

### Formula One - Presentation

ACU 2019 Team



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Racing 101

### Reminders

#### Reminder

A car can perform various instructions:

- accelerate
- brake
- turn
- ٠.

#### Problem

How do we order these instructions to reach our goal?





- Go slow
- One instruction at a time
- Safe trajectory



```
function ChooseMove()
{
   if angle is not right then
       TurnRightOrLeft()
   else if speed is too high
       Brake()
   else
       Accelerate()
}
```



• correct the angle beween the car and the checkpoint



- · correct the angle beween the car and the checkpoint
- · drive towards the checkpoint



- · correct the angle beween the car and the checkpoint
- · drive towards the checkpoint
- stop on the checkpoint



- · correct the angle beween the car and the checkpoint
- · drive towards the checkpoint
- stop on the checkpoint
- Rince and repeat





### Goal

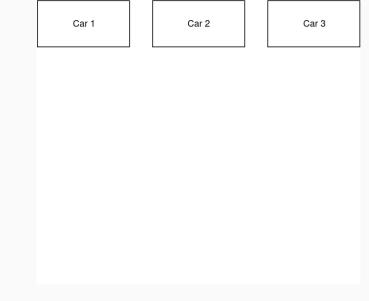
- · We want to select the best next instruction
- We can't afford to go random



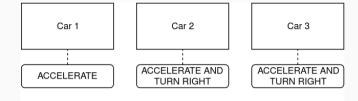
#### Overview

- · Create a clone
- · Make it execute some instructions
- Analyze the result
- · Select the next instruction depending on the result

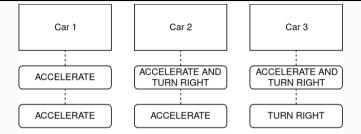




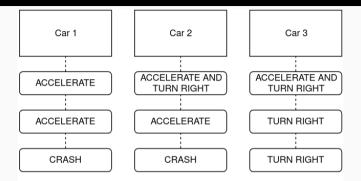




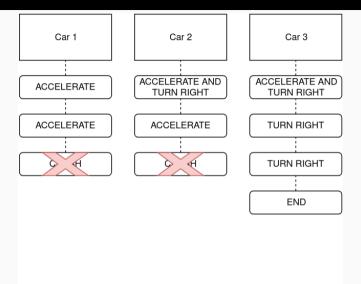




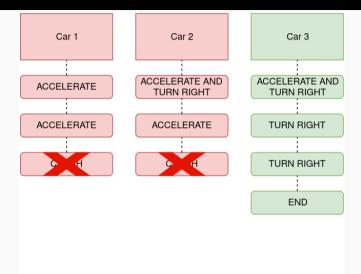
















## **Going further**

- Use sin/cos for your angles and curves
- Relaxed checkpoints
- ٠.
- Bezier curves... eventually

#### Reminder

Get it right, then get it fast.



Any questions?

