_3: Use fine-tuning transfer learning on 10% of the training data with data augmentation.
- 4. model\_4: Use fine-tuning transfer learning on 100% of the training data with data augmentation.

While all of the experiments will be run on different versions of the training data, they will all be evaluated on the same test dataset, this ensures the results of each experiment are as comparable as possible.

All experiments will be done using the EfficientNetB0 model within the tf.keras.applications module.

To make sure we're keeping track of our experiments, we'll use our create\_tensorboard\_callback() function to log all of the model training logs.

We'll construct each model using the Keras Functional API and instead of implementing data augmentation in the ImageDataGenerator class as we have previously, we're going to build it right into the model using the <a href="mailto:tf.keras.layers.experimental.preprocessing">tf.keras.layers.experimental.preprocessing</a> module.

Let's begin by downloading the data for experiment 1, using feature extraction transfer learning on 1% of the training data with data augmentation.

```
# Download and unzip data
!wget https://storage.googleapis.com/ztm_tf_course/food_vision/10_food_classes_1_percent.z
unzip_data("10_food_classes_1_percent.zip")

# Create training and test dirs
train_dir_1_percent = "10_food_classes_1_percent/train/"
test_dir = "10_food_classes_1_percent/test/"

--2021-02-16 02:15:55-- https://storage.googleapis.com/ztm tf_course/food_vision/10
Resolving storage.googleapis.com (storage.googleapis.com)... 172.217.7.208, 172.217.5
Connecting to storage.googleapis.com (storage.googleapis.com)|172.217.7.208|:443...c
HTTP request sent, awaiting response... 200 OK
Length: 133612354 (127M) [application/zip]
Saving to: '10_food_classes_1_percent.zip.1'

10_food_classes_1_p 100%[==========================] 127.42M 194MB/s in 0.7s

2021-02-16 02:15:56 (194 MB/s) - '10_food_classes_1_percent.zip.1' saved [133612354/1]
```

How many images are we working with?

# Walk through 1 percent data directory and list number of files

```
walk_through_dir("10_food_classes_1_percent")

There are 2 directories and 0 images in '10_food_classes_1_percent'.
There are 10 directories and 0 images in '10_food_classes_1_percent/train'.
There are 0 directories and 7 images in '10_food_classes_1_percent/train/ice_cream'.
There are 0 directories and 7 images in '10_food_classes_1_percent/train/ramen'.
There are 0 directories and 7 images in '10_food_classes_1_percent/train/chicken_wing
There are 0 directories and 7 images in '10_food_classes_1_percent/train/pizza'.
There are 0 directories and 7 images in '10_food_classes_1_percent/train/steak'.
There are 0 directories and 7 images in '10_food_classes_1_percent/train/fried_rice'
There are 0 directories and 7 images in '10_food_classes_1_percent/train/hamburger'.
There are 0 directories and 7 images in '10_food_classes_1_percent/train/sushi'.
There are 0 directories and 7 images in '10_food_classes_1_percent/train/chicken_curr
There are 0 directories and 0 images in '10_food_classes_1_percent/test'.
There are 0 directories and 0 images in '10_food_classes_1_percent/test'.
There are 0 directories and 250 images in '10_food_classes_1_percent/test/ice_cream'
```

```
There are 0 directories and 250 images in '10_food_classes_1_percent/test/chicken_wir There are 0 directories and 250 images in '10_food_classes_1_percent/test/chicken_wir There are 0 directories and 250 images in '10_food_classes_1_percent/test/pizza'.

There are 0 directories and 250 images in '10_food_classes_1_percent/test/steak'.

There are 0 directories and 250 images in '10_food_classes_1_percent/test/fried_rice
There are 0 directories and 250 images in '10_food_classes_1_percent/test/hamburger'
There are 0 directories and 250 images in '10_food_classes_1_percent/test/grilled_sal
There are 0 directories and 250 images in '10_food_classes_1_percent/test/sushi'.

There are 0 directories and 250 images in '10_food_classes_1_percent/test/sushi'.
```

Alright, looks like we've only got seven images of each class, this should be a bit of a challenge for our model.

Note: As with the 10% of data subset, the 1% of images were chosen at random from the original full training dataset. The test images are the same as the ones which have previously been used. If you want to see how this data was preprocessed, check out the Food Vision Image Preprocessing notebook.

Time to load our images in as tf.data.Dataset objects, to do so, we'll use the image dataset from directory() method.

Data loaded. Time to augment it.

### Adding data augmentation right into the model

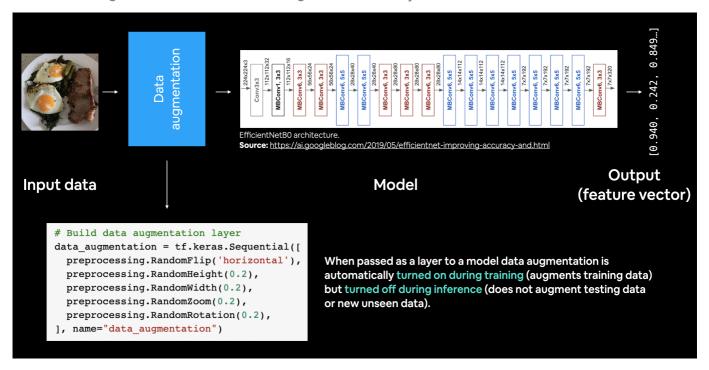
Previously we've used the different parameters of the ImageDataGenerator class to augment our training images, this time we're going to build data augmentation right into the model.

How?

Using the <u>tf.keras.layers.experimental.preprocessing</u> module and creating a dedicated data augmentation layer.

This a relatively new feature added to TensorFlow 2.2+ but it's very powerful. Adding a data augmentation layer to the model has the following benefits:

- Preprocessing of the images (augmenting them) happens on the GPU rather than on the CPU (much faster).
  - Images are best preprocessed on the GPU where as text and structured data are more suited to be preprocessed on the CPU.
- Image data augmentation only happens during training so we can still export our whole model and use it elsewhere. And if someone else wanted to train the same model as us, including the same kind of data augmentation, they could.



Example of using data augmentation as the first layer within a model (EfficientNetB0).

