

Homework 3

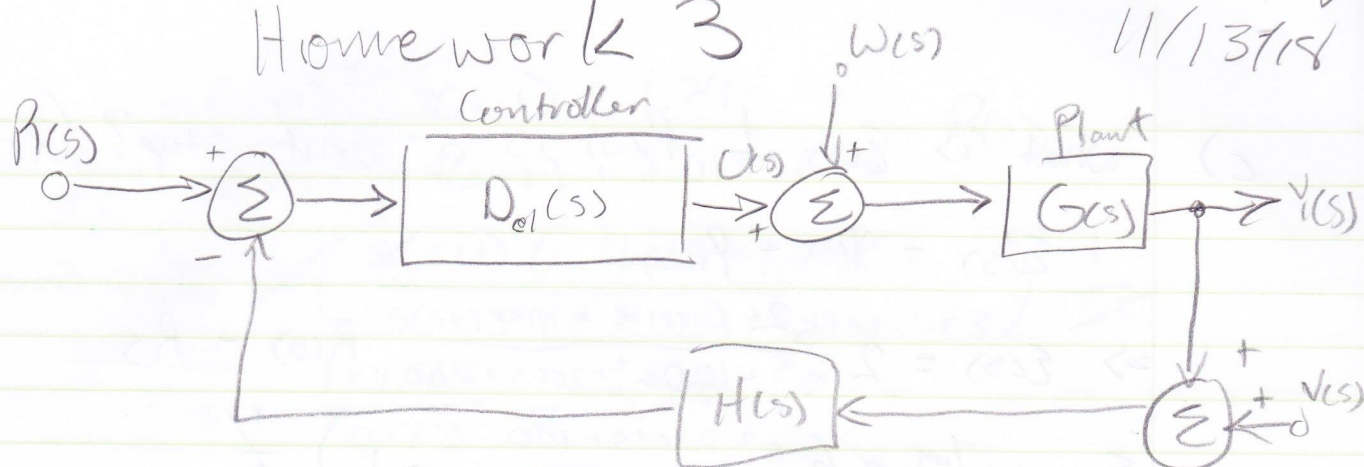


Figure 1

4.8

$$G(s) = \frac{1}{s}, \quad D_c(s) = \frac{2(s+1)}{s}, \quad H(s) = \frac{100}{s+100}$$

a) Find $\frac{Y(s)}{R(s)}$.

$$\frac{Y(s)}{R(s)} = \frac{Y(s)}{Y(s)} = \frac{D_c G}{1 + D_c G H} = \frac{\frac{2(s+1)}{s^2}}{1 + \frac{200(s+1)}{s^2(s+100)}}$$

$$= \frac{(2s+2)(s+100)}{s^2(s+100) + 200s + 200} = \frac{2s^2 + 202s + 200}{s^3 + 100s^2 + 200s + 200}$$

$$\boxed{\frac{Y(s)}{R(s)} = 2 \frac{s^2 + 101s + 100}{s^3 + 100s^2 + 200s + 200}}$$

b) Find $\frac{Y(s)}{W(s)}$.

$$\frac{Y(s)}{W(s)} = \frac{G}{1 + D_c G H} = \frac{\frac{1}{s}}{1 + \frac{200(s+1)}{s^2(s+100)}}$$

$$\boxed{\frac{Y(s)}{W(s)} = \frac{s^2 + 100s}{s^3 + 100s^2 + 200s + 200}}$$

c) what is $E(s)$ if $R(s)$ is a unit-step? ($R(s) = \frac{1}{s}$)

$$E(s) = Y(s) - R(s)$$

$$\Rightarrow E(s) = 2 \frac{s^2 + 101s + 100}{s^3 + 100s^2 + 200s + 200} R(s) - R(s)$$

$$E(t \rightarrow \infty) = \lim_{s \rightarrow 0} s \left(2 \frac{s^2 + 101s + 100}{s^3 + 100s^2 + 200s + 200} - 1 \right) \frac{1}{s}$$

