2ab) Explicit Version

fx >>

```
Z Editor - D:\Users\jpearc6\Documents\MATLAB\HouseHolder.m

▼ x
   HouseHolder.m × +
1  function [Q,R] = HouseHolder(A)
2
3 -
      [m, n] = size(A);
 4
 5 -
      R = A;
 6 -
     Q = eye(m);
 7 - for k = 1:n
8 -
         u = R(k:m,k);
9 -
         e = zeros(length(u),1); e(1) = 1;
10 -
         v = u - norm(u)*e;
11
         H = eye(m);
12 -
13 -
         H(k:m, k:m) = H(k:m, k:m) - (2/(v'*v))*(v*v');
14
15 -
         R = H'*R;
16 -
         Q = Q*H;
17 -
     end
Command Window
                                                                                                            0
                                                                                                             ×
New to MATLAB? See resources for Getting Started.
  >> [Q,R] = HouseHolder(A)
  0 =
     0.7071 -0.5883 0.1903 0.3430
         0 0.3922 0.9037 0.1715
     0.7071 0.5883 -0.1903 -0.3430
         0 0.3922 -0.3330 0.8575
  R =
     1.4142 -0.7071 0.7071
             2.5495 0.1961
     -0.0000
     0.0000 0.0000 3.2344
      0.0000 0.0000
                             0
```

2ab) Implicit Version

2.5495

0

0.0000 0

fx >>

0.1961 3.2344

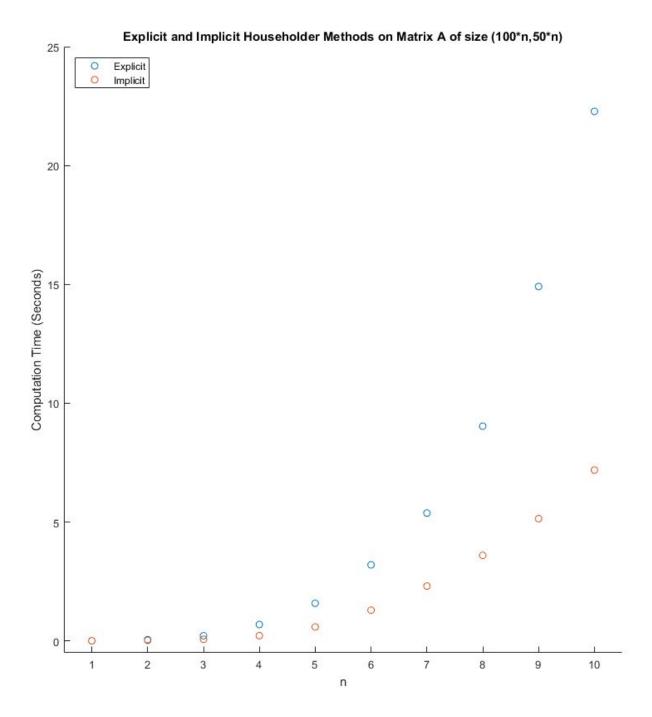
0 3.2344 0 -0.0000

```
Editor - D:\Users\jpearc6\Documents\MATLAB\HouseHolderlm.m
HouseHolderlm.m × +
 1  function [Q,R] = HouseHolderIm(A)
                                                                                                              ^
 2
 3 -
      [m,n] = size(A);
 4 -
     V = zeros(m,n);
 5 -
     R = A;
 6 - for k = 1:n
 7 -
         u = R(k:m,k);
 8 -
         e = zeros(length(u),1); e(1) = 1;
 9 -
          v = u - norm(u) *e;
10 -
          v = v/norm(v);
11
12 -
          R(k:m,k:n) = (R(k:m,k:n)-(2*v*(v'*R(k:m,k:n))));
13 -
          V(k:m,k) = v; %keep vectors to recover Q
14 -
      end
15
16 -
      Q = eye(m);
17
18 - for j=n:-1:1
19 -
        v = V(j:m,j);
20 -
          Q(j:m,j:m) = Q(j:m,j:m) - 2*v*(v' * Q(j:m,j:m));
21 -
                                                                                                               0
Command Window
New to MATLAB? See resources for Getting Started.
  >> [Q,R] = HouseHolderIm(A)
  Q =
      0.7071 -0.5883 0.1903 0.3430
         0 0.3922 0.9037 0.1715
      0.7071 0.5883 -0.1903 -0.3430
          0 0.3922 -0.3330 0.8575
  R =
                       0.7071
      1.4142 -0.7071
```