Note: At the time of writing, the preprocessing layers we're using for data augmentation are in *experimental* status within the in TensorFlow library. This means although the layers should be considered stable, the code may change slightly in a future version of TensorFlow. For more information on the other preprocessing layers available and the different methods of data augmentation, check out the <u>Keras preprocessing layers guide</u> and the <u>TensorFlow data</u> augmentation guide.

To use data augmentation right within our model we'll create a Keras Sequential model consisting of only data preprocessing layers, we can then use this Sequential model within another Functional model.

If that sounds confusing, it'll make sense once we create it in code.

The data augmentation transformations we're going to use are:

- RandomFlip flips image on horizontal or vertical axis.
- RandomRotation randomly rotates image by a specified amount.
- RandomZoom randomly zooms into an image by specified amount.
- RandomHeight randomly shifts image height by a specified amount.

- RandomWidth randomly shifts image width by a specified amount.
- Rescaling normalizes the image pixel values to be between 0 and 1, this is worth mentioning because it is required for some image models but since we're using the tf.keras.applications implementation of EfficientNetB0, it's not required.

There are more option but these will do for now.

```
import tensorflow as tf
from tensorflow.keras import layers
from tensorflow.keras.layers.experimental import preprocessing

# Create a data augmentation stage with horizontal flipping, rotations, zooms
data_augmentation = keras.Sequential([
    preprocessing.RandomFlip("horizontal"),
    preprocessing.RandomRotation(0.2),
    preprocessing.RandomHeight(0.2),
    preprocessing.RandomHeight(0.2),
    preprocessing.RandomWidth(0.2),
    # preprocessing.Rescaling(1./255) # keep for ResNet50V2, remove for EfficientNetB0
], name = "data_augmentation")
```

And that's it! Our data augmentation Sequential model is ready to go. As you'll see shortly, we'll be able to slot this "model" as a layer into our transfer learning model later on.

But before we do that, let's test it out by passing random images through it.

```
# View a random image
import matplotlib.pyplot as plt
import matplotlib.image as mpimg
import os
import random
target class = random.choice(train data 1 percent.class names) # choose a random class
target_dir = "10_food_classes_1_percent/train/" + target_class # create the target directo
random_image = random.choice(os.listdir(target_dir)) # choose a random image from target d
random_image_path = target_dir + "/" + random_image # create the choosen random image path
img = mpimg.imread(random_image_path) # read in the chosen target image
plt.imshow(img) # plot the target image
plt.title(f"Original random image from class: {target_class}")
plt.axis(False); # turn off the axes
# Augment the image
augmented img = data augmentation(tf.expand dims(img, axis=0)) # data augmentation model r
plt.imshow(tf.squeeze(augmented_img)/255.) # requires normalization after augmentation
plt.title(f"Augmented random image from class: {target_class}")
plt.axis(False);
```

Original random image from class: grilled\_salmon



Augmented random image from class: grilled\_salmon



Run the cell above a few times and you can see the different random augmentations on different classes of images. Because we're going to add the data augmentation model as a layer in our upcoming transfer learning model, it'll apply these kind of random augmentations to each of the training images which passes through it.

Doing this will make our training dataset a little more varied. You can think of it as if you were taking a photo of food in real-life, not all of the images are going to be perfect, some of them are going to be orientated in strange ways. These are the kind of images we want our model to be able to handle.

Speaking of model, let's build one with the Functional API. We'll run through all of the same steps as before except for one difference, we'll add our data augmentation Sequential model as a layer immediately after the input layer.

# Model 1: Feature extraction transfer learning on 1% of the data with data augmentation

```
# Setup input shape and base model, freezing the base model layers
input_shape = (224, 224, 3)
base_model = tf.keras.applications.EfficientNetB0(include_top=False)
base_model.trainable = False

# Create input layer
inputs = layers.Input(shape=input_shape, name="input_layer")
```

```
# Add in data augmentation Sequential model as a layer
x = data augmentation(inputs)
# Give base_model inputs (after augmentation) and don't train it
x = base_model(x, training=False)
# Pool output features of base model
x = layers.GlobalAveragePooling2D(name="global_average_pooling_layer")(x)
# Put a dense layer on as the output
outputs = layers.Dense(10, activation="softmax", name="output_layer")(x)
# Make a model with inputs and outputs
model_1 = keras.Model(inputs, outputs)
# Compile the model
model_1.compile(loss="categorical_crossentropy",
          optimizer=tf.keras.optimizers.Adam(),
          metrics=["accuracy"])
# Fit the model
history_1_percent = model_1.fit(train_data_1_percent,
              epochs=5.
              steps_per_epoch=len(train_data_1_percent),
              validation_data=test_data,
              validation_steps=int(0.25* len(test_data)), # validate for less steps
              # Track model training logs
              callbacks=[create_tensorboard_callback("transfer_learning", "1_percent")
   Saving TensorBoard log files to: transfer_learning/1_percent_data_aug/20210216-021736
   Epoch 1/5
   Epoch 2/5
   Epoch 3/5
   Epoch 4/5
   Epoch 5/5
```

Wow! How cool is that? Using only 7 training images per class, using transfer learning our model was able to get ~40% accuracy on the validation set. This result is pretty amazing since the <u>original Food-101 paper</u> achieved 50.67% accuracy with all the data, namely, 750 training images per class (**note:** this metric was across 101 classes, not 10, we'll get to 101 classes soon).

If we check out a summary of our model, we should see the data augmentation layer just after the input layer.

```
# Check out model summary
model 1.summary()
```

Model: "model\_1"

Layer (type)	Output Shape	Param #
<pre>input_layer (InputLayer)</pre>	[(None, 224, 224, 3)]	0
data_augmentation (Sequentia	(None, None, None, 3)	0
efficientnetb0 (Functional)	(None, None, None, 1280)	4049571
global_average_pooling_layer	(None, 1280)	0
output_layer (Dense)	(None, 10)	12810

Total params: 4,062,381 Trainable params: 12,810

Non-trainable params: 4,049,571

There it is. We've now got data augmentation built right into the our model. This means if we saved it and reloaded it somewhere else, the data augmentation layers would come with it.

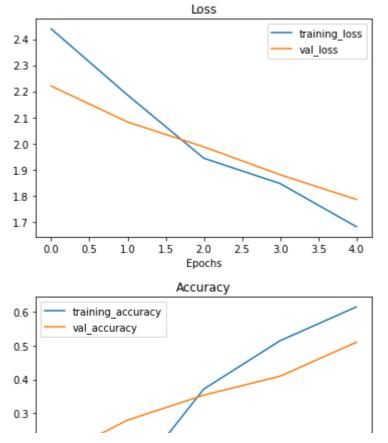
The important thing to remember is **data augmentation only runs during training**. So if we were to evaluate or use our model for inference (predicting the class of an image) the data augmentation layers will be automatically turned off.