$$E(t \rightarrow \infty) = \frac{200}{200} - 1 = 0.$$

d) what if $R(s)$ is a unit-ramp? ($R(s) = \frac{1}{s^2}$)

$$E(t \rightarrow \infty) = \lim_{s \rightarrow 0} s \left(2 \frac{s^2 + 101s + 100}{s^3 + 100s^2 + 200s + 200} - \frac{s^3 + 100s^2 + 200s + 200}{s^3 + 100s^2 + 200s + 200} \right) \frac{1}{s^2}$$

$$= \lim_{s \rightarrow 0} \left(\frac{-s^3 - 98s^2 + 2s - 100}{s^4 + 100s^3 + 200s^2 + 200s} \right)$$

$$E(t \rightarrow \infty) = \frac{1}{100}$$

4.9 For Figure 1, suppose that $G(s) = \frac{1}{s(s+1)^2}$, $D_c(s) = 0.73$,
 c) $H(s) = \frac{2.75s + 1}{0.36s + 1}$

What is the value of the velocity error coefficient K_v ?

$$E(s) = R(s) - Y(s) = \left(1 - \frac{D_c G}{1 + D_c G H} \right) R(s) = \left(\frac{1 + D_c G H}{1 + D_c G H} - \frac{D_c G}{1 + D_c G H} \right) R(s)$$

$$E(s) = \frac{1 + D_c G (H - 1)}{1 + D_c G H} R(s)$$

$$E(s) = \frac{1 + \frac{0.73}{s(s+1)^2} \left(\frac{2.75s+1}{0.36s+1} - 1 \right)}{1 + \frac{0.73(2.75s+1)}{s(s+1)^2(0.36s+1)}} R(s) = \frac{1 + \frac{0.73}{s(s+1)^2} \cdot \frac{2.39s}{0.36s+1}}{1 + \frac{0.73(2.75s+1)}{s(s+1)^2(0.36s+1)}} R(s)$$

$$E = \frac{s(s+1)^2(0.36s+1) + 1.74s}{s(s+1)^2(0.36s+1) + 2.01s + 0.73} R(s)$$

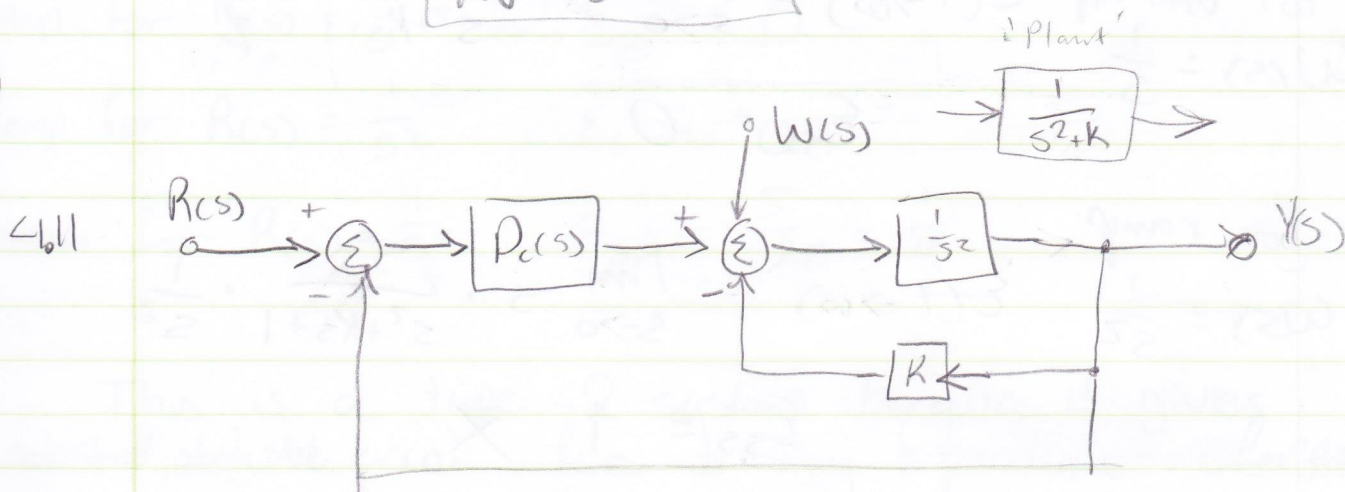
$$E(t \rightarrow \infty) = \lim_{s \rightarrow 0} s \left(\frac{s(s+1)^2(0.36s+1) + 1.74s}{s(s+1)^2(0.36s+1) + 2.01s + 0.73} \right) \frac{1}{s^2}$$