2c) Code and Output

fx >>

```
Editor - D:\Users\jpearc6\Documents\MATLAB\compareHouseholderV1V2.m
                                                                                                           HouseHolderIm.m × compareHouseholderV1V2.m × HouseHolder.m × +
1 _ function [expTimes, imTimes] = compareHouseholderV1V2(n)
2
3 -
       expTimes = zeros(1,10);
4 -
      imTimes = zeros(1,10);
5
 6 - for k = 1:n
7 -
         A =randn (100 * k, 50 * k);
8
         %Explicit Method
9 -
         tic;
10 -
         HouseHolder(A);
11 -
         expTimes(k) = toc;
12
         %Implicit Method
13 -
         tic;
         HouseHolderIm(A);
14 -
15 -
          imTimes(k) = toc;
     end
16 -
                                                                                                             0
Command Window
                                                                                                              ×
New to MATLAB? See resources for Getting Started.
  >> [Explicit, Implicit] = compareHouseholderV1V2(10)
  Explicit =
     0.0072 0.0501 0.2181 0.6892 1.5830 3.1996 5.3804 9.0319 14.9093 22.2760
  Implicit =
      0.0037 0.0250 0.0681 0.2191 0.5875 1.2932 2.3080 3.5981 5.1426 7.1873
```



As in class the least squares problem can be represented as follows:

$$min_{\alpha} ||y - A\alpha||_2$$

Where,

$$y = (0.0131, 0.0542, 0.1652, 0.5614, 1.6412, 2.9546, 4.9099, 8.3626, 10.9059, 15.4361)^T$$

$$n = (1, 2, 3, 4, 5, 6, 7, 8, 9, 10)^T$$

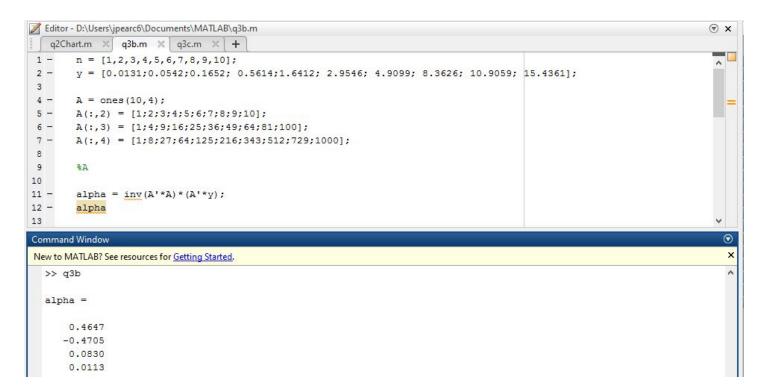
$$A = (n^0, n^1, n^2, n^3)$$

$$\alpha = (w_0, w_1, w_2, w_3)^T$$

3)b)

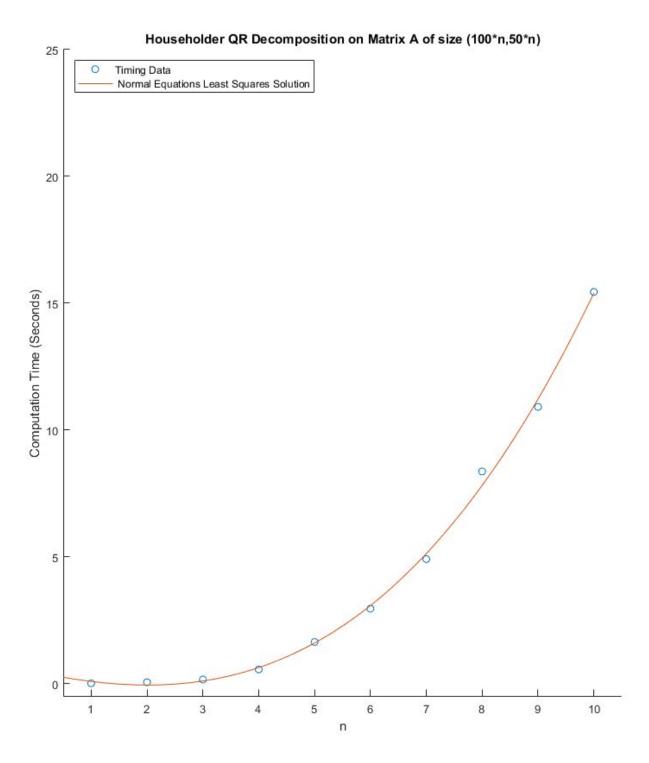
$$\alpha = (A^T A)^{-1} (A^T y)$$

Using Matlab to solve for α :