To see this in action, let's evaluate our model on the test data.

The results here may be slightly better/worse than the log outputs of our model during training because during training we only evaluate our model on 25% of the test data using the line validation\_steps=int(0.25 \* len(test\_data)). Doing this speeds up our epochs but still gives us enough of an idea of how our model is going.

Let's stay consistent and check out our model's loss curves.

```
# How does the model go with a data augmentation layer with 1% of data
plot_loss_curves(history_1_percent)
```



It looks like the metrics on both datasets would improve if we kept training for more epochs. But we'll leave that for now, we've got more experiments to do!

...

# Model 2: Feature extraction transfer learning with 10% of data and data augmentation

Alright, we've tested 1% of the training data with data augmentation, how about we try 10% of the data with data augmentation?

But wait...

Question: How do you know what experiments to run?

Great question.

The truth here is you often won't. Machine learning is still a very experimental practice. It's only after trying a fair few things that you'll start to develop an intuition of what to try.

My advice is to follow your curiosity as tenaciously as possible. If you feel like you want to try something, write the code for it and run it. See how it goes. The worst thing that'll happen is you'll figure out what doesn't work, the most valuable kind of knowledge.

From a practical standpoint, as we've talked about before, you'll want to reduce the amount of time between your initial experiments as much as possible. In other words, run a plethora of smaller experiments, using less data and less training iterations before you find something promising and then scale it up.

In the theme of scale, let's scale our 1% training data augmentation experiment up to 10% training data augmentation. That sentence doesn't really make sense but you get what I mean.

We're going to run through the exact same steps as the previous model, the only difference being using 10% of the training data instead of 1%.

```
# Get 10% of the data of the 10 classes (uncomment if you haven't gotten "10_food_classes_
# !wget https://storage.googleapis.com/ztm_tf_course/food_vision/10_food_classes_10_percen
# unzip_data("10_food_classes_10_percent.zip")

train_dir_10_percent = "10_food_classes_10_percent/train/"
test_dir = "10_food_classes_10_percent/test/"
```

Data downloaded. Let's create the dataloaders.

Awesome! We've got 10x more images to work with, 75 per class instead of 7 per class.

Let's build a model with data augmentation built in. We could reuse the data augmentation Sequential model we created before but we'll recreate it to practice.

```
# Create a functional model with data augmentation
import tensorflow as tf
from tensorflow.keras import layers
from tensorflow.keras.layers.experimental import preprocessing
from tensorflow.keras.models import Sequential

# Build data augmentation layer
data_augmentation = Sequential([
    preprocessing.RandomFlip('horizontal'),
    preprocessing.RandomHeight(0.2),
    preprocessing.RandomWidth(0.2),
    preprocessing.RandomZoom(0.2),
    preprocessing.RandomRotation(0.2),
    # preprocessing.Rescaling(1./255) # keep for ResNet50V2, remove for EfficientNet
], name="data_augmentation")
```

```
# Setup the input shape to our model
input_shape = (224, 224, 3)
# Create a frozen base model
base_model = tf.keras.applications.EfficientNetB0(include_top=False)
base_model.trainable = False
# Create input and output layers
inputs = layers.Input(shape=input_shape, name="input_layer") # create input layer
x = data_augmentation(inputs) # augment our training images
x = base_model(x, training=False) # pass augmented images to base model but keep it in inf
x = layers.GlobalAveragePooling2D(name="global_average_pooling_layer")(x)
outputs = layers.Dense(10, activation="softmax", name="output_layer")(x)
model_2 = tf.keras.Model(inputs, outputs)
# Compile
model_2.compile(loss="categorical_crossentropy",
              optimizer=tf.keras.optimizers.Adam(lr=0.001), # use Adam optimizer with base
              metrics=["accuracy"])
```

### Creating a ModelCheckpoint callback

Our model is compiled and ready to be fit, so why haven't we fit it yet?

Well, for this experiment we're going to introduce a new callback, the ModelCheckpoint callback.

The <u>ModelCheckpoint</u> callback gives you the ability to save your model, as a whole in the <u>SavedModel</u> format or the <u>weights (patterns) only</u> to a specified directory as it trains.

This is helpful if you think your model is going to be training for a long time and you want to make backups of it as it trains. It also means if you think your model could benefit from being trained for longer, you can reload it from a specific checkpoint and continue training from there.

For example, say you fit a feature extraction transfer learning model for 5 epochs and you check the training curves and see it was still improving and you want to see if fine-tuning for another 5 epochs could help, you can load the checkpoint, unfreeze some (or all) of the base model layers and then continue training.

In fact, that's exactly what we're going to do.

But first, let's create a ModelCheckpoint callback. To do so, we have to specify a directory we'd like to save to.

**Question:** What's the difference between saving the entire model (SavedModel format) and saving the weights only?

The <u>SavedMode1</u> format saves a model's architecture, weights and training configuration all in one folder. It makes it very easy to reload your model exactly how it is elsewhere. However, if you do not want to share all of these details with others, you may want to save and share the weights only (these will just be large tensors of non-human interpretable numbers). If disk space is an issue, saving the weights only is faster and takes up less space than saving the whole model.

Time to fit the model.

Because we're going to be fine-tuning it later, we'll create a variable initial\_epochs and set it to 5 to use later.

We'll also add in our checkpoint\_callback in our list of callbacks.