$$= \frac{1 + 1.74}{0.73} = 3.75$$

$$\frac{1}{K_v} = E_{ss} \text{ for } R(s) = \frac{1}{s^2} \text{ (unit ramp)}$$

$$\frac{1}{K_v} = 3.75$$

$$K_v = 0.267$$



- a) What condition must $D_c(s)$ satisfy so that the system can track a ramp reference with constant error

Since the Plant is a type 2 system ($G(s) = \frac{1}{s^2 + k}$), $D_c(s)$ has to include an integrator to track a ramp reference with constant error.

4.11 b)

for disturbance $W(s)$
 Set $R(s) = 0$, $W(s) \neq 0$

$$E = R - Y = -Y$$

$$\Rightarrow \frac{E}{W} = T_W = \frac{1}{\frac{s^2 + K}{1 + \frac{1}{s(s^2 + K)}}}$$

$$= \frac{1}{s^2 + K + \frac{1}{s}}$$

$$\frac{E(s)}{W(s)} = \frac{s}{s^2 + Ks + 1}$$

for unit step $E(t \rightarrow \infty) = \lim_{s \rightarrow 0} s \cdot \frac{s}{s^2 + Ks + 1} \cdot \frac{1}{s}$
 $W(s) = \frac{1}{s}$

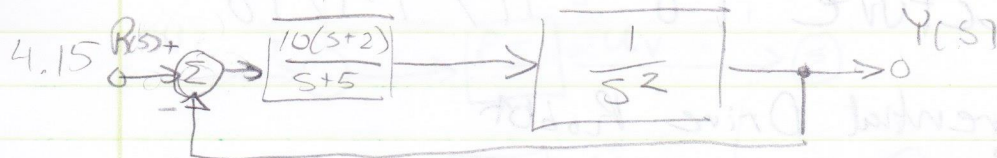
$$E_{ss} = 0$$

for ramp
 $W(s) = \frac{1}{s^2}$

$$E(t \rightarrow \infty) = \lim_{s \rightarrow 0} s \cdot \frac{s}{s^2 + Ks + 1} \cdot \frac{1}{s^2}$$

$$E_{ss} = 1 \quad \times$$

the system can handle step-disturbances
 with 0 steady-state error.



a) Find the system type for reference tracking and the corresponding error constant for the system

$$E = \frac{1}{1 + \frac{10(s+2)}{(s+5)s^2}} = \frac{s^2(s+5)}{s^2(s+5) + 10(s+2)}$$

$$= \frac{s^3 + 5s^2}{s^3 + 5s^2 + 10s + 20} \quad s^2$$

step for $R(s) = \frac{1}{s}$ $E_{ss} = 0$

ramp for $R(s) = \frac{1}{s^2}$ $E_{ss} = 0$

parabola for $R(s) = \frac{1}{s^3}$ $E_{ss} = \frac{5}{20} = \frac{1}{4}$

This is a type -2 system, because it gives constant steady state error for tracking a parabolic reference

Static
error
constant

$$\frac{1}{K_a} = E_{ss}$$

$$K_a = \frac{1}{E_{ss}} = 4$$