Normal Equations Least Squares Cubic Polynomial Solution:

$$time(x) = 0.4647 - 0.4705x + 0.0830x^2 + 0.0113x^3$$



Given the reduced QR decomposition of A,

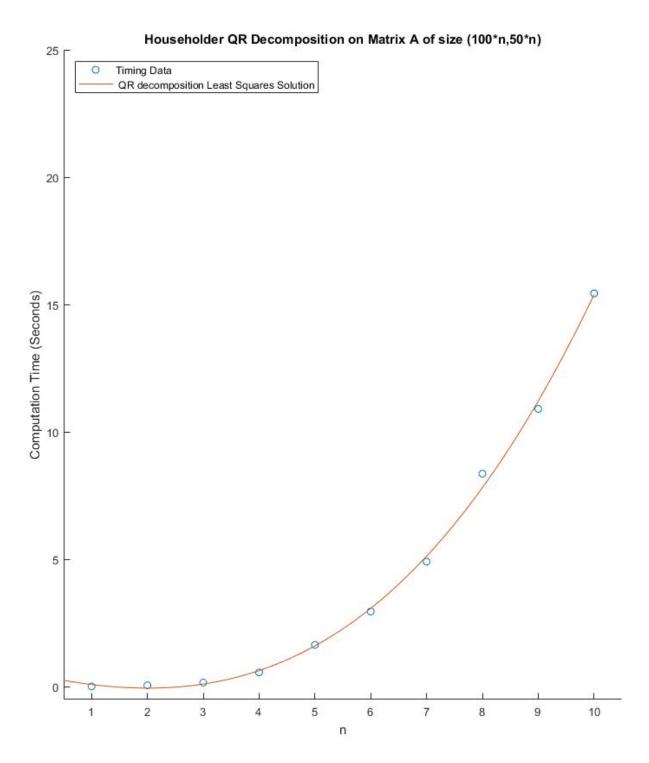
$$\alpha = R^{-1}(Q^T y)$$

Using Matlab to solve for α :

```
Editor - D:\Users\jpearc6\Documents\MATLAB\q3c.m
                                                                                                                      q2Chart.m × q3b.m × q3c.m × +
     n = [1,2,3,4,5,6,7,8,9,10];
      times = [0.0131;0.0542;0.1652; 0.5614;1.6412; 2.9546; 4.9099; 8.3626; 10.9059; 15.4361];
2 -
3
       A = ones(10,4);
       A(:,2) = [1;2;3;4;5;6;7;8;9;10];
       A(:,3) = [1;4;9;16;25;36;49;64;81;100];
       A(:,4) = [1;8;27;64;125;216;343;512;729;1000];
10
11 -
       [Q,R] = qr(A,0);
12 -
       alpha = inv(R)*(Q'*times);
13 -
       alpha
                                                                                                                         •
Command Window
                                                                                                                          ×
New to MATLAB? See resources for Getting Started.
  >> q3c
  alpha =
      0.4647
     -0.4705
      0.0830
      0.0113
```

QR Decomposition Least Squares Cubic Polynomial Solution:

$$time(x) = 0.4647 - 0.4705x + 0.0830x^2 + 0.0113x^3$$



3d)i)

750 x 375 Matrix. Therefore $x = \frac{750}{100} = 7.5$

$$time(7.5) = 0.4647 - 0.4705(7.5) + 0.0830(7.5)^2 + 0.0113(7.5)^3 = 6.372$$

According to my model, I expect this Householder algorithm to run for 6.372 seconds for a 750 x 375 size matrix 3d)ii)

10000 x 5000 Matrix. Therefore $x = \frac{10000}{100} = 100$

$$time(100) = 0.4647 - 0.4705(100) + 0.0830(100)^2 + 0.0113(100)^3 = 12083.415$$

According to my model, I expect this Householder algorithm to run for 12083.415 seconds for a 10000 x 5000 size matrix