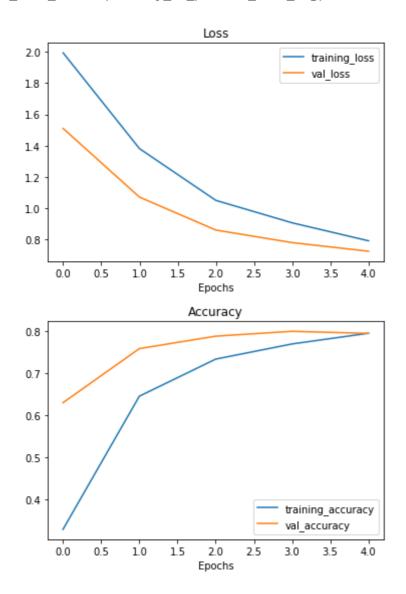
```
# Fit the model saving checkpoints every epoch
initial_epochs = 5
history 10 percent data aug = model 2.fit(train data 10 percent,
                                epochs=initial epochs,
                                validation_data=test_data,
                                validation_steps=int(0.25 * len(test_data)), # d
                                 callbacks=[create_tensorboard_callback("transfer
                                         checkpoint_callback])
   Saving TensorBoard log files to: transfer learning/10 percent data aug/20210216-0218!
    Epoch 1/5
    24/24 [============== ] - 16s 452ms/step - loss: 2.1809 - accuracy: 0
   Epoch 00001: saving model to ten_percent_model_checkpoints_weights/checkpoint.ckpt
    Epoch 2/5
    Epoch 00002: saving model to ten_percent_model_checkpoints_weights/checkpoint.ckpt
    Epoch 3/5
    Epoch 00003: saving model to ten percent model checkpoints weights/checkpoint.ckpt
    24/24 [=============== ] - 8s 338ms/step - loss: 0.9191 - accuracy: 0.7
   Epoch 00004: saving model to ten_percent_model_checkpoints_weights/checkpoint.ckpt
    Epoch 5/5
    Epoch 00005: saving model to ten percent model checkpoints weights/checkpoint.ckpt
```

Would you look at that! Looks like our ModelCheckpoint callback worked and our model saved its weights every epoch without too much overhead (saving the whole model takes longer than

just the weights).

Let's evaluate our model and check its loss curves.

# Plot model loss curves
plot\_loss\_curves(history\_10\_percent\_data\_aug)



Looking at these, our model's performance with 10% of the data and data augmentation isn't as good as the model with 10% of the data without data augmentation (see <code>model\_0</code> results above), however the curves are trending in the right direction, meaning if we decided to train for longer, its metrics would likely improve.

Since we checkpointed (is that a word?) our model's weights, we might as well see what it's like to load it back in. We'll be able to test if it saved correctly by evaluting it on the test data.

To load saved model weights you can use the the <u>load\_weights()</u> method, passing it the path where your saved weights are stored.

Now let's compare the results of our previously trained model and the loaded model. These results should very close if not exactly the same. The reason for minor differences comes down to the precision level of numbers calculated.

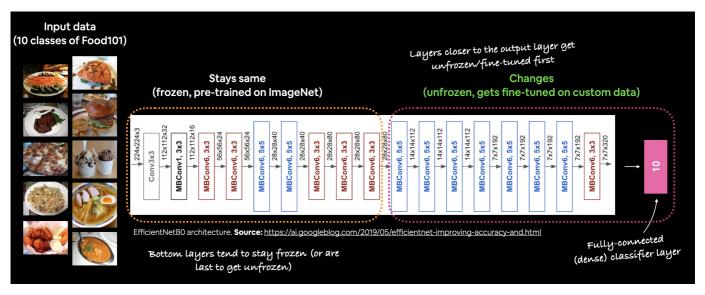
```
# If the results from our native model and the loaded weights are the same, this should ou results_10_percent_data_aug == loaded_weights_model_results
```

False

If the above cell doesn't output True, it's because the numbers are close but not the *exact* same (due to how computers store numbers with degrees of precision).

However, they should be very close...

### Model 3: Fine-tuning an existing model on 10% of the data



High-level example of fine-tuning an EfficientNet model. Bottom layers (layers closer to the input data) stay frozen where as top layers (layers closer to the output data) are updated during training.

So far our saved model has been trained using feature extraction transfer learning for 5 epochs on 10% of the training data and data augmentation.

This means all of the layers in the base model (EfficientNetB0) were frozen during training.

For our next experiment we're going to switch to fine-tuning transfer learning. This means we'll be using the same base model except we'll be unfreezing some of its layers (ones closest to the top) and running the model for a few more epochs.

The idea with fine-tuning is to start customizing the pre-trained model more to our own data.

Note: Fine-tuning usually works best *after* training a feature extraction model for a few epochs and with large amounts of data.

We've verified our loaded model's performance, let's check out its layers.

True

Looking good. We've got an input layer, a Sequential layer (the data augmentation model), a Functional layer (EfficientNetB0), a pooling layer and a Dense layer (the output layer).

How about a summary?

#### model\_2.summary()

Model: "model\_2"

Layer (type)	Output Shape	Param #
input_layer (InputLayer)	[(None, 224, 224, 3)]	0
data_augmentation (Sequentia	(None, None, None, 3)	0
efficientnetb0 (Functional)	(None, None, None, 1280)	4049571
global_average_pooling_layer	(None, 1280)	0
output_layer (Dense)	(None, 10)	12810
Total params: 4,062,381		

Total params: 4,062,381 Trainable params: 12,810

Non-trainable params: 4,049,571

Alright, it looks like all of the layers in the efficientnetb0 layer are frozen. We can confirm this using the trainable\_variables attribute.

```
# How many layers are trainable in our base model?
print(len(model_2.layers[2].trainable_variables)) # layer at index 2 is the EfficientNetB0
```

This is the same as our base model.

0

0

```
print(len(base_model.trainable_variables))
```

We can even check layer by layer to see if the they're trainable.

```
4 stem conv False
5 stem bn False
6 stem activation False
7 block1a dwconv False
8 block1a_bn False
9 block1a_activation False
10 block1a_se_squeeze False
11 block1a_se_reshape False
12 block1a se reduce False
13 block1a_se_expand False
14 block1a_se_excite False
15 block1a_project_conv False
16 block1a_project_bn False
17 block2a_expand_conv False
18 block2a_expand_bn False
19 block2a expand activation False
20 block2a_dwconv_pad False
21 block2a_dwconv False
22 block2a_bn False
23 block2a_activation False
24 block2a_se_squeeze False
25 block2a_se_reshape False
26 block2a_se_reduce False
27 block2a_se_expand False
28 block2a_se_excite False
29 block2a_project_conv False
30 block2a project bn False
31 block2b_expand_conv False
32 block2b_expand_bn False
33 block2b_expand_activation False
34 block2b dwconv False
35 block2b_bn False
36 block2b_activation False
37 block2b_se_squeeze False
38 block2b_se_reshape False
39 block2b_se_reduce False
40 block2b_se_expand False
41 block2b_se_excite False
42 block2b_project_conv False
43 block2b project bn False
44 block2b drop False
45 block2b add False
46 block3a_expand_conv False
47 block3a_expand_bn False
48 block3a expand activation False
49 block3a_dwconv_pad False
50 block3a dwconv False
51 block3a_bn False
52 block3a activation False
53 block3a_se_squeeze False
54 block3a se reshape False
55 block3a se reduce False
56 block3a se expand False
57 block3a se excite False
50 hlock22 project conv Ealco
```

Beautiful. This is exactly what we're after.

