#### Jonathan Distler

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# **Education**

Bachelor's Degree in Science, Cornell University; Ithaca, New York

Expected Graduation: May 2027 Major: Mechanical Engineering

Minor: Physics GPA: 3.62

Selected Coursework: Electricity and Magnetism Honors, Dynamics, Statics and Mechanics of Solids, Thermodynamics, Differential Equations, Lasers and Photonics, Special Relativity, Independent Research

# **Experience**

### **Magpie Aerospace Engineering Project Intern**

January 2024-Present

Cornell University Aerospace Adversary Lab; Ithaca, New York

- -Cooperating with a large team of co-workers to facilitate multi-disciplinary aerospace and cybersecurity projects, funded by the US Department of Defense
- -Applying SITL, ROS 2, Gazebo, C++, and Python to develop procedures within aerospace simulations to avoid obstacles with an autonomous 6-degree-of-freedom drone to test obstacle avoidance methods readily
- -Setting up an indoor GPS system coupled with ROS 2 to serially communicate with a group-developed drone and allow for accurate indoor remote control with a mapping accuracy of up to 2 cm
- -Successfully co-authored a systems paper for autonomous drones, which was submitted to a journal

#### **Cornell Hyperloop Project Team Member**

September 2024-Present

Cornell University Hyperloop Project Team; Ithaca, New York

- -Working as a part of the structures subteam to coordinate the development of a magnetic-levitation system for use in a high-speed hyperloop train propulsion
- -Modeled the heat transfer delivered to the hyperloop train via the battery packs, and determined the rate of heat exchange for a 240 W battery system
- -Modelling the impulses delivered to the battery pack system due to braking and track deviations, to judge the success of the battery pack enclosure system
- -Successfully developed a battery pack enclosure system minimizing cost (~\$200), safely protecting over \$2,000 worth of electronic components, and allowing for easy access

### **Human-Drone Interaction Research Intern**

December 2023-June 2024

Virginia Tech Department of Mechanical Engineering; Blacksburg, Virginia

- -Co-developed a conceptual framework for a mass drone delivery system to address food insecurity within rural communities
- -Co-authored a paper accepted and presented at the IEEE Region 8 MIPRO Conference (<u>Exploring the Utilization of Drone Technology to Promote Food Security</u>)

#### **Biomechanical Engineering Project Intern**

June 2024-August 2024

Virginia Tech Department of Mechanical Engineering; Blacksburg, Virginia

- -Created an H-Bot control system to time-stamped ultrasound images of octopus movements using Matlab and Serial Communication techniques to have more accurate surface scans of soft tissue
- -Successfully developed a novel soft robotic muscle prototype capable of expanding and contracting to intended diameters and lengths, using material property analysis as part of a research team
- -Successfully developed a software program to model the muscle's movements using Java

#### **Computer Science Genome Data Analysis Intern**

May 2022-September 2022

Virginia Tech Department of Computer Science; Blacksburg, Virginia

- -Created an interactive Python notebook that used JSON and API to retrieve expansive datasets
- -Leveraged the data to show data trends among the 500 fastest benchmarked computers in the world
- -Used data analysis skills I was able to derive data and trends from pulled data sets and successfully published findings ( <u>CS Genome Project</u>)

# **Stormwater Maintenance Assistant Manager**

August 2019-August 2024

Storm Water Solutions; Blacksburg, Virginia

- -Utilized civil and environmental engineering techniques to preserve bioretention ponds and prevent flooding at a local level, as a part of Blacksburg Town Council's Stormwater Initiative.
- -Implemented changes to prior bioretention ponds to successfully pass all town-sanctioned inspections.