Now to fine-tune the base model to our own data, we're going to unfreeze the top 10 layers and continue training our model for another 5 epochs.

This means all of the base model's layers except for the last 10 will remain frozen and untrainable. And the weights in the remaining unfrozen layers will be updated during training. Ideally, we should see the model's performance improve.

Question: How many layers should you unfreeze when training?

There's no set rule for this. You could unfreeze every layer in the pretrained model or you could try unfreezing one layer at a time. Best to experiment with different amounts of unfreezing and fine-tuning to see what happens. Generally, the less data you have, the less layers you want to unfreeze and the more gradually you want to fine-tune.

Resource: The <u>ULMFiT (Universal Language Model Fine-tuning for Text Classification) paper</u> has a great series of experiments on fine-tuning models.

To begin fine-tuning, we'll unfreeze the entire base model by setting its trainable attribute to True. Then we'll refreeze every layer in the base model except for the last 10 by looping through them and setting their trainable attribute to False. Finally, we'll recompile the model.

Wonderful, now let's check which layers of the pretrained model are trainable.

```
# Check which layers are tuneable (trainable)
for layer number, layer in enumerate(base model.layers):
  print(layer number, layer.name, layer.trainable)
     0 input_3 False
     1 rescaling 2 False
     2 normalization 2 False
     3 stem_conv_pad False
     4 stem_conv False
     5 stem_bn False
     6 stem_activation False
     7 block1a dwconv False
     8 block1a bn False
     9 block1a activation False
     10 block1a_se_squeeze False
     11 block1a_se_reshape False
     12 block1a_se_reduce False
     13 block1a se expand False
     14 block1a_se_excite False
```

```
15 block1a_project_conv False
16 block1a_project_bn False
17 block2a expand conv False
18 block2a expand bn False
19 block2a expand activation False
20 block2a_dwconv_pad False
21 block2a_dwconv False
22 block2a_bn False
23 block2a activation False
24 block2a_se_squeeze False
25 block2a_se_reshape False
26 block2a_se_reduce False
27 block2a_se_expand False
28 block2a_se_excite False
29 block2a_project_conv False
30 block2a project bn False
31 block2b_expand_conv False
32 block2b_expand_bn False
33 block2b_expand_activation False
34 block2b_dwconv False
35 block2b bn False
36 block2b_activation False
37 block2b_se_squeeze False
38 block2b_se_reshape False
39 block2b_se_reduce False
40 block2b_se_expand False
41 block2b se excite False
42 block2b_project_conv False
43 block2b_project_bn False
44 block2b_drop False
45 block2b_add False
46 block3a_expand_conv False
47 block3a_expand_bn False
48 block3a expand activation False
49 block3a_dwconv_pad False
50 block3a_dwconv False
51 block3a_bn False
52 block3a_activation False
53 block3a_se_squeeze False
54 block3a se reshape False
55 block3a se reduce False
56 block3a se expand False
57 block3a_se_excite False
58 block3a_project_conv False
```

Nice! It seems all layers except for the last 10 are frozen and untrainable. This means only the last 10 layers of the base model along with the output layer will have their weights updated during training.

(F) Question: Why did we recompile the model?

Every time you make a change to your models, you need to recompile them.

In our case, we're using the exact same loss, optimizer and metrics as before, except this time the learning rate for our optimizer will be 10x smaller than before (0.0001 instead of Adam's default of 0.001).

We do this so the model doesn't try to overwrite the existing weights in the pretrained model too fast. In other words, we want learning to be more gradual.

Note: There's no set standard for setting the learning rate during fine-tuning, though reductions of 2.6x-10x+ seem to work well in practice.

How many trainable variables do we have now?

```
print(len(model_2.trainable_variables))
12
```

# Fine tune for another 5 epochs

Wonderful, it looks like our model has a total of 10 trainable variables, the last 10 layers of the base model and the weight and bias parameters of the Dense output layer.

Time to fine-tune!

We're going to continue training on from where our previous model finished. Since it trained for 5 epochs, our fine-tuning will begin on the epoch 5 and continue for another 5 epochs.

To do this, we can use the initial\_epoch parameter of the <u>fit()</u> method. We'll pass it the last epoch of the previous model's training history (history\_10\_percent\_data\_aug.epoch[-1]).

```
fine_tune_epochs = initial_epochs + 5
# Refit the model (same as model_2 except with more trainable layers)
history_fine_10_percent_data_aug = model_2.fit(train_data_10_percent,
                           epochs=fine_tune_epochs,
                           validation_data=test_data,
                           initial_epoch=history_10_percent_data_aug.e
                           validation_steps=int(0.25 * len(test_data))
                           callbacks=[create tensorboard callback("tra
  Saving TensorBoard log files to: transfer_learning/10_percent_fine_tune_last_10/2021@
  Epoch 5/10
  Epoch 6/10
  24/24 [============== ] - 8s 329ms/step - loss: 0.5747 - accuracy: 0.8
  Epoch 7/10
  Epoch 8/10
  Epoch 9/10
  Epoch 10/10
```

Note: Fine-tuning usually takes far longer per epoch than feature extraction (due to updating more weights throughout a network).

Remember, the results from evaluating the model might be slightly different to the outputs from training since during training we only evaluate on 25% of the test data.

Alright, we need a way to evaluate our model's performance before and after fine-tuning. How about we write a function to compare the before and after?

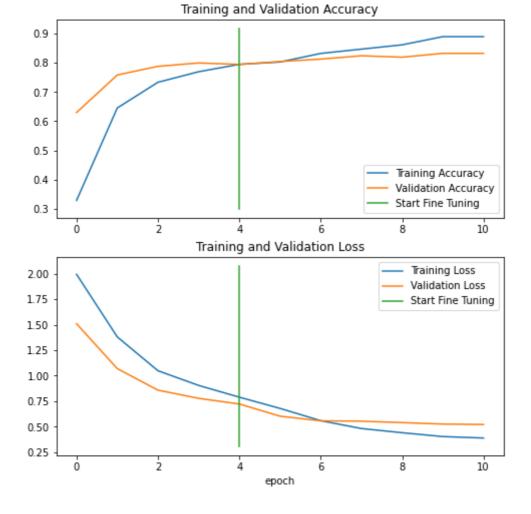
```
def compare_historys(original_history, new_history, initial_epochs=5):
   Compares two model history objects.
   # Get original history measurements
   acc = original_history.history["accuracy"]
   loss = original_history.history["loss"]
   print(len(acc))
   val_acc = original_history.history["val_accuracy"]
   val loss = original history.history["val loss"]
   # Combine original history with new history
   total_acc = acc + new_history.history["accuracy"]
   total_loss = loss + new_history.history["loss"]
   total_val_acc = val_acc + new_history.history["val_accuracy"]
   total val loss = val loss + new history.history["val loss"]
   print(len(total_acc))
   print(total acc)
   # Make plots
   plt.figure(figsize=(8, 8))
   plt.subplot(2, 1, 1)
   plt.plot(total_acc, label='Training Accuracy')
   plt.plot(total_val_acc, label='Validation Accuracy')
   plt.plot([initial epochs-1, initial epochs-1],
              plt.ylim(), label='Start Fine Tuning') # reshift plot around epochs
   plt.legend(loc='lower right')
   plt.title('Training and Validation Accuracy')
   plt.subplot(2, 1, 2)
   plt.plot(total loss, label='Training Loss')
   plt.plot(total_val_loss, label='Validation Loss')
   plt.plot([initial_epochs-1, initial_epochs-1],
              nl+ vlim() label='Chant Eine Tuning'\ # nachift nlot anound enache
```

```
pic.yiim(), label= Start Fine runing ) # result piot around epochs
plt.legend(loc='upper right')
plt.title('Training and Validation Loss')
plt.xlabel('epoch')
plt.show()
```

This is where saving the history variables of our model training comes in handy. Let's see what happened after fine-tuning the last 10 layers of our model.

5

11 [0.3293333351612091, 0.64533333497047424, 0.7333333492279053, 0.76933333625793457, 0.79



Alright, alright, seems like the curves are heading in the right direction after fine-tuning. But remember, it should be noted that fine-tuning usually works best with larger amounts of data.

## Model 4: Fine-tuning an existing model all of the data

Enough talk about how fine-tuning a model usually works with more data, let's try it out.

We'll start by downloading the full version of our 10 food classes dataset.

```
# Download and unzip 10 classes of data with all images
!wget https://storage.googleapis.com/ztm tf course/food vision/10 food classes all data.zi
unzip data("10 food classes all data.zip")
# Setup data directories
train dir = "10 food classes all data/train/"
test dir = "10 food classes all data/test/"
     --2021-02-16 02:48:30-- <a href="https://storage.googleapis.com/ztm">https://storage.googleapis.com/ztm</a> tf course/food vision/10
     Resolving storage.googleapis.com (storage.googleapis.com)... 172.217.164.144, 172.25
     Connecting to storage.googleapis.com (storage.googleapis.com) | 172.217.164.144 | :443...
     HTTP request sent, awaiting response... 200 OK
     Length: 519183241 (495M) [application/zip]
     Saving to: '10_food_classes_all_data.zip'
     10 food classes all 100%[===========] 495.13M 124MB/s in 4.1s
     2021-02-16 02:48:35 (121 MB/s) - '10_food_classes_all_data.zip' saved [519183241/5191
# How many images are we working with now?
walk_through_dir("10_food_classes_all_data")
     There are 2 directories and 0 images in '10_food_classes_all_data'.
     There are 10 directories and 0 images in '10_food_classes_all_data/train'.
     There are 0 directories and 750 images in '10_food_classes_all_data/train/ice_cream'
     There are 0 directories and 750 images in '10_food_classes_all_data/train/ramen'.
     There are 0 directories and 750 images in '10_food_classes_all_data/train/chicken_wir
     There are 0 directories and 750 images in '10_food_classes_all_data/train/pizza'.
     There are 0 directories and 750 images in '10_food_classes_all_data/train/steak'.
     There are 0 directories and 750 images in '10_food_classes_all_data/train/fried_rice
     There are 0 directories and 750 images in '10_food_classes_all_data/train/hamburger'
     There are 0 directories and 750 images in '10_food_classes_all_data/train/grilled_sal
     There are 0 directories and 750 images in '10_food_classes_all_data/train/sushi'.
     There are 0 directories and 750 images in '10_food_classes_all_data/train/chicken_cur
     There are 10 directories and 0 images in '10 food classes all data/test'.
     There are 0 directories and 250 images in '10_food_classes_all_data/test/ice_cream'.
     There are 0 directories and 250 images in '10_food_classes_all_data/test/ramen'.
     There are 0 directories and 250 images in '10 food classes all data/test/chicken wing
     There are 0 directories and 250 images in '10_food_classes_all_data/test/pizza'.
     There are 0 directories and 250 images in '10_food_classes_all_data/test/steak'.
     There are 0 directories and 250 images in '10_food_classes_all_data/test/fried_rice'
     There are 0 directories and 250 images in '10 food classes all data/test/hamburger'.
     There are 0 directories and 250 images in '10_food_classes_all_data/test/grilled_salm
     There are 0 directories and 250 images in '10_food_classes_all_data/test/sushi'.
     There are 0 directories and 250 images in '10_food_classes_all_data/test/chicken_curr
```

And now we'll turn the images into tensors datasets.

```
train data id classes tull = tt.keras.preprocessing.image dataset trom directory(train dir
                                                                                    label mod
                                                                                    image siz
# Note: this is the same test dataset we've been using for the previous modelling experime
test_data = tf.keras.preprocessing.image_dataset_from_directory(test_dir,
                                                                  label mode="categorical",
                                                                  image_size=IMG_SIZE)
     Found 7500 files belonging to 10 classes.
     Found 2500 files belonging to 10 classes.
Oh this is looking good. We've got 10x more images in of the training classes to work with.
The test dataset is the same we've been using for our previous experiments.
```

As it is now, our model 2 has been fine-tuned on 10 percent of the data, so to begin fine-tuning on all of the data and keep our experiments consistent, we need to revert it back to the weights we checkpointed after 5 epochs of feature-extraction.

To demonstrate this, we'll first evaluate the current model 2.

```
# Evaluate model (this is the fine-tuned 10 percent of data version)
model_2.evaluate(test_data)
    79/79 [============ ] - 10s 118ms/step - loss: 0.4870 - accuracy: 0
    [0.4869591295719147, 0.8388000130653381]
```

These are the same values as results fine tune 10 percent.

```
results_fine_tune_10_percent
     [0.48695918917655945, 0.8388000130653381]
```

Now we'll revert the model back to the saved weights.

[0.7046542763710022, 0.8080000281333923]

# Load model from checkpoint, that way we can fine-tune from the same stage the 10 percent model\_2.load\_weights(checkpoint\_path) # revert model back to saved weights

```
<tensorflow.python.training.tracking.util.CheckpointLoadStatus at 0x7fcd9da1e4a8>
```

And the results should be the same as results\_10\_percent\_data\_aug.

```
# After loading the weights, this should have gone down (no fine-tuning)
model 2.evaluate(test data)
    79/79 [============ ] - 10s 117ms/step - loss: 0.7047 - accuracy: 0
```

```
# Check to see if the above two results are the same (they should be)
results_10_percent_data_aug
```

[0.7046541571617126, 0.8080000281333923]

Alright, the previous steps might seem quite confusing but all we've done is:

- 1. Trained a feature extraction transfer learning model for 5 epochs on 10% of the data (with all base model layers frozen) and saved the model's weights using ModelCheckpoint.
- 2. Fine-tuned the same model on the same 10% of the data for a further 5 epochs with the top 10 layers of the base model unfrozen.
- 3. Saved the results and training logs each time.
- 4. Reloaded the model from 1 to do the same steps as 2 but with all of the data.

The same steps as 2?

Yeah, we're going to fine-tune the last 10 layers of the base model with the full dataset for another 5 epochs but first let's remind ourselves which layers are trainable.

```
# Check which layers are tuneable in the whole model
for layer number, layer in enumerate(model 2.layers):
  print(layer_number, layer.name, layer.trainable)
     0 input_layer True
     1 data_augmentation True
     2 efficientnetb0 True
     3 global_average_pooling_layer True
     4 output_layer True
Can we get a little more specific?
# Check which layers are tuneable in the base model
for layer number, layer in enumerate(base model.layers):
  print(layer number, layer.name, layer.trainable)
     0 input_3 False
     1 rescaling_2 False
     2 normalization 2 False
     3 stem_conv_pad False
     4 stem conv False
     5 stem_bn False
     6 stem activation False
     7 block1a_dwconv False
     8 block1a bn False
     9 block1a activation False
     10 block1a_se_squeeze False
     11 block1a_se_reshape False
```

12 block1a\_se\_reduce False
13 block1a\_se\_expand False
14 block1a\_se\_excite False
15 block1a project conv False

```
16 block1a_project_bn False
17 block2a_expand_conv False
18 block2a expand bn False
19 block2a_expand_activation False
20 block2a dwconv pad False
21 block2a_dwconv False
22 block2a_bn False
23 block2a_activation False
24 block2a_se_squeeze False
25 block2a_se_reshape False
26 block2a_se_reduce False
27 block2a_se_expand False
28 block2a_se_excite False
29 block2a_project_conv False
30 block2a_project_bn False
31 block2b expand conv False
32 block2b_expand_bn False
33 block2b_expand_activation False
34 block2b_dwconv False
35 block2b_bn False
36 block2b activation False
37 block2b_se_squeeze False
38 block2b_se_reshape False
39 block2b_se_reduce False
40 block2b_se_expand False
41 block2b_se_excite False
42 block2b project conv False
43 block2b_project_bn False
44 block2b drop False
45 block2b_add False
46 block3a_expand_conv False
47 block3a_expand_bn False
48 block3a expand activation False
49 block3a_dwconv_pad False
50 block3a dwconv False
51 block3a_bn False
52 block3a_activation False
53 block3a_se_squeeze False
54 block3a_se_reshape False
55 block3a se reduce False
56 block3a se expand False
57 block3a se excite False
```

Looking good! The last 10 layers are trainable (unfrozen).

50 hlock22 project conv Ealco

We've got one more step to do before we can begin fine-tuning.

Do you remember what it is?

I'll give you a hint. We just reloaded the weights to our model and what do we need to do every time we make a change to our models?

Recompile them!

This will be just as before.

```
metrics=["accuracy"])
```

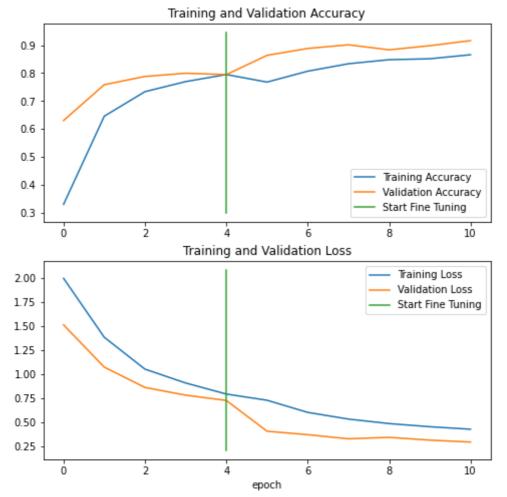
Alright, time to fine-tune on all of the data!

```
# Continue to train and fine-tune the model to our data
fine_tune_epochs = initial_epochs + 5
history fine 10 classes full = model 2.fit(train data 10 classes full,
                              epochs=fine tune epochs,
                              initial_epoch=history_10_percent_data_aug.epoch
                              validation_data=test_data,
                              validation_steps=int(0.25 * len(test_data)),
                              callbacks=[create_tensorboard_callback("transfe
   Saving TensorBoard log files to: transfer_learning/full_10_classes_fine_tune_last_10/
   Epoch 5/10
   235/235 [============= ] - 49s 190ms/step - loss: 0.7943 - accuracy:
   Epoch 6/10
   Epoch 7/10
   Epoch 8/10
   235/235 [============= ] - 46s 192ms/step - loss: 0.5030 - accuracy:
   Epoch 9/10
   235/235 [============= ] - 45s 191ms/step - loss: 0.4611 - accuracy:
   Epoch 10/10
```

Note: Training took longer per epoch, but that makes sense because we're using 10x more training data than before.

Let's evaluate on all of the test data.

Nice! It looks like fine-tuning with all of the data has given our model a boost, how do the training curves look?



Looks like that extra data helped! Those curves are looking great. And if we trained for longer, they might even keep improving.

## Viewing our experiment data on TensorBoard

Right now our experimental results are scattered all throughout our notebook. If we want to share them with someone, they'd be getting a bunch of different graphs and metrics... not a fun time.

But guess what?

Thanks to the TensorBoard callback we made with our helper function create\_tensorflow\_callback(), we've been tracking our modelling experiments the whole time.

How about we upload them to TensorBoard.dev and check them out?

We can do with the tensorboard dev upload command and passing it the directory where our experiments have been logged.

Note: Remember, whatever you upload to TensorBoard.dev becomes public. If there are training logs you don't want to share, don't upload them.

```
# View tensorboard logs of transfer learning modelling experiments (should be 4 models)
# Upload TensorBoard dev records
!tensorboard dev upload --logdir ./transfer_learning \
    --name "Transfer learning experiments" \
    --description "A series of different transfer learning experiments with varying amounts
    --one shot # exits the uploader when upload has finished
```

2020-09-17 22:51:36.043126: I tensorflow/stream\_executor/platform/default/dso\_loader Data for the "graphs" plugin is now uploaded to TensorBoard.dev! Note that uploaded to Data for the "histograms" plugin is now uploaded to TensorBoard.dev! Note that uploaded Data for the "hparams" plugin is now uploaded to TensorBoard.dev! Note that uploaded Upload started and will continue reading any new data as it's added to the logdir. To stop uploading, press Ctrl-C.

View your TensorBoard live at: <a href="https://tensorboard.dev/experiment/2076kw3PQbK101Byfg">https://tensorboard.dev/experiment/2076kw3PQbK101Byfg</a>;

```
[2020-09-17T22:51:37] Uploader started.
[2020-09-17T22:51:47] Total uploaded: 128 scalars, 0 tensors, 5 binary objects (9.1 National Listening for new data in logdir...

Done. View your TensorBoard at https://tensorboard.dev/experiment/2076kw3PQbKl01Byfg;
```

Once we've uploaded the results to TensorBoard.dev we get a shareable link we can use to view and compare our experiments and share our results with others if needed.

You can view the original versions of the experiments we ran in this notebook here: <a href="https://tensorboard.dev/experiment/2076kw3PQbKl0IByfg5B4w/">https://tensorboard.dev/experiment/2076kw3PQbKl0IByfg5B4w/</a>

**Question:** Which model performed the best? Why do you think this is? How did fine-tuning go?

To find all of your previous TensorBoard.dev experiments using the command tensorboard dev list.

```
# View previous experiments
!tensorboard dev list
```

2020-09-17 22:51:48.747476: I tensorflow/stream\_executor/platform/default/dso\_loader Data for the "graphs" plugin is now uploaded to TensorBoard.dev! Note that uploaded to Data for the "histograms" plugin is now uploaded to TensorBoard.dev! Note that uploaded Data for the "hparams" plugin is now uploaded to TensorBoard.dev! Note that uploaded https://tensorboard.dev/experiment/2076kw3PQbKl0lByfg5B4w/

Transfer learning experiments Name Description A series of different transfer learning experiments with Ιd 2076kw3PQbKl0lByfg5B4w Created 2020-09-17 22:51:37 (15 seconds ago) 2020-09-17 22:51:47 (5 seconds ago) Updated Runs 10 Tags 3 Scalars 128 Tensor bytes Binary object bytes 9520961

https://tensorboard.dev/experiment/73taSKxXQeGPQsNBcVvY3g/

Name EfficientNetB0 vs. ResNet50V2

Description Comparing two different TF Hub feature extraction models

```
      Id
      73taSKxXQeGPQsNBcVvY3g

      Created
      2020-09-14 05:02:48

      Updated
      2020-09-14 05:02:50
```

Runs 4
Tags 3
Scalars 40
Tensor bytes 0

Binary object bytes 3402042

Total: 2 experiment(s)

And if you want to remove a previous experiment (and delete it from public viewing) you can use the command:

tensorboard dev delete --experiment\_id [INSERT\_EXPERIMENT\_ID\_TO\_DELETE]

- # Remove previous experiments
- # !tensorboard dev delete --experiment\_id OUbW0O3pRqqQgAphVBxi8Q

2020-09-17 22:51:53.982454: I tensorflow/stream\_executor/platform/default/dso\_loader Data for the "graphs" plugin is now uploaded to TensorBoard.dev! Note that uploaded c Data for the "histograms" plugin is now uploaded to TensorBoard.dev! Note that uploace Data for the "hparams" plugin is now uploaded to TensorBoard.dev! Note that uploaded No such experiment OUbW0O3pRqqQgAphVBxi8Q. Either it never existed or it has already

### **\*** Exercises

- 1. Write a function to visualize an image from any dataset (train or test file) and any class (e.g. "steak", "pizza"... etc), visualize it and make a prediction on it using a trained model.
- 2. Use feature-extraction to train a transfer learning model on 10% of the Food Vision data for 10 epochs using <a href="mailto:tf-keras.applications.EfficientNetB0">tf-keras.applications.EfficientNetB0</a> as the base model. Use the <a href="ModelCheckpoint">ModelCheckpoint</a> callback to save the weights to file.
- 3. Fine-tune the last 20 layers of the base model you trained in 2 for another 10 epochs. How did it go?
- 4. Fine-tune the last 30 layers of the base model you trained in 2 for another 10 epochs. How did it go?

### 

- Read the <u>documentation on data augmentation</u> in TensorFlow.
- Read the <u>ULMFit paper</u> (technical) for an introduction to the concept of freezing and unfreezing different layers.
- Read up on learning rate scheduling (there's a <u>TensorFlow callback</u> for this), how could this influence our model training?

If you're training for longer, you probably want to reduce the learning rate as you go...
the closer you get to the bottom of the hill, the smaller steps you want to take.
Imagine it like finding a coin at the bottom of your couch. In the beginning your arm
movements are going to be large and the closer you get, the smaller your movements